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Processing of On-Board Recorded Data for Quick Analysis of Aircraft Performance

Norman H. Michaud

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Processing of On-Board Recorded Data for Quick Analysis of Aircraft Performance

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National Aeronautics
and Space Administration

**Scientific and Technical
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Foreword

The National Aeronautics and Space Administration (NASA), Wallops Flight Center participated in the flight testing operations of the NASA/ARMY Rotor Systems Research Aircraft (RSRA) project. Flight testing began at Wallops in July 1977 and scheduled to terminate upon acceptance of the aircraft in August 1979.

This publication is based upon the set of computer programs designed to meet the 24 hour data processing requirement for "quick look" analysis. The entire set of programs have been designed under one software system called EASE (Early Analysis System Evaluation). This system can be adapted to similar helicopter projects requiring "quick look" information on helicopter performance. The basic structure of the EASE system is the design of the Raw Data File. Hence, modifications of project requirements based upon the method of input or output to the Raw Data File can be easily incorporated into the EASE system.

The EASE system was successfully designed with the aid of Mr. Ken Lewis of Sikorsky Aircraft and Mr. Jon Stripling of NASA, Wallops Flight Center. Individual software contributions to the EASE system were performed by Mr. Terry D. Sommers, and Mr. David L. Davis, and Mr. Donald Woodward of the Computer Applications Section, NASA Wallops Flight Center; Mrs. Jeannette Wessells, Mr. Tom Taylor, Mr. Joseph Lapierre, Mr. Gus Dovi, and Mr. Leslie Brimer of Computer Science Corporation.

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PROCESSING OF ON-BOARD RECORDED
DATA FOR QUICK ANALYSIS OF AIRCRAFT PERFORMANCE

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INTRODUCTION

The Early Analysis System Evaluation (EASE) is a collection of independent software programs designed to provide an overview of flight performance within twenty-four hours. Because of the short time frame for processing flight data, this system does not provide detailed analysis of flight performance. However, sufficient information is available for such analysis. There are twelve major tasks that compose the EASE software system. These are:

(1) SETUP reads the information necessary to process data for a particular flight operation. These data are then stored on a random file for access and updating by other tasks in the software system.

(2) SCAN reads the digitized data tapes, performs minor editing, stores the data in the raw data file and computes the statistics in raw units.

(3) RDFRD is a set of subroutines used by the remaining tasks in accessing data and statistics from the raw data file.

(4) ABTASK computes the linear coefficients for the data based upon known laboratory measurements and pre-flight and post-flight calibrations.

(5) STATPRINT provides a formatted listing by sensor of the computed statistics from either the SCAN or DPTASK programs. Data can be represented either in raw units or engineering units.

(6) DPTASK derives certain information from the aircraft's instrumented data. These parameters, such as airspeed, are computed as a function of specific instrumented data. Such information is computed, then stored on the raw data file along with its statistics.

(7) DATASK provides a different formatted listing of the statistical data than the STATPRINT task. Up to 18 different sensors are grouped on an output listing in column format for comparative analysis.

(8) CYCLE COUNTS of certain data indicating aircraft stress points. By comparing a known stress point concern level value to the flight data, an output listing is generated by this task to indicate the number of data points exceeding 75 percent of this level in 25 percent incremental intervals.

(9) TIME HISTORY is a plotting routine of the data in engineering units versus time. Up to twelve different sensors can be plotted on one plot page.

(10) HARMONIC ANALYSIS computes the harmonic coefficients on sensor data for given flight maneuvers. The first ten coefficients for both the sine and cosine terms are computed as well as the resultant coefficients and the associated phase angles.

(11) UPGEN maintains a catalogue of sensor identifications that are used by various tasks for titling the data on output listings. Data is referenced initially by mnemonic names through the SETUP task. These mnemonics are used to identify the information contained in the Universal Parameter Catalogue (UPC) file.

(12) TPDMP and TABLE PRINT perform utility functions for the EASE software. TPDMP provides a selected dump of the magnetic tape digitized by the EMR 6130 computer system. TABLE PRINT provides a listing of the current contents of the Table File portion of the Raw Data File.

During flight operations, data is being recorded only during experimental maneuvers. The system requires the data to be identified and processed by each maneuver of the flight. A d.c. signal is recorded during flight operations which determines the stream of data being recorded for a given flight maneuver. When this signal, called the run tone, is "on" the information contained on the data tapes is valid experimental data for a given flight maneuver. A run tone "off" condition indicates the termination of data gathering for that maneuver. Using this recorded run tone signal, each burst of data represents the information recorded for one flight maneuver.

Processing of the flight data through the EASE system groups the data by the identified flight maneuvers and calculates statistics for each flight maneuver. The data and statistics are stored on the raw data files (RDF). These files are classified as random files so that specified portions of the flight data are quickly accessible.

The data are initially recorded in analog form in two different modes: pulse coded modulation (PCM), and frequency modulation (FM). Different processing techniques are applied to the PCM and FM recorded data. PCM data is digitized at a fixed time sampling rate. The FM data is first processed through a peak stress analyzer. This step in the processing system is a hardware function that samples a channel of FM data at a sample rate based upon the revolution of the helicopter's main rotor or tail rotor. A sampling rate of five samples per main rotor revolution will produce five data samples for one 360 degree revolution of the main rotor.

A channel of data input to the peak stress analyzer produces two channels of output data. One channel contains the peak or maximum values of the input signal while the other channel contains the valley or minimum values. The peak stress analyzer used for the project can process up to twenty input channels of data at one time producing a total of forty channels of data -- twenty peak channels and twenty valley channels. These output channels of the peak stress analyzer are then digitized.

Because of the hardware limitation of twenty data channels available on the peak stress analyzer and the fact that data processing requirements dictate different main and tail rotor sampling rates for different types of data, data digitization must be performed in multiple passes of the data. Selected channels of data are processed together through the peak stress analyzer at a given sampling rate and digitized from beginning to end of the flight. This is defined as a pass of data. A second grouping of data channels is similarly processed, yielding a second pass of data. This continues until all possible FM data configurations have been processed through the peak stress analyzer.

The digitization process of the flight data therefore produces two types of digital data on 9-track magnetic tape. Both types of data not only use different processing techniques, but also produce two different types of formats. These formats are defined in the SCAN routine. The EASE system accepts both the PCM and FM data for processing.

All the information including the digitized data and computed statistics is maintained on the Raw Data File (RDF) for each flight. The RDF is a set of random physical files that contain all the necessary flight information. There are four basic file configurations established for the EASE system: the Table File, the Statistics File, the Data Files, and the Universal Parameter Catalogue (UPC) File. The UPC File is a common file used by every flight in the project while the other three are uniquely built for each flight. The Table File is initially built by the SETUP routine. It is a random file assigned to file code 07. The entire file is 42 logical records in length with each record fixed at 600 words. The SETUP routine documentation provides a detailed description of the Table File.

The Statistics File contains the statistics in raw (machine count) units for each sensor and computed for each flight maneuver. The file is a random file with each logical record having a fixed length of 400 words. This file is built by the SCAN routine onto file code 09 as it reads and stores the digitized data.

The configuration of the Statistics File conforms to the pass and flight maneuver constraint definition of the system. These constraints are defined so that data for no more than 40 sensors is to be grouped together for flight processing during one pass. The flight being processed can have no more than 100 defined flight maneuvers. Using these constraints, the positioning of data on the Statistical File can be defined.

Each sensor is assigned by the SETUP routine to a particular pass and to one of the 40 sensor positions of the pass. Each pass is numbered from 1 to 20 and the assigned position of the sensors in each pass is numbered from 1 to 40. The flight maneuvers are also assigned numerical values (called run numbers) from 1 to 100 by the SETUP routine.

The statistical data is randomly stored based upon this indexing scheme. The record address is a function of the pass number and run number. It is defined as:

$$100*(IPASS-1)+IRUN,$$

where IPASS is the pass number and IRUN is the run number.

There are 10 data words assigned for the statistical elements for each sensor. Since there is a maximum of 40 sensors per pass, each data record contains the statistics computed for each flight maneuver for a given pass. The defined position of each sensor through the SETUP routine determines which set of 10 data words contains the statistics for a given sensor. A set of statistics is found by the formula:

$$10*(IELEM-1)+IPOS,$$

where IELEM is the assigned element number of the sensor through the SETUP routine and IPOS is an indexed value from 1 to 10 for each statistical element for that sensor. The statistics stored within the 10 words index by IPOS are:

- (1) the maximum value,
- (2) the corresponding vibratory component of peak stressed FM data at the time of maximum steady value or the corresponding steady value at the time of maximum vibratory,
- (3) the minimum value,
- (4) the corresponding vibratory or steady component at the time of minimum steady or vibratory value, respectively,
- (5) the average value,
- (6) the standard deviation,
- (7) the 95 percentile value for the vibratory FM data only,
- (8) the total number of points processed for this maneuver,
- (9) the total number of error points for the maneuver, and
- (10) a 6-character error code status word. Characters 1, 2, and 3 are not used; character 4 non-zero value signals errors due to loss of synchronization; character 5 non-zero value signals over full scale data error; and character 6 non-zero value signals data parity error. A detailed description of the computation of these statistics and their meanings is given under the SCAN task.

The data file is also configured as random with each pass of data being assigned to one physical file. The file code for each data file is assigned a number that is 10 plus the assigned pass number. For example, the data file for pass 5 is assigned to file code 15.

The physical size of a record within these files are 640-words in length. The records are blocked by flight maneuvers. That is, whether or not a complete record is filled with data, a new record is begun with a change in flight maneuver. The configuration of the 640-word data file record is of two types: one type of configuration for data being processed and recorded through the SCAN routine, and the other for data being processed and recorded through the DPTASK routine. In either type, data is grouped into

a frame of data with multiple frames within the 640-word record. A frame of data is defined as an array of data sampled or derived at a given time for all sensors described for a given pass. That is, the sensor grouping described through the SETUP routine for a given pass determines the array configuration for a frame of data. In both types of data configuration, the first two words of the data record contain the run number assigned to the flight maneuver and the number of frames of data that are stored on this record.

For the data processed through the SCAN routine, 11 data words are used for a frame of data. The first word of each frame is the recorded time in milliseconds for the data samples being recorded. Since the data being scanned has only a 9-bit accuracy, four data samples are packed into one 36-bit data word. Hence, ten words contain 40 samples of data. A maximum of 58 frames of data can be recorded into one 640-word record.

The derived parameter data, however, is calculated in engineering units and requires a full data word for each sample. There are, therefore, 41 data words required for a frame of derived parameter -- the first word being the time tag and the next 40 being the data samples. Fifteen such data frames can be recorded on a 640-word record.

The EASE software system package is flexible in its mode of operation. The distinct tasks that are required for a particular operation are executed as separate activities in the order that they are required. The normal flow of processing is first to define the data configuration for flight and sensor data constants through the SETUP routine; second to read the flight data and compute their statistics through the SCAN routine; third to compute the engineering unit conversion factors through the ABTASK routine; fourth to compute the derived parameters through the DPTASK routine; and fifth to provide the requested output data through the STATPRINT, DATASK, CYCLECOUNT, and TIME HISTORY plot routines. However, either because of the lack of complete information or because of data errors, this normal flow of EASE activities may have to be altered. These circumstances must be investigated by the system user when preparing a run for processing. Figure 1 gives a visual description of the EASE digital processing scheme.

Each task requires a specific card input setup that can be classified into three categories: first is the program deck with its associated job control cards; second is the job control cards for the file configuration; and third is the data cards required for flight parameters.

The deck setup for the computer program and its associated job control language is the standard configuration for the computer system being used. The job control cards for the data file configuration is also a function of the requirements for the computer system's file description requirements. The software requires specific file codes for each data file and expects the files to be configured in a random mode. The description of these files to the computer's operating system is dictated by the particular computer file description requirement. Appendix A summarizes the job control language required to

execute each program on the Honeywell 600 computer system. The remainder of this section describes the use of each task in the EASE system along with their data card descriptions.

SETUP

The purpose of the SETUP routine is to build the Table File. The Table File is used to describe the Data File format and flight parameters for a given flight. There are five tables that are defined within the Table File. These are the Header Table, the Pass Table, the Sensor Table, the Calrun Table, and the Event Table. These tables are built through card input.

The format of the Table File is defined as a random file consisting of a total of 42 physical records. Each record is pre-defined as a particular type of table. The structure of the Table File is described in figure 2. The SETUP routine initially builds these files through card input.

This task is designed for interaction with an input card deck for properly transferring the table information into the respective record areas of the Table File. Communication with the program is primarily performed by using unique two-character codes in columns one and two of the input card deck. The necessary communication required by the program is divided into three major categories. The first category is called the "L1" level of input. This level of input informs the software to begin processing in either an initialize or update mode and to terminate processing. These cards must be the first and last cards of the input data deck setup. The second category, called the "L2" level of input, informs the software that the following data cards in the deck setup contain the data values for a particular table. All data cards following an "L2" level card up to the next "L2" level card or the final "L1" level card contain the data values for the table specified by the leading "L2" card. The detailed entries for each table form the third category of data.

The order of input for the Header Table and the Event Table is unimportant. However, the information for the Pass Tables is located on an "L2" level card that precedes the Sensor Table data for that named pass. Also, the Calrun Table data indicates which events contain pre- and post-calibration data for a named sensor. The program requires that the Sensor Table be present in order to cross-reference the two tables.

The "L1" level cards used in the SETUP routine are described in figure 3. The option name specified on the first card informs the program that the execution of this task is either to initialize the Table File or update the current Table File with the input data cards. The update option assumes that only those input cards present require value changes in the current data file. There are a few remarks that must be stated for proper execution of this program in the update mode:

(1) If the value of only one data field is to be modified, all information that is specified for that card image must be present. The SETUP routine reads a card image and will modify each data value that is expected on that data card.

(2) Because of the interrelationship of the Pass Tables, Sensor Tables, and Calrun Tables, any modification to a given Pass Table or to any one sensor referenced to a given pass requires that the Pass Table, all sensors referenced to that pass and the Calrun Tables must be included in the deck setup.

(3) A modification to the Calrun Tables do not require the inclusion of the Pass or Sensor Table data. However, the entire set of Calrun Table data cards must be included for one change in the Calrun Table setup.

One additional remark that pertains to the execution of this task in either the initialize or update mode is that the Calrun Tables must be placed after the Pass and Sensor Table data cards.

The Header Table consists of four data cards preceded by an "L2" level card. Input for the initialize mode will store blank or zero values for data fields left blank or for data fields defined for a missing data card. The update mode requires all the data fields on a supplied input card to contain the proper data values. Data fields that are blank will cause blank or zero data to be stored in that Header Table data element. Only those card images requiring data modifications need to be supplied. Figure 4 contains a description of the data elements in the Header Table and figure 5 gives the data card image format for this table.

The Pass Table is contained in records 2 through 21 of the Table File. Each record contains information pertaining to one defined data pass. The EASE system is thus limited to a maximum of 20 data passes. Each data pass is assigned, through card input, a pass number from 1 to 20. This pass number is used to assign the record number for storing the Pass Table data in the Table File. Pass Table data for pass "i" is assigned to record number "i + 1" of the Table File.

A pass has been defined as the processing of flight data for a group of sensors from beginning to end of the flight at a common sampling rate. Since the peak stress converter is capable of processing no more than 40 output channels of data at one time, the EASE system is designed to process no more than 40 channels of data on one pass also. This is true in the EASE system even in handling the PCM data which is digitized with more than 40 channels of data at a time.

There is a natural association of the Pass Table with the Sensor Table because of the definition of a pass. The order of card input for the Pass Table information on an assigned pass is associated with a specific set of sensors. The card image description for the Pass Table is, therefore, described along with the Sensor Table in figure 8.

The data elements within each Pass Table record is described in figure 6. The data contents of the Pass Tables will change to reflect information derived from the processing

of other tasks. In particular, the pass status word, ISTATC, will be updated by the SCAN routine to indicate the data is now available and it will be updated by the ABTASK routine to indicate the engineering unit conversion factors are now available. The array IADDR will be updated to reflect the data file addresses for each maneuver.

The Sensor Table contains information necessary to fully describe each data parameter processed in each pass. There is a maximum of 40 sensors described in each pass of data. The set of parameters processed together for a given pass are being sampled at a common sampling rate. This is the basic requirement for grouping parameters for a defined pass. The Sensor Table information is stored in records 22 through 41 of the Table File. The Sensor Table data for pass "i" is found in record number "i + 21" of the Table File. By using the address of the Table File records, the EASE system can therefore determine the pass associated with the Sensor Table data. Using a similar design feature, the contents of each Sensor Table record defines the ordering of the parameters within a pass.

Each parameter requires 13 data words for its description. With a maximum of 40 parameters per pass, a Sensor Table data record contains a maximum of 520 data words. The 13 data words for a given sensor "j" are then found in data word location "13j - 12" through "13j." The information contained in the 13 data words for each sensor are described in figure 7. Figure 8 outlines the data card images for the pass and sensor data for a given flight pass.

Data processed through the peak stress converter require specific ordering for Sensor Table entries. One data signal entering the peak stress converter produces two components of the data - a peak and a valley. In the case of data defined with pre-processing codes of vibratory and steady, the peak and valley components are mathematically combined to produce these two components. In the case of amplitude and phase components, two data signals are entered into the peak stress converter - one is the amplitude signal and the other the phase signal. Four data components are then produced - two for the amplitude and two for the phase.

The order of card input to the Sensor Table is important for data processed in this manner. For the vibratory and steady component sensor definition, the card image describing the vibratory component must precede the card image defining the steady component; for amplitude - phase data, the amplitude component must precede the phase component. The assignment of storage location for these components in the Statistics and Raw Data Files must also be in a similar ordering scheme.

The Calrun Table is used to associate the correct pre- and post-calibration maneuver number to every sensor on the flight. There are three different types of calibrations performed both before the flight begins and soon after the flight ends. Data is recorded with full loads on the instrumentation for the R-Cal; with no loads for the Z-Cals; and full stick and pedal positions for the transducer or X-Cals. Each type

of calibration is performed in a definite sequence and the data for each calibration step is recorded as a burst similar to a flight maneuver.

Not all calibration steps are applicable to every sensor. A series of calibrations are performed so that the necessary calibrations are available for each active sensor. The Calrun Tables are used to indicate which data maneuver numbers contain the correct information for each sensor.

There are two types of input cards required for the Calrun Tables. One specifies the six assigned maneuver numbers for pre- and post-calibrations for a group of sensors. The other specifies the sensors associated with that calibration scheme. The order of input is important. The card containing the calibration run numbers must precede those containing the sensor mnemonics associated with that set of run numbers. The cards containing the run numbers are identified by the code "CT" punched in columns 1 and 2. The cards containing the sensor mnemonics are identified by the code "CS" in columns 1 and 2.

The first set of calibration run numbers are associated with a majority of the sensors activated for the flight. Rather than list such a long list of sensors mnemonics, the first grouping of data cards for the Calrun Table contains the characters "AC" punched in columns 4 and 5 of the "CS" card that are associated with the "CT" card read. At most, eight sensor mnemonics can be specified on one "CS" card. Since more than eight sensors can be associated with a defined calibration run scheme, more than one "CS" card is acceptable for input. The procedure of associating a sensor to the last table of calibration run numbers is by either encountering a blank field for a sensor mnemonic on a "CS" card or encountering a new "CT" card. A maximum of 20 calibration run table entries can be specified.

The entry numbers associated with a calibration run table are calculated by the software. Each set of tables are numbered consecutively as they are read by the software. These entry numbers are entered into the Sensor Tables as the value of CALADR for the proper sensor.

This entry number also is used in the formatting of the Calrun Table record of the Table File. All Calrun Table entries are recorded in record number 42 of the Table File. Each entry contains six values that are the calibration run numbers. With a maximum of 20 entries, the Calrun Table can have at most 120 words of data. Data words "6i-5" through "6i" contain the calibration run numbers for entry "i". Figure 9 is a description of the Calrun Table and figure 10 is a description of the card images for this table.

The Event Table is a list of the flight maneuver information. It contains a 24 character field used to define a title for the experimental maneuver, the type of maneuver being performed and the time the event began. This table is an important aspect of the system since the data is being evaluated for each maneuver.

The card input requirements for this table are relatively straightforward compared to the Pass, Sensor, and Calrun Tables. The information required for each event is placed on a single input card. The order of input is dictated by the order of the maneuvers as given on the Flight Log. A run number is assigned to each maneuver.

The information for the Event Table is stored in record 43 of the Table File. There is a maximum of 100 maneuvers that can be defined for a given flight. Each maneuver requires six data words for its second entry making the Event Table size a maximum of 600 data words in length. The entry for run number "i" is placed in data words "6i-5" through "6i".

The data field contents for each maneuver in the Event Table is described in figure 11. The card image description for each maneuver is described in figure 12. The order of input for the Event Table relative to the input of the other four tables is irrelevant. Only the order of the data cards within the Event Table is important.

The SETUP routine provides the initial description of flight parameters. Items that are included in this description are the aircraft configuration information, the configuration of the digitizing process by passes, the sensor configuration of the data being processed, the pre- and post-calibration configuration for each sensor, and the description of the events that were performed on the flight.

This routine can be operated in two modes. The first is the initialize mode where all data entries for each table are initialized to the data provided on input cards. The second mode is the update mode where information supplied on data cards alter the previously stored Table File data.

The SETUP routine provides a limited editing capability on the set of input data cards. When errors are found in the setup of the input data card deck that can be checked by SETUP, appropriate error messages are printed and none of the information provided by the execution of this job is recorded. This is to insure that additional errors are not included into the Table File especially during an update mode. Items that are checked include the correct order of data cards, data fields using a specific numeric or character code entries contain only the allowable entries, and the maximum allowable sizes of each table is not exceeded. Items that cannot be edited include such things as incorrect spelling of character entries, incorrect entries of allowable codes, and incorrect data value entries that fall within the allowable range of the data. Care should therefore be taken to insure all entries to the Table File are correct. A detailed check using the output listing provided by the SETUP routine should be made to insure correctness of the information recorded in the Table File.

SCAN

This program is used to record the digitized data onto the Raw Data File, and compute and store the defined statistics. This program is the data processing task for the EASE system. The SCAN program accepts digitized data produced in the Televent II¹ format and sequentially reads each time-tagged frame of data.

Each frame of data is a set of digitized data samples in the form of an array. The association of a data sample within a frame of data to a given sensor is defined through the SETUP program for each flight. The variable, "IPARIN" of the Sensor Table, indexes the appropriate data word within the data frame. Each referenced data sample is also stored into the Raw Data File in a position determined by the variable "IPARDF" of the Sensor Table. The flight data to be processed is divided into passes, digitized by different pre-processing schemes, originally recorded as different types of data, and partitioned according to a prescribed set of flight maneuvers.

A pass of data is a complete set of data frames for a flight configured according to the Sensor Table for that pass. Each pass is numbered through input to the SETUP program. The location of data for each sensor is then fixed during the processing of a pass by the set of "IPARIN" indices noted in the Sensor Table for that pass.

The type of data being processed must also be known since the data is digitized differently for each type of data. There are only two types of data that are recorded: FM and PCM data. Both use the Televent II recording scheme but the length of their data frames and the bit configuration of each data sample are different. A PCM data frame is 110 data words in length and each data sample contains nine bits of data plus one odd-parity bit. An FM data frame is 42 data words in length and each data sample contains nine bits of data plus three bits of "noise" data. Hence, the decoding of information requires that SCAN recognizes these differences. This is given through the variable "SRDIN" of the Pass Table input through SETUP.

The pre-processing code specified through the variable "PPC" of the Sensor Table informs the SCAN program on how to handle the input data. The pre-processing for FM data may require that the information pass through the peak stress converter before digitizing. This would provide a pair of data points for each sensor. These points are the maximum and minimum data values within the specified sampling interval. These points are then combined in SCAN to produce the vibratory and steady components of the sensor. Data having pre-processing codes of amplitude and phase are also processed through the peak stress converter but are processed in the SCAN program differently than vibratory and steady data.

¹ See Appendix B for a description of the Televent II format.

Finally, the partitioning of the data by a prescribed flight maneuver scheme must also be known by the SCAN program. This is normally provided by a run tone signal that is digitized and recorded within each frame of data. When the run tone is "on," that is, a high data value recorded, the data contained within that frame of data is to be processed. When the run tone value drops to a minimum value, this signals the end of data sampling for a flight maneuver. The run tone switching to a high value in a successive frame of data signals the beginning of a set of data frames for the next maneuver. Such a scheme for partitioning the data into separate maneuvers is not assumed to be foolproof so that a means of identifying the partitioning scheme is provided as card input to the SCAN program. The partitioning of sets of data frames into bursts permits the program to calculate statistics for each maneuver.

The SCAN program calculates the required statistics for each sensor as the data is being read. There are ten statistical values recorded for each flight maneuver on each sensor. These are the maximum and minimum points, average, standard deviation, total number of samples in the event, number of error points and coded word denoting the type of data error. In addition to these seven values, data processed through the peak stress components for a sensor require the corresponding component value at the time of maximum and minimum recorded value for the vibratory and steady data. That is, the data value of the vibratory component at the time of maximum and minimum steady is recorded in the statistics record. The steady values are similarly recorded at the time of maximum and minimum vibratory values. The 95th percentile point is the tenth statistic. It is only computed for vibratory component data.

It is then evident that the processing requirements are rather complex and require additional information to relate the SCAN program as to how the data is presented in the input file and how it is to be processed and transferred to the raw data file. Some of the information is available from the Table File stored by the SETUP program. However, some of the information that is needed must be supplied directly to the SCAN program. This is done through card input.

There are three types of data cards that are used by the SCAN program. Each is distinguished by a two character coded value in the first two columns. The card coded by "SD" is the pass configuration card. The card coded by "BT" is the burst processing card and the one coded by "L1" is a processing termination card. Figures 13, 14, and 15 outline the information required by each type of input card.

The order of card input follows the logical sequence of processing the data. The first data card must be an "SD" card in order to inform the SCAN program as to which pass is to be processed and where the data is to be found on the input file. Following the "SD" card are the "BT" cards that instruct the program to process those data bursts that cannot be processed by the run tone signal. If more than one pass is to be processed, another "SD" card followed by its required "BT" cards are then read. This scheme

continues until all passes to be processed are defined. The last card of the input data deck is the "L1" card.

There are four types of conditions for processing a burst of data. One is by the run tone signal, another by time, a third by skipping an erroneous burst of data and lastly by defining a burst when one was not present on the input file. These four types of conditions are defined by the variable "ICOND" on the "BT" card. "BT" cards need not be present to describe the processing mode of each burst of data. Only those conditions where processing of a data burst other than run tone need to be included in the input deck. If a "BT" card is not present for a numbered burst, it will automatically be processed using the run tone. Figure 14 contains the coded values of "ICOND" for the different burst selection conditions.

In order to process data through the SCAN program, supporting documentation must be available with the input file. This includes a burst interval listing and a flight log. The digitized data is pre-processed using the run tone signal onto a magnetic tape. At the time of digitization, a burst interval listing is generated noting the time interval for detected bursts by run tone. The total number of these intervals must coincide with the total number of events outlined on the flight log. When there is a discrepancy between these two pieces of information, both forms must be studied to determine where the discrepancy is and how to correct it. This is done by inserting "BT" cards into the input data deck for the SCAN program specifying the processing condition for that burst of data. For example, it may be that burst number ten is a set of data frames with the run tone having been keyed on when an actual maneuver did not take place. This burst would then have to be skipped in the processing of the data tape by using a "BT" card for burst number ten with "ICOND" equal to one. Another possibility is that the run tone was not turned off between two maneuvers so that two maneuvers have been detected as one burst of data. In this case, the "BT" cards would contain a value of two for "ICOND" along with the maneuver time intervals. The SCAN program would then process these bursts by time intervals. Finally, there may have been a defined maneuver according to the flight log but the run tone signal was not on. In this case no data is present on the input tape and a "BT" card would be needed with "ICOND" equal to three.

The SCAN program is the main processing routine for the EASE system. It requires execution of the SETUP program in order to define the configuration of the data on the pre-processed magnetic tape. A study of the flight log and a listing of the burst intervals contained on the input file is required to properly align each burst of data to the prescribed flight maneuvers. Samples of the burst interval listing and flight log are found in figures 16 and 17.

RDFRD

This is the subprogram for accessing data and statistics from the Raw Data File (RDF). It is designed to use as a sub-module of each program requiring access to information on the RDF. This subprogram consists of three subroutines - RDFRD, RDFSUB, and UNPACK. The subroutine, RDFRD, accesses data samples or statistics requested through the input argument list and returns the information to the calling program either in raw units or in engineering units. If the requested data is not available, RDFRD returns the appropriate error codes which can be interpreted by the calling program. The subroutine RDFSUB is used when the calling program furnishes only the mnemonic name, pre-processing code and sample rate for the requested data. RDFSUB then searches the Table File to determine the pass and element number as well as the engineering unit coefficients so that RDFRD can locate and convert the requested information. UNPACK is used by the subroutine RDFRD when data samples are requested by the calling program. Each data sample within the RDF has been packed so that each computer word contains four successive data sample values. UNPACK extracts the appropriate "byte" for the requested data samples.

Figure 18 is a list of the arguments for subroutines RDFRD and RDFSUB. Since the subprogram RDFRD is not an independent program, there is no card input directly required by this subprogram. All information is furnished through the appropriate program that accesses the RDF and thus requires the use of the RDFRD subprogram.

ABTASK

This program computes the engineering unit coefficients for linear conversion of the data contained on the RDF. The operation of this program depends upon information on the Table File. No card input is required at the time of execution of the ABTASK program. The engineering unit coefficients are computed for every sensor defined in the Table File whose data has been entered into the RDF by the SCAN program. Hence, successful execution of the SETUP program and SCAN program is required before this program can perform meaningfully.

ABTASK first checks the present value of "ISTATC" of each Pass Table record (see figure 6). The engineering unit coefficients will only be calculated if "ISTATC" equals one. This indicates that the data has been scanned and entered into the RDF but the engineering unit coefficients have not yet been calculated. Once a pass has been found with such a condition, each entry of the Sensor Table for that pass is polled for additional information.

Within the Sensor Table, the data field contents of "PPC," "IPARDF," "CALITYP," "EUCV1," "EUCV2," and "CALADR" are needed by ABTASK. (See figure 7 for the definition

of these variables.) The engineering unit coefficients, calculated by ABTASK, are stored in the Sensor Table under the variables "A" and "B". Some of the information extracted from the Sensor Table play a minor role in the logical flow of the program. The value of "PPC" satisfies the requirement for computing the engineering unit terms for vibratory data. For the vibratory component data, the "A" term is as computed for the associated steady component while its "B" term is zero. The variable "IPARDF" is used to locate the appropriate average and standard deviation values for each sensor from the Statistics File, and the variable "CALADR" references the appropriate Calibration Run Table entries for that sensor. The variable "CALTYP" determines the type of calibration procedure required for each sensor. Because of the varied types of instrumentation available, several types of calibration procedures have been established. These procedures then require different types of linear conversion equations to compute the engineering unit terms. These have been categorized into five types for ABTASK: ACX, ACZ, PC, AB1, and AB2.

In addition to defining the type of calibration for each sensor, the total range and offset values in engineering units are supplied through the variables "EUCV1" and "EUCV2" respectively. The actual raw unit measurements for these values must be supplied also. These are furnished through the pre- and post- calibration steps performed for each flight. This information is contained on the RDF and is determined by the Calrun Table referenced by each sensor.

The equations for computing the A and B terms for each type of calibration is as follows: For the ACZ type of calibration,

$$A = \frac{EUCV1}{\bar{R} - \bar{Z}},$$

where

$$\bar{R} = (PRE * \bar{R}_e + POST * \bar{R}_t) / (PRE + POST);$$

\bar{R}_e = average in raw units (RU) of the pre- R cal run;

\bar{R}_t = average RU of post- R cal run;

PRE = 0 if there is no pre- R cal, = 1 if there is;

POST = 0 if there is no post- R cal, = 1 if there is;

and

$$\bar{Z} = (PRE * \bar{Z}_e + POST * \bar{Z}_t) / (PRE + POST);$$

\bar{Z}_e = average RU of pre- zero cal run;

\bar{Z}_t = average RU of post- zero cal run;

and

$$B = EUCV2 - (A * \bar{Z}).$$

For the ACX type of calibration, the engineering unit terms are

$$A = \frac{EUCV1}{\bar{R} - \bar{Z}},$$

and

$$B = \text{EUCV2} - (A * \bar{X})$$

where

$$\bar{X} = (\text{PRE} * \bar{X}_e + \text{POST} * \bar{X}_t) / (\text{PRE} + \text{POST});$$

\bar{X}_e = the average RU of the pre- X ducer cal run;

\bar{X}_t = the average RU of the post- X ducer cal run.

For the physical calibrations (type PC)

$$A = \frac{\text{EUCV2} - \text{EUCV1}}{\bar{H} - \bar{L}}$$

where

$$\bar{H} = (\text{PRE} * \bar{H}_e + \text{POST} * \bar{H}_t) / (\text{PRE} + \text{POST});$$

\bar{H}_e = average in RU of the pre- physical high cal run;

\bar{H}_t = average in RU of the post- physical high cal run;

and

$$\bar{L} = (\text{PRE} * \bar{L}_e + \text{POST} * \bar{L}_t) / (\text{PRE} + \text{POST});$$

\bar{L}_e = average in RU of the pre- physical low cal run;

\bar{L}_t = average in RU of the post- physical low cal run;

and

$$B = \text{EUCV1} - (A * \bar{L}).$$

For the AB1 type of calibration, no data is used for calculations

and

$$A = \text{EUCV1},$$

$$B = \text{EUCV2}.$$

And for the AB2 type of calibration, no data is required for calculation,

$$A = \frac{\text{EUCV1}}{(\text{EUCV2}/100.0) * \text{ACS}}$$

where

$$\text{ACS} = 512.0$$

and

$$B = 0.0$$

The average raw unit values used in the calculations for the ACZ, ACX and PC types of calibrations are referenced by the run number values specified in the Calrun Tables (see figure 9). If any entry to the Calrun Table is zero, there is no average value for

that type of calibration. This method is used when either the pre- or post-calibration values are required for a given sensor. In those cases where the Calrun entry is zero or the average value is null for both the pre- and post-calibrations the A and B terms cannot be calculated. The program then assigns $A = 1.0$ and $B = 0.0$. The calculated A and B terms are then entered into the appropriate Sensor Table position. When all sensors for a given pass have their engineering unit coefficients calculated, the "ISTATC" variable in the Pass Table is redefined as "2."

Three types of printout formats are produced by ABTASK. These reports summarize, on a pass basis, the information used to calculate the engineering unit coefficients as well as the coefficient values. Figure 19 lists the event numbers used for each Calrun Table entry used for the sensors in a pass. These run number entries correspond to the assigned event numbers associated with the Event Table (see figure 11).

The average value in raw units, its percent of full scale, the percent full scale shift between the pre- and post-calibration values and the standard deviation values is presented in figure 20. Percent full scale is based on the mid-range of the data being 0 percent. A value of 511 for the average value in raw units represents the null value. An outline of the final A and B terms calculated for each sensor along with the type of calibration, the calibration run table entry number and the given EUCV1 and EUCV2 terms is contained in figure 21.

STATPRINT

The STATPRINT program furnishes a tabulation of the statistical values for each flight maneuver for a given sensor. The statistical values are presented either in raw units or engineering units. Figure 22 is a sample of the report produced by the STATPRINT program. The purpose of this program is to furnish a detailed report on the statistical values for a given sensor. It is not a practical summary list for normal flight analysis due to the bulk of data that would be produced on all sensors of a given flight. Its primary use is in furnishing this data when detailed analysis is required.

The mode of operation for the STATPRINT program is controlled by card input. There is only one input card format required for any mode of operation. Figure 23 outlines the input card format for this program. There are three basic modes of program execution: a request for statistics of a specified sensor; a request for statistics for all sensors of a specified pass; and a request for statistics on all sensors within a given flight. The reports will be in either raw or engineering units depending upon the value of "ICONV" specified on the input card. There can be any number of input cards depending on what statistical reports are requested.

In order to furnish statistical data for a given sensor, information must be furnished for the mnemonic name, pre-processing code, and sample rate of the data

('NAME," "PPC," "SR'). This must be identical to the same information present in the Table File as input through the SETUP program. The STATPRINT program utilizes the subprogram RDFRD to locate the position of the statistics on the RDF by searching the Table File for sensors having the information from the cards read by STATPRINT. Failure to find the entry in the Table File results in an error message rather than the required statistics tabulation. When all sensors for one pass is required as output, the correct pass number in variable "IPASS" is all that is required for input. To process the statistical tabulations for all sensors of a given flight, no pass or sensor information is given on the input card.

In addition to specifying which of the three modes of output is requested, the request must include the appropriate code for "ICONV" for either raw or engineering values. An error will be noted if engineering unit values are requested and ABTASK has not been executed for the requested data.

DPTASK

The Derived Parameter or DPTASK program computes the values of selected parameters that are not directly sensed and recorded during flight. These parameters are derived as functions of directly sensed data. The input data is extracted from the RDF to calculate the derived parameter data. Statistics on the derived parameters are computed in the same manner as the directly sensed data.

The data and statistics computed in the DPTASK program is in engineering units. This is the exception to the raw data file format where all data stored in the RDF from the SCAN program is in raw units. Hence, ABTASK need not be executed for the derived parameter data. Consequently, this data cannot be extracted in raw units nor can the data values be packed into four data samples per computer word.

The calculation of the derived parameters follow the same general format for processing directly sensed data. Parameters are grouped similar to the normal grouping of sensor data with no more than 40 sensors per derived parameter pass. The definition of these sensors is controlled by the subroutine DPDEF which assigns the mnemonic names, pre-processing codes, and sample rates. This information is transferred to the Table File making appropriate entries to the Pass and Sensor Tables. The data and statistics are then assigned to the RDF according to the entries to the Table File. Accessing of derived parameter data can thus be performed through the RDFRD subprogram with only minor modifications due to the data not being packed. Calculation of the defined parameters is also performed through the subroutine DPDEF. Modifications to the set of derived parameters requires software changes to the subroutine DPDEF only. These modifications are transparent to the remainder of the DPTASK program or to the rest of the programs in

the EASE system. Appendix C contains the current set of derived parameters defined by subroutine DPDEF.

There is one data card required as input to the DPTASK program. As mentioned earlier, the subroutine DPDEF assigns a set of parameters to a given pass and builds the Pass and Sensor Tables for these sensors onto the Table File. Within DPDEF, the sensors are grouped into passes called derived parameter passes. The derived parameter pass must be assigned a unique pass number to fit within the other assigned pass numbers of a given flight. The input data card is used to assign a flight pass number to a derived parameter pass being processed. Figure 24 defines the card image for input to DPTASK.

DATASK

The Data Analysis or DATASK program furnishes the user a report of the pertinent statistics for up to 18 sensors on one report page. This provides a comparative view on the behavior of interrelated sensors during each flight maneuver. A sample of the printout report provided by the DATASK program is found in figure 25. There are several aspects of this printout that must be explained in order to understand the information presented.

Each page of printout contains four lines of title information, noted as (1) on figure 25. This is provided on input data cards. The column titles (2), are also initially provided on input cards that specify the mnemonic name, pre-processing code, and sample rate of the requested data. The mnemonic name and pre-processing code is then translated to a column title (3), if found in the Universal Parameter Catalogue (UPC) File (see UPCGEN program). The sample rate of the data (4) is listed under the sensor's column title. The titles provided for each line (5) or series of lines (6) is the name of the flight maneuver. This information is extracted from the Event Table of the Table File. Within the Event Table, each flight maneuver is either classified as a calibration, steady or transient maneuver. The DATASK program only lists the statistical data for non-calibration maneuvers unless specified differently by card input to this program. Only one line of output is required for steady maneuvers (5) and three lines are required for transient maneuvers (6).

The statistics listed for a steady maneuver are the 95th percentile for vibratory data and the average for all other data. For a transient maneuver the data is listed in the following format:

	PPC	PPC	PPC	PPC	PPC
	=D	=V	=S	=A	=P
Line 1	STAT5	STAT4	STAT3	STAT5	STAT5
Line 2	STAT1	STAT2	STAT1	STAT1	-
Line 3	STAT3	STAT1	STAT2	STAT3	-

where

STAT1 = the maximum value for the flight maneuver,

STAT2 = for vibratory, the corresponding value of the vibratory component of the sensor when the steady component is its maximum value; for steady, the corresponding steady value for the maximum vibratory value.

STAT3 = the minimum value for the flight maneuver,

STAT4 = the corresponding vibratory value for the minimum steady value,

STAT5 = the average value of the data for the flight maneuver,

PPC = pre-processing code, where D = Direct, V = Vibratory, S = Steady, A = Amplitude, and P = Phase.

The report does not explicitly indicate the type of flight maneuver but it is implied by the number of output lines presented. The DATASK program determines this by checking the event type code for each maneuver referenced in the Event Table. One further remark in regard to the DATASK output report is that a blank field indicates that there are no statistics for that parameter during the indicated flight maneuver. An entire column of blanks could indicate that the referenced parameter was not on during the entire flight. Or, such a condition could also indicate that the input card may be incorrectly referencing a parameter either due to a mispunch of the mnemonic name, pre-processing code, or the sample rate.

There are three types of input cards required by the DATASK program: the title cards, the maneuver specification cards, and the parameter specification cards. The title cards must be the first four cards of the input card deck and each contains any alphanumeric characters in columns 1 through 72.

The maneuver specification cards are next in order of card input. These input cards allow specific flight maneuvers only to be reported on the printout. The flight maneuver number associated with each run as described for the Event Table is entered right-justified in columns 2-6. As many maneuver specification cards as required are read by the DATASK program. A card with the word "END" in column 1-3 terminates the processing of maneuver specification cards. Under normal operations, the requirements for the DATASK output request all non-calibration runs to be processed. Rather than input a large set of data cards for this mode of operation, the DATASK program assumes such a procedure when no maneuver specifications card except the "END" card is present.

The parameter specification cards are then processed into the program. These cards are grouped into pages with each page containing up to 18 parameter cards each. An input data card with the word "PAGE" in columns 1-4 is required in describing a page grouping. This card is then followed with up to 18 parameter identification cards with one sensor described per card. The final page group being processed must be followed by a card with the word "END" in columns 1-3.

The format for the parameter identification cards are: Columns 1-8 (left-justified) is the sensor mnemonics; column 10 is the pre-processing code; and columns 15-17 (right-justified) is the sample rate. The input card description for the DATASK program is outlined in figure 26.

CYCLE COUNTS

This program operates only on the vibratory component of parameters pre-processed through the Peak Stress Converter. It provides a count of the number of vibratory data values which occur in each of eight class intervals. The lower edge of the first class interval is defined as 75 percent of the stated concern level value in the Sensor Table for that parameter. Each successive class interval up to the eighth and final class is defined in increasing steps of 25 percent of the concern level. The final class interval counts the number of data samples above 250 percent of the stated level of concern.

A sensor's vibratory component will be cycle counted for a given flight maneuver only if the following conditions are satisfied: (1) a concern level value greater than zero has been defined for the sensor in its Sensor Table; (2) either the 75 percent level is reached for at least one data sample within an event or that one-half the difference between the absolute maximum and absolute minimum is reached during an event; and (3) cycle counting has been specified by card input for a given flight maneuver or parameter. The absolute maximum level is defined as the maximum of the sum of the steady and vibratory components of the sensor ($S+V$) and the absolute minimum level as the minimum of ($S-V$).

The type of card inputs which define what vibratory data is to be cycle counted are the maneuver specification cards and the parameter specification cards. Maneuver specification cards are required only when specific events are to be cycle counted. Otherwise, all non-calibration events will be cycle counted. Parameter specification cards are required for two modes of parameter selection: all available vibratory parameters for a specified pass; or only for specified vibratory parameters. The default mode is to cycle count all vibratory components for the flight. A four-card title specification is also included as part of the input data deck. The title cards must be present to execute the CYCLE COUNT program. Figure 27 outlines the data card input requirements.

A sample of the output report produced by this program appears in figure 28. The area on the report indicated by (1) is the title specification information as it appeared on the input cards. The line indicated by (2) includes the sensor name, sample rate, and the value of its concern level. The column titles indicated by (3) define the statistical values presented for each flight maneuver that was cycle counted. The column, "N TOTAL," (4) indicates the total number of data samples for that flight maneuver. The remaining column headings indicate the eight classes (5). The last line of the report (6) contains the absolute maximum and absolute minimum for the flight and the total number of samples in each of the eight class intervals. Each sensor that has been cycle counted is reported in this manner.

TIME HISTORY

The function of the Time History program is to generate a plot of time history data from the RDF. The basic format consists of a 25 x 42 cm plot of up to 12 parameters. Arrangement of the parameters is four rows of three parameters each. Parameters from the first (left most) column are plotted with a solid line. Parameters from the center and the right most columns are plotted with long and short dashed lines, respectively. All y-axes for each parameter are four cm in length.

The time scale (x-axis) is fixed at 30 cm in length. The time scale is automatically adjustable to 1.5×10^J , 3.0×10^J , or 6.0×10^J , where J is an integer which will create a sufficiently large scale in seconds for the time span plotted. The time scale is defined as elapsed time of a flight maneuver.

The arrangement of the 12 parameters on a plot is defined as a plot group format (PGF). Provisions have been established to permit up to 40 parameters to be defined each in up to nine PGFs per program execution. This permits data comparison of flight information for different parameters. In the plotting of data values, if null samples are encountered, the plotting pen is lifted resulting in a visible discontinuity in the graph.

Most of the labeling and PGF assignments are controlled by card input. There are five types of input cards described for the program. These types, in their prescribed order of input, are: (1) General Title Card; (2) Plot Row Labels Card; (3) Parameter Specifications Cards; (4) Heading Label Cards; and (5) Burst Selection Cards. The General Title Card must be the first card of the input data deck. It contains any alphanumeric characters in columns 2 to 73. The information contained on the card is printed at the top of all plots. (See (1) of figure 33.)

The Plot Row Labels card prints a two-line row label on the plot, each line containing at most 18 characters each. There are four rows per plot and they are numbered from one to four - top to bottom. The row labels are specified by PGF and row number. Card format for the Plot Row Labels is found in figure 29. An example of the labeling of the plot row label is designated as (2) in figure 33. A maximum of 36 (9 PGFs x 4 rows) plot row label cards may be included for a job run. Termination of the plot row labels card input is with a card containing zero in column 5. It is not necessary to provide any information for row labeling. However, the deck setup must include the card with zero in column 5.

The Parameter Specification Cards consist of two input cards per parameter. Figure 30 describes the format of these cards. Up to 40 parameter card groups may be defined for plotting. Termination of this group of card input is by including a card containing blanks in columns 1-8 at the end of this group.

The fourth group of input cards are the Heading Label Cards. This information is placed beneath the General Title Card information on the plot and is designated as (3) in figure 33. Up to eight heading items may be defined on a plot. Termination of the Heading Label Cards is by including a card with zeroes in columns 1-5. Description of the Heading Label Cards format is found in figure 31.

The final set of input cards are the Burst Selection Cards. Two cards are required per burst. A description of these cards are found in figure 32. The Burst Selection Card group also requires a termination card which contains a zero in column 5.

Direct output of the Time History Plot Program is a tape formatted to produce the requested plots on a CALCOMP plotter. The information has been scaled to a metric scale and produced on a 25 x 42 cm area. A sample of a plot produced by this program is found in figure 33.

HARMONIC ANALYSIS

This program determines the harmonic coefficient and phase angles for the Fourier series expressed as:

$$Y = A_0 + A_1 \cos X + B_1 \sin X + A_2 \cos 2X + \dots$$

and

$$Y = C_0 + C_1 \cos(X - \phi_1) + C_2 \cos(2X - \phi_2) + \dots$$

Given a set of data values for a given parameter sampled at a fixed sample rate, the coefficients, A_i , B_i , and C_i , and the phase angles, ϕ_i , are computed on a cycle by cycle basis. The values of each coefficient and phase angle computed during each cycle are averaged and presented in a printout on a flight maneuver basis. A sample of the printout report is found in figure 34.

The definition of the data set used to compute the harmonic coefficients and phase angles is established through card input. Two types of information must be included for calculating the harmonic coefficients: a list of the flight maneuvers and a list of sensors and number of cycles to be processed. The order of card input is first the flight maneuver or "run" cards, then the sensor mnemonic information. Formats for these card images is found in figure 35. The program first reads a list of flight maneuver numbers from the run cards and continues to read this information until the characters "RUN" do not appear in columns 1-3 of the input card. The program then assumes that such a data card contains the sensor information and processes the card image under that assumption. The program continues to process data and calculate the harmonic coefficients and phase angles for each defined parameters for the given set of flight maneuvers. The program will terminate execution after the final input sensor has been processed.

UPCGEN

The Universal Parameter Catalogue Generator or UPCGEN program maintains the Universal Parameter Catalogue (UPC) File and provides a sorted listing of the file. This file is a catalogue of all known sensor mnemonics with their pre-processing codes and contains the column and line titles and a data precision code for the respective sensors. This information is used in the various reports generated by the software in the EASE System.

The UPC file is a random file and resides permanently in the computer system for access by the EASE software system. The entries to the UPC file are arranged alphabetically by sensor mnemonic and pre-processing code. Each record with the file is 280 words in length. The first record within the UPC file is a table of contents which contains a list of the mnemonic names and pre-processing codes of the first entry of each successive 280 word record of the UPC file. This record is uniquely defined with the characters "UPC" in the first word of the record. The second word contains the total number of entries in the UPC file. Each successive two-word entries contain the mnemonic name and pre-processing code of the first entry of each data record in the file. A maximum of 139 entries are possible in this table of contents record.

Each 280-word record in the UPC file contains catalogue information for 20 UPC entries. Hence, the UPC file can grow to a maximum of 2760 entries (20 words per record, with a maximum of 139 records). Each catalogue entry requires 14 data words. A new catalogue entry begins at word number $14*(i-1)+1$ where i is the catalogue entry number within a record ($i=1,20$). A description of the 14 data words for each catalogue entry is found in figure 36.

The UPCGEN program maintains the UPCFILE by allowing addition and deletion of catalogue entries through card input. A set of command cards are used to indicate to the program what type of processing should be performed on the catalogue entries being read. The allowable commands by the UPCGEN program are: "INITIA," "DELETE," "INSERT," "ROLLEM." When the UPCGEN program encounters an input data card containing these words in columns 1-6, the appropriate program logic to perform these commands is set into operation. The catalogue entries following such a command will be processed according to the logic set into operation by that command. The command "INITIA" is used to initialize the UPC file. It assumes no UPC file has been initiated previously so that no entries exist on a UPC file. The program then processes the input catalogue entries and begins to build the UPC file. Each entry is read into a scratch file for sorting before placing the entries into the permanent UPC file. The sorting and building of the UPC file is not performed until the command card "ROLLEM" is encountered in the input deck. This command triggers the logic that assumes all data entries have been placed on the temporary scratch file and the sorting and building procedures can now begin.

The commands "DELETE" and "INSERT" are used to modify an existing UPC file. The "DELETE" command is used to eliminate an entry from the UPC file where the "INSERT" places a new entry, in its proper sorted sequence, onto the UPC file.

Again, these two commands only indicate to the program how the data following these command cards are to be processed. The command "ROLLEM" must be included before the actual deletions and insertions can take place. Catalogue entry modifications are combinations of deletions and insertions. The present entry is commanded to be deleted followed by the corrected entry commanded to be inserted. For any type of processing to be performed on the UPC file, the command card "ROLLEM" is the last card of the input deck.

The order of input for the various modes of processing defined by the UPCGEN program is as follows:

1. to initialize a UPC file
"INITIA"
Catalogue entries (one entry per card)
"ROLLEM";
2. to add new entries to an existing UPC file
"INSERT"
Catalogue entries (one entry per card)
"ROLLEM";
3. to delete existing UPC file data
"DELETE"
Catalogue entries (one entry per card)
"ROLLEM";

4. and to modify existing entries
"DELETE"
Catalogue entries (one entry per card)
"INSERT"
Catalogue entries (one entry per card)
"ROLLEM".

The card image format for a catalogue entry is described in figure 37.

The UPCGEN program provides a list of the current UPC file after the requested processing has been completed. The file list is provided as a sorted list by sensor mnemonic and pre-processing code and list sorted first by category then by sensor mnemonic and pre-processing code. Each sensor is assigned a two-character category code which allows the entries to be defined into a subset of sensors with similar characteristics. Figures 38 and 39 are sample printouts of the two lists provided by this program.

TPDMP AND TABLE PRINT

There are two programs written for the EASE system to verify data being processed. One program, TPDMP, provides a selected listing of the contents of the digitized data tape as received for initial processing. The other program, TABLE PRINT, provides a listing of the current contents of a flight's Table File.

The TPDMP program reads a 9-track digital tape that is configured in the Televent II (see Appendix B) format and provides a listing of the specified data words within a frame of data for either a given time interval or a given number of data frames. The TPDMP program determines what portion of the input tape is to be listed from information supplied through input cards. Figure 40 contains the card format required by this program and figure 41 is a sample of the output provided. The data values are listed as octal numbers.

The TABLE-PRINT program requires no card input for execution. Each of the tables defined in the Table File (see "SETUP") are listed with their current contents. This program is useful particularly for those data elements generated by the SETUP, SCAN, and ABTASK programs. Figures 42a through 42e are samples of the output listing provided by the TABLE-PRINT program.

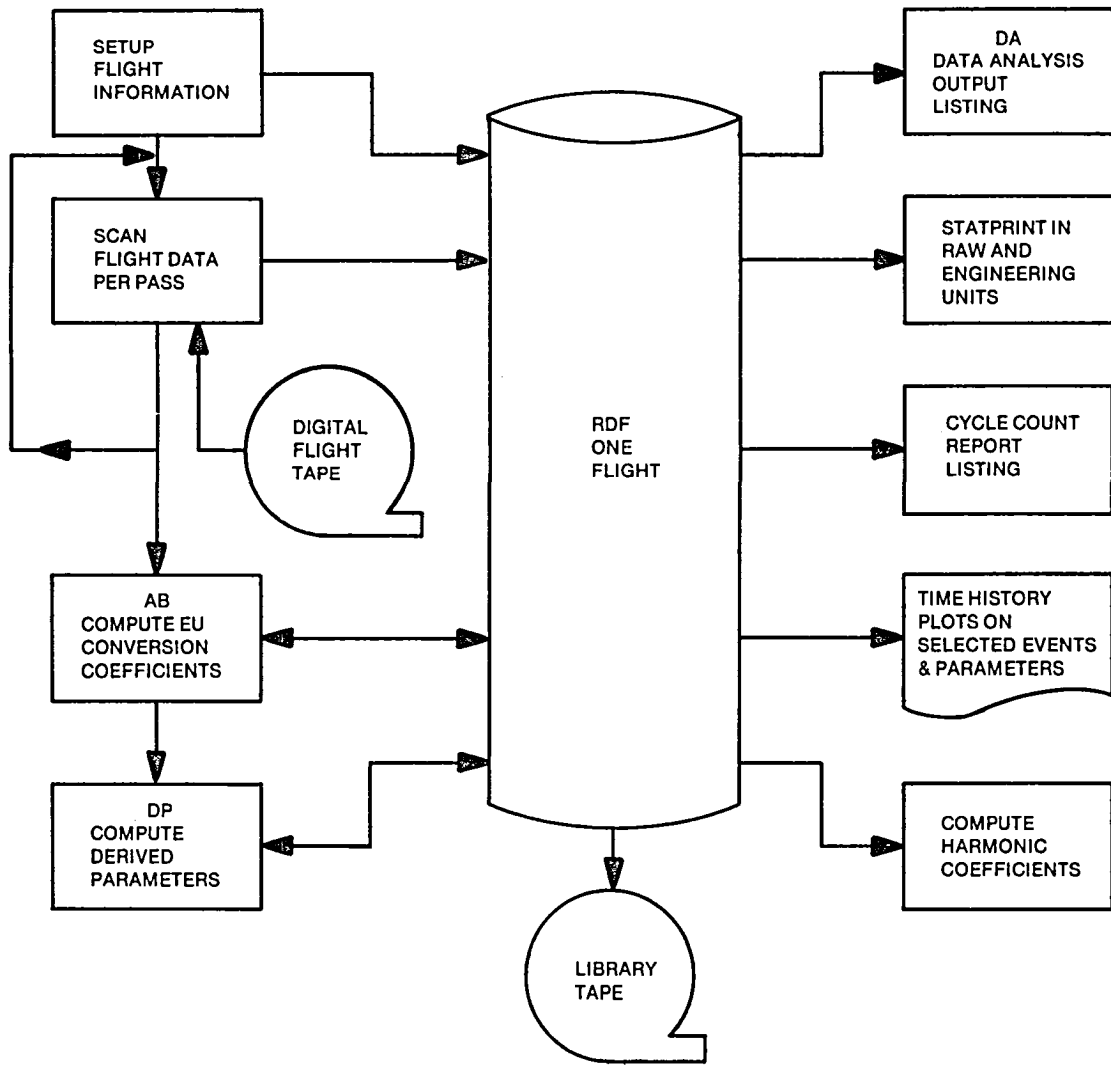


Figure 1 - EASE digital processing scheme.

RECORD NO.	TABLE FILE CONTENTS
1	Header Table
2	Pass 1 Table
3	Pass 2 Table
21	Pass 20 Table
22	Sensor Table for Pass 1
23	Sensor Table for Pass 2
41	Sensor Table for Pass 20
42	Calrun Table
43	Event Table

Figure 2 - Table file record layout

CARD NO.	COLS.	CARD FIELD CONTENTS
1	1-2	Data value "L1"
	6-10	Data value "SETUP"
	21-30	Data value "INITIALIZE" when program is to run in the initialize mode.
		Data value "UPDATE" when program is to run in the update mode. (left justified)
Last	1-2	Data value "L1"
	6-14	Data value "END SETUP"

NOTE: These two cards must be the first and last data cards of the input data cards.

Figure 3 - Description of card image for "L1" level input.

VARIABLE NAME	DESCRIPTION	WORD(S) NO.	DATA TYPE
MAXPAS	Maximum pass number used	1	I
MEVENT	Number of flight maneuvers	2	I
	Not used	3	
FTIME	Beginning time of flight (secs)	4	F.P.
FLIGHT	Flight identification	5	C
DATE	Date of Flight (DDMMYY)	6	C
TAPENO	Aircraft tape number	7	C
AIRCR	Aircraft name	8, 9	C
PILOT	Pilot name	10, 11	C
COPIL	Copilot name	12, 13	C
OBSERV	Observer Name	14, 15	C
ETP	Engineering test plan	16	C
ESGW	Estimated gross weight	17	F.P.
KPR	Airspeed probe recovery factor	19	F.P.
HPC	T-58 engine chaff (horsepower at 100%)	20	F.P.
MRC	Main rotor rpm at 100%	21	F.P.
Ri	Main rotor radius in feet	22	F.P.
RT	Tail rotor radius in feet	23	F.P.
GT	Tail rotor to main rotor rpm ratio	24	F.P.
GTS	Tail rotor shaft-rpm	25	F.P.
RELHU	Relative humidity	26	F.P.
RFBOOM	Not used	27	F.P.

Figure 4 - Header table data description.

CARD NO.	COLS.	CARD FIELD CONTENTS
1	1-2	Data value of "L2"
	6-11	Data value of "HEADER"
2	1-2	Data value of "HT"
	4	Data value of "1"
	7-8	MAXPAS (right-justified)
	11-13	MEVENT (right-justified)
	21-29	FTIME (HHMMSS.SS)
3	1-2	Data value of "HT"
	4	Data value of "2"
	6-11	FLIGHT (left-justified)
	12-17	DATE (left-justified)
	24-29	TAPENO (left-justified)
	31-42	AIRCR (left-justified)
	44-55	PILOT (left-justified)
	56-67	COFIL (left-justified)
	68-79	OBSERV (left-justified)
4	1-2	Data value of "HT"
	4	Data value of "3"
	5-10	ETP (left-justified)
	11-20	ESGW
	21-30	ESCG
	31-40	KPR
	41-50	HPC
	51-60	MRC
	61-70	R
5	1-2	Data value of "HT"
	4	Data value of "4"
	11-20	RT
	21-30	GT
	31-40	GTS
	41-50	RELHU

Figure 5 - Header table card image description.

VARIABLE NAME	DESCRIPTION	WORD(S) NO.	DATA TYPE
MAXPAR	Actual number of parameters defined for this pass	1	I
SRDIN	Sample rate of input data and type of sampling rate NOTE: Sample rate type is a 1-character code The acceptable codes are: X = Sampling rate is based on time through the PCM data stream M = Sampling rate is based on the main rotor revolution rate through the FM data stream T = Sampling rate is based on the tail rotor revolution rate through the FM data stream Blank = Sampling rate is based on time through the FM data stream	2	C
SRDATA	Sample rate of EASE data file and type of sampling rate (see Note above for sample rate type codes)	3	C
ISTATC	Status code for data availability Code = 0, data for this pass is not available in the raw data file = 1, data for this pass is available in the raw data file (RDF) = 2, data for this pass is available in the RDF for output in engineering units.	4	I
IADDR	Array containing the record address at which the data for a given maneuver is first found for this pass. The entries for this array are indexed by the assigned number for each flight maneuver. The number of entries for this array is one more than the number of flight maneuvers. The last entry to this array is the next available address for data on the RDF for this pass.	5-105	I

Figure 6 - Pass table data description.

VARIABLE NAME	DESCRIPTION	WORD NO.* 13 (j-1)+	DATA TYPE
SNAM	Mnemonic name of sensor	1, 2	C
PPC	Pre-processing code. Valid entries are "D" for direct processing, "V" for FM vibratory, "S" for FM steady, "A" for amplitude, and "P" for phase components of processed data.	3	C
IPARIN	Assigned word location within data frame formatted by the TELEVENT II system (see Appendix B)	4	I
IPARDF	Assigned word location of data transferred to the raw data file (RDF)	5	I
CALTYP	Type of calibration algorithm to be applied in ABTASK routine. Valid entries are: Z, X, P, 1, 2 (see ABTASK section of documentation)	6	C
EUCV1	Engineering unit value for sensor's full deflection (used in ABTASK algorithms)	7	F.P.
EUCV2	Engineering unit value for sensor's zero offset (used in ABTASK algorithms)	8	F.P.
A	A - term for sensor as computed by ABTASK	9	F.P.
B	B - term for sensor as computed by ABTASK	10	F.P.
CALADR	Calrun table entry index (automatically inserted when calrun table entries are processed)	11	I
	Not used	12	
CONLVL	Level of concern (applicable to FM vibratory components only and used for cycle counting)	13	F.P.

* Each sensor table record is 520 words in length, with 13 words per sensor. The data description for the "jth" sensor is found in words 13j-12 through 13j of this record.

Figure 7 - Sensor table data description.

CARD NO.	COLS.	CARD FILED CONTENTS
1 2-41 (one per sensor)	1-2	Data value of "L2"
	6-9	Data value of "PASS" (left-justified)
	20-21	Assigned pass number (right-justified)
	25-26	Numerical value of SRDIN (right-justified)
	27	Type code of SRDIN
	32-33	Numerical value of SRDATA (right-justified)
	34	Type code of SRDATA
	1-2	Data value of "ST"
	3-10	SNAM (left-justified)
	12	PPC
	14-16	IPARIN (right-justified)
	18-20	IPARDF (right-justified)
	22-23	FM track number assigned (right-justified)
	25-26	FM channel number assigned (right-justified)
	28	CALTYP
	30-39	EUCV1
	40-49	EUCV2
	50-55	Analog tape designation (left-justified)
	56-65	CONLVL

Figure 8 - Description of card image for pass & sensor tables.

VARIABLE NAME	DESCRIPTION	WORD(S) NO.* 6 (i-1)+	DATA TYPE
ICE(1)	Pre-Z or Pre-H calibration run number	1	I
ICE(2)	Pre-R or Pre-L calibration run number	2	I
ICE(3)	Pre-X calibration run number	3	I
ICE(4)	Post-Z or Post-H calibration run number	4	I
ICE(5)	Post-R or Post-L calibration run number	5	I
ICE(6)	Post-X calibration run number	6	I

* Each calrun table record is 120 words in length, with six words per entry group. The entry group for the "ith" calrun table is found in words 6i-5 through 6i.

Figure 9 - Calrun table data description.

CARD NO.	COLS	CARD FIELD CONTENTS
1	1-2 6-11	Data value of "L2" Data value of "CALRUN"
2	1-2 6-8 11-13 16-18 21-23 26-28 31-33	Data value of "CT" ICE(1) (right-justified) ICE(2) (right-justified) ICE(3) (right-justified) ICE(4) (right-justified) ICE(5) (right-justified) ICE(6) (right-justified)
3	1-2 4-5	Data value of "CS" Data value of "AC"
NOTE: Cards 2 & 3 describe the calrun entry for the "Auto Cals.". This group of calruns will be applied to all non-AB1 and non-AB2 type of cals for each sensor. The remaining groups of calrun entries will modify the calrun entries for those sensors specified on the "CS" cards. The order of input for additional entries to the calrun table is one "CT" card followed by as many "CS" cards that are required to include the sensors to be referenced.		
TYPE "CT"		Card image is the same as defined for card 2 above
TYPE "CS"	1-2 4-11 13-20 22-29 31-38 40-47 49-56 58-65 67-74	Data value of "CS" Each entry contains the sensor name, "SNAM" as entered in the sensor table (left-justified). Note: A blank field terminates a grouping of sensors referencing a calrun entry. A "CS" card with each field containing a sensor name will check the card code to see if more sensors are given. ("CS" or a new entry "CT").

Figure 10 - Calrun table card image description.

VARIABLE NAME	DESCRIPTION	WORD(S) NO.* 6 (i-1) +	DATA TYPE
EVENT	Event name.	1,2,3,4	C
ETYPE	Event type code. Allowable codes are: Z = zero calibration, R = full load calibration, X = transducer cal event, T = transient type of data maneuver, S = steady type of data maneuver, I = ignore-numbered event contains no applicable data.	5	C
ETIME	Beginning time of event (seconds).	6	F.P.

* Event table record contains 600 words for a maximum of 100 events. Each event uses six words of the record. The "ith" numbered event is found in words 6i-5 through 6i.

Figure 11 - Event table data description.

CARD NO.	COLS	CARD FIELD CONTENTS
1 2 thru run no. plus 1	1-2	Data value of "L2"
	6-10	Data value of "EVENT"
	1-2	Data value of "ET"
	5-7	Run number assigned to maneuver (right-justified)
	12-34	EVENT (left-justified)
	38	ETYPE
	41-49	ETIME (HHMMSS.SS) - not a required input. SCAN task calculates this data entry to be the minimum data frame time tag of the first frame of data of each event for each PCM pass. Card input is provided to correct possible erroneous time data values contained on the digitized input tape.

Figure 12 - Event table card image description.

CARD NO.	COLS.	CARD FIELD CONTENTS
"SD"	1-2	Data value "SD".
	9-10	Pass number (corresponds to pass number defined in the SETUP program) (right-justified).
	14-15	File code of input data tape (right-justified) (corresponds to the file code designation on the job control card-see Appendix A).
	16-20	File number for this pass on input data tape (right-justified)
	25	Time option-applicable for PCM data only = 0 use time recorded during flight which is contained in the data frame; = 1 use time tag furnished when data was digitized.
	28-30	Total number of data bursts to be processed for this pass (right-justified).
	31-35	Code to signify pass to be scanned contains data requiring tracking filter analysis (right-justified) = 0 no tracking filter analysis for this pass; = 1 tracking filter analysis to be performed.

Figure 13 - Card format for "SD" cards of SCAN.

CARD NO.	COLS.	CARD FIELD CONTENTS
"BT"	1-2	Data value "BT".
	6-10	Burst number (right-justified).
	15	"ICOND", Condition Code ICOND = 0, process burst by run tone ("BT" card not required for burst processed for ICON=0); ICOND = 1, skip burst of data defined by run tone signal; ICOND = 2, process burst of data by time interval specified on this card; ICOND = 3, burst of data not on data tape for defined maneuver. Process a "dummy" record of data & statistics for this maneuver.
	21-32	Beginning time of burst (required for ICOND = 2) Format is HH-MM-SS.SSS.
	34-45	Ending time of burst (required for ICOND = 2) Format is HH-MM-SS.SSS.

Figure 14 - Card format for "BT" cards for SCAN.

CARD NO.	COLS.	CARD FIELD CONTENTS
"L1"	1-2	Data value "L1". Must be present as last card of input data deck.

Figure 15 - Card format for "L1" card for SCAN.

RSRA 545-49 FLT 3 7263				START		STOP	
	WB	GS	WB	GS			
01	900-00-00-00,013	095-20-39-52,888	900-00-00-00,851	095-20-40-19,709			
02	900-00-00-00,988	095-20-40-23,831	900-00-00-00,688	095-20-40-51,514			
03	900-00-00-00,201	095-20-40-55,616	900-00-00-00,238	095-20-41-23,636			
04	900-00-00-00,213	095-20-41-27,700	900-00-00-00,826	095-20-41-55,296			
05	900-00-00-00,938	095-20-41-59,357	900-00-00-00,376	095-20-42-29,779			
06	900-00-00-00,922	095-20-43-45,591	900-00-00-00,847	095-20-44-14,500			
07	900-00-00-00,297	095-20-44-18,359	900-00-00-00,422	095-20-44-49,466			
08	900-00-00-00,910	095-20-44-53,329	900-00-00-00,910	095-20-45-21,318			
09	900-00-00-00,097	095-20-45-25,163	900-00-00-00,635	095-20-45-53,690			
10	900-00-00-00,085	095-20-45-57,558	900-00-00-00,847	095-20-46-24,312			
11	900-00-00-00,772	095-20-46-28,167	900-00-00-00,047	095-20-47-01,433			
12	900-00-00-00,217	095-20-47-05,592	900-00-00-00,104	095-20-47-12,477			
13	901-00-00-00,742	095-20-47-16,586	901-00-00-00,804	095-20-47-23,646			
14	903-00-00-00,004	095-20-47-27,761	903-00-00-00,754	095-20-47-33,510			
15	900-00-00-00,742	095-20-47-37,640	900-00-00-00,992	095-20-47-45,888			
16	901-00-00-00,967	095-20-47-50,002	901-00-00-00,192	095-20-47-56,226			
17	903-00-00-00,617	095-20-48-00,339	903-00-00-00,929	095-20-48-07,650			
18	900-00-00-00,979	095-20-48-11,798	900-00-00-00,079	095-20-48-19,895			
19	900-00-00-00,329	095-20-48-24,013	900-00-00-00,054	095-20-48-33,735			
20	900-00-00-00,017	095-20-48-37,871	900-00-00-00,617	095-20-48-47,468			
21	900-00-00-00,104	095-20-48-51,586	900-00-00-00,242	095-20-48-59,720			
22	900-00-00-00,935	095-20-49-03,935	900-00-00-00,448	095-20-49-09,445			
23	900-00-00-00,585	095-20-49-13,587	900-00-00-00,448	095-20-49-23,446			
24	900-00-00-00,448	095-20-49-27,560	900-00-00-00,523	095-20-49-30,634			
25	900-00-00-00,223	095-20-49-34,761	900-00-00-00,060	095-20-49-37,597			
26	900-00-00-00,323	095-20-49-41,734	900-00-00-00,810	095-20-49-46,219			
27	000-00-16-17,455	095-20-49-50,546	000-00-16-24,005	095-20-49-57,094			
28	000-00-16-25,555	095-20-49-58,643	000-00-16-30,180	095-20-50-03,267			
29	000-00-31-57,216	095-20-50-07,527	000-00-32-07,028	095-20-50-17,338			
30	000-00-32-26,603	095-20-50-21,530	000-00-32-36,916	095-20-50-31,841			
31	000-00-32-49,703	095-20-50-36,018	000-00-32-57,678	095-20-50-43,992			
32	000-00-42-59,928	095-20-50-48,149	000-00-43-38,741	095-20-51-26,958			
33	000-00-53-28,278	095-20-51-31,070	000-00-54-59,803	095-20-51-02,592			
34	900-01-35-04,441	095-20-53-06,372	900-01-35-09,741	095-20-53-11,673			
LWS	900-01-35-23,566	095-20-53-19,967	900-01-35-23,616	095-20-53-20,017			
LWS	900-01-35-23,616	095-20-53-20,017	900-01-35-23,653	095-20-53-20,054			
LWS	900-01-35-23,666	095-20-53-20,067	900-01-35-23,728	095-20-53-20,117			
LWS	900-01-35-23,728	095-20-53-20,117	900-01-35-23,766	095-20-53-20,154			
LWS	900-01-35-23,766	095-20-53-20,154	900-01-35-38,58	095-20-53-20,242			
LWS	900-01-35-23,903	095-20-53-20,292	900-01-35-23,966	095-20-53-20,354			

Figure 16 - Burst interval listing.

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Figure 17 - Flight log.

SUBROUTINE RDFRD (ITOS, ITYPE, ICONV, IRUN, NPAR, NAMES, PPC, SR, ISMPL, LSMPL, OUTBUF, ISZBUF, TOS, NFOUT, MSG, IER)	
ARG	DEFINITION
1. ITOS	= 0, when initial call with given set of param spec's which must be used to search sensor tables. = 1, when previous call with same set of param spec's has been used to define table of subscripts argument (TOS) thus averting search of sensor table.
2. ITYPE	= 0, when data samples are being requested. = 1, when statistics are being requested.
3. ICONV	= 0, if results are to be in raw units. = 1, if results are to be in eng. units.
4. IRUN	Run (event) number requested.
5. NPAR	Number of parameters requested.
6. NAMES	Array of parameter mnemonics (NPAR in length).
7. PPC	Array of parameter preprocess codes (NPAR in length).
8. SR	Array of parameter sample rates (NPAR in length). If data is being requested, all must be same.
9. ISMPL	Beginning sample number requested, if data.
10. LSMPL	Ending sample number requested, if data.
11. OUTBUF	Output buffer for data or statistics
12. ISZBUF	Size of OUTBUF: if asking for stats, size should be (10xNPAR) if asking for data, size should be (LSMPL-ISMPL+1)x(NPAR).
13. TOS	Table of subscripts, four words per parameter built within routine when ITOS = 0 for possible subsequent calls with same set of parameters. Used by routine, thus averting search of sensor table; when ITOS = 1, the four words are: <div style="display: flex; align-items: center; margin-top: 10px;"><div style="margin-right: 20px;"><div style="display: flex; flex-direction: column; align-items: flex-start;"><div>TOS (1) = PASS number</div><div>TOS (2) = ELEMENT number</div><div>TOS (3) = A</div><div>TOS (4) = B</div></div><div style="font-size: 3em; margin: 0 10px;">}</div><div>when parameter is available.</div></div> Zeros are inserted in all four words when parameter is not available.</div>
14. NFOUT	Output array of actual number of frames returned for each parameter (NPAR in length). For stats, NFOUT will equal 10.
15. MSG	Array of output parameter messages (NPAR in length). = 0, no errors = 1, less data returned than requested because ending sample requested is greater than last sample available. = 2, beginning sample requested is greater than last sample available.
16. IER	Output error code determined as the sum of the following individual codes: = 0 No errors, = 1 CAL run requested, = 2 Parameter level errors exist, = 4 No such run, = 8 Buffer size error.

Figure 18 - Subprogram RDFRD argument list.

/C545 R FLIGHT FLT-5 PASS 9 DATE 041078

CALIBRATION RUN TABLE (CRNTIB) SUMMARY
ENTRY PRE-Z/LQ PRE-R/HI PRE-XDUC POST-Z/LQ POST-R/HI POST-XDUC

1	4	5	4	40	41	40
2	3	2	1	39	38	37
3	1	2	1	37	38	37
4	1	3	1	37	39	37
6	12	13	0	30	31	0
7	13	12	0	31	30	0
8	3	2	11	39	38	29
9	11	14	0	29	32	0

Figure 19 - ABTASK calibration run table summary.

[illegible]

Figure 20 - ABTASK raw units statistic summary.

/5545 R FLIGHT-FLT-5 PASS 9 DATE 041078

PARAMETER	CNTAB,ENT	CAL-TYPE	EUCV1	EUCV2	A TERM	B TERM
HEAD180	D	ACZ	71,3000002	180,0000000	0.5922891E 00	0.26599960E 02
NR	D	ACZ	61,0000000	61,0000000	0.24197992E 00	-0.1929894E 01
HRQ1	D	ACX	45600,0000000	0.	0.30738403E 03	-0.78306273E 05
PITCHATT	D	ACX	24,8000000	3,0000000	0.23161020E 00	-0.5834832E 02
ROLLATT	D	ACX	40,0999999	0.5000000	0.36780883E 00	-0.94196196E 02
WIACTUP	D	ACX	1616,0000000	0.	0.12779575E 02	-0.33054575E 04
WIACTLO	D	ACX	1632,0000000	0.	0.12920761E 02	-0.3310560E 04
WIACTUP	D	ACX	1508,0000000	0.	0.12320266E 02	-0.3372092E 04
PITCHRAT	D	ACX	75,3000002	0.	0.30185559E 00	-0.77578133E 02
ROLLRAT	D	ACX	149,7000008	0.	0.58687822E 00	-0.1518290E 03
WIACTLO	D	ACX	1649,0000000	0.	0.13034498E 02	-0.3335501E 04
TRIMBIT	D	PC	58,2000000	25,7000000	0.11229718E 00	-0.1768041E 02
WIACTUP	D	ACX	74,8999996	0.	0.30066695E 00	-0.77022924E 02
VIPBOOH	D	ACX	0,6410700	0.0100000	0.12819122E 02	-0.96593265E 04
IV	D	ACX	11,7000000	10,0000000	-0.95093376E 01	0.3309944E 02
LGMIXIP	D	PC	0.	100,0000000	0.34723268E 00	-0.37155332E 02
LATHIXIP	D	PC	0.	100,0000000	0.39331694E 00	-0.6586633E 02
GOLHIXIP	D	PC	0.	100,0000000	0.45329996E 00	-0.1218392E 03
LATSTKP	D	PC	0.	100,0000000	0.32385986E 00	-0.155439E 02
LGSTKP	D	PC	0.	100,0000000	0.37014018E 00	-0.2366437E 02
COLLSTKP	D	PC	0.	100,0000000	0.22988750E 00	-0.28003789E 01
PEDP	D	PC	0.	100,0000000	-0.60421578E 00	0.19878928E 03
PITCHACC	D	ACX	153,2000008	0.	0.60886704E 00	-0.1563170E 03
ROLLACC	D	ACX	307,7000008	0.	0.12310250E 01	-0.31622376E 03
YAWACC	D	ACX	150,2500000	0.	0.62526488E 00	-0.16057217E 03
LOADFACT	D	ACX	-2,0700000	1,0000000	-0.92843084E 02	0.31104607E 01
NO10PCT	D	ACX	72,8000002	0.	0.52258934E 00	-0.3359777E 03
NO20PCT	D	ACX	74,0100002	0.	0.53588072E 00	-0.33994077E 03
NO1NFPCT	D	ACZ	63,9770002	62,0310001	0.24788571E 00	-0.2186978E 01
NO2NFPCT	D	ACZ	61,5999999	62,3000002	0.24738954E 00	-0.20212851E 01
AILPOSR	D	PC	389,0000000	63,0000000	0.98787632E 00	0.4818485E 02
FLAPOSR	D	PC	0.	-22,0000000	0.66263983E 01	-0.46209528E 01
HBOOH	D	ACZ	4043,0000000	-41,0000000	0.20377895E 02	-0.53017223E 04
ITATBOOH	D	ACZ	29,7400000	0,2200000	0.23650864E 00	-0.60536599E 02

Figure 21 - ABTASK engineering unit summary.

STATISTICS	FLY-5	RAW UNITS	PASS-3	AVERAGE	STD. DEV.	PERCENTILE	N POINTS	ER COUNT	ER TYP
1	MANEUVER	TR BLD STRESS P-2	MINIMUM						
2	XCAL PADS 1	MAXIMUM							
3	XCAL PADS 1		4.000	4.667	0.474	5.000	48	0	000000
4	XCAL PADS 1		4.000	4.694	0.4628	5.000	109	1	000000
5	XCAL PADS 2		4.000	4.586	0.4962	5.000	70	0	000000
6	XCAL PADS 2		4.000	4.686	0.4635	5.000	69	0	000000
7	XCAL PADS 2		4.000	4.734	0.4632	5.000	94	0	000000
8	XCAL PADS 2		4.000	4.640	0.5056	5.000	89	0	000000
9	XCAL PADS 2		4.000	4.663	0.4748	5.000	104	0	000000
10	XCAL PADS 2		4.000	4.678	0.4699	5.000	90	0	000000
11	XCAL PADS 2		4.000	4.686	0.4914	5.000	86	0	000000
12	XCAL PADS 2		4.000	4.712	0.4532	5.000	146	0	000000
13	XCAL PADS 2		4.000	4.674	0.4949	5.000	89	0	000000
14	XCAL PADS 2		4.000	4.718	0.4519	5.000	110	0	000000
15	XCAL PADS 2		4.000	4.710	0.4576	5.000	62	0	000000
16	XCAL PADS 2		4.000	4.705	0.4509	5.000	88	0	000000
17	XCAL PADS 2		4.000	4.782	0.4118	5.000	1715	0	000000
18	XCAL PADS 2		4.000	4.686	0.4532	5.000	1419	0	000000
19	XCAL PADS 2		4.000	4.692	0.4576	5.000	299	0	000000
20	XCAL PADS 2		4.000	4.618	0.4576	5.000	471	0	000000
21	XCAL PADS 2		4.000	4.618	0.4576	5.000	541	0	000000
22	XCAL PADS 2		4.000	4.618	0.4576	5.000	492	0	000000
23	XCAL PADS 2		4.000	4.618	0.4576	5.000	1381	0	000000
24	XCAL PADS 2		4.000	4.618	0.4576	5.000	781	0	000000
25	XCAL PADS 2		4.000	4.618	0.4576	5.000	1192	0	000000
26	XCAL PADS 2		4.000	4.618	0.4576	5.000	494	0	000000
27	XCAL PADS 2		4.000	4.618	0.4576	5.000	987	0	000000
28	XCAL PADS 2		4.000	4.618	0.4576	5.000	1333	0	000000
29	XCAL PADS 2		4.000	4.618	0.4576	5.000	1111	0	000000
30	XCAL PADS 2		4.000	4.618	0.4576	5.000	3708	0	000000
31	XCAL PADS 2		4.000	4.618	0.4576	5.000	56	0	000000
32	XCAL PADS 2		4.000	4.618	0.4576	5.000	80	0	000000
33	XCAL PADS 2		4.000	4.618	0.4576	5.000	71	0	000000
34	XCAL PADS 2		4.000	4.618	0.4576	5.000	58	0	000000
35	XCAL PADS 2		4.000	4.618	0.4576	5.000	55	0	000000
36	XCAL PADS 2		4.000	4.618	0.4576	5.000	72	0	000000
37	XCAL PADS 2		4.000	4.618	0.4576	5.000	87	0	000000
38	XCAL PADS 2		4.000	4.618	0.4576	5.000	90	0	000000
39	XCAL PADS 2		4.000	4.618	0.4576	5.000	91	0	000000
40	XCAL PADS 2		4.000	4.618	0.4576	5.000	79	0	000000

Figure 22 - Sample output for STATPRINT program.

CARD NO.	COLS.	CARD FIELD CONTENTS
1 → n	1-2	IPASS - Pass number requested (right-justified) - only required if all sensors of one pass are to be tabulated.
	3-10	NAME - Mnemonic name of sensor (left-justified)
	15	PPC - Pre-processing code of sensor
	16-20	SR - Sample rate at which sensor has been processed onto the RDF (right-justified) NOTE: NAME, PPC, SR to be furnished when a specific sensor is to be tabulated
	25	ICONV - = 0 data tabulated in raw units = 1 data tabulated in engineering units

Figure 23 - Description of card image for STATPRINT.

CARD NO.	COLS	CARD FIELD CONTENTS
1	1	NPASS - Number of derived parameter passes to be processed.
	2-3	JPASS(1) - Derived parameter pass number to be processed first (right-justified)
	4-5	KPASS(1) - Pass number assigned to first derived parameter pass (right-justified)
	6-7	JPASS(2) - Derived parameter pass number processed second (right-justified)
	8-9	KPASS(2) - Pass number assigned to second derived parameter pass (right-justified)
	10-11	JPASS(3) - Derived parameter pass number processed third (right-justified)
	12-13	KPASS(3) - Pass number assigned to third derived parameter pass (right-justified)
	14-15	JPASS(4) - Derived parameter pass number processed fourth (right-justified)
	16-17	KPASS(4) - Pass number assigned to fourth derived parameter pass (right-justified)
	18-19	JPASS(5) - Derived parameter pass number processed fifth (right-justified)
	20-21	KPASS(5) - Pass number assigned to fifth derived parameter pass (right-justified)

Figure 24 - Card image for DPTASK program.

1		2		3		4		5		6	
7TP 78033 FLT 5/ DATE 041078		CALC MAIN		RT		30X		20X		20X	
A/C NO: 549		A/S ROTOR		30X		20X		20X		20X	
TEST TYPE FIRST FLIGHT HANDLING QUALITIES AND STRUCTURAL		BLADE		30X		20X		20X		20X	
L/R CONF: FULL CORR: CONF: CPU PITCH: 100-50 ROLL: 100-100 YAW: 100-100		PITCH		30X		20X		20X		20X	
		ROTOR		30X		20X		20X		20X	
		BLADE		30X		20X		20X		20X	
		PITCH		30X		20X		20X		20X	
		FLAP		30X		20X		20X		20X	
		HONT		30X		20X		20X		20X	
		DEG		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	
		(SI)		30X		20X		20X		20X	
		(V)		30X		20X		20X		20X	

CARD NO.	COLS.	CARD FIELD CONTENTS
1-4	1-72	Title Cards: Any alphanumeric characters
5-n		Maneuver specification cards (one per run).
	2-6	Run number (right-justified). NOTE: No run numbers specified indicates all non-calibration runs to be processed.
n+1	1-3	Value of "END" required input card even when no maneuver identification cards have been included.
n+2→m		Parameter specification cards.
n+2	1-4	Value of "Page".
n+3 etc.	1-8	Sensor mnemonic (left-justified).
	10	Pre-processing code.
	15-17	Sample rate (right-justified). NOTE: Up to 18 parameter identification cards allowed within a page grouping. Repeat page grouping as necessary beginning with data card containing "Page" in columns 1-4.
Last	1-3	Value of "END".

Figure 26 - Card description for DATASK program.

CARD NO.	COLS.	CARD FIELD CONTENTS
1-4	2-72	Title specification cards containing any alphanumeric characters.
1→n	(1-5)	Maneuver specification cards Flight maneuver number (right-justified) one entry per card. No maneuver specification cards will default the program to cycle count all non-calibration maneuvers.
n+1	1-3	Value of "END" Note: This card must be present even if no cards containing flight maneuver numbers are present.
n+2→m		Parameter specification cards Type of input for parameter specification determines three modes of operation: Mode = 1, all vibratory components with concern level > 0 to be cycle counted; Mode = 2, all vibratory components with concern level > 0 within stated pass number to be cycle counted; Mode = 3, specified sensor's vibratory component to be cycle counted if concern level > 0.
	4-5	Type of input required for each mode: Mode = 1, one blank card. Mode = 2, pass number (right-justified). Mode = 3,
	11-18	sensor mnemonic name (left-justified).
	20-25	sample rate (right-justified).

Figure 27 - Card input for cycle count program.

<div> <div>FTP 72523 FLT 5 DATE 04-10-78</div> <div>A/C NO. 549 GROSS WEIGHT 27110 LBS, C.G. 302.1 IN</div> </div>														
<div>TEST TYPE FIRST FLIGHT, HANDLING QUALITIES AND STRUCTURAL</div>														
A/P CONFIG. FULL COMP. GDRF, CPU PITCH: 100-50 ROLL 100-100 YAW 100-100														
<div> <div>2</div> <div>3</div> <div>4</div> <div>5</div> </div>														
SR 1T VIBRATORY CYCLE COUNT CONCERN LEVEL C = 90														
MANEUVER	RUN NO.	STEADY (S)	MEAN	QAX	(S)	(3)	QMAX (V)	ABSOLUTE LEVELS		VIBRATORY (V)		(V) MAX		TOTAL
								MAX	MIN	QMAX	QMIN	(S) PTILE	(S) MAX	
L/B AND CLIMB AT 70 KTS	15	30	59	54	54	54	54	135	39	66	71	81	1715	196
AT CLIMBING TURN 70 KTS	16	37	54	47	123	39	65	123	39	66	76	1419	30	30
CF 80 KTS, AUX C.I.	17	31	46	34	110	42	63	110	42	63	71	1471	11	11
LF 90 KTS, AUX C.I.	18	29	44	41	118	50	63	118	50	63	71	1471	82	82
CF 100 KTS, AUX C.I.	19	24	38	29	101	51	60	101	51	60	68	70	492	21
AT TURN 80 KTS, 15/30 DEG	20	23	42	29	105	42	63	105	42	63	57	71	1381	2
LF 100 KTS, 15/30 DEG	21	28	42	29	97	40	52	97	40	52	61	65	1192	2
AT TURN 80 KTS, 15/30 DEG	22	30	47	31	107	39	53	107	39	53	63	70	494	1
LF 80 KTS, 30/60 UP, 60	23	40	67	54	146	42	79	146	42	79	86	1333	717	717
CL 580 FPM, 80 KTS, 60	24	40	67	54	146	42	79	146	42	79	86	1333	717	717
6 FLIGHT SUMMARY														1060

Figure 28 - Sample printout for cycle count program.

CARD NO.	COLS.	CARD FIELD CONTENTS
1→36	5	Page group format number (integer value 1→9)
	10	Row number (integer 1→4 for rows numbered from top (1) to bottom (4))
	11-18	Alphanumeric information for first line of label.
	29-46	Alphanumeric information for second line of label.
Last	5	Data value of "0". NOTE: Last card must be included in deck setup even if no plot row label cards are included.

Figure 29 - Time history plot row labels card format.

CARD NO.	COLS.	CARD FIELD CONTENTS
2n-1*	1-8	Mnemonic for sensor (left-justified)
	9	Preprocessing code
	12-4	Sample rate (right-justified)
	19-36	18 Character Y-Axis label - first line (See(4), Fig. 33)
	37-54	18 Character Y-Axis label - second line (See(5), Fig. 33)
	55-58	Four character direction note for upper level of scale (See(6), Fig. 33)
	59-62	Four character direction note for lower level of scale (See(7), Fig. 33)
	63-64	Parameter's plot position number for PGF#1 (right-justified)
	65-66	Parameter's plot position number for PGF#2 (right-justified)
	79-80	Parameters plot position number for PGF#9 (right-justified) NOTE: Plot positions are number 1-12 beginning with the top left-most position down to the bottom right-most position.
2n*	1-10	Range of primary scale (floating point).
	11-20	Value at bottom of primary scale (floating point).
	21-30	Range of secondary scale (floating point).
	31-40	Value at bottom of secondary scale (floating point). NOTE: Primary scale will be used unless data exceeds scale by 20%.
	41-42	Scale precision index number for printing scale (right-justified).
	44	Option flag to reference all value to first non-null value. If entry is "1", the first non-null data sample will be subtracted from all subsequent samples. *Above 2-card formats to be repeated for a maximum of 40 parameters. (n=1→40)
Last	1-8	Blank - required card to terminate parameter specification card group.

Figure 30 - Time history parameter specification card format.

CARD NO.	COLS.	CARD FIELD CONTENTS
1→8	5	Heading number (1-8)
	6-13	Eight character information for line 1.
	14-21	Eight character information for line 2.
	22-29	Eight character information for line 3.
Last	5	Data value of "0" - must be included to terminate input of heading label card group even if none have been included in the deck setup.

Figure 31 - Time history heading label card format.

CARD NO.	COLS.	CARD FIELD CONTENTS
2m-1*	1-5	Flight maneuver number to be plotted (right-justified).
	6-10	PGF number to be used for this plot (right-justified).
	11-20	Start time of plot in seconds of elapsed time into maneuver (floating point) (0.0 sec. would designate a start time at the beginning of a maneuver).
	21-30	Elapsed stop time of plot in sec (floating point).
	31-78	Alphanumeric title of maneuver (See(8), Fig. 33).
	80	Option to list data being plotted: = 0 no printout to be produced, = 1 printout of data values produced.
2m*	1-10	Line 4 of heading label for heading #1.
	11-10	Line 4 of heading label for heading #2.
	21-30	Line 4 of heading label for heading #3.
	31-40	Line 4 of heading label for heading #4.
	41-50	Line 4 of heading label for heading #5.
	61-70	Line 4 of heading label for heading #6.
	71-80	Line 4 of heading label for heading #7. (See(9) of Fig. 33)
		*NOTE: Above 2-card format to be repeated for each plot to be generated
Last	5	Data value of "0" - must be included as last card of this group.

Figure 32 - Time history burst selection card format.

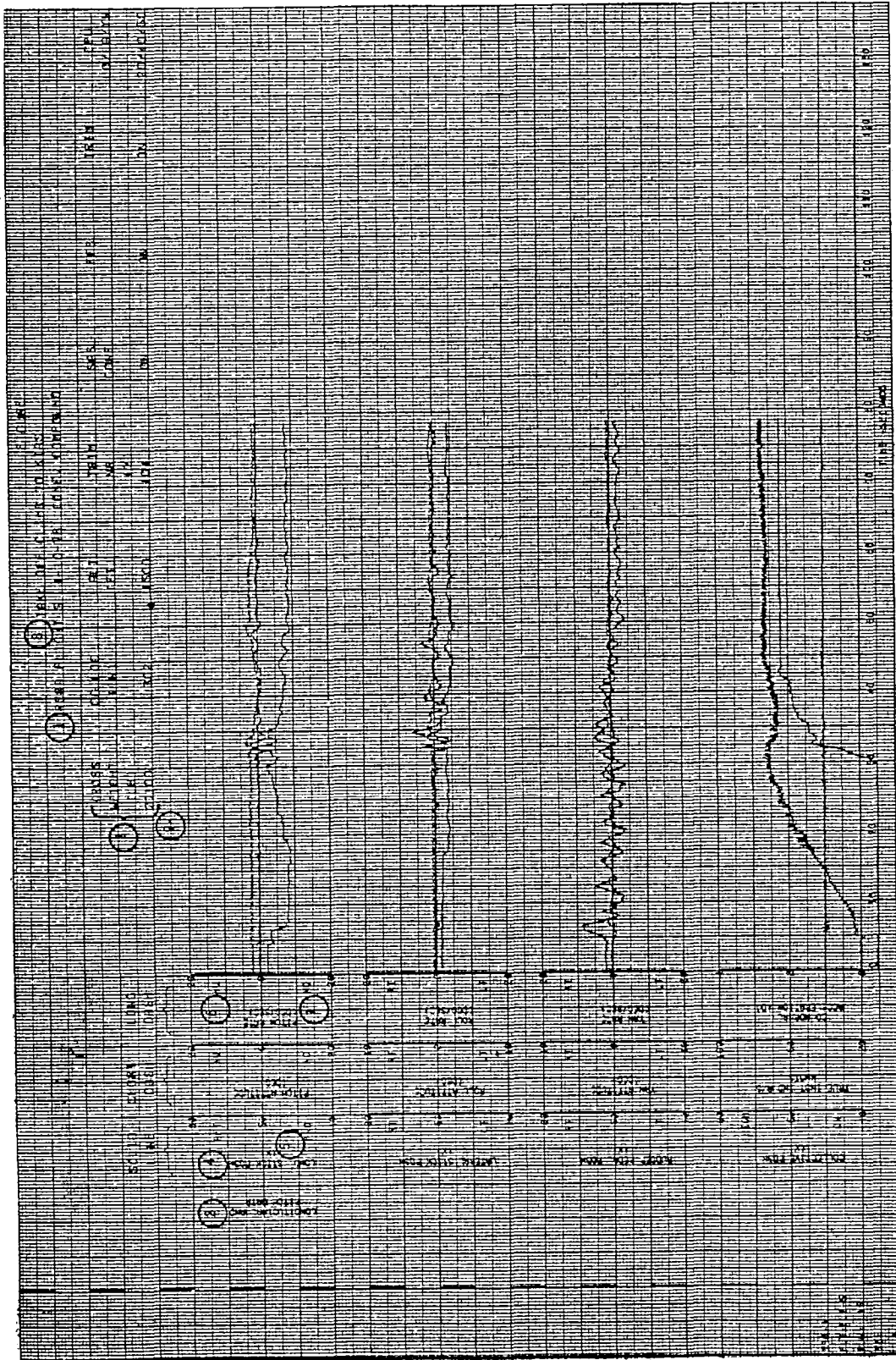


Figure 33 - Sample time history plot.

ARMONIC ANALYSIS VCOPEV VCOPEV D

[illegible]

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CARD NO.	COLS.	CARD FIELD CONTENTS
1 & 2	1-72	General title cards.
3→n	1-3	Data value "RUN".
	6-10	Flight maneuver numbers to be processed (right-justified).
	11-15	NOTE: First blank field encountered on card image terminates the processing of input flight maneuver numbers.
	16-20	
	21-25	
	26-30	
	31-35	
	76-80	
n+1→m	1-8	Sensor mnemonic name (left-justified).
	11-15	Sample rate of sensor data (right-justified).
	16-20	Beginning cycle number of data within flight maneuver to commence calculation of harmonic coefficients and phase angles (right-justified).
	21-25	Ending cycle number (right-justified).

Figure 35 - Card image for Harmonic Analysis program.

VARIABLE NAME	DESCRIPTION	WORD(S) NO.	DATA TYPE
DNAME	Concatenated name and pre-processing code of sensor (first eight characters are mnemonic name and eleventh character is pre-processing code).	1,2	C
PC	Parameter category code.	3	C
JINDEX	Integer precision code index.	4	I
CTITL	Six word column title.	5 10	C
LTITL	Four word line title.	11 14	C

Figure 36 - Data description of UPC file data entry.

CARD NO.	COLS.	CARD FIELD CONTENTS
1→n	1-2	Parameter category code.
	4-11	Sensor mnemonic name (left-justified).
	13	Preprocessing code for sensor entry.
	16-17	Integer precision code index (right-justified).
	19-54	The 36-character column title.
	57-80	The 24-character line title.

Figure 37 - UPCGEN program data card description.

F0BFUS00	V SA	1	FWD	FUS	#10	P31	(V)	FWD	FUS	#10	(V)
F0BFUS01	V SA	1	FWD	FUS	#1	P31	(S)	FWD	FUS	#1	(S)
F0BFUS02	V SA	1	FWD	FUS	#1	P31	(V)	FWD	FUS	#1	(V)
F0BFUS02	V SA	1	FWD	FUS	#2	P31	(S)	FWD	FUS	#2	(S)
F0BFUS02	V SA	1	FWD	FUS	#2	P31	(V)	FWD	FUS	#2	(V)
F0BFUS03	V SA	1	FWD	FUS	#3	P31	(S)	FWD	FUS	#3	(S)
F0BFUS03	V SA	1	FWD	FUS	#3	P31	(V)	FWD	FUS	#3	(V)
F0BFUS04	V SA	1	FWD	FUS	#4	P31	(S)	FWD	FUS	#4	(S)
F0BFUS04	V SA	1	FWD	FUS	#4	P31	(V)	FWD	FUS	#4	(V)
F0BFUS05	V SA	1	FWD	FUS	#5	P31	(S)	FWD	FUS	#5	(S)
F0BFUS05	V SA	1	FWD	FUS	#5	P31	(V)	FWD	FUS	#5	(V)
F0BFUS06	V SA	1	FWD	FUS	#6	P31	(S)	FWD	FUS	#6	(S)
F0BFUS06	V SA	1	FWD	FUS	#6	P31	(V)	FWD	FUS	#6	(V)
F0BFUS07	V SA	1	FWD	FUS	#7	P31	(S)	FWD	FUS	#7	(S)
F0BFUS07	V SA	1	FWD	FUS	#7	P31	(V)	FWD	FUS	#7	(V)
F0BFUS08	V SA	1	FWD	FUS	#8	P31	(S)	FWD	FUS	#8	(S)
F0BFUS08	V SA	1	FWD	FUS	#8	P31	(V)	FWD	FUS	#8	(V)
F0BFUS09	V SA	1	FWD	FUS	#9	P31	(S)	FWD	FUS	#9	(S)
F0BFUS09	V SA	1	FWD	FUS	#9	P31	(V)	FWD	FUS	#9	(V)
F0	D SM	0	MAIN	ROTOR	LONG	FORCE	LBS (S)	MR	LONG	FORCE	LBS (S)
F0	D SM	0	MAIN	ROTOR	LAT	FORCE	LBS (S)	MR	LAT	FORCE	LBS (S)
F0	D SM	0	MAIN	ROTOR	VERT	FORCE	LBS (S)	MR	VERT	FORCE	LBS (S)
H0BOH	D RK	0	PRESS	ALT	BOOM	FT		PRESS	ALTITUDE	(BOOM) FT	
H0BOOM	D RK	0	DENS	ALT	BOOM	FT		DENSITY	ALTITUDE	(BOOM) FT	
H0HEAD00	D HA	0	COMP	HEAD	+/-	180	DEG	COMPASS	HEAD +/-	180-DEG	
H0LATST0M	D HM	0	HEL0	LAT	SERVO	TRIM	DEG	HEL0	LAT	SERVO	TRIM-DEG
H0LGSTRM	D RM	0	HEL0	LONG	SERVO	TRIM	DEG	HEL0	LG	SERVO	TRIM-DEG
H0RRR	D PT	0	MAIN	ROTOR	POWER	HP		MAIN	ROTOR	POWER	HP
H0RB	D PT	0	TOTAL	STRN	GAGE	POWER		TOTAL	STRAIN	GAGE	POWER
H0RM	D PT	0	TOTAL	ENG	POWER	HP		TOTAL	ENGINE	POWER	HP
H0RR	D PT	0	TAIL	ROTOR	POWER	HP		TAIL	ROTOR	POWER	HP
H0STBAC1	S SA	1	H0RZ	STAB	ACT	ROD	P31	(S)	H0RZ	STAB	ACT ROD PSI(S)
H0STBAC1	V SA	1	H0RZ	STAB	ACT	ROD	P31	(V)	H0RZ	STAB	ACT ROD PSI(V)
H0STBAC1	V SA	0	H0RZ	STAB	ELEV	POS	%	(S)	HZ	STAB	ELEV POS-% (S)
H0STBAC1	V SA	0	H0RZ	STAB	ELEV	POS	%	(V)	HZ	STAB	ELEV POS-% (V)
YAU1	S SM	1	ISOL	AXIAL	LOAD	#1		LB(S)ISOL	AXIAL	LOAD #1	(S)
YAU1	V SM	1	ISOL	AXIAL	LOAD	#1		LB(V)ISOL	AXIAL	LOAD #1	(V)
YAU2	S SM	1	ISOL	AXIAL	LOAD	#2		LB(S)ISOL	AXIAL	LOAD #2	(S)
YAU2	V SM	1	ISOL	AXIAL	LOAD	#2		LB(V)ISOL	AXIAL	LOAD #2	(V)
YAU3	S SM	1	ISOL	AXIAL	LOAD	#3		LB(S)ISOL	AXIAL	LOAD #3	(S)
YAU3	V SM	1	ISOL	AXIAL	LOAD	#3		LB(V)ISOL	AXIAL	LOAD #3	(V)
YAU4	S SM	1	ISOL	AXIAL	LOAD	#4		LB(S)ISOL	AXIAL	LOAD #4	(S)
YAU4	V SM	1	ISOL	AXIAL	LOAD	#4		LB(V)ISOL	AXIAL	LOAD #4	(V)
J0506TH	D RK	0	ICE	BATH	REF	TEMP	DEG C	ICE	BATH	REF	TEMP DEG C

Figure 38 - UPCGEN sample listing of sorted sensor data.

BLEVERDR	S SA	0	ELEV	CONT	ROD R	LBS	(S)	ELEV	CONT	ROD R	LBS (S)
BLEVERDR	V SA	0	ELEV	CONT	ROD R	LBS	(V)	ELEV	CONT	ROD R	LBS (V)
BLEVERDR	S SA	0	ELEV	CONT	ROD	LBS	(S)	ELEV	CONT	ROD	LBS (S)
BLEVERDR	V SA	0	ELEV	CONT	ROD	LBS	(V)	ELEV	CONT	ROD	LBS (V)
FLAPBPOS	D SA	0	FLAP	CONT	POS	X		FLAP	CONT	POS-X	
FMBFUS10	S SA	1	FWD	FUS	#10		PSI	(S)	FWD	FUS #10	(S)
FMBFUS10	V SA	1	FWD	FUS	#10		PSI	(V)	FWD	FUS #10	(V)
FMBFUS1	S SA	1	FWD	FUS	#1		PSI	(S)	FWD	FUS #1	(S)
FMBFUS1	V SA	1	FWD	FUS	#1		PSI	(V)	FWD	FUS #1	(V)
FMBFUS2	S SA	1	FWD	FUS	#2		PSI	(S)	FWD	FUS #2	(S)
FMBFUS2	V SA	1	FWD	FUS	#2		PSI	(V)	FWD	FUS #2	(V)
FMBFUS3	S SA	1	FWD	FUS	#3		PSI	(S)	FWD	FUS #3	(S)
FMBFUS3	V SA	1	FWD	FUS	#3		PSI	(V)	FWD	FUS #3	(V)
FMBFUS4	S SA	1	FWD	FUS	#4		PSI	(S)	FWD	FUS #4	(S)
FMBFUS4	V SA	1	FWD	FUS	#4		PSI	(V)	FWD	FUS #4	(V)
FMBFUS5	S SA	1	FWD	FUS	#5		PSI	(S)	FWD	FUS #5	(S)
FMBFUS5	V SA	1	FWD	FUS	#5		PSI	(V)	FWD	FUS #5	(V)
FMBFUS6	S SA	1	FWD	FUS	#6		PSI	(S)	FWD	FUS #6	(S)
FMBFUS6	V SA	1	FWD	FUS	#6		PSI	(V)	FWD	FUS #6	(V)
FMBFUS7	S SA	1	FWD	FUS	#7		PSI	(S)	FWD	FUS #7	(S)
FMBFUS7	V SA	1	FWD	FUS	#7		PSI	(V)	FWD	FUS #7	(V)
FMBFUS8	S SA	1	FWD	FUS	#8		PSI	(S)	FWD	FUS #8	(S)
FMBFUS8	V SA	1	FWD	FUS	#8		PSI	(V)	FWD	FUS #8	(V)
FMBFUS9	S SA	1	FWD	FUS	#9		PSI	(S)	FWD	FUS #9	(S)
FMBFUS9	V SA	1	FWD	FUS	#9		PSI	(V)	FWD	FUS #9	(V)
HZSTBACT	S SA	1	HORZ	STAB	ACT	ROD	PSI	(S)	HORZ	STAB	ACT ROD PSI(S)
HZSTBACT	V SA	1	HORZ	STAB	ACT	ROD	PSI	(V)	HORZ	STAB	ACT ROD PSI(V)
HZSTELER	S SA	0	HORZ	STAB	ELEV	POS	X	(S)	HZ	STAB	ELEV POS-X (S)
HZSTELER	V SA	0	HORZ	STAB	ELEV	POS	X	(V)	HZ	STAB	ELEV POS-X (V)
LAIJCB	S SA	1	LEFT	ARON	INPUT	CR	LB	(S)	LB(S)	LEFT	ARON INPUT CR LB (S)
LAIJCB	V SA	1	LEFT	ARON	INPUT	CR	LB	(V)	LB(V)	LEFT	ARON INPUT CR LB (V)
LDGGBKER	S SA	1	LEFT	DRAG	BRAKE	CONT	ROD	PSI(S)	RSI-SLT	CRAG	BRAKE CR PSI(S)
LDGGBKER	V SA	1	LEFT	DRAG	BRAKE	CONT	ROD	PSI(V)	RSI-SLT	CRAG	BRAKE CR PSI(V)
LEGRBR	S SA	1	LEFT	ELEV	GRND	ROD	PSI	(S)	(S)	LT	ELEV GRND ROD PSI (S)
LEGRBR	V SA	1	LEFT	ELEV	GRND	ROD	PSI	(V)	(V)	LT	ELEV GRND ROD PSI (V)
LEGRBCE	D SA	1	LONG	STK	FORCE	LB			AF	LONG	STIBK FORCE-LB
LHDBRABL	S SA	1	LOWER	HORZ	STAB	DRAG	LEFT	PSI	(S)	SLOW	HZ STAB DRAG LT PSIS
LHDBRABL	V SA	1	LOWER	HORZ	STAB	DRAG	LEFT	PSI	(V)	SLOW	HZ STAB DRAG LT PSIV
LHDBRAGR	S SA	1	LOWER	HORZ	STAB	DRAG	RIGHT	PSI	(S)	SLOW	HZ STAB DRAG RT PSIS
LHDBRAGR	V SA	1	LOWER	HORZ	STAB	DRAG	RIGHT	PSI	(V)	SLOW	HZ STAB DRAG RT PSIV
LHDLIFYL	S SA	1	LOWER	HORZ	STAB	LIFT	LEFT	PSI	(S)	SLOW	HZ STAB LIFT LT PSIS
LHDLIFYL	V SA	1	LOWER	HORZ	STAB	LIFT	LEFT	PSI	(V)	SLOW	HZ STAB LIFT LT PSIV
LHDLIFYR	S SA	1	LOWER	HORZ	STAB	LIFT	RIGHT	PSI	(S)	SLOW	HZ STAB LIFT RT PSIS
LHDLIFYR	V SA	1	LOWER	HORZ	STAB	LIFT	RIGHT	PSI	(V)	SLOW	HZ STAB LIFT RT PSIV

Figure 39 - UPCGEN sample listing of sorted data by category.

CARD NO.	COLS.	CARD FIELD CONTENTS
1→n	2-18	Starting time.
	20-36	Stopping time. NOTE: The format for both starting and stopping time is DAY HR MIN SEC XXX-XX-XX-XX.XXXX
	40-43	Number of records (right-justified).
	45-46	Tape file number (right-justified).
	48-50	Starting data word number (right-justified).
	52-54	Stopping data word number (right-justified). NOTE: If any of the above data fields are zero or blank the following procedures are assumed. 1) If the stopping time is zero or blank, then the number of records specified in columns 40-43 are listed. 2) If the number of records is also zero or blank, then twenty records will be listed. 3) If the file number is zero or blank, then a file number of "1" is assumed. 4) If the starting and stopping data word numbers are blank, then all data words within each frame is listed. *NOTE: Any number of data cards may be present for listing different portions of the data residing on the input tape.

Figure 40 - Description of card image for TPDMP program.

RSRA 545,7203 FLT05
WORDS 1 TO 42 FILE NO. 1

100-15-36-23, 990	001511 000447 003730 003641 003703 003646 003637 003620 004023 003754 004011 003735 004061 004027 003602 003517
	002624 002567 003575 003525 004077 003761 003655 003576 003652 003613 003737 003635 003543 003451 003717 003617
	003590 003515 003612 003507 003613 003545 003671 003612 003611 003575 001511
100-15-36-23, 1690	001516 000455 003734 003646 003712 003650 003642 003623 004032 003764 004020 003744 004065 004030 003607 003526
	002631 002573 003577 003540 003076 003764 003654 003575 003654 003514 003740 003640 003543 003451 003714 003617
	003591 003515 003610 003505 003613 003545 003673 003611 003702 003600 001516
100-15-36-23, 2404	001517 000453 003723 003640 003703 003647 003635 003615 004025 003755 004010 003734 004054 004023 003501 003520
	002623 002565 003577 003543 004070 003757 003647 003575 003656 003613 003740 003636 003541 003446 003701 003616
	003596 003510 003605 003502 003603 003542 003665 003607 003665 003574 001517
100-15-36-23, 3105	001513 000453 003726 003637 003701 003647 003640 003617 004023 003754 004010 003731 004060 004025 003603 003514
	002627 002566 003576 003547 004072 003756 003655 003574 003654 003613 003740 003633 003544 003447 003713 003620
	003593 003513 003610 003503 003610 003542 003670 003610 003674 003575 001513
100-15-36-23, 3810	001517 000456 003725 003634 003703 003647 003640 003615 004021 003755 004007 003727 004060 004017 003601 003517
	002624 002565 003574 003520 004071 003755 003647 003574 003654 003614 003735 003636 003541 003443 003704 003616
	003527 003512 003611 003506 003611 003544 003671 003611 003672 003600 001517
100-15-36-23, 4510	001517 000452 003722 003634 003701 003645 003634 003614 004020 003752 004007 003731 004054 004021 003601 003518
	002621 002561 003572 003543 004063 003754 003646 003570 003651 003613 003735 003627 003541 003444 003714 003615
	003527 003511 003606 003504 003607 003543 003673 003614 003672 003575 001517
100-15-36-23, 5220	001515 000453 003741 003652 003712 003651 003645 003624 004035 003767 004020 003746 004071 004033 003610 003527
	002613 002573 003601 003553 004103 003765 003657 003576 003651 003613 003735 003631 003540 003444 003710 003612
	003524 003507 003601 003501 003610 003542 003667 003610 003672 003575 001515
100-15-36-23, 5930	001515 000451 003726 003636 003702 003651 003640 003616 004023 003754 004007 003734 004062 004023 003603 003524
	002625 002566 003574 003547 004066 003754 003643 003570 003651 003611 003732 003630 003537 003443 003705 003616
	003525 003507 003607 003505 003607 003544 003670 003610 003673 003601 001515
100-15-36-23, 6630	001515 000452 003720 003633 003677 003646 003637 003614 004020 003753 004004 003731 004057 004022 003577 003517
	002617 002527 003576 003512 004072 003757 003646 003571 003652 003614 003736 003632 003536 003445 003710 003616
	003527 003513 003606 003501 003604 003541 003664 003605 003663 003571 001515
100-15-36-23, 7340	001523 000456 003730 003643 003703 003652 003641 003621 004027 003760 004013 003745 004064 004027 003601 003524
	002614 002566 003574 003510 004070 003757 003653 003573 003651 003610 003732 003631 003537 003445 003716 003613
	003524 003507 003604 003502 003606 003541 003672 003605 003675 003574 001523
100-15-36-23, 8043	001515 000454 003730 003642 003705 003651 003637 003617 004030 003760 004013 003735 004061 004026 003602 003522
	002615 002566 003573 003540 004074 003756 003650 003576 003653 003611 003735 003634 003541 003451 003676 003617

Figure 41 - Sample listing of TPDMP program.

*** HEADER RECORD INFORMATION FOR FLIGHTS FLI-5***

MAXIMUM PASS NUMBER= 13

MAXIMUM NUMBER OF RUNS= 47

DATE OF FLIGHT= 041078

FLIGHT TAPE NUMBER= 51-A8

AIRCRAFT= /C545 R PILOT= INE COPILOT= STOPER OBSERVER=

ONCE PER FLIGHT DATA VALUES

ETP= 720-3 ESGW= 0.2711E 05 ESCG= 302.1

KPR= 0.9000 HPC= 1216; HRC= 203.0

RA 31.00 RT= 5.300 GT= 6.123

GYS= 3030; FTBOOM= 0; FHBOOM= 0.

Figure 42a. - Sample listing of TABLE PRINT program. (Header Table)

*** PASS INFORMATION FOR FLIGHT= FLI-5***

PASS NO	1	2	3	4	5	6	7	8	9	10	11	12	13
NPAR	30	0	24	40	36	40	28	12	34	29	36	0	29
SRDIN	1M		5M	5M	5M	5M	5M	1T	80X	80X	80X	0	20X
SRDATA	1M		5M	5M	5M	5M	5M	1T	20X	20X	5X		20X
ISTATC	2	0	2	2	2	2	2	2	2	2	2	0	3

DATA MAP

1	1	0	1	1	1	1	1	1	1	1	1	1	0
2	3	0	3	3	3	3	3	2	3	3	2	0	0
3	5	0	5	5	5	5	5	4	6	6	3	0	0
4	7	0	7	7	7	7	7	6	8	8	4	0	0
5	9	0	9	9	9	9	9	8	10	10	5	0	0
6	11	0	11	11	11	11	11	10	13	13	6	0	0
7	13	0	13	13	13	13	13	12	16	16	7	0	0
8	15	0	15	15	15	15	15	14	19	19	8	0	0
9	17	0	17	17	17	17	17	16	22	22	9	0	0
10	19	0	19	19	19	19	19	18	25	25	10	0	0
11	22	0	22	22	22	22	22	21	29	29	11	0	0
12	24	0	24	24	24	24	24	23	32	32	12	0	0
13	26	0	26	26	26	26	26	25	35	35	13	0	0
14	28	0	28	28	28	28	28	27	37	37	14	0	0
15	30	0	30	30	30	30	30	29	40	40	15	0	1
16	35	0	35	35	35	35	35	34	43	43	16	0	106
17	39	0	39	39	39	39	39	38	47	47	17	0	194
18	40	0	40	40	40	40	40	39	49	49	18	0	213
19	42	0	42	42	42	42	42	41	51	51	19	0	242
20	44	0	44	44	44	44	44	43	53	53	20	0	276
21	46	0	46	46	46	46	46	45	55	55	21	0	307
22	50	0	50	50	50	50	50	49	59	59	22	0	392
23	53	0	53	53	53	53	53	52	63	63	23	0	440
24	57	0	57	57	57	57	57	56	67	67	24	0	514
25	59	0	59	59	59	59	59	58	69	69	25	0	545
26	62	0	62	62	62	62	62	61	71	71	26	0	605
27	66	0	66	66	66	66	66	65	75	75	27	0	688
28	70	0	70	70	70	70	70	69	79	79	28	0	756

Figure 42b. - Sample listing of TABLE PRINT program. (Pass Table)

*** SENSOR INFORMATION FOR FLIGHTS FLT-SPASS. 4***

I	NAME	PP	IPIN	IPDF	CAL	EUCV1	EUCV2	CONCVL	A	B	CRPT	PSTAT
1	MARGBOE	V	3	1	X	14370.0	0.	620.000	103.394	0.	3	1
2	MARGBOE	S	4	2	X	14370.0	0.	0.	103.394	-26412.5	3	1
3	MARGBOE	V	5	3	X	14656.0	0.	620.000	107.995	0.	3	1
4	MARGBOE	S	6	4	X	14656.0	0.	0.	107.995	-27902.3	3	1
5	LRL	V	7	5	X	17000.00	0.	0.	-33.3404	0.	3	1
6	LRL	S	8	6	X	17000.00	0.	0.	-33.3404	9552.37	3	1
7	TRTHRN	V	9	7	X	2822.00	0.	500.000	21.6472	0.	3	1
8	TRTHRN	S	10	8	X	2822.00	0.	0.	21.6472	-5661.29	3	1
9	RL	V	11	9	X	7000.00	0.	0.	33.4756	0.	3	1
10	RL	S	12	10	X	7000.00	0.	0.	33.4756	-8847.16	3	1
11	MRLIFTA	V	13	11	X	14250.0	0.	2150.00	106.676	0.	3	1
12	MRLIFTA	S	14	12	X	14250.0	0.	0.	106.676	-27369.4	3	1
13	MRLIFTB	V	15	13	X	1491.0	0.	2150.00	105.370	0.	3	1
14	MRLIFTB	S	16	14	X	1491.0	0.	0.	105.370	-27256.6	3	1
15	MRLIFTC	V	17	15	X	1404.0	0.	2150.00	101.399	0.	3	1
16	MRLIFTC	S	18	16	X	1404.0	0.	0.	101.399	-26606.8	3	1
17	MRLIFTD	V	19	17	X	14116.0	0.	2150.00	102.055	0.	3	1
18	MRLIFTD	S	20	18	X	14116.0	0.	0.	102.055	-26223.7	3	1
19	MADRAQ	V	21	19	X	4586.00	0.	1160.00	32.5289	0.	3	1
20	MADRAQ	S	22	20	X	4586.00	0.	0.	32.5289	-8495.11	3	1
21	WINGJ	V	23	21	X	13708.0	0.	0.	158.314	0.	3	1
22	WINGJ	S	24	22	X	13708.0	0.	0.	158.314	-40973.2	3	1
23	WINGL	V	25	23	X	7330.00	0.	0.	70.4227	0.	3	1
24	WINGL	S	26	24	X	7330.00	0.	0.	70.4227	-17771.6	3	1
25	WINGH	V	27	25	X	13998.0	0.	0.	139.188	0.	3	1
26	WINGH	S	28	26	X	13998.0	0.	0.	139.188	-36188.0	3	1
27	WINGI	V	29	27	X	13735.0	0.	0.	138.989	0.	3	1
28	WINGI	S	30	28	X	13735.0	0.	0.	138.989	-35536.2	3	1
29	VNGTPT	V	31	29	X	13.9100	0.	0.	0.741501E-01	0.	3	1
30	VNGTPT	S	32	30	X	13.9100	0.	0.	0.741501E-01	-19.4413	3	1
31	LHSLIFTL	V	33	31	X	2089.80	0.	0.	15.3998	0.	3	1
32	LHSLIFTL	S	34	32	X	2089.80	0.	0.	15.3998	-4070.59	3	1
33	WINGK	V	35	33	X	16590.0	0.	0.	154.248	0.	3	1
34	WINGK	S	36	34	X	16590.0	0.	0.	154.248	-39195.7	3	1
35	WINGH	V	37	35	X	7026.00	0.	0.	66.5122	0.	3	1
36	WINGH	S	38	36	X	7026.00	0.	0.	66.5122	-16856.8	3	1
37	LHSLIFTR	V	39	37	X	2089.80	0.	0.	15.5479	0.	3	1
38	LHSLIFTR	S	40	38	X	2089.80	0.	0.	15.5479	-3909.92	3	1
39	LOWGTPT	V	41	39	X	13.4800	0.	0.	-0.703989E-01	0.	3	1
40	LOWGTPT	S	42	40	X	13.4800	0.	0.	-0.703989E-01	17.7484	3	1

Figure 42c. - Sample listing of TABLE PRINT program. (Sensor Table)

EVENT RECORD INFORMATION FOR FLIGHT# FLI-5***

I EVENT	TYPE	TIME
1 XCAL PADS 1	X	54478,014
2 RCAL PADS 1	R	54487,846
3 ZCAL PADS 1	Z	54499,978
4 XCAL PADS 2	X	54509,534
5 RCAL PADS 2	R	54518,848
6 ZCAL PADS 2	Z	54529,855
7 LEAD STOP, SIDESLIP#20	X	54540,559
8 LAG STOP, SIDESLIP#20	X	54552,401
9 TR OUTBD, TF34 MAX, A#20	X	54563,309
10 TR INBD, TF34 G.I., A#20	X	54573,958
11 LT=LT-LO=FWD, FLAPS UP	X	54589,063
12 LT=LT-HI=FWD, FLAPS UP	X	54599,870
13 RT=RT-LO=AFT, FLAPS DWN	X	54612,219
14 RT=RT-HI=AFT, FLAPS DWN	X	54620,968
15 L/O AND CLIMB AT 70 KTS	T	54632,088
16 RT CLIMBING TURN, 70 KTS	T	54715,118
17 LF 70 KTS, AUX G.I.	S	54785,588
18 LF 80 KTS, AUX G.I.	S	54803,837
19 LF 90 KTS, AUX G.I.	S	54830,100
20 LF 100 KTS, AUX G.I.	S	54859,681
21 RT TURN 80 KTS, 15/30DG	T	54887,018
22 LF 60 KTS, AUX G.I.	T	54955,252
23 LT TURN 80KTS, 15/30DEG	T	54995,746
24 LF 80 KTS, GEAR UP	T	55055,434
25 PPD 500 FPM, 80KTS, GU	T	55082,986
26 CL 500 FPM, 80KTS, GU	T	55132,620
27 PPD 500 FPM, LT/RT IN, GU	T	55199,294
28 APPROACH AND LANDING	T	55254,785
29 LT=LT-LO=FWD, FLAPS UP	X	55427,814
30 LT=LT-HI=FWD, FLAPS UP	X	55436,938
31 RT=RT-LO=AFT, FLAPS DWN	X	55447,807
32 RT=RT-HI=AFT, FLAPS DWN	X	55458,073
33 LEAD STOP, SIDESLIP#20	X	55467,273
34 LAG STOP, SIDESLIP#20	X	55476,322
35 TR OUTBD, TF34 MAX, A#20	X	55486,534
36 TR INBD, TF34 G.I., A#20	X	55497,872
37 XCAL PADS 1	X	55509,501
38 RCAL PADS 1	R	55521,049
39 ZCAL PADS 1	Z	55531,514

Figure 42d. - Sample listing of TABLE PRINT program. (Event Table)

*** CALRUN INFORMATION FOR FLIGHTS FLI-5***

ENTRY	PRE-Z/LO	PRE-R/HI	PRE-XDUC	POST-Z/LO	POST-R/HI	POST-XDUC
1	4	5	4	40	41	40
2	3	2	1	39	38	37
3	1	2	1	37	38	37
4	1	3	1	37	39	37
5	6	5	4	42	41	40
6	12	13	0	30	31	0
7	13	12	0	31	30	0
8	3	2	11	39	38	29
9	11	14	0	29	32	0
10	7	8	0	33	34	0
11	9	10	0	35	36	0
12	10	9	0	36	35	0
13	0	0	0	0	0	0
14	0	0	0	0	0	0
15	0	0	0	0	0	0
16	0	0	0	0	0	0
17	0	0	0	0	0	0
18	0	0	0	0	0	0
19	0	0	0	0	0	0
20	0	0	0	0	0	0

Figure 42e. - Sample listing of TABLE PRINT program. (Calrun Table)

APPENDIX A

The Honeywell 600 Job Control Language for the EASE System

The EASE software system was originally designed for operation on the Honeywell 600 computer system. Many of the design features have been defined for optimal use of this computer equipment using DSS 180 disk packs. These disk packs can contain approximately 145 million bits or 4.032 million 36-bit data words of usable storage. The operation of the EASE system has been configured to allow sufficient storage for a complete flight of data on one DSS 180 disk pack.

The Raw Data File (RDF) for a flight consists of several physical files: the Table File, the Statistics File, and the Data Files -- one for each pass of data. One DSS 180 disk pack is designed for storing a basic flight data configuration for the RSRA project. Figure A-1 is a summary of the file configuration for the RDF. Such a file scheme is sufficient for most flights.

The structure of the file configuration is defined through the Honeywell 600 File Management System¹. A physical space is defined through the File Management System by a catalogue file structure. Presently, there are two DSS 180 disk packs assigned. Each is configured with the same physical size for the files in the RDF so that data from two flights can be processed at one time. The distinction between data files configured on one disk pack from those on the second disk pack is by the catalogue file structure. This structure definition begins from the assigned user master catalogue name RSRATEST. Sub-catalogue names are assigned under RSRATEST for each disk pack.

These sub-catalogue names are FLTA and FLTB. Under the sub-catalogue FLTA, is another catalogue name residing on the disk pack called PCKA. Similarly, under FLTB is a catalogue called PCKB. File names are then assigned to each physical file required by the RDF. The disk pack with a sub-catalogue structure of FLTA/PCKA is assigned a label name of RSRA1 and the disk pack structured as FLTB/PCKB is assigned a label name of RSRA2. Hence, data to be stored or accessed using the disk pack RSRA1 is defined through the catalogue string RSRATEST/FLTA/PCKA, and for disk pack RSRA2 the catalogue string is RSRATEST/FLTB/PCKB.

The names assigned to each of the physical files of the RDF are the same for both RSRA1 and RSRA2. These file names are stated in figure A-1. All of these file names are associated with a respective file code within each program of the EASE system. For example, the Table File, named TBLFL, is assigned a file code of 07. This association is defined through the job control language for the Honeywell 600 system. It is through this

¹DB54, File Management Supervisor, Honeywell 600 System Reference Manual, March 1973.

means that the program being run is identified, all user supplied and system routines are loaded, and all peripheral allocations are made. The following is a brief description in the order of input, of the job control language cards required by each program of the EASE system². The title of each card described is contained on the job control card beginning in column 8.

SNUMB. This is the first card of any job run and is inserted by the computer operations personnel. It contains a unique number for the job being executed.

IDENT. The second card is a program identification card. It contains the assigned program number for the software.

USERID. This card informs the operating system what user master catalogue is being accessed along with the appropriate password identification.

MSG1. This card contains textual information that is written on the operator's console. It is used here to inform the operator which removable disk pack is to be placed on-line.

OPTION. This card is used here to automatically allocate the card reader, card punch, and line printer to the normal FORTRAN defined file codes.

EXECUTE. This control card instructs the operating system to load the program and any required system library routines and executes the program.

LIMITS. This control card contains four pieces of information required to load and execute the program. First is the amount of CPU time in decimal hours required to execute the program. Second is the amount of memory in computer words to load all user and system routines. Third is the overlay area required in computer words. And last is the total amount of lines of output to be generated on the line printer. All of these values are basically limits that instruct the operating system not to exceed.

TAPE, TAPE9, FILE, PRMFL, SYSOUT. These are the peripheral allocation cards. Each one allocates a particular type of input/output device to be used by the program. The "TAPE" card allocates a 7-track tape handler, the "TAPE9" card allocates a 9-track tape handler, the "FILE" card allocates a scratch disk area, the "PRMFL" card allocates a particular assigned permanent file area, and the "SYSOUT" card assigns the printer in an off-line mode. Each of these cards contain further information to associate a named file code form within the software to these devices.

ENDJOB. This is the last card in the job run and instructs the operating system that no further activities are to be processed for this job run.

The program and input data decks are also included as part of a job run. The program deck is placed after the "OPTION" card and the input data cards are placed immediately preceding the "ENDJOB" card.

²BS19, Control Cards Reference Manual, Honeywell 600 System Reference Manual, February 1973.

Figures A-2 through A-13 contain the job control language cards required to execute each of the programs in the EASE system. These figures are examples using the RSRA1 disk pack for the RDF. These examples can be applied to another assigned disk pack simply by requesting the appropriate disk pack on the 'MSG1' card and defining the correct catalogue file string on the 'PRMFL' cards. For example, to use the RSRA2 disk pack in the SETUP program, the text of the 'MSG1' card would be changed to read: 1, PLEASE MOUNT DISC PACK RSRA2. The 'PRMFL' card would be changed to read 07, R/W,R, RSRATEST\$XXXX/FLTB/PCKB/TBLFL.

Within the information contained in each of the 'USERID' and 'PRMFL' control cards, the file defined as 'XXXX' must contain the correct password assigned to the user master catalogue, RSRATEST. This information shall be given to authorized users of the system. Also, on the 'TAPE' and 'TAPE 9' control cards allocating input tapes, the field designated as 'NNNN' is to be replaced by the assigned magnetic tape number.

It is not necessary to run each program independently. For example, the SETUP, SCAN, and ABTASK programs could be stacked to execute as one job run with each of the three programs as separate activities. To do this, only one set of job control cards for SNUMB, IDENT, USERID, MSG1, and ENDJOB are required. That is the first four job control cards are required only once and can be eliminated from the beginning of the deck setup for the SCAN and ABTASK. Also the ENDJOB is only required after the last activity so this card can be eliminated from the end of the SETUP and SCAN program. Figure A-14 lists the deck setup for running these three programs as one job run. This can be done for any of the programs in the EASE system. However, care should be taken so that the order of activities follows a logical operational procedure for processing the data.

RDF File	Data File Sample Rate	No. Samples Per Sec.	File Name Mnemonic	File Code	Size in Links*
Table File			TBLFL	07	7
Statistics File			STATS	09	149
Pass 1 Data File	1/M	Approx. 3	PASS 1	11	25
Pass 2 Data File	1/M	Approx. 3	PASS 2	12	25
Pass 3 Data File	5/M	Approx. 17	PASS 3	13	72
Pass 4 Data File	5/M	Approx. 17	PASS 4	14	72
Pass 5 Data File	5/M	Approx. 17	PASS 5	15	72
Pass 6 Data File	5/M	Approx. 17	PASS 6	16	72
Pass 7 Data File	5/M	Approx. 17	PASS 7	17	72
Pass 8 Data File	1/T	Approx. 17	PASS 8	18	72
Pass 9 Data File	20X	20	PASS 9	19	72
Pass 10 Data File	20X	20	PASS 10	20	72
Pass 11 Data File	5X	5	PASS 11	21	21
Pass 12 Data File	5X	5	PASS 12	22	21
Pass 13 Derived Par. Data File	20X	20	PASS 13	23	226
Total Size of RDF					1050

* 1 Link = 3840 words

Figure A-1. - File configuration for RSRA raw data file (RDF)

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	
\$	IDENT	112320,EASE
\$	MSG1	1,PLEASE MOUNT DISC PACK RSRA1
\$	USERID	RSRATEST\$ <u>XXXX</u>
\$	OPTION	FORTRAN
(Program decks)		
\$	EXECUTE	
\$	LIMITS	08,19K,,2K
\$	SYSOUT	08
\$	PRMFL	07,R/Q,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/TBLFL
\$	FILE	01,AIR,3R
(Data cards)		
\$	ENDJOB	
*** EOF		

Figure A-2. - Setup routine deck setup using disk pack:RSRA1.

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	
\$	IDENT	112320,EASE
\$	MSG1	1,PLEASE MOUNT DISC PACK RARA1
\$	USERID	RSRATEST\$ <u>XXXX</u>
(Program deck)		
\$	EXECUTE	
\$	LIMITS	50,24K,,2K
\$	TAPE9	03,X1D,,NNNN
\$	PRMFL	07,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/TBLFL
\$	PRMFL	09,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/STATS
\$	PRMFL	11,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS1
\$	PRMFL	12,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS2
\$	PRMFL	13,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS3
\$	PRMFL	14,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS4
\$	PRMFL	15,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS5
\$	PRMFL	16,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS6
\$	PRMFL	17,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS7
\$	PRMFL	18,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS8
\$	PRMFL	19,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS9
\$	PRMFL	20,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS10
\$	PRMFL	21,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS11
\$	PRMFL	22,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS12
(Data cards)		
\$	ENDJOB	
***EOF		

Figure A-3. - Scan routine deck setup using disk pack RSRA1.

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	
\$	IDENT	112320,EASE
\$	MSG1	1,PLEASE MOUNT DISC PACK RARA1
\$	USERID	RSRATEST\$ <u>XXXX</u>
\$	OPTION	FORTRAN
(Program deck)		
\$	EXECUTE	
\$	LIMITS	10,16K,2K
\$	PRMFL	07,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/TBLFL
\$	PRMFL	09,R,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/STATS
\$	ENDJOB	
***EOF		

Figure A-4. - Abtask deck setup using disk pack RSRA1.

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	
\$	IDENT	112320,EASE
\$	MSG1	1,PLEASE MOUNT DISC PACK RSRA1
\$	USERID	RSRATEST\$ <u>XXXX</u>
\$	OPTION	FORTRAN
(Program deck)		
\$	EXECUTE	
\$	LIMITS	20,16K,,10K
\$	PRMFL	07,R,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/TBLFL
\$	PRMFL	09,R,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/STATS
\$	PRMFL	35,R,R,RSRATEST\$ <u>XXXX</u> /UPCFL
(Data cards)		
\$	ENDJOB	
***EOF		

Figure A-5. - Statprint deck setup using disk pack RSRA1.

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	
\$	IDENT	112320,EASE
\$	MSG1	1,PLEASE MOUNT DISC PACK RSRA1
\$	USERID	RSRATEST\$ <u>XXXX</u>
\$	OPTION	FORTRAN
(Program deck)		
\$	EXECUTE	
\$	LIMITS	50,23K,,2K
\$	PRMFL	07,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/TBLFL
\$	PRMFL	09,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/STATS
\$	PRMFL	19,R,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS9
\$	PRMFL	20,R,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS10
\$	PRMFL	23,R/W,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS13
(Data cards)		
\$	ENDJOB	
***EOF		

Figure A-6. - Dptask deck setup using disk pack RSRA1.

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	
\$	IDENT	112320,EASE
\$	MSG1	1,PLEASE MOUNT DISC PACK RSRA
\$	USERID	RSRATEST\$ <u>XXXX</u>
\$	OPTION	FORTRAN
(Program deck)		
\$	EXECUTE	
\$	LIMITS	20,17K,,5K
\$	PRMFL	07,R,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/TBLFL
\$	PRMFL	09,R,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/STATS
\$	PRMFL	35,R,R,RSRATEST\$ <u>XXXX</u> /UPCFL
(Data cards)		
\$	ENDJOB	
***EOF		

Figure A-7. - Datask program deck setup using disk pack RSRA1.

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	112320,EASE
\$	IDENT	1,PLEASE MOUNT DISC PACK RSRA1
\$	MSG1	RSRATEST\$XXXX
\$	USERID	FORTRAN
\$	OPTION	
(Program deck)		
\$	EXECUTE	
\$	LIMITS	20,18K,,5K
\$	PRMFL	07,R,R,RSRATEST\$XXXX/FLTA/PCKA/TBLFL
\$	PRMFL	09,R,R,RSRATEST\$XXXX/FLTA/PCKA/STATS
\$	PRMFL	11,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS1
\$	PRMFL	12,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS2
\$	PRMFL	13,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS3
\$	PRMFL	14,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS4
\$	PRMFL	15,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS5
\$	PRMFL	16,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS6
\$	PRMFL	17,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS7
\$	PRMFL	18,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS8
(Data cards)		
***EOF		

Figure A-8. - Cycle count deck setup using disc pack RSRA1.

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	112320,EASE
\$	IDENT	1,PLEASE MOUNT DISC PACK RSRA1
\$	MSG1	RSRATEST\$XXXX
\$	USERID	FORTRAN
\$	OPTION	
(Program deck)		
\$	EXECUTE	
\$	LIMITS	20,22K,5K
\$	PRMFL	07,R,R,RSRATEST\$XXXX/FLTA/PCKA/TBLFL
\$	PRMFL	09,R,R,RSRATEST\$XXXX/FLTA/PCKA/STATS
\$	PRMFL	19,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS9
\$	PRMFL	21,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS11
\$	PRMFL	22,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS12
\$	PRMFL	23,R,R,RSRATEST\$XXXX/FLTA/PCKA/PASS13
\$	TAPE	50,x50D,,,556-BPI-PLOT-TAPE
\$	SYSOUT	59
(Data cards)		
\$	ENDJOB	
***EOF		

Figure A-9. - Time history deck setup using disk pack RSRA1.

<u>Col. 1</u>	<u>Col. 8</u>	<u>Col. 16</u>
\$	SNUMB	
\$	IDENT	112320,EASE
\$	MSG1	1,PLEASE MOUNT DISC PACK RSRA1
\$	USERID	RSRATEST\$ <u>XXXX</u>
\$	OPTION	FORTTRAN
(Program deck)		
\$	EXECUTE	
\$	LIMITS	20,22K,5K
\$	PRMFL	07,R,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/TBLFL
\$	PRMFL	24,R,R,RSRATEST\$ <u>XXXX</u> /FLTA/PCKA/PASS14
\$	PRMFL	35,R,R,RSRATEST\$ <u>XXXX</u> /UPCFL
(Data cards)		
\$	ENDJOB	
***EOF		

Figure A-10. - Harmonic analysis deck setup using disk pack RSRA1.

<u>Col. 1</u>	<u>Col. 8</u>	<u>Col. 16</u>
\$	SNUMB	
\$	IDENT	112320,EASE
\$	USERID	RSRATEST\$ <u>XXXX</u>
\$	OPTION	FORTTRAN
(Program deck)		
\$	EXECUTE	
\$	LIMITS	15,15K,5K
\$	PRMFL	35,R/W,R,RSRATEST\$ <u>XXXX</u> /UPCFL
\$	FILE	36,x36R,15R
(Data cards)		
\$	ENDJOB	
***EOF		

Figure A-11. - Upcgen program deck setup.

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	
\$	IDENT	111230,EASE
\$	OPTION	FORTRAN
(Program deck)		
\$	EXECUTE	
\$	LIMITS	25,16K,,10K
\$	SYSOUT	06
\$	TAPE9	01,X1D,, <u>NNNN</u> ,,INPUT-TAPE
(Data cards)		
\$	ENDJOB	

Figure A-12. - Tpdmp program deck setup.

Col. <u>1</u>	Col. <u>8</u>	Col. <u>16</u>
\$	SNUMB	
\$	IDENT	112320,EASE
\$	MSG1	1,PLEASE MOUNT DISC PACK RSRA1
\$	USERID	RSRATEST\$ <u>XXXX</u>
\$	OPTION	FORTRAN
(Program deck)		
\$	EXECUTE	
\$	LIMITS	08,16K,,1K
\$	PRMFL	07,R,R,RSRATESTS <u>XXXX</u> /FLTA/PCKA/TBLFL
\$	ENDJOB	

Figure A-13. - Table print program deck setup.

Col. 1	Col. 8	Col. 16
\$	SNUMB	
\$	IDENT	112320,EASE
\$	MSG1	1,PLEASE MOUNT DISC PACK RSRA1
\$	USERID	RSRATEST\$XXXX
\$	OPTION	FORTRAN
(Setup routine program deck)		
\$	EXECUTE	
\$	LIMITS	08,19K,,2K
\$	SYSOUT	08
\$	PRMFL	07,R/Q,R,RSRATEST\$XXXX/FLTA/PCKA/TBLFL
\$	FILE	01,AIR,3R
(Data cards)		
\$	OPTION	FORTRAN
(Scan routine program deck)		
\$	EXECUTE	
\$	LIMITS	50,24K,,2K
\$	TAPE9	03,X1D,,NNNN
\$	PRMFL	07,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/TBLFL
\$	PRMFL	09,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/STATS
\$	PRMFL	11,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS1
\$	PRMFL	12,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS2
\$	PRMFL	13,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS3
\$	PRMFL	14,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS4
\$	PRMFL	15,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS5
\$	PRMFL	16,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS6
\$	PRMFL	17,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS7
\$	PRMFL	18,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS8
\$	PRMFL	19,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS9
\$	PRMFL	20,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS10
\$	PRMFL	21,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS11
\$	PRMFL	22,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/PASS12
(Data cards)		
\$	OPTION	FORTRAN
(Abtask routine program deck)		
\$	EXECUTE	
\$	LIMITS	10,16K,2K
\$	PRMFL	07,R/W,R,RSRATEST\$XXXX/FLTA/PCKA/TBLFL
\$	ENDJOB	
***EOF		

Figure A-14. - Deck setup to execute setup, scan, and abtask.

APPENDIX B

TELEVENT II

Real Time Digital Tape Format Description

ANSI/IBM Compatible

Handler: 9 track

Density: 800 bpi

Parity: Odd

Computer Word Size: 16 bits (msb = bit #16; lsb = #1)

Three types of records are recorded: (1)-Header Record; (2)-Data Description Record; (3)-Data Record.

Header Record

Record Size: 45 words

The header record contains alphanumeric information in EBCDIC and is identified by the first word being equal to zero. The information contained in the header record is obtained during the primary module setup of each data link. One header record is generated for each header card encountered.

<u>Word</u>	<u>Contents</u>
1	000000
2	Number of words/record (45)
3-4	4 char. link ID in EBCDIC
5	Reel Sequence Number
6-45	80 EBCDIC alphanumeric characters

Data Description Record

Record Size: 10 words

The data description record contains the information necessary to describe the data records for a specific link, format, and source. This type of record is identified by the first word containing a -1 in 2's complement form (177777₈). One data description record is present for each type of data record recorded.

<u>Word</u>	<u>Contents</u>
1	-1 (2's complement)
2	Number of words/record (10)
3-4	4 char. link ID in EBCDIC
5 bits 16-13	Zero
bits 12-11	Source ID
	0 - Analog tape
	1 - PCM Simulator
	2 - Manual
bits 10-5	6 least significant bits of first EBCDIC char. of format ID. (alpha)

<u>Word</u>	<u>Contents</u>
bits 4-1	4 least significant bits of second EBCDIC character of format ID. (numeric)
6 bit 16	= 0 for "Software Merged" time = 1 for "Hardware Merged" time
bits 15-8	Zero
bits 7-5	Time identification bits* = 0 - No time is recorded < 4 - Number of "Normal" time words recorded (T_n) > 4 - Bits 6 and 5 indicate the number of "Merged" time words recorded (T_m) = 4 - Time is recorded in "Both" mode.
bits 4-1	Handler number
7	Number of frames/physical record. (F)
8	Number of words/frame. (W)
9	Number of sync words recorded for PCM data links. (S)
10	2 EBCDIC blanks.

Data Record

Record size: Variable

Data records are identified by the first word being greater than zero.

The record size can be calculated by;

$$B = F(T_m + S + W) + T_n + 5$$

where;

B = Physical record size

F = Number of frames/physical record

W = Number of words/frame

S = Number of sync words/frame (PCM only)

T_n = Number of "normal" time words recorded

T_m = Number of "merged" time words recorded

F, W, S, T_n and T_m are obtained from the Data Description Record for the specified source, link, and format.

The format of all data records is as follows:

<u>Word</u>	<u>Contents</u>
1	Same as word 5 of corresponding Data Description Record
2	Number of words/physical record (B)
3-4	4 char. link ID in EBCDIC
5	Block count of data records for this source, link, and format.
6	Real time digital data including any time words and frame sync words
(B)	

Time Recording Modes

The system has 3 words of time that can be recorded in a variety of ways. The format of these 3 time words is as follows:

Time Word 1	Tenths of Sec.	Hundredths of Sec.	Thousandths of Sec.	Undefined
	16 13	12 9	8 5	4 1

Time Word 2		Tens of Min.	Units of Min.		Tens of Sec.	Units of Sec.
	1			1		
	16	15 13	12 9	8	7 5	4 1

Time Word 3	Hund. of Days	Tens of Days	Units of Days	Tens of Hr.	Units of Hr.
	16 15	14 11	10 7	6 5	4 1

A. Normal Time

When Normal Time is indicated in bits 7-5 of word 6 of the corresponding Data Description Record, only 1 time tag is supplied for the entire physical record irrespective of the number of frames contained therein. The time tag represents the GMT of when the last data word of the buffer was received. The indicated number of Normal Time words are placed at the end of the physical record with the least significant time word being recorded first.

<u>Tn</u>	<u>Time Words Recorded</u>
1	1
2	1, 2
3	1, 2, 3

B. Merged Time

When bits 7-5 of word 6 of the corresponding Data Description Record indicated 1, 2, or 3 Merged Time words are being recorded, each frame of data within the physical record is time tagged with TM time words as follows:

<u>Tm</u>	<u>Time Words Recorded</u>
1	1
2	1, 2
3	1, 2, 3

The least significant time word is recorded first in each group of time words.

Merged Time can be obtained via either hardware or software as indicated in bit 16 of word 6 of the corresponding Data Description Record. For Hardware Merged time, T_m time words are recorded for each frame immediately following the last word of each frame or immediately following the last sync word of each frame if any sync words are present. (Sync words appear only with PCM data where the sync is not being stripped).

For Software Merged time, T_m number of time words are recorded for each frame with all of the time words for all of the frames in a physical record appearing at the end of the buffer beginning immediately after the last word (or sync word) of the last frame.

The time tagging for PCM data corresponds to the last bit of the sync pattern. For the A/D link (AMQ), the time tag is obtained after the last word of the frame has been sampled.

C. Both

When bits 7-5 of word 6 of the corresponding Data Description Record = 100_2 , time is recorded in what is referred to as the Both mode. In this mode, 3 words of Normal Time are recorded at the end of the buffer along with 1 word of Merged Time. The time tagging for the two types of time are the same as those previously described.

Frame Sync Pattern

When data from one of the PCM links is being digitized, the operator can request to "strip" the frame sync pattern. Under this condition, no sync words appear on the digital tape and word 9 of the corresponding Data Description Record = 0. When the frame sync pattern is not being stripped, (S) number of sync words as indicated in word 9 of the corresponding Data Description Record appear after the last word of each frame. The number of words/frame (W) does not include PCM sync pattern words.

APPENDIX C

Derived Parameters

There are certain elements of aircraft performance that cannot be directly instrumented but are functions of one or more instrumented elements of the aircraft. Such elements cannot be processed directly but must be derived based upon their defined algorithms. These elements are processed through the routine "DPTASK" for their point by point derivations as well as the calculation of their statistics.

This appendix lists the parameters that are currently derived through "DPTASK" along with their algorithms. Figure C-1 contains the list of flight constants used in the equations. Figure C-2 lists the definition of the input variables used and Figure C-3 lists the definition of the variables being derived.

The algorithms currently defined in "DPTASK" are as follows:

$$V_{IT} = 1479.K_1 \quad (C\ 1)$$

where

$$K_1 = \sqrt{(1 + .06805 V_{IP})^{.2857} - 1.} \quad (C\ 2)$$

$$V_{CAS} = \text{Linear Interpolation Table Lookup } f(V_{IT}) \quad (C\ 3)$$

$$V_{EI} = (V_{CAS}) \left(\sqrt{\text{DELTA}} \right) \left(\frac{K_2}{K_1} \right) \quad (C\ 4)$$

where

$$\text{DELTA} = (1.0 - .000006875H)^{5.256} \quad (C\ 5)$$

$$K_2 = \sqrt{\left(1 + \frac{144. V_{IP}}{2116.2 \text{ DELTA}}\right)^{.2857} - 1.} \quad (C\ 6)$$

$$F_{AT} = \text{ITAT} - .00013177 \text{ KPR} (V_{EI} \sqrt{\frac{.0023769}{\text{DENS}}})^2 \quad (C\ 7)$$

where

$$\text{DENS} = \frac{2116.2 \text{ DELTA} - .378277 \text{ PRESSV}}{3089.7 (\text{ITAT} + 273.16)} \quad (C\ 8)$$

and

$$\text{PRESSV} = \text{RELHUM} [2.685 + .013232(\text{ITAT} + 17.78)^{2.245}] \quad (C\ 9)$$

$$V_T = V_{CAS} \sqrt{\rho_o / \rho} \quad (C10)$$

where

$$\rho_o = .0023769 \quad (C11)$$

and

$$\rho = \frac{2116.2 \text{ DELTA} - .378277 \text{ PRESSV}_1}{3089.7 (\text{FAT} + 273.16)} \quad (C12)$$

and

$$\text{PRESSV}_1 = \text{RELHUM} [2.685 + 0.13232 (\text{FAT} + 17.78)^{2.245}] \quad (C13)$$

$$\text{TAT} = \text{FAT} + .000131714 V_T^2 \quad (C14)$$

$$H_D = \frac{1. - \left(\frac{\rho}{\rho_0}\right)^{.235}}{.000006875} \quad (C15)$$

$$\Omega R = \frac{(2\pi) (R) (NR) (MRC)}{(60) (100)} \quad (C16)$$

$$\Omega_{TR} = \frac{(2\pi) (R_T) (NR) (MRC) (GT)}{(60) (100)} \quad (C17)$$

$$\mu = \frac{1.6889 V_T}{\Omega R} \quad (C18)$$

$$MACH_A = \frac{\Omega R + 1.6889 V_T}{65.7689 \sqrt{FAT + 273.16}} \quad (C19)$$

$$SHP_1 = \frac{(NF_1) (Q_1) (HPC)}{10000.} \quad (C20)$$

$$SHP_2 = \frac{(NF_2) (Q_2) (HPC)}{10000.} \quad (C21)$$

$$HP_{TOTAL} = SHP_1 + SHP_2 \quad (C22)$$

$$CP_{ENG\ TOT} = \frac{550\ HPT}{\rho\ \pi\ R^2\ (\Omega R)^3} \quad (C23)$$

$$HP_{MR} = \frac{(NR) (MRQ) (MRC)}{(5252) (100)} \quad (C24)$$

$$CP_{MAIN} = \frac{550\ HP_{MR}}{\rho\ \pi\ R^2\ (\Omega R)^3} \quad (C25)$$

$$HP_{TR} = \frac{(NR) (TRQ) (GTS)}{(5252) (100)} \quad (C26)$$

$$CP_{TAIL} = \frac{550\ HP_{TR}}{\rho\ \pi\ R^2\ (\Omega R)^3} \quad (C27)$$

$$HP_S = HP_{MR} + HP_{TR} \quad (C28)$$

$$CP_{TOT} = \frac{550\ HP_S}{\rho\ \pi\ R^2\ (\Omega R)^3} \quad (C29)$$

$$YAW = HEAD - HEAD_1 \quad (C30)$$

where

HEAD₁ is the value of the first sample in data burst.

$$F_X = \text{ISOLB} + .2588 (\text{LIFTD} - \text{LIFTA}) \quad (\text{C31})$$

$$F_Y + \text{ISOLA} - \text{ISOLC} + .2588 (\text{LIFTB} - \text{LIFTC}) \quad (\text{C32})$$

$$F_Z = .9659 (\text{LIFTA} + \text{LIFTB} + \text{LIFTC} + \text{LIFTD}) \quad (\text{C33})$$

$$M_X = 57.88 (\text{ISOLA} - \text{ISOLC}) - 31.98 (\text{LIFTB} + \text{LIFTC}) \quad (\text{C34})$$

$$M_Y = -53. \text{ISOLB} + 32.639 \text{LIFTA} - 2.656 \text{LIFTB} - 37.9515 \text{LIFTD} - 2.656 \text{LIFTC} \quad (\text{C35})$$

$$M_Z = -17.75 \text{ISOLA} - 23.25 \text{ISOLC} + .7118 \text{LIFTB} - \text{LIFTC}) - 82. \text{QLINK} \quad (\text{C36})$$

$$\text{AR} = -.0000024\text{A}^3 + .0008353\text{A}^2 - .2677\text{A} + 114.5 \quad (\text{C37})$$

SYMBOL	DEFINITION	VALUE
KPR	Temperature probe recovery factor	.9
RELHUM	Relative humidity	0.
HPC	T58 Engine chaff horsepower @ 100%	1215.69
MRC	Main rotor RPM @ 100% NR	203.
R	Main rotor radius ft	31.
R _T	Tail rotor radius ft	5.3
GT	Gear ratio between tail rotor and main rotor	6.123
GTS	Tail rotor shaft RPM @ 100% NR	3030.

Figure C-1. Flight Constants for Derived Parameters

SYMBOL	MNEMONIC	DEFINITION
ITAT	ITATBOOM	Indicated total air temperature (BOOM) (deg C)
V _{IP}	VIPBOOM	Indicated airspeed (BOOM) (PSID)
H	HBOOM	Pressure altitude (BOOM) (ft)
HEAD	HEAD180	Compass heading (+ 180 deg)
Q ₁	NO1QPCT	No. 1 engine torque %
Q ₂	NO2QPCT	No. 2 engine torque %
NF ₁	NO1NFPCT	No. 1 engine power turbine speed %
NF ₂	NO2NFPCT	No. 2 engine power turbine speed %
MRQ	MRQ1	Main rotor shaft torque ft-lb
TRQ	TRQ	Tail rotor shaft torque ft-lb
NR	NR	Main rotor speed %
LIFTA	MRLIFTA	Main rotor LIFT A (forward) (1b)
LIFTB	MRLIFTB	Main rotor LIFT B (right hand) (1b)
LIFTC	MRLIFTC	Main rotor LIFT C (left hand) (1b)
LIFTD	MRLIFTD	Main rotor LIFT D (aft) (1b)
ISOLA	ISAFAPR	Forward lefthand latitude ISOLATOR
ISOLB	ISOFAPR	Forward longitude ISOLATOR
ISOLC	ISAFBPR	Aft right hand latitude ISOLATOR
QLINK	XMSNSGT	Transit torque link
A	AILPOSR	Right aileron position

Figure C-2. Input Variables for Derived Parameters

SYMBOL	MNEMONIC	DEFINITION
V_{IT}	VITBOOM	True instrumented indicated airspeed (BOOM) (KNOTS)
V_{CAS}	VCASBOOM	Calibrated airspeed (BOOM) (KNOTS)
V_{EI}	VEIBOOM	Equivalent airspeed (BOOM) (KNOTS)
FAT	FATBOOM	Free air temperature (BOOM) (DEGREES C)
V_T	VTBOOM	True airspeed (BOOM) (KNOTS)
TAT	TATBOOM	Total air temperature (BOOM) (DEGREES C)
H_D	HDBOOM	Density altitude (BOOM) (FEET)
Ω_R	OMEGAR	Main rotor tip speed (ft/sec)
Ω_{TR}	OMEGATR	Tail rotor tip speed (ft/sec)
μ	MU	Main rotor tip speed ratio
$MACH_A$	MACHA	Advanced blade tip mach number
SHP_1	NO1SHP	No. 1 engine shaft horsepower
SHP_2	NO2SHP	No. 2 engine shaft horsepower
HP_{TOTAL}	HPT	Total engine horsepower
$CP_{ENG\ TOT}$	CPTE	Total engine power coefficient
HP_{MR}	HPMR	Main rotor horsepower
CP_{MAIN}	CPM	Main rotor power coefficient
HP_{TR}	HPTR	Tail rotor horsepower
CP_{TAIL}	CPTAIL	Tail rotor power coefficient
HP_S	HPS	Total strain gage power
CP_{TOT}	CPT	Total power coefficient
YAW	YAWFTRM	Yaw attitude (DEGREE)
F_X	FX	Main rotor longitudinal force (lb)
F_Y	FY	Main rotor latitudinal force (lb)
F_Z	FZ	Main rotor vertical force (lb)
M_X	MX	Main rotor roll moment (in-lb)
M_Y	MY	Main rotor pitch moment (in-lb)
M_Z	MZ	Main rotor yaw moment (in-lb)
AR	AILPOSP	Right aileron position (%)

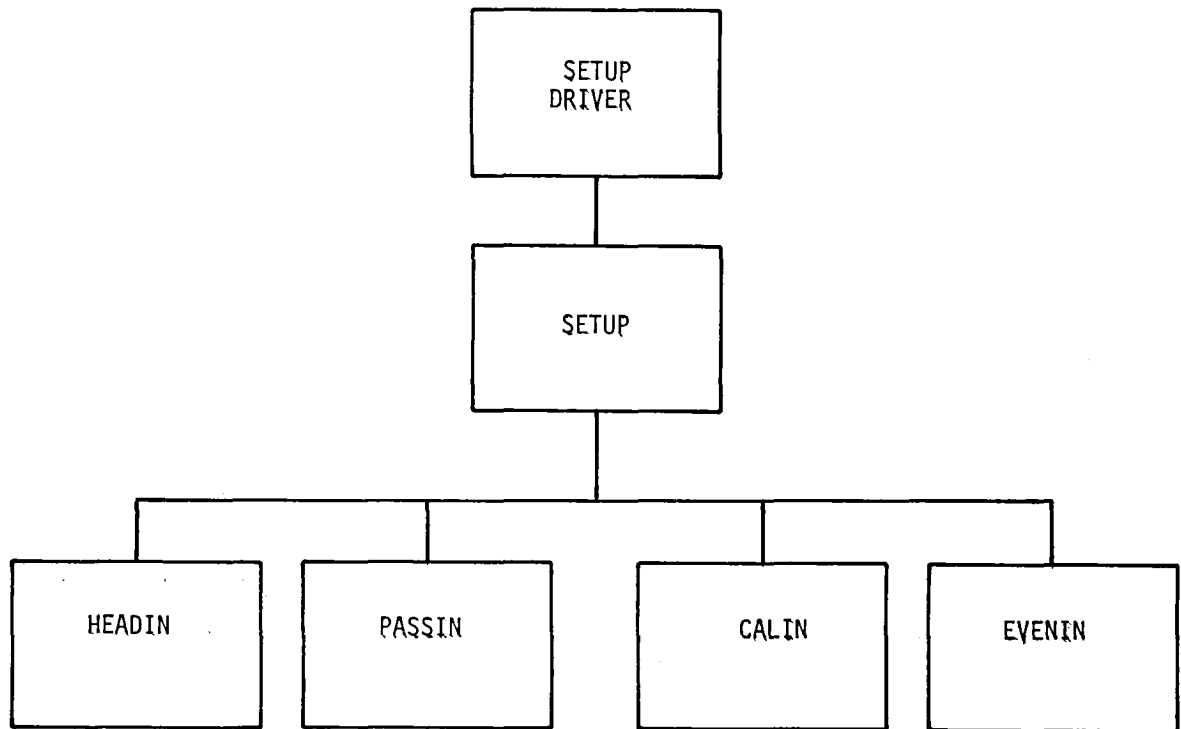
Figure C-3. Derived Parameter Variable Definitions

APPENDIX D

Program Flowcharts

This appendix describes the programming logic used in each independent software task of the EASE system and provides a basic understanding of the methods used to develop each task in the overall operational requirements. A collection of the flowcharts and a listing of each subroutine documentation cards are included here.

A hierarchy chart of each program used in the EASE system precedes the set of subroutine documentation and flowcharts applicable to each respective program.



HIERARCHY CHART for SETUP PROGRAM

*****MAIN SETUP DRIVER*****

PROGRAM IDENTIFICATION

PROGRAM NAME ---- MAIN SETUP DRIVER
PROGRAM NUMBER ----- 112320
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW-625/635
MEMORY ----- ALL FILES OPEN (20K)
PERIPHERALS ----- CARD READER,PRINTER
LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

TO CALL APPROPRIATE TASK TO BE GENERATED.

METHOD

CHECK INPUT CARD FOR CORRECT TASK NAME AND OPTION NAME
AND CALL APPROPRIATE TASK.

INPUT/OUTPUT

CCODE - INPUT AND OUTPUT ARGUMENT CONTAINING CARD CODE
CARD - INPUT AND OUTPUT ARGUMENT CONTAINING CHARACTER INFORMATION
TNAME - INPUT ARGUMENT CONTAINING TASK NAME
OPT - INPUT AND OUTPUT ARGUMENT CONTAINING OPTION NAME
NOOP - INPUT AND OUTPUT ARGUMENT CONTAINING NUMBER OF
ERRORS COUNTED FROM BAD INPUTS.
JCDCNT - INPUT AND OUTPUT ARGUMENT CONTAINING TOTAL NUMBER OF
CARDS INPUT

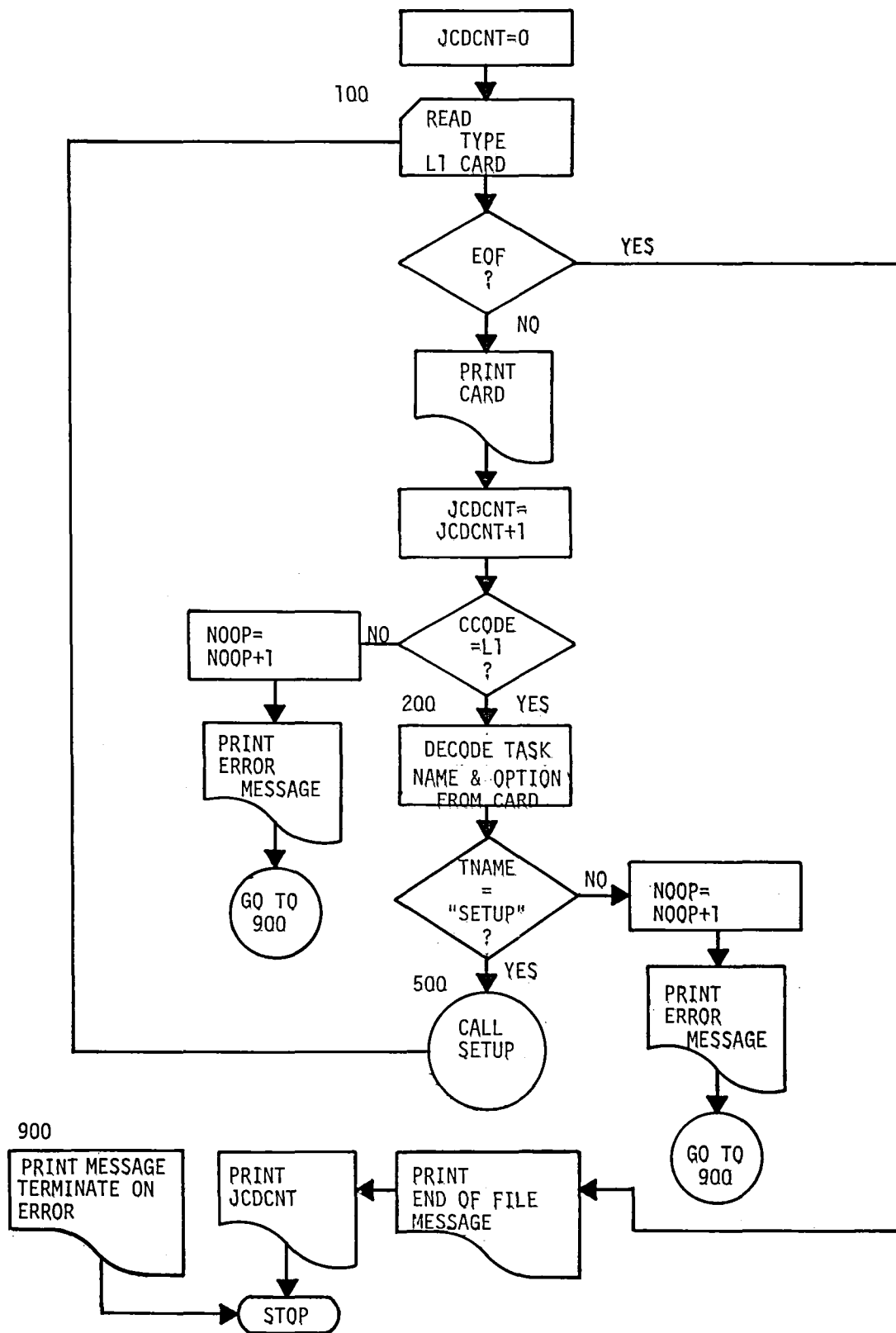
CALLING SEQUENCE

CALL SETUP

COMMON AREAS

DATIN - CARD,OPT,TNAME,CCODE,NOOP,JCDCNT

SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS
AND TABLE FILE FORMATS OR FOR ANY OTHER SPECIFIC INFORMATION.



*****SURROUTINE SETUP*****

PROGRAM IDENTIFICATION

PROGRAM NAME ---- SUBROUTINE SETUP
 PROGRAM NUMBER ----- 112320
 AUTHOR ----- TERRY D. SOMMERS

 COMPUTER ----- HW-625/635
 MEMORY -----
 PERIPHERALS ----- CARD READER,PRINTER,DISC,TAPE
 LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

TO INITIALIZE OR UPDATE A TABLE FILE WHICH WILL
 BE USED BY OTHER RSRA ROUTINES

METHOD

CHECK OPTION FOR "INITIALIZE" OR "UPDATE" AND EITHER
 ZERO OLD TABLES OR READ CURRENT TABLES FROM DISC
 INTO MEMORY. READ A CARD AND CHECK CARD CODE TO
 DETERMINE ANY OR ALL TABLE ROUTINES TO BE USED.
 WRITE NEW OR UPDATED TABLES TO DISC FILE 07 AND
 RETURN TO DRIVER ROUTINE. TABLES WILL ONLY BE SAVED IF
 NOOP VALUE IS 0.

INPUT/OUTPUT

CCODE - INPUT AND OUTPUT ARGUMENT CONTAINING CARD CODE
 CARD - INPUT AND OUTPUT ARGUMENT CONTAINING CHARACTER INFORMATION
 TNAME - INPUT ARGUMENT CONTAINING TASK NAME
 OPT - INPUT AND OUTPUT ARGUMENT CONTAINING OPTION NAME
 NOOP - INPUT AND OUTPUT ARGUMENT CONTAINING NUMBER OF
 ERRORS COUNTED FROM BAD INPUTS.
 JCDCNT - INPUT AND OUTPUT ARGUMENT CONTAINING TOTAL NUMBER OF
 CARDS INPUT
 THEAD - INPUT OR OUTPUT ARGUMENT CONTAINING HEADER TABLE
 INFORMATION
 TPASS - INPUT OR OUTPUT ARGUMENT CONTAINING PASS TABLE
 INFORMATION
 TSENSE - INPUT OR OUTPUT ARGUMENT CONTAINING SENSOR TABLE
 INFORMATION
 TEVENT - INPUT OR OUTPUT ARGUMENT CONTAINING EVENT TABLE
 INFORMATION
 ICALNO - INPUT OR OUTPUT ARGUMENT CONTAINING CALIBRATION
 TABLE INFORMATION
 SCTAR - INPUT OR OUTPUT ARGUMENT CONTAINING SENSOR TABLE
 INFORMATION FOR SCRATCH TAPE FILE 01
 TABREC - ARGUMENT CONTAINING A TABLE RECORD 600 WORDS/REC
 NTBL - ARGUMENT CONTAINING NAME OF TABLE TO BE
 INITIALIZED OR UPDATED
 FILE 07 - RANDOM DISC FILE FOR TABLES
 FILE 01 - RANDOM SCRATCH TAPE FILE FOR SENSOR TABLES ONLY
 520 WORDS/REC.

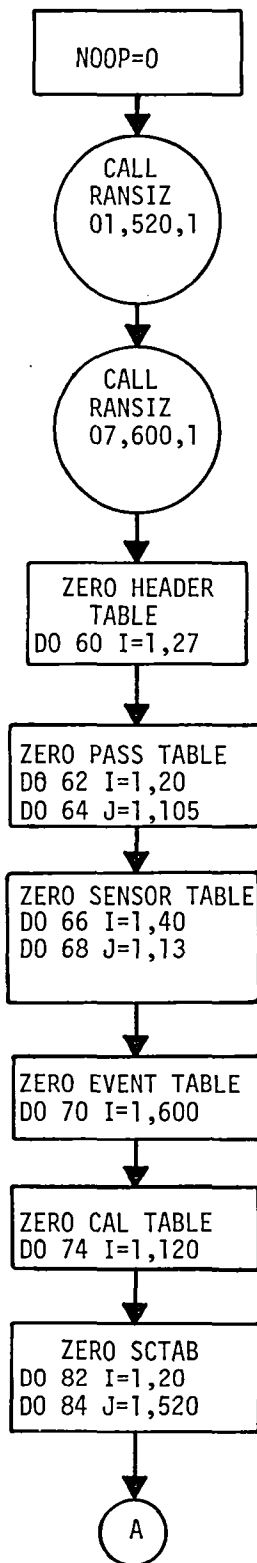
CALLING SEQUENCE

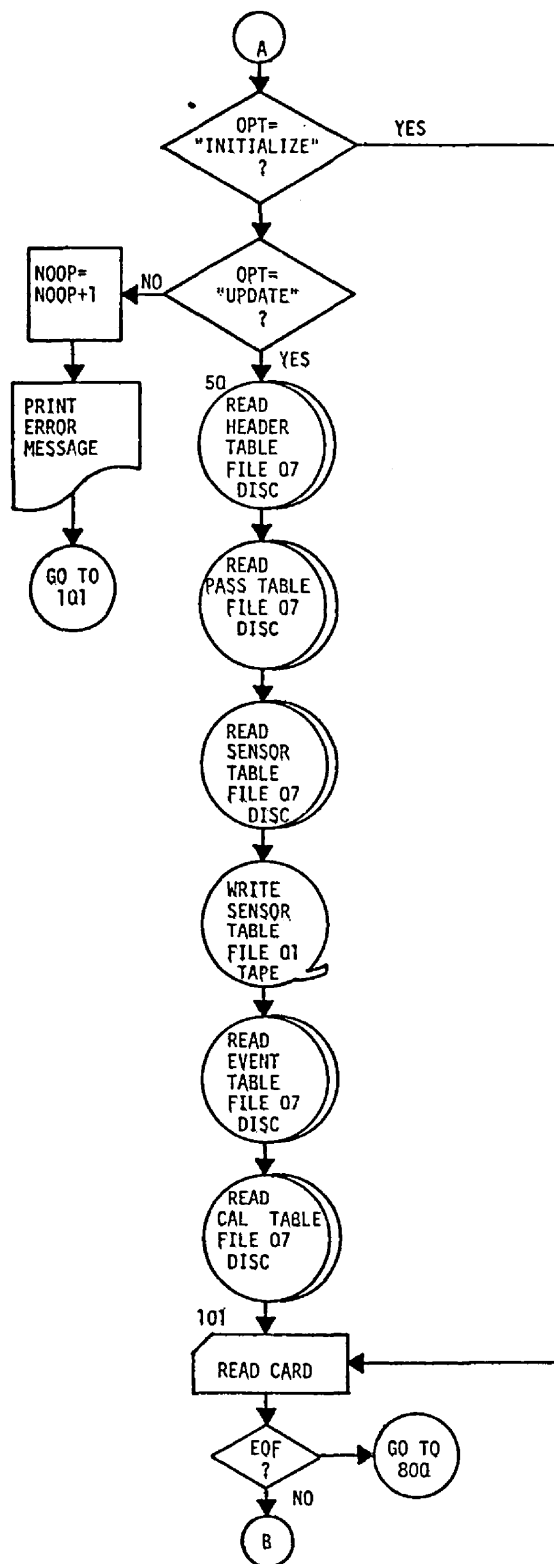
CALL HEADIN
CALL PASSIN
CALL EVENIN
CALL CALIN

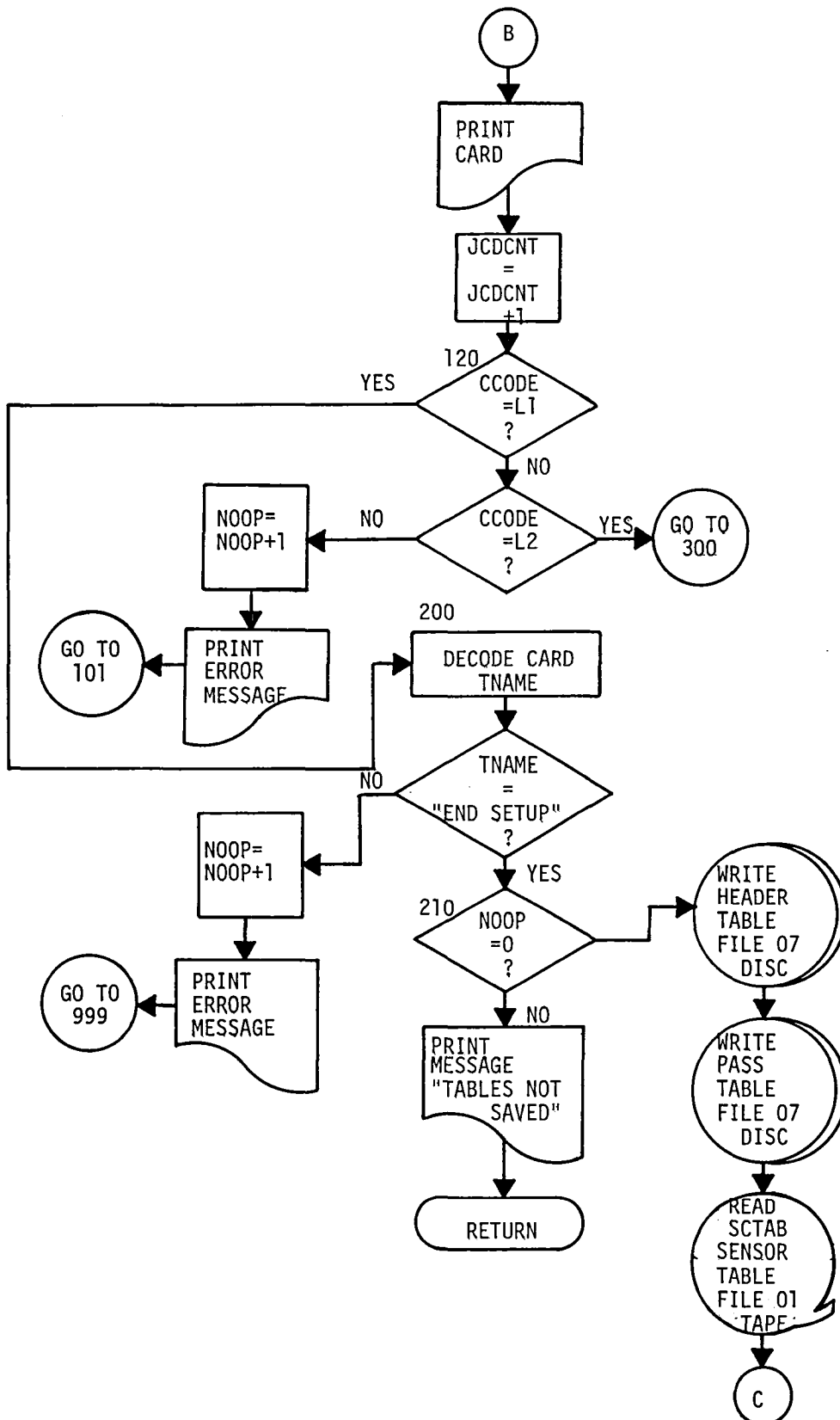
COMMON AREAS

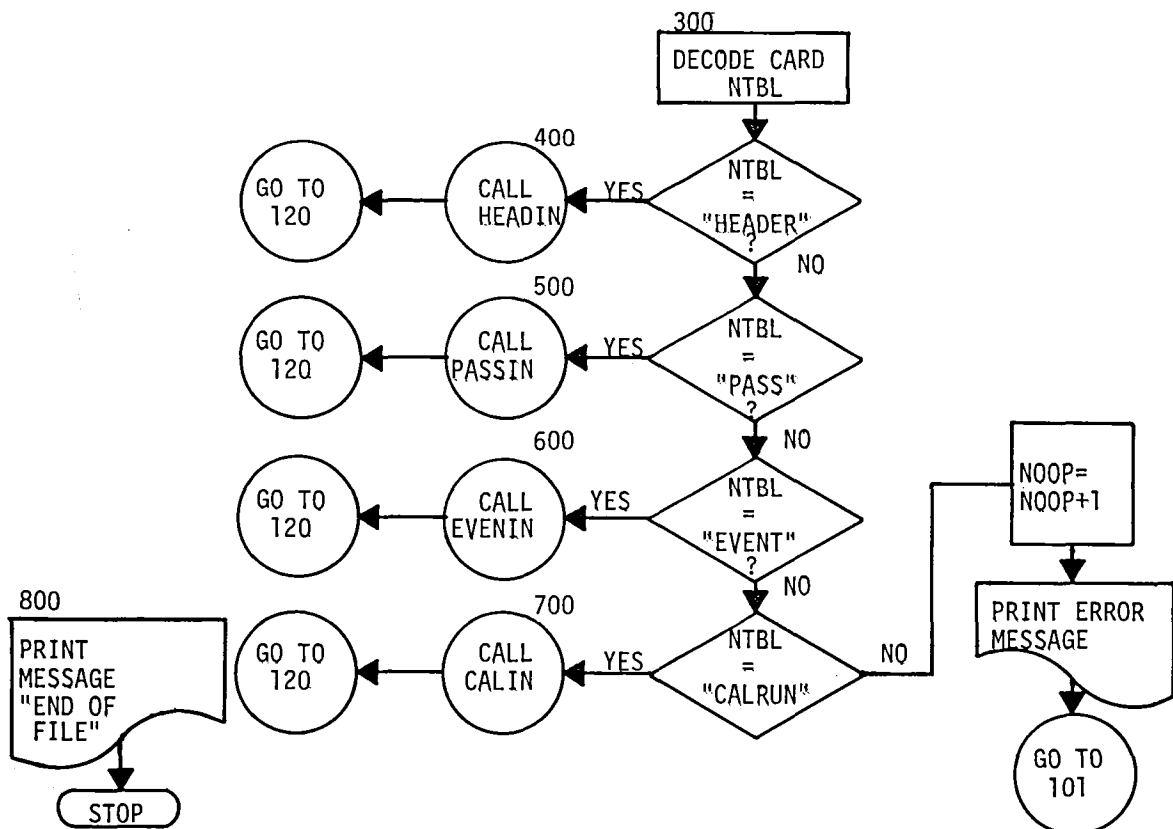
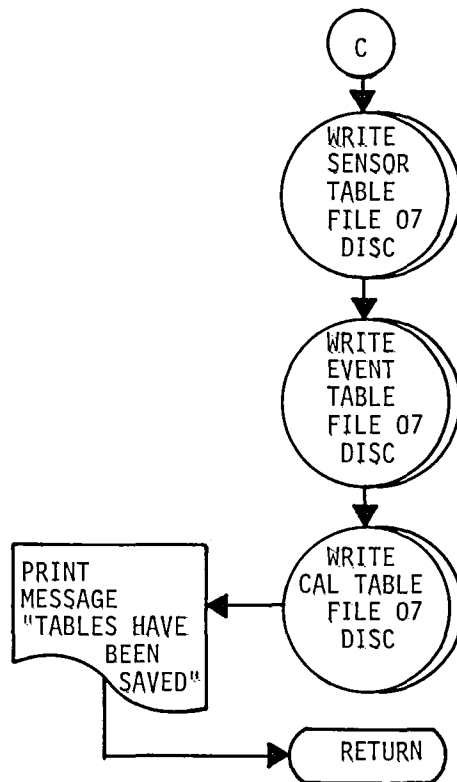
DATIN - CARD,OPT,TNAME,CCODE,NOOP,JCDCNT
TABL1 - THEAD
TABL2 - TPASS
TABL3 - TSENSE
TABL4 - TEVENT
TABL5 - ICALNO

SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS
AND TABLE FILE FORMATS OR FOR ANY OTHER SPECIFIC INFORMATION.









*****SUBROUTINE HEADIN*****

PROGRAM IDENTIFICATION

PROGRAM NAME ---- SUBROUTINE HEADIN
PROGRAM NUMBER ----- 112320
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW-625/635
MEMORY -----
PERIPHERALS ----- CARD READER,PRINTER
LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

TO BUILD OR UPDATE HEADER TABLE

METHOD

CHECK HEADER CARD NUMBER AND DECODE ACCORDINGLY. EDIT
CARD PARAMETERS AND STORE INFORMATION IN HEADER COMMON
AREA TO BE WRITTEN IN SETUP ROUTINE.

INPUT/OUTPUT

CCODE - INPUT AND OUTPUT ARGUMENT CONTAINING CARD CODE
CARD - INPUT AND OUTPUT ARGUMENT CONTAINING CHARACTER INFORMATION
NOOP - INPUT AND OUTPUT ARGUMENT CONTAINING NUMBER OF
 ERRORS COUNTED FROM BAD INPUTS.
JCDCNT - INPUT AND OUTPUT ARGUMENT CONTAINING TOTAL NUMBER OF
 CARDS INPUT
THEAD - HEADER TABLE NAME OR ARRAY
ICDCT - COUNTER FOR NUMBER OF HEADER CARDS READ
IHCDNO - INPUT ARGUMENT CONTAINING HEADER CARD NUMBER
HEADER CARD NO. 1
 MAXPAS - MAXIMUM NUMBER OF PASSES DURING FLIGHT
 MEVENT - MAXIMUM NUMBER OF EVENTS DURING FLIGHT
 MBURST - MAXIMUM NUMBER OF BURSTS FOR 6130 TAPE DURING FLIGHT
 FTIME - BEGINNING TIME OF FLIGHT
HEADER CARD NO. 2
 FLIGHT - FLIGHT INFORMATION
 DATE - DATE OF FLIGHT (DDMMYY)
 TAPENO - TAPE NUMBER OF 6130 TAPE
 AIRCRI + AIRCR2 - AIRCRAFT NAME
 PILOT1 + PILOT2 - PILOT NAME
 COPIL1 + COPIL2 - COPILOT NAME
 OBSER1 + OBSER2 - OBSERVER NAME
HEADER CARD NO. 3
 ETP - ENGINEERING TEST PLAN
 ESGW - ENGINEERING GROSS WEIGHT
 ESCG - ENGINEERING CENTER GRAVITY
 KPR(0.9) - AIRSPEED PROBE RECOVERY FACTOR
 HPC(1215.69) - T-58 ENGINE CHAFF(HP AT 100 PERCENT)
 MRC(203) - MAIN ROTOR (RPM AT 100 PERCENT)
 R(31) - MAIN ROTOR RADIUS(FEET)

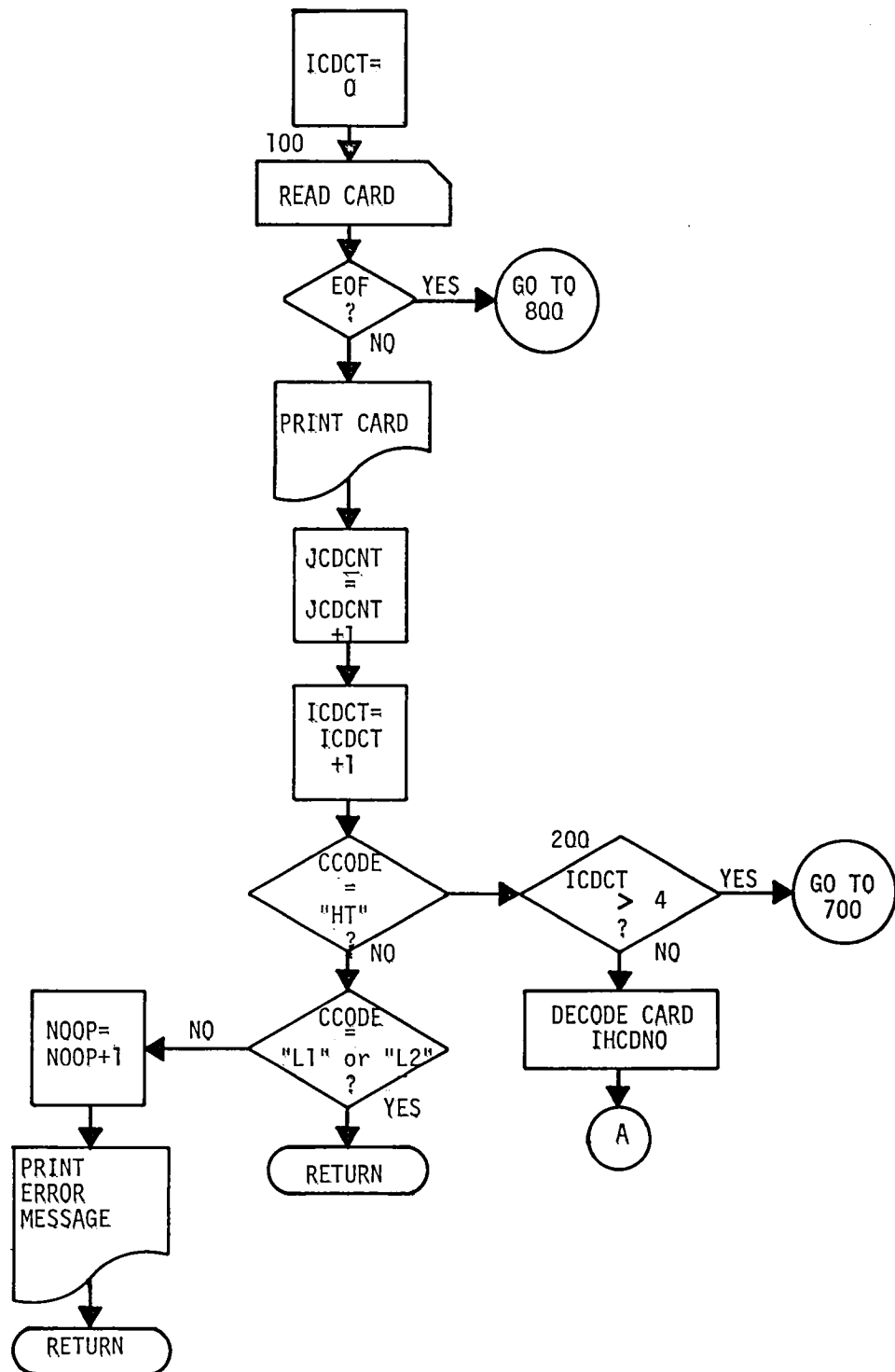
HEADER CARD NO. 4

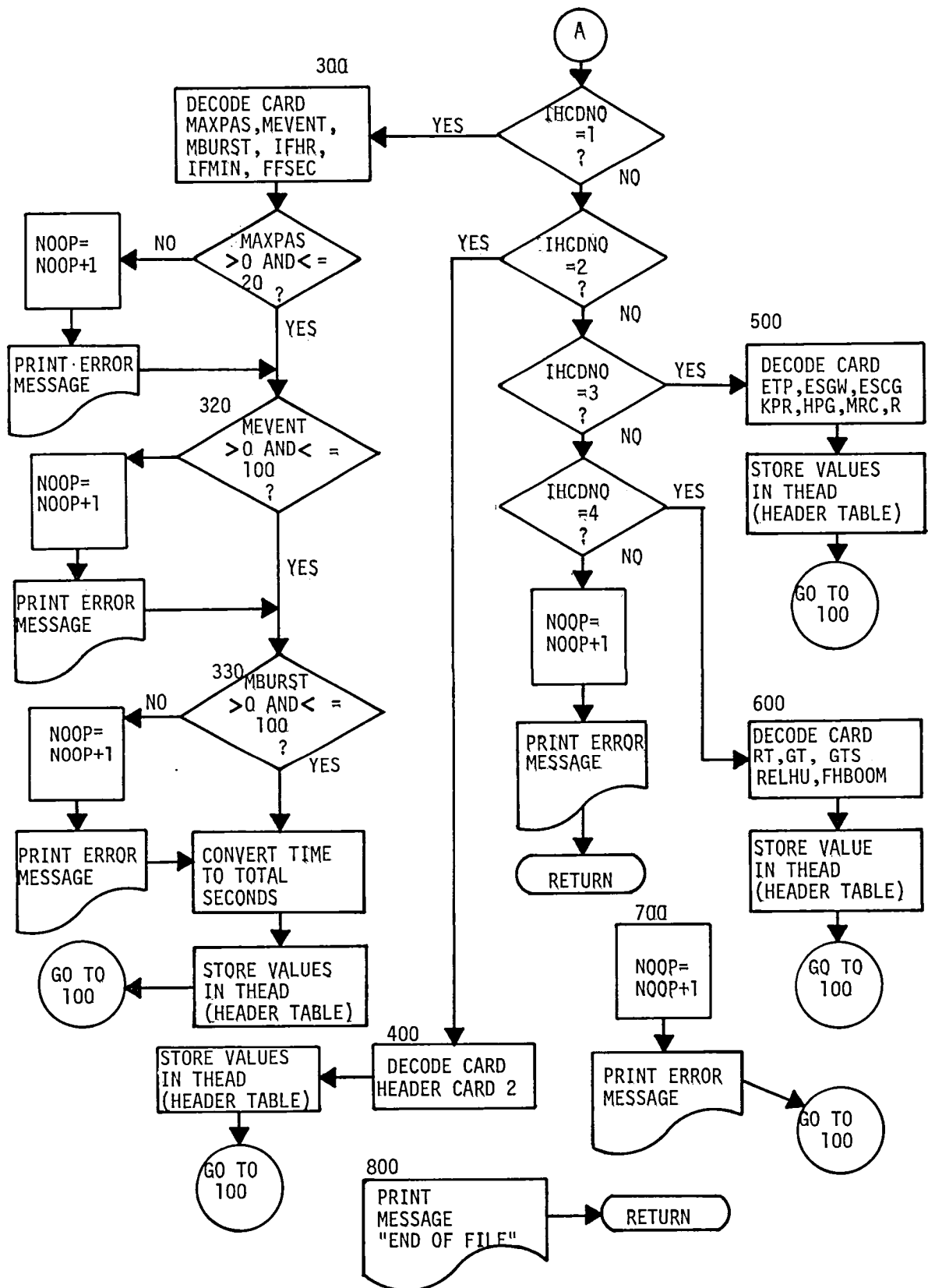
RT(5.3) - TAIL ROTOR RADIUS(FEET)
GT(6.123) - TAIL ROTOR TO MAIN ROTOR(RPM RATIO)
GTS(3030) - TAIL ROTOR SHAFT(RPM)
RELHU(0) - RELATIVE HUMIDITY(UNUSED)
FHBOOM - UNUSED

COMMON AREAS

DATIN - CARD,OPT,TNAME,CCODE,NOOP,JCDCNT
TABL1 - THEAD

SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS
AND TABLE FILE FORMATS OR FOR ANY OTHER SPECIFIC INFORMATION.





*****SUBROUTINE PASSIN*****

PROGRAM IDENTIFICATION

PROGRAM NAME ---- SUBROUTINE PASSIN
PROGRAM NUMBER ----- 112320
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW-625/635
MEMORY -----
PERIPHERALS ----- CARD READER,PRINTER,TAPE
LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

TO BUILD OR UPDATE PASS TABLES AND SENSOR TABLES AND
TO SEARCH TABLES FOR DUPLICATION OF SENSOR NAME,
PREPROCESSING CODE AND SAMPLE RATE

METHOD

DECODE INFORMATION IN PASS CARD AND STORE IN PASS TABLES.
CHECK FOR SENSOR CARDS AND DECODE. EDIT CARD PARAMETERS
FOR CORRECT INFORMATION. STORE VALUES IN SENSOR TABLES.
WRITE SCRATCH FILE 01. READ SCRATCH FILE AND SEARCH
FOR DUPLICATION OF SENSOR NAME, PREPROCESSING CODE AND
SAMPLE RATE.

INPUT/OUTPUT

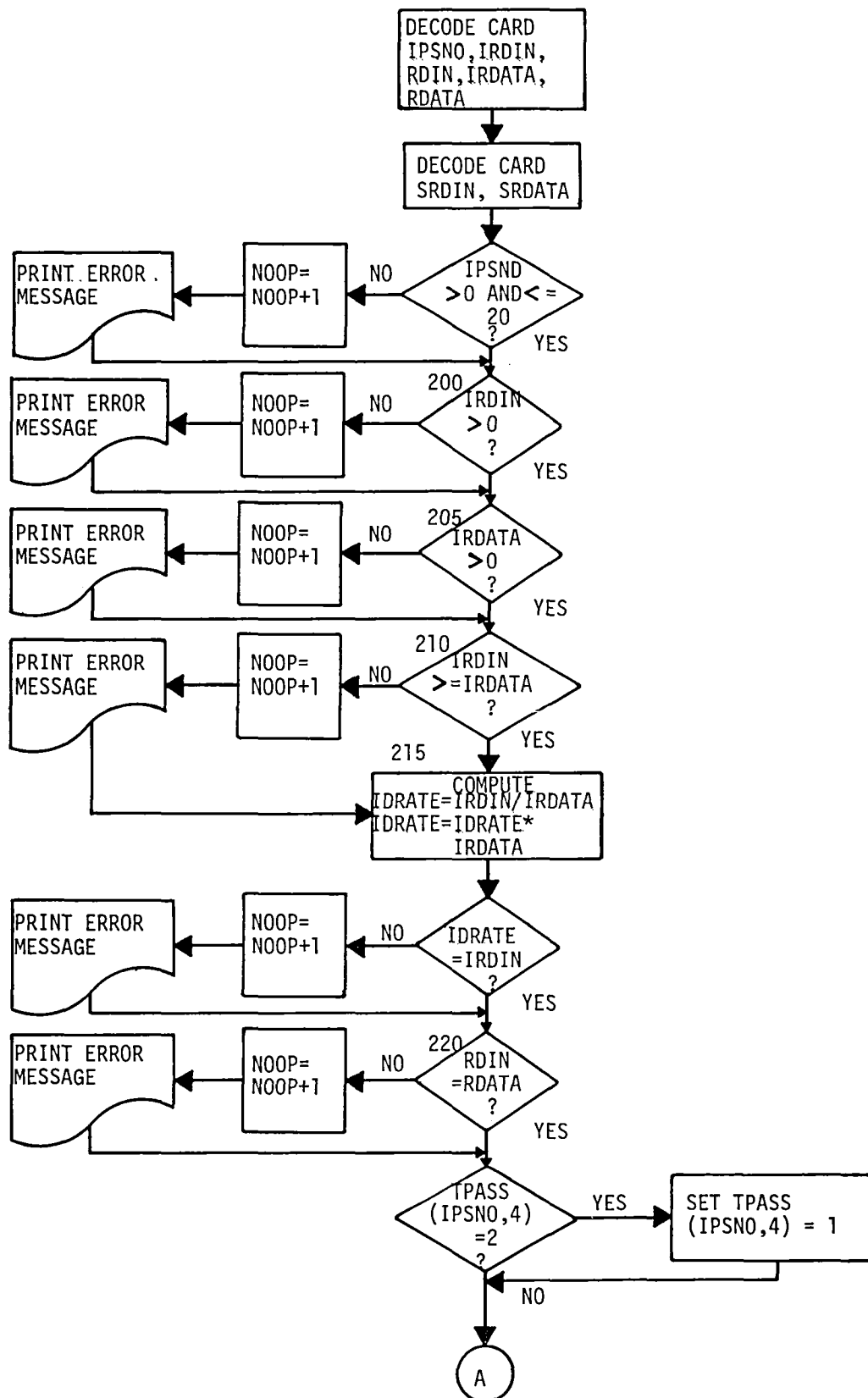
CCODE - INPUT AND OUTPUT ARGUMENT CONTAINING CARD CODE
CARD - INPUT AND OUTPUT ARGUMENT CONTAINING CHARACTER INFORMATION
NOOP - INPUT AND OUTPUT ARGUMENT CONTAINING NUMBER OF
ERRORS COUNTED FROM BAD INPUTS.
JCDCNT - INPUT AND OUTPUT ARGUMENT CONTAINING TOTAL NUMBER OF
CARDS INPUT
IPSNO - PASS NUMBER
IRDIN - INTEGRAL VALUE OF 6130 TAPE SAMPLE RATE
ROIN - 6130 SAMPLE RATE TYPE(X,M,T ,)
IRDATA - INTEGRAL VALUE OF DATA FILE SAMPLE RATE
RDATA - DATA FILE SAMPLE RATE TYPE(X,M,T,)
ISTATC - STATUS CODE FOR DATA AVAILABILITY
0 = NOT AVAILABLE
1 = AVAILABLE
2 = AB TASK RUN
3 = DERIVED PARAMETER PASS
MAXPAR - ACTUAL NUMBER OF PARAMETERS FOR PASS
TPASS - PASS TABLE ARRAY
SRDIN - COMBINED INTEGRAL VALUE AND TYPE FOR SAMPLE RATE
SRDATA - COMBINED INTEGRAL VALUE AND TYPE FOR SAMPLE RATE
SCTAB - SENSOR TABLE ARRAY FOR SCRATCH FILE
TSENSE - SENSOR TABLE ARRAY
IDRATE - INCREMENT VALUE OF 6130 SAMPLE RATE
SNC1 - FIRST CHARACTER OF SENSOR NAME

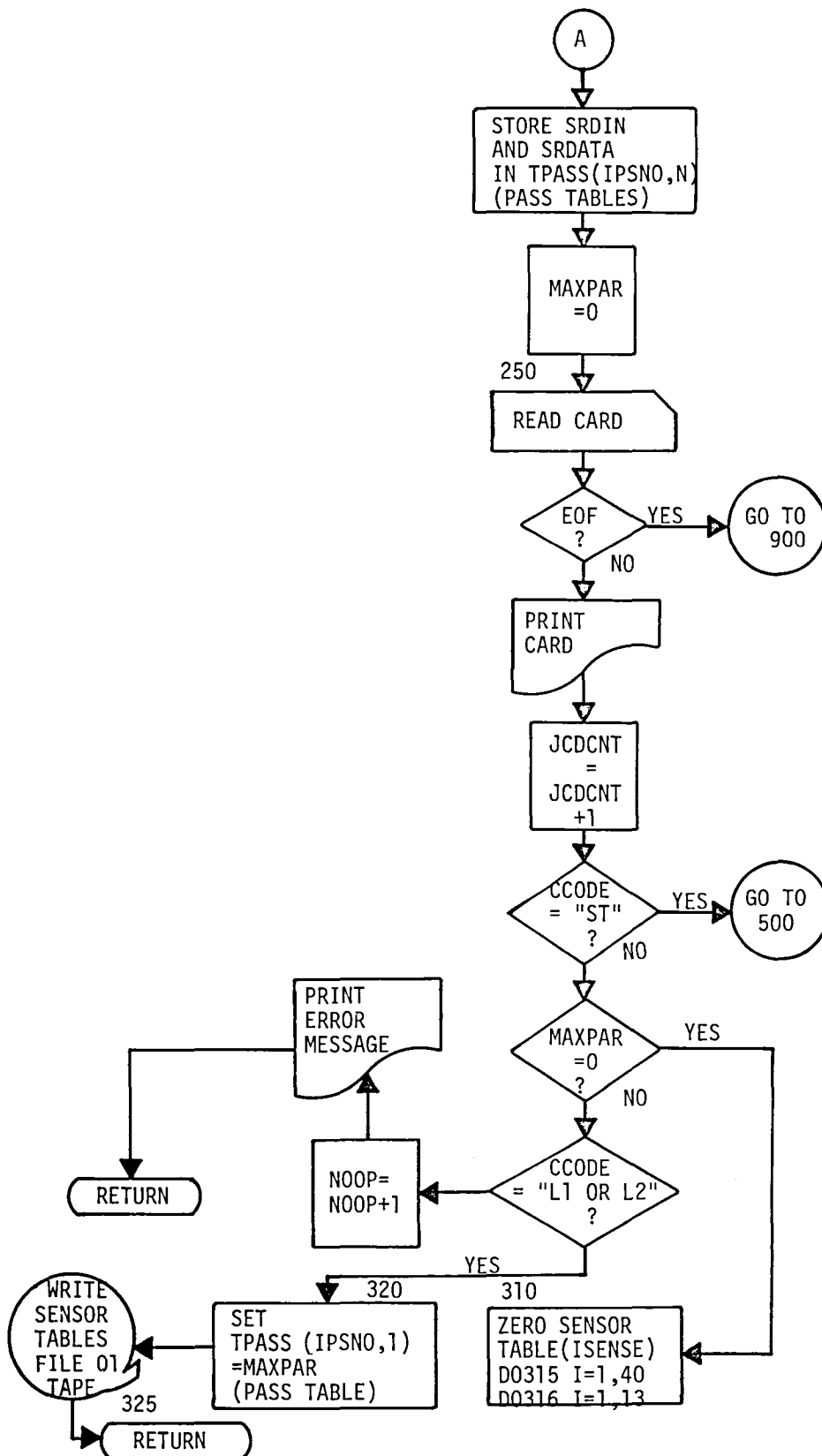
ST CARD
SNAM1 + SNAM2 - SENSOR NAME
PPC - PREPROCESSING CODE
 V = VIBRATORY
 S = STEADY
 D = DIRECT
IPARIN - 6130 TAPE PARAMETER LOCATION
IPARDF - DATA FILE PARAMETER LOCATION
ITRACK - 6130 TAPE TRACK NUMBER
ICHAN - 6130 TAPE CHANNEL NUMBER
CALTYP - CALIBRATION TYPE(Z,X,P,1,2)
EUCV1 - FACTORY CAL "A" TERM
EUCV2 - FACTORY CAL "B" TERM
FILNO - NOT USED
CONLEV - CONCERN LEVEL VALUE

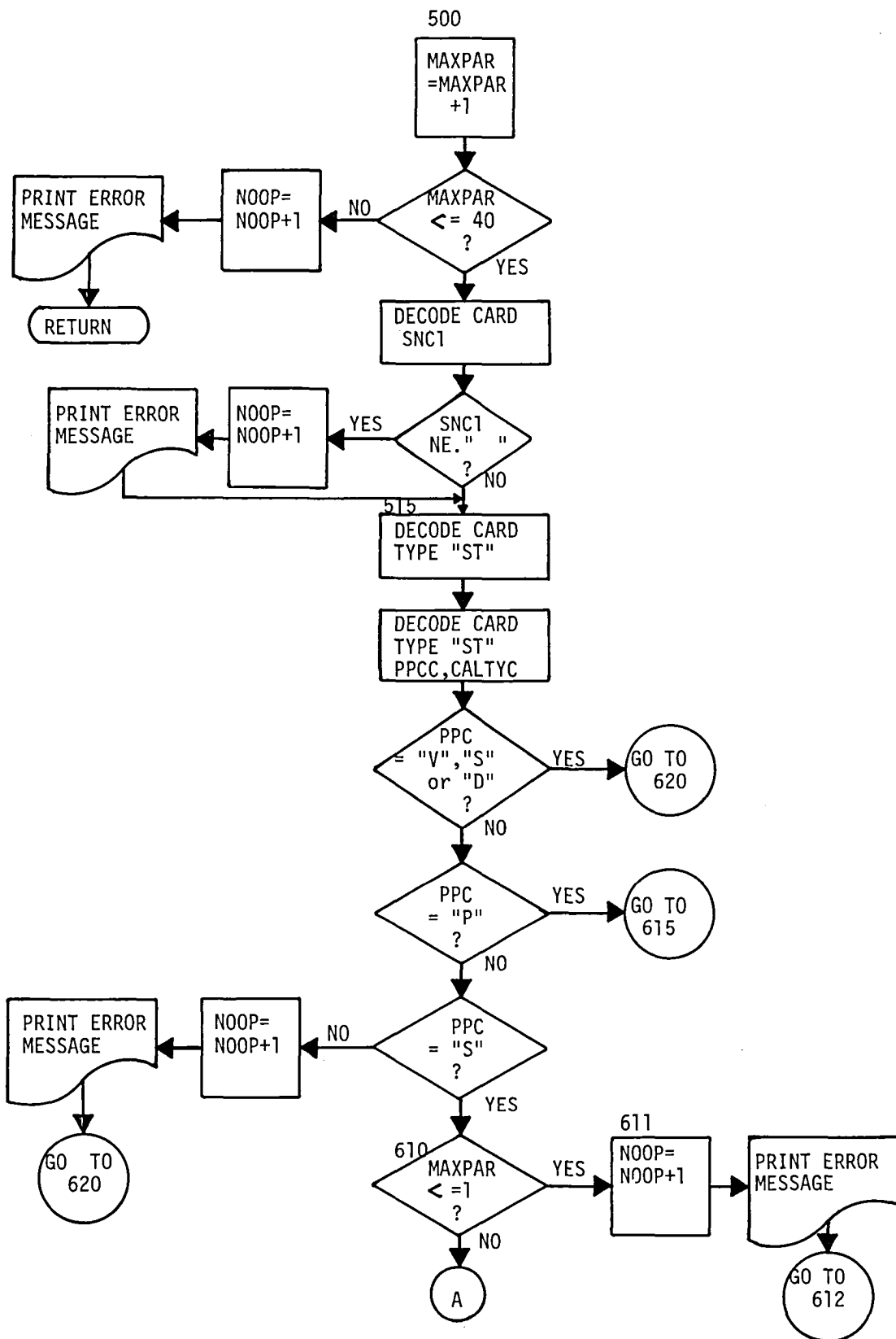
COMMON AREAS

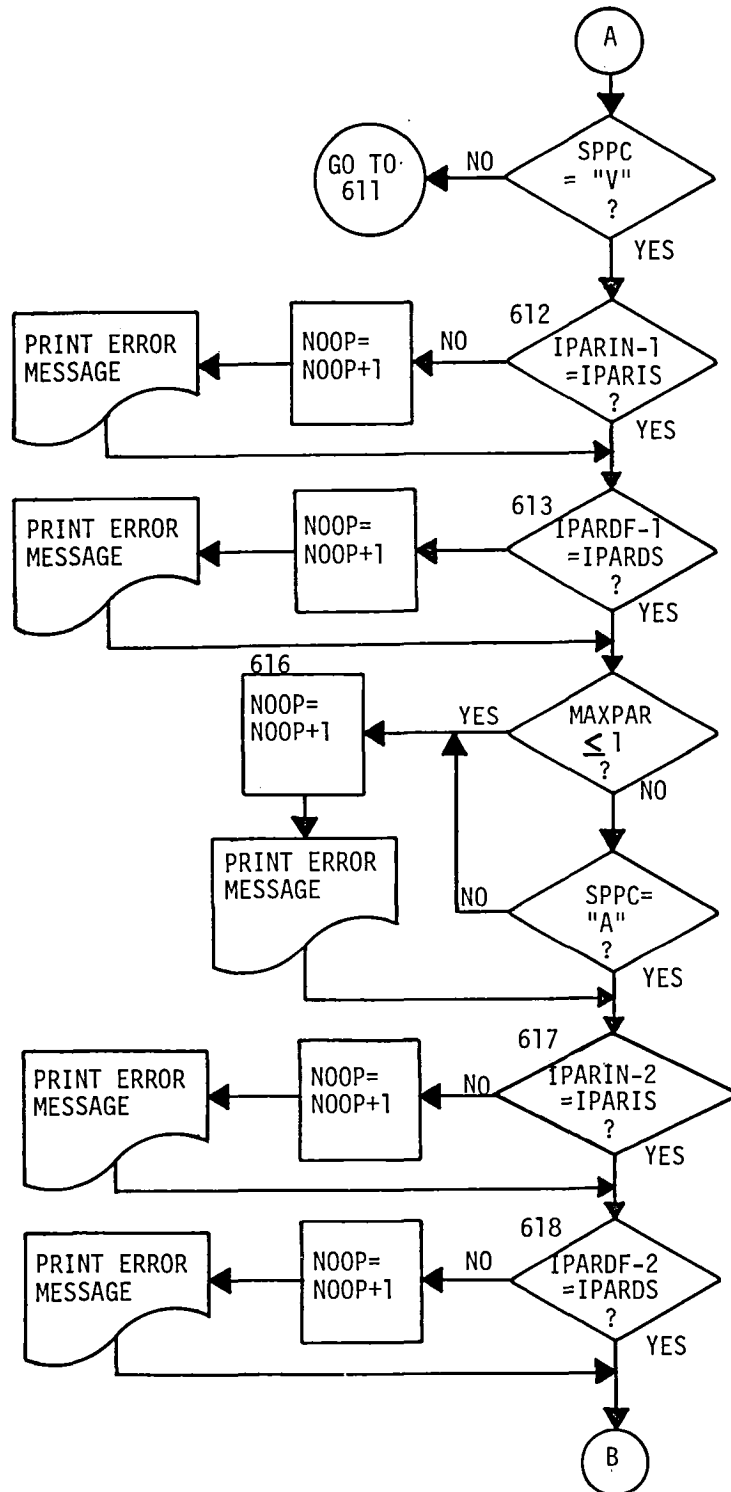
DATIN - CARD,OPT,TNAME,CCODE,NOOP,JCDCNT
TABL2 - TPASS
TABL3 - TSENSE

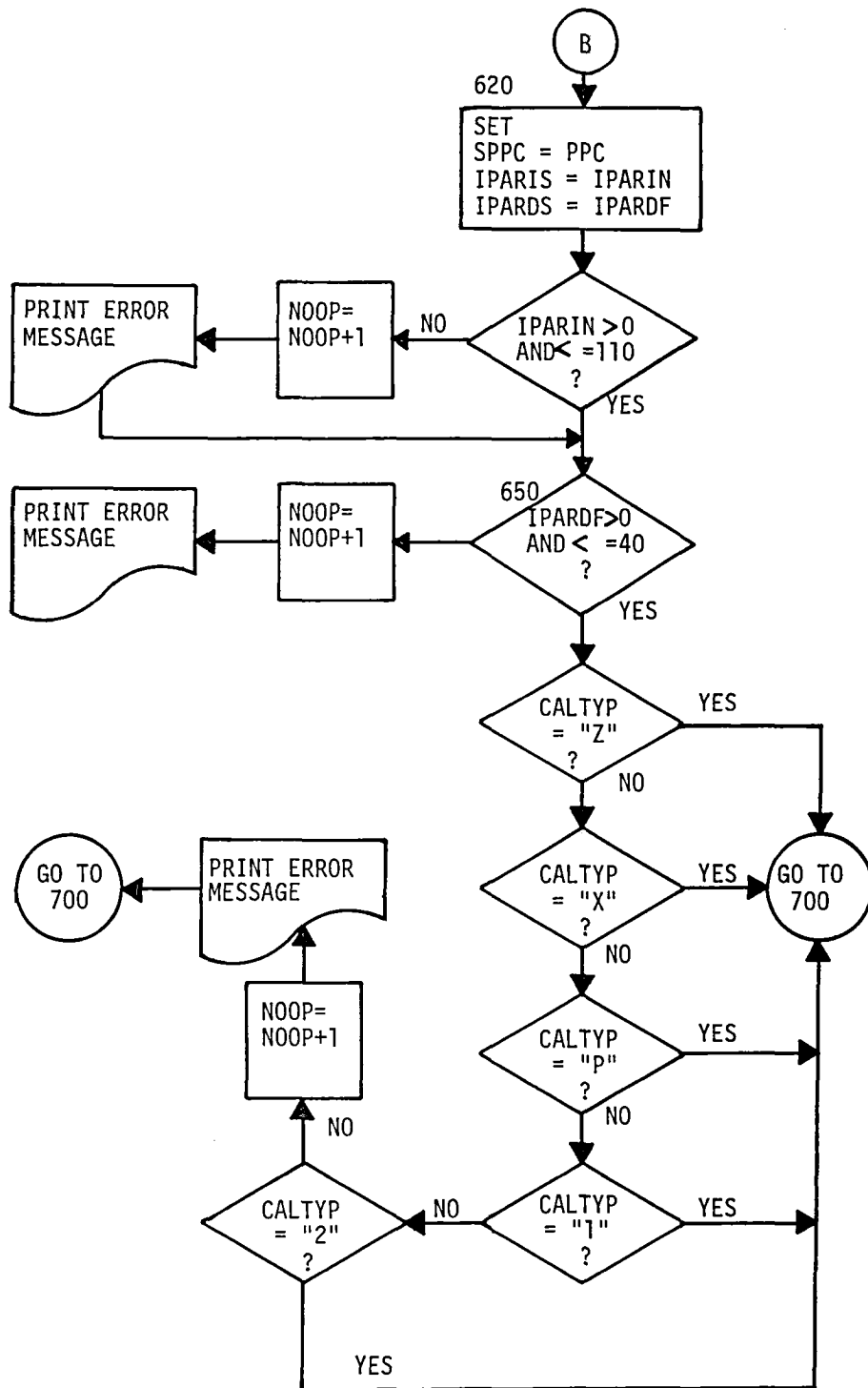
SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS
AND TABLE FILE FORMATS OR FOR ANY OTHER SPECIFIC INFORMATION.













*****SUBROUTINE CALIN*****

PROGRAM IDENTIFICATION

PROGRAM NAME ---- SUBROUTINE CALIN
PROGRAM NUMBER ----- 112320
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW-625/635
MEMORY -----
PERIPHERALS ----- CARD READER,PRINTER,TAPE
LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

TO BUILD OR UPDATE CALIBRATION TABLES. TO SCAN SENSOR
TABLES FOR MATCH OF SENSOR NAMES.

METHOD

CHECK CARD FOR CALIBRATION TYPE, DECODE CARD AND EDIT
PARAMETERS. SCAN SENSOR TABLES FOR MATCH OF SENSOR NAMES
SET CAL POINTER TO CORRECT VALUE. STORE CALIBRATION TABLE
IN ARRAY TO BE WRITTEN IN SETUP ROUTINE. WRITE CORRECTED
SENSOR TABLES ON SCRATCH FILE 01.

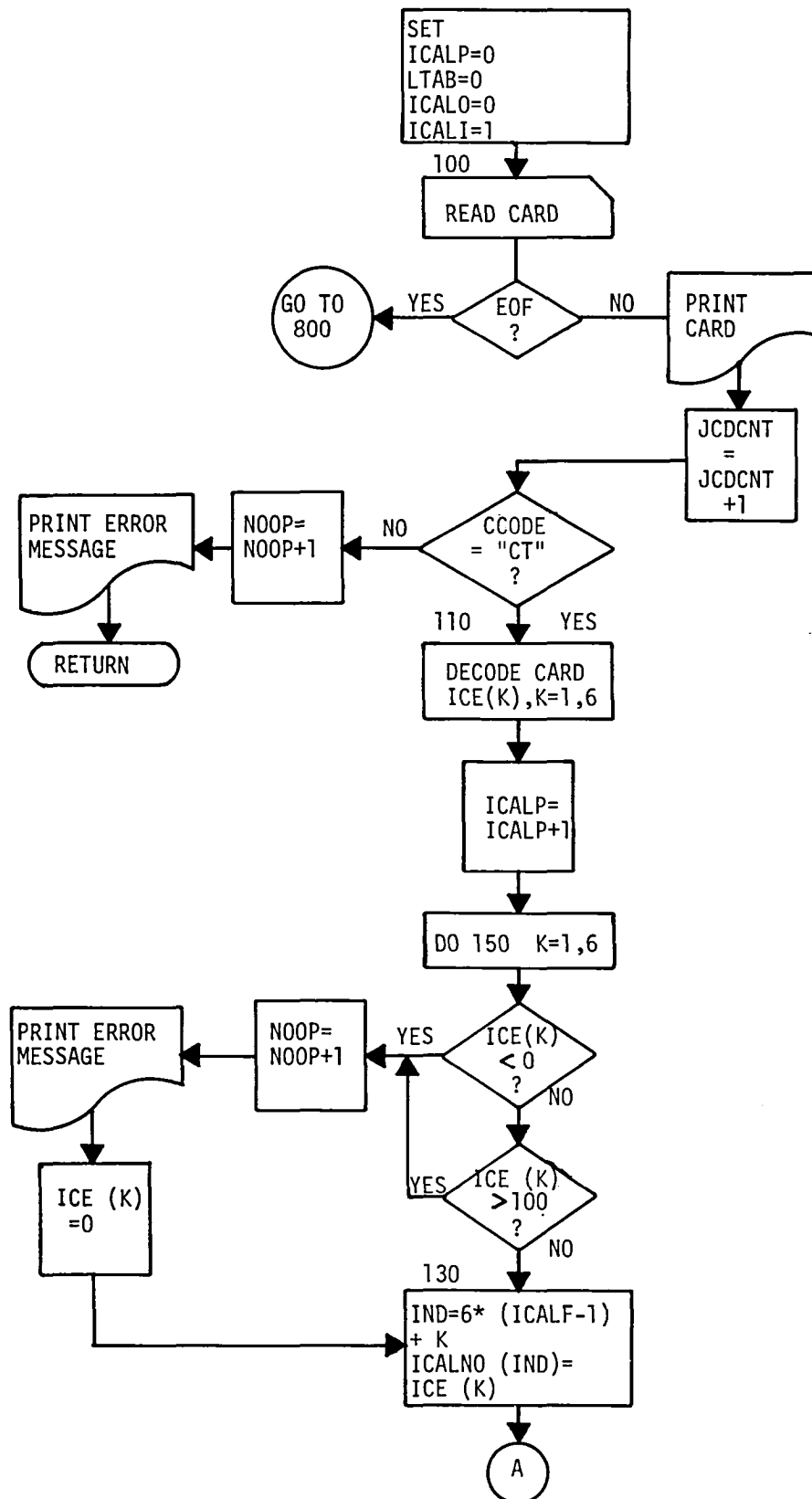
INPUT/OUTPUT

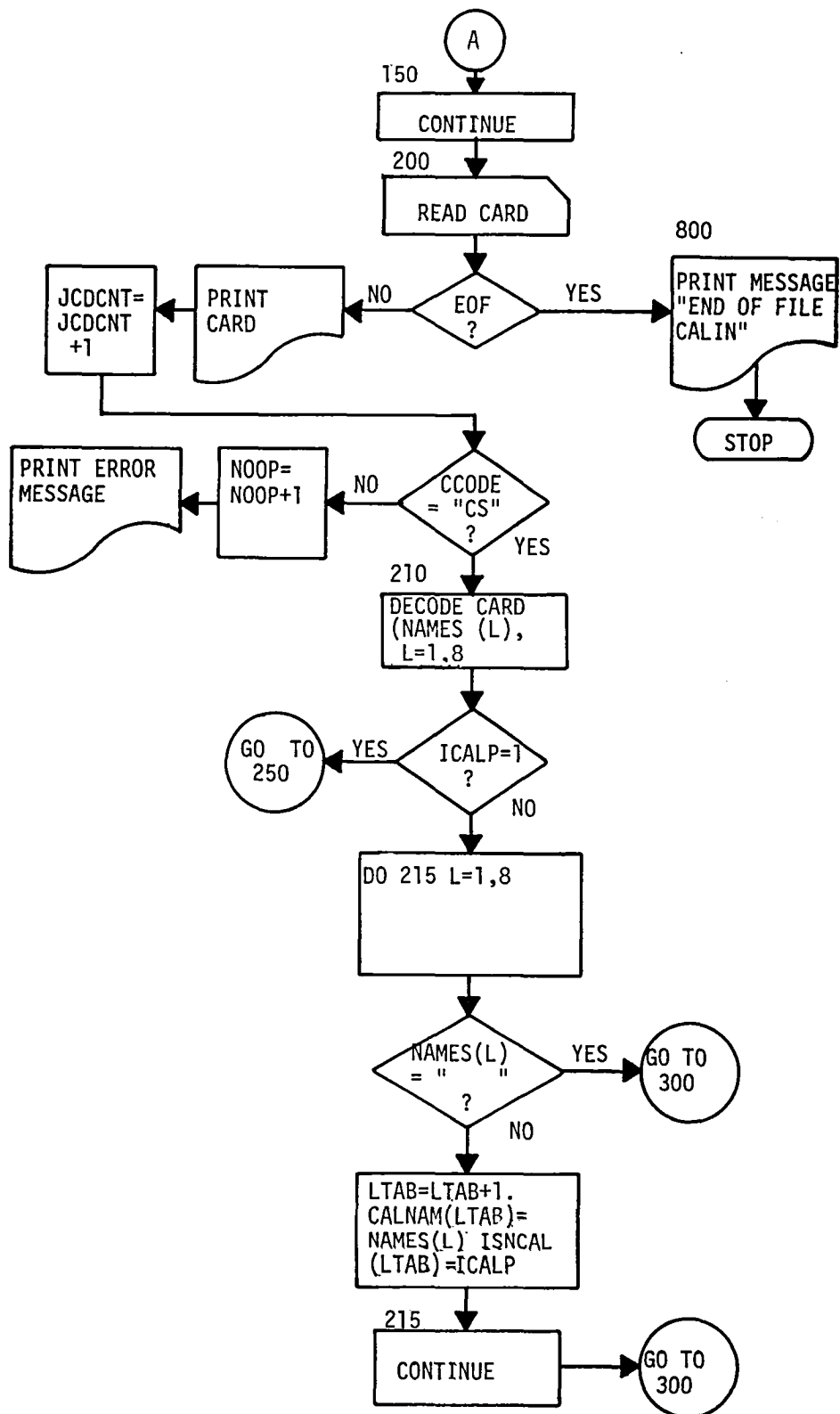
CCODE - INPUT AND OUTPUT ARGUMENT CONTAINING CARD CODE
CARD - INPUT AND OUTPUT ARGUMENT CONTAINING CHARACTER INFORMATION
NOOP - INPUT AND OUTPUT ARGUMENT CONTAINING NUMBER OF
ERRORS COUNTED FROM BAD INPUTS.
JCDCNT - INPUT AND OUTPUT ARGUMENT CONTAINING TOTAL NUMBER OF
CARDS INPUT
LTA B - COUNTER FOR INDEXING
ICALP - COUNTER FOR INDEXING
ICAL0 - CALIBRATION POINTER 0
ICAL1 - CALIBRATION POINTER 1
ICALNO - CALIBRATION TABLE ARRAY
NAMES - SENSOR NAME
ICE - PRE OR POST CAL EVENT NUMBER
SENTAB - SENSOR TABLE ARRAY (SCRATCH FILE 01)
CALTC - CALIBRATION TYPE

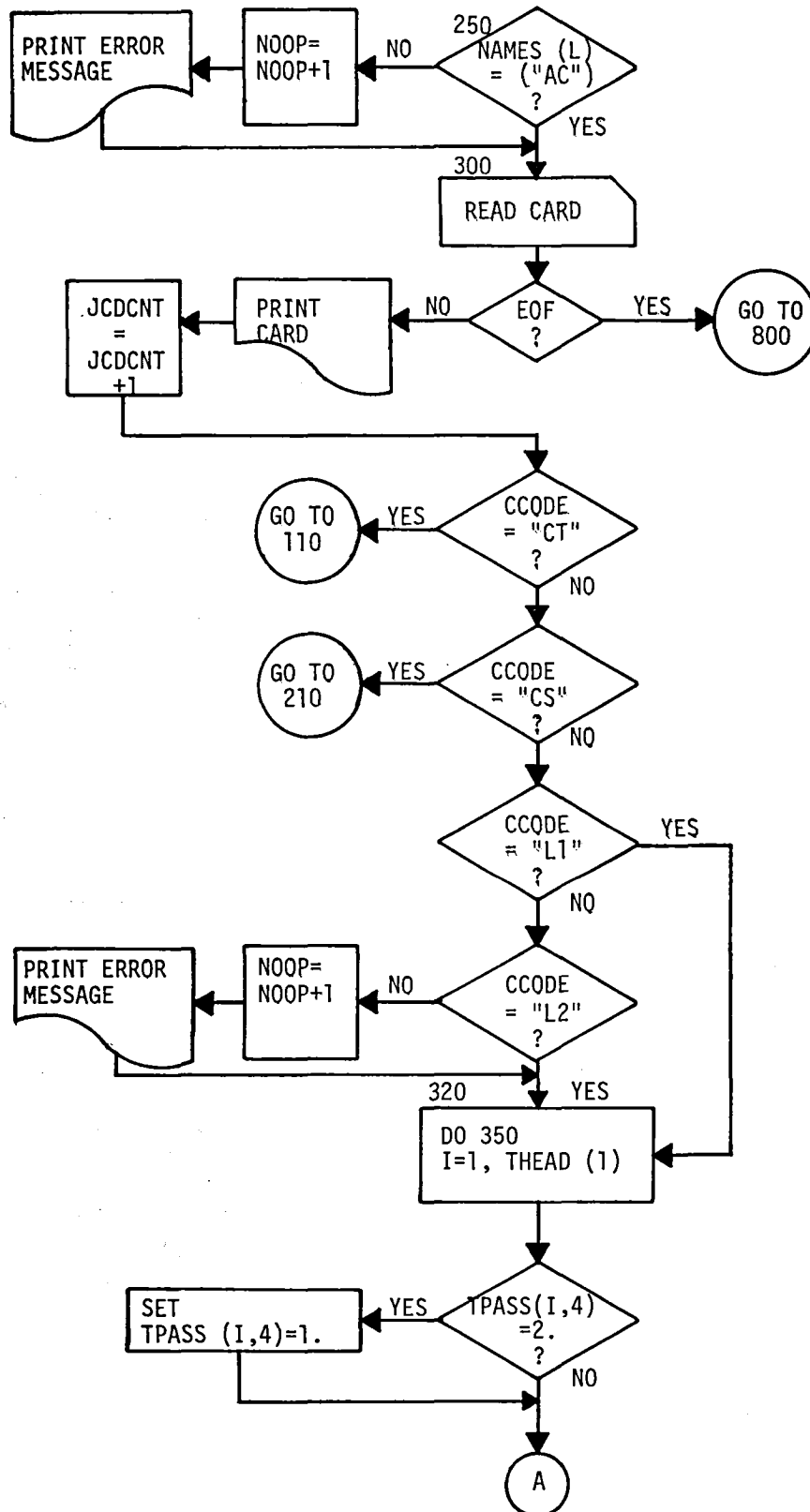
COMMON AREAS

DATIN - CARD,OPT,TNAME,CCODE,NOOP,JCDCNT
TABL1 - THEAD
TABL2 - TPASS
TABL5 - ICA LNO

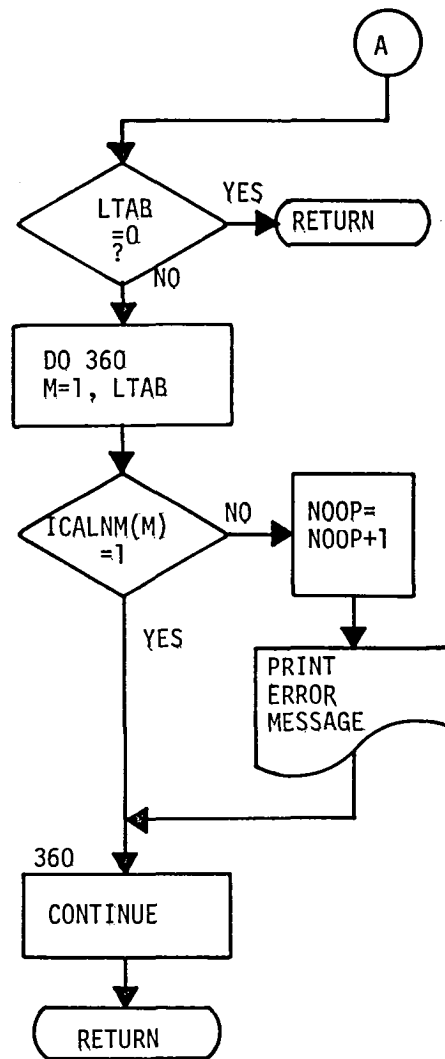
SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS
AND TABLE FILE FORMATS OR FOR ANY OTHER SPECIFIC INFORMATION.











*****SUBROUTINE EVENIN*****

PROGRAM IDENTIFICATION

PROGRAM NAME ---- SUBROUTINE EVENIN
PROGRAM NUMBER ----- 112320
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW-625/635
MEMORY -----
PERIPHERALS ----- CARD READER,PRINTER
LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

TO BUILD OR UPDATE EVENT TABLES

METHOD

READ EVENT CARDS, DECODE AND EDIT PARAMETERS FOR ERRORS.
STORE VALUES IN EVENT TABLE TO BE WRITTEN IN SETUP ROUTINE.

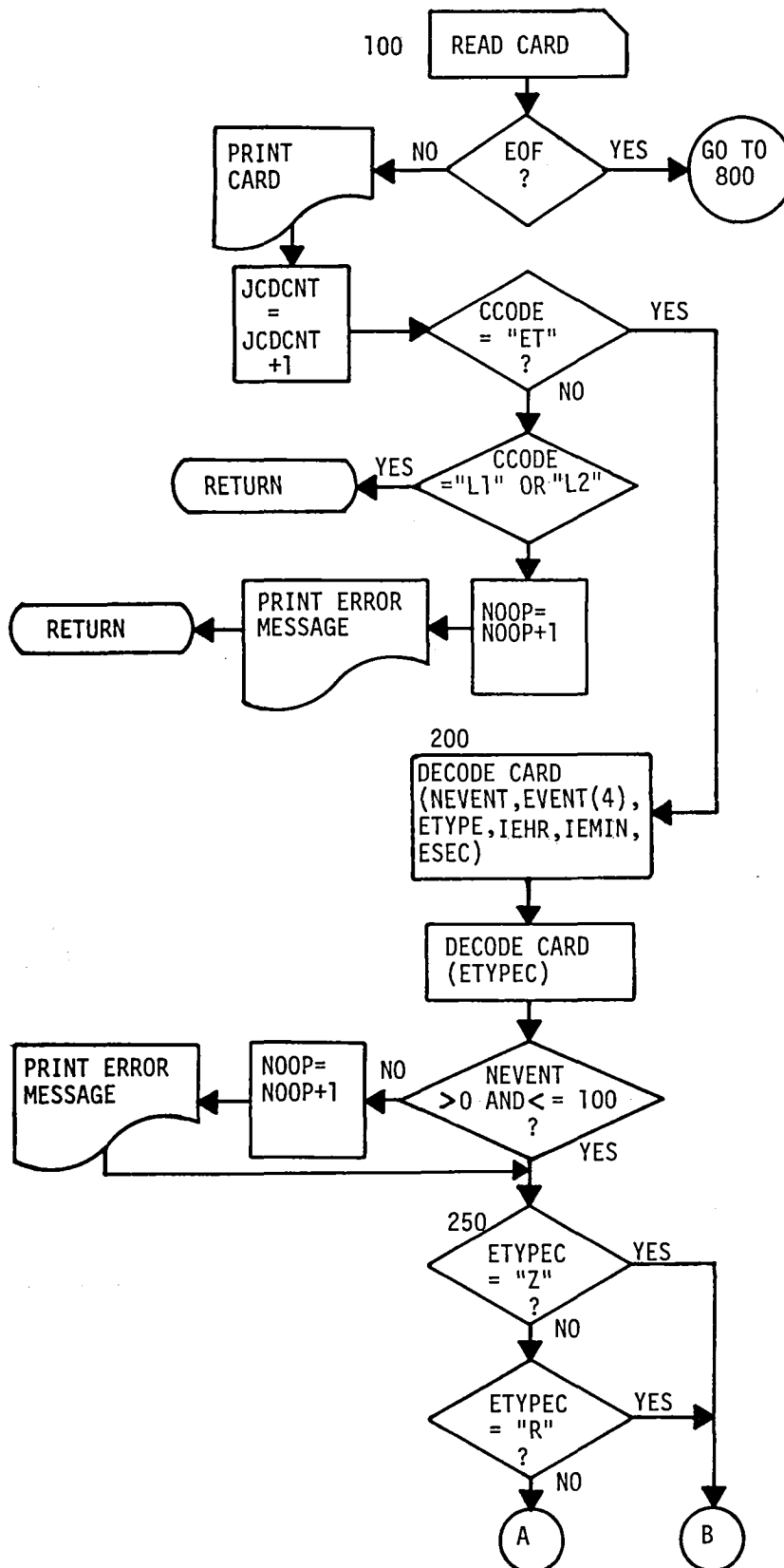
INPUT/OUTPUT

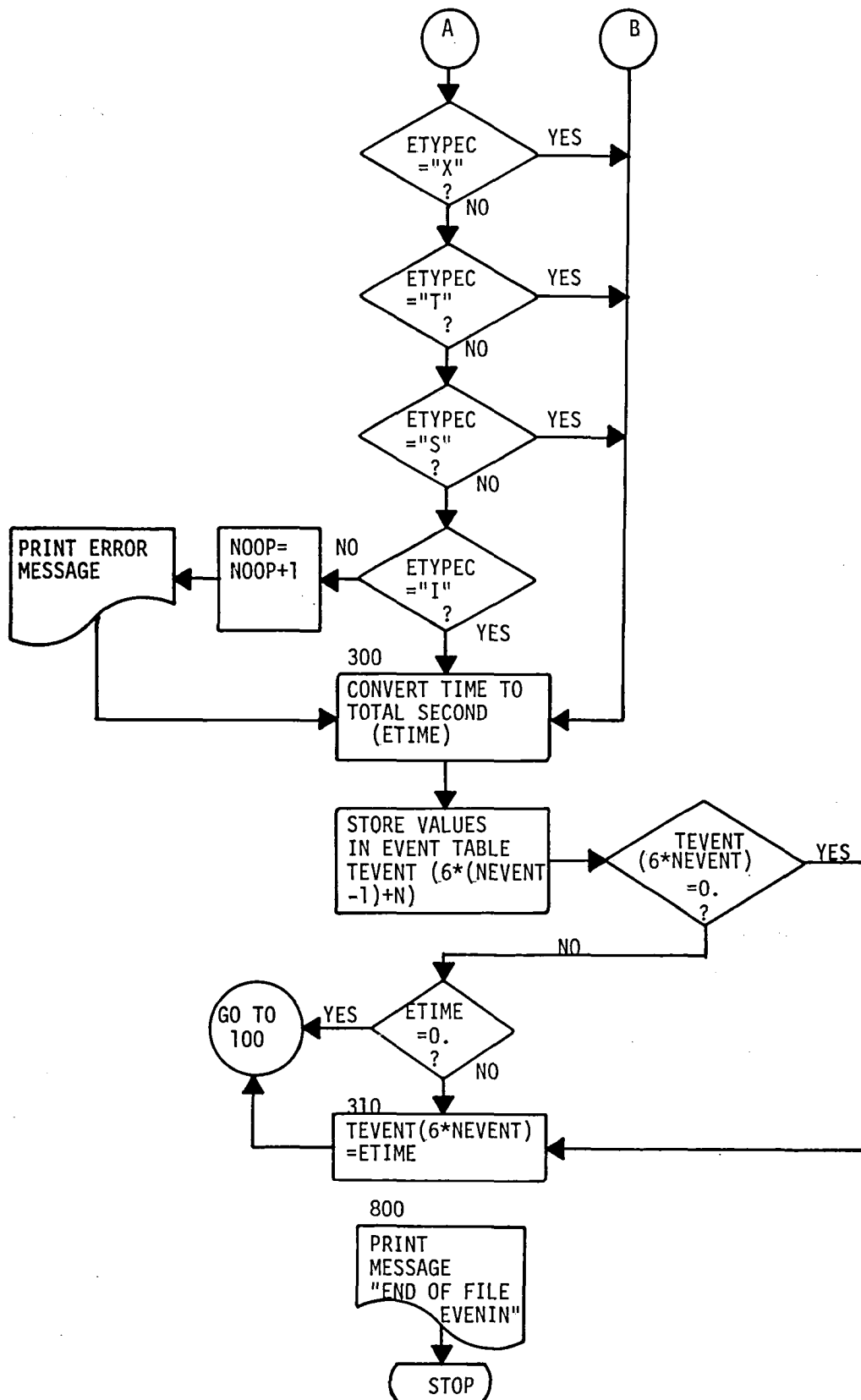
CCODE - INPUT AND OUTPUT ARGUMENT CONTAINING CARD CODE
CARD - INPUT AND OUTPUT ARGUMENT CONTAINING CHARACTER INFORMATION
NOOP - INPUT AND OUTPUT ARGUMENT CONTAINING NUMBER OF
 ERRORS COUNTED FROM BAD INPUTS.
JCDCNT - INPUT AND OUTPUT ARGUMENT CONTAINING TOTAL NUMBER OF
 CARDS INPUT
ET CARD
 NEVENT - EVENT NUMBER
 EVENT1 + EVENT2 + EVENT3 + EVENT4 - EVENT NAME
 ETYPE - EVENT TYPE (Z,R,X,T,S,I)
 ETIME - TIME OF EVENT
TEVENT - EVENT TABLE ARRAY

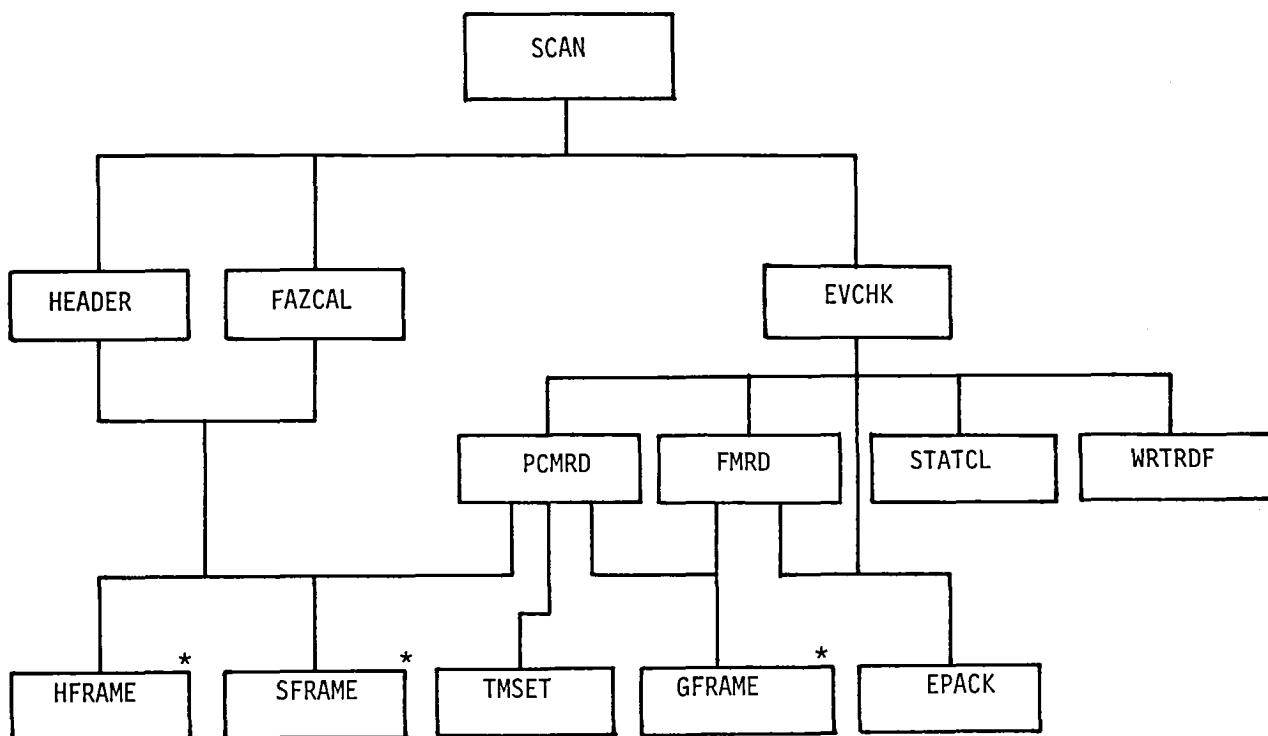
COMMON AREAS

DATIN - CARD,OPT,TNAME,CCODE,NOOP,JCDCNT
TABL4 - TEVENT

SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS
AND TABLE FILE FORMATS OR FOR ANY OTHER SPECIFIC INFORMATION.







*Program Modules SFRAME, HFRAME, GFRAME documentation in NASA, WFC Program Library

HIERARCHY CHART for SCAN PROGRAM

*****SCAN - PROGRAM NUMBER 1.1.2326

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN IV

*****MACHINE - HW 625/635

*****PROGRAM AUTHOR - JEANETTE WESSELLS

*****PURPOSE -

THIS IS THE MAIN PROGRAM WHICH READS PCM AND FM DIGITIZED INPUT DATA IN TELEVENT FORMAT, COMPUTES BASIC STATISTICS, AND STORES DATA AND STATISTICS IN RANDOM FILES ACCEPTABLE TO OTHER EASE PROGRAMS.

*****METHOD -

THIS PROGRAM ACCEPTS EITHER PCM OR FM TAPES CONTAINING DATA RECORDED BY RSRA AIRCRAFT FLIGHT.

THE DIGITIZATION OF PCM DATA TAPE IS BY STANDARD PROCEDURES. FM DATA IS DIGITIZED BY USE OF A PEAK - STRESS CONVERTER WHICH TAKES A CHANNEL OF DATA AND, DEPENDING ON THE SPECIFIED SAMPLING RATE, OUTPUTS A CHANNEL OF PEAK VALUES AND A CHANNEL OF VALLEY VALUES WITHIN THAT SAMPLING RATE. THESE TWO CHANNELS ARE COMBINED TO GIVE VIBRATORY AND STEADY COMPONENTS OF THE ORIGINAL DATA. THE BASIC STATISTICS ARE COMPUTED FOR THESE COMPONENTS.

PCM DATA IS GROUPED ACCORDING TO PASSES. A PASS IS A SET OF DATA WITH NO MORE THAN 40 CHANNELS, EACH CHANNEL REPRESENTING A SPECIFIC PARAMETER, COVERING THE ENTIRE FLIGHT FOR THESE CHANNELS AND SAMPLED AT THE SAME RATE.

A PASS IS FURTHER DIVIDED INTO BURSTS REPRESENTING DATA FOR A PARTICULAR FLIGHT MANEUVER. DATA BURSTS CAN BE DISTINGUISHED BY EITHER RUN TONE SIGNAL OR A GIVEN TIME INTERVAL. NORMAL MODE IS BY RUN TONE. CARD INPUT IS REQUIRED WITH BURST NUMBER AND START AND STOP TIMES FOR TIME INTERVAL. STATISTICS ARE COMPUTED AND STORED FOR EACH CHANNEL OF DATA BY THESE DATA BURSTS.

EACH PASS AND FLIGHT MANEUVER IS DEFINED IN THE SETUP ROUTINE. GIVEN THE PASS NUMBER, FILE NUMBER, AND FILE CODE DESIGNATOR, SETUP WILL SUPPLY NECESSARY PARAMETER CONFIGURATION OF THE INPUT DATA.

THE ENTIRE PASS OF DATA IS THEN PROCESSED THROUGH THIS ROUTINE.

*****SYSTEMS INPUT FILES -

FILE 03 = INPUT TAPE

FILE 04 = INPUT TAPE, IF MULTI-REEL IS NECESSARY

FILE 05 = CARD READER

FILE 07 = TABLE FILE

*****SYSTEMS OUTPUT FILES -

FILE 06 = PRINTER

FILE 07 = TABLE FILE

FILE 09 = STATISTICS FILE

FILES 11,12,...31 = PASS DATA FILES

*****INPUT -

CARD -78 CHARACTER CARD IMAGE

CCODE -2 CHARACTER CARD CODE FOUND IN FIRST 2 COLUMNS OF
 -INPUT CARD -- IDENTIFIES INPUT DATA WITHIN "CARD"

ETIME -BEGINNING TIME (SEC) OF MANEUVER UP TO 100 ENTRIES
 -ARRAY IS EXTRACTED FROM EVENT TABLE

NPASS -PASS NUMBER BEING PROCESSED (CARD INPUT)

IFC -FILE CODE OF INPUT TAPE (CARD INPUT)

ITCD -CODE DESIGNATING WHICH TIME WORD TO USE (CARD INPUT)
 --0,AIRBOURNE TIME
 --1,GROUND STATION TIME

IFILNO -LOGICAL FILE WHERE PASS = NPASS TO BE FOUND ON
 -INPUT TAPE (CARD INPUT)

MBURST -MAXIMUM NUMBER OF DATA BURSTS FOUND ON INPUT TAPE
 -FOR THIS PASS (CARD INPUT)

JPARIN -WORD NUMBER OF SENSOR DATA WITHIN THE DATA FRAME
 -MAXIMUM 40 WORDS (FROM SENSOR TABLE)

JPARDF -WORD NUMBER OF SENSOR DATA WITHIN THE DATA FILE
 -FRAME (FROM SENSOR TABLE)

PPC -PRE-PROCESSING CODE OF SENSOR (FROM SENSOR TABLE)

LASTFL -COUNTER FOR CURRENT LOGICAL FILE BEING PROCESSED

TABREC -600-WORD ARRAY OF TABLE DATA READ FROM FILE 07

IDATA -640-WORD RECORD ARRAY FOR DATA IMAGE OF PACKED
 -DATA ON DATA FILE

 NEVENT -MANEUVER NUMBER

 IBURST -BURST NUMBER (CARD INPUT)

 ICOND -CODE TO DESIGNATE HOW "IBURST" IS TO BE HANDLED
 -(CARD INPUT)
 --0,NORMAL CONDITION - BURST INTERVAL DETERMINED
 - BY RUN TONE
 --1,BURST INTERVAL DETERMINED BY RUN TONE IS NOT
 - TO BE PROCESSED
 --2,BURST INTERVAL IS DETERMINED BY TIME
 - NOTE< TIME VALUES TO AND TF ARE REQUIRED
 --3,NO DATA BURST EXISTS ON INPUT TAPE FOR A VALID
 - MANEUVER -- MUST WRITE A RECORD OF NULLS FOR
 - STATISTICS AND INCREMENT NEVENT

 TO -BEGINNING TIME OF DATA BURST (SEC) (CARD INPUT)

 TF -ENDING TIME OF DATA BURST (SEC) (CARD INPUT)

 KADDR -CURRENT ADDRESS OF DATA FILE RECORD FOR NPASS

 IRETST -TAPE STATUS AS RETURNED FROM GFRAME
 -10,END OF FILE ON TAPE

 NCOND -VALUE FOR ICOND FOR CURRENT BURST = "NBURST"

 INTRVL -RATIO OF INPUT SAMPLE RATE VS. DATA FILE SAMPLE
 -RATE

*****OUTPUT -

NPASS -PASS NUMBER BEING PROCESSED

 SRDIN -INPUT SAMPLE RATE

 SRDATA -DATA FILE SAMPLE RATE

 NEVENT -MANEUVER NUMBER

 IADDR -STORED ADDRESS ARRAY OF MANEUVER NUMBER

 KADDR -CURRENT ADDRESS OF DATA FILE RECORD FOR NPASS

 ETO -BURST START TIME

 ETF -BURST STOP TIME

 NFRM -NUMBER OF FRAMES OF DATA WITHIN BURST

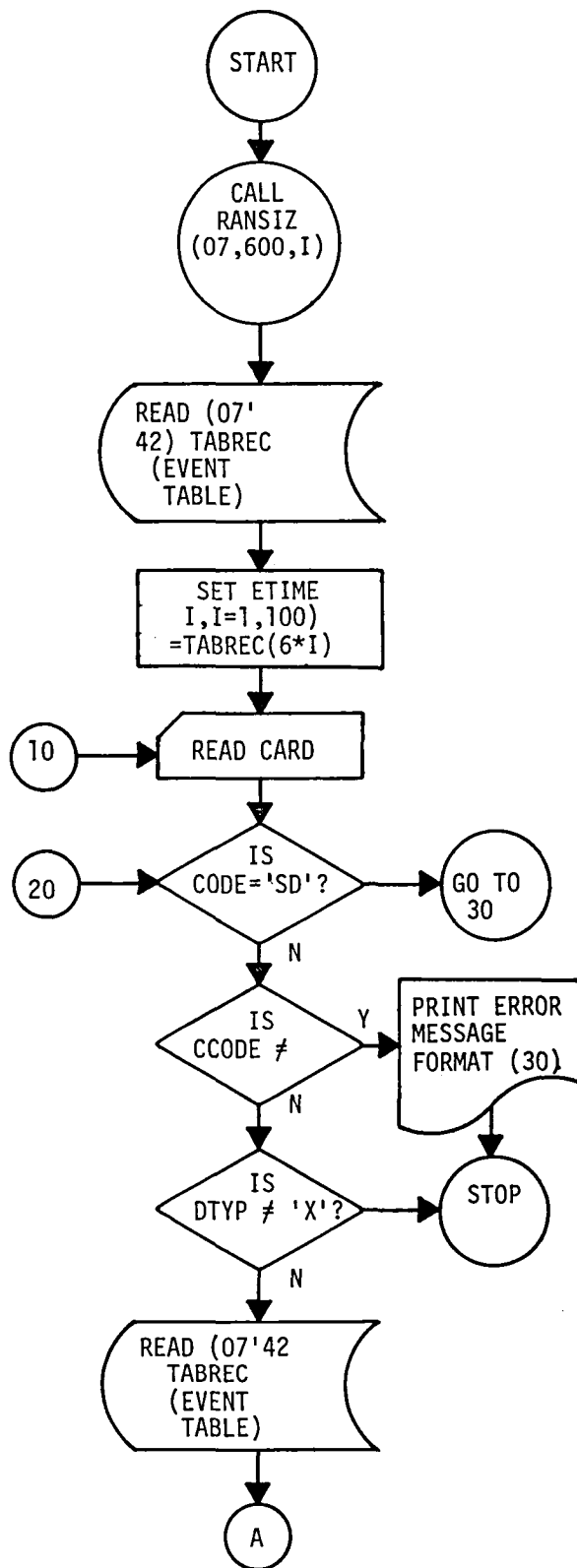
 NLOS -NUMBER OF LOSS OF SYNS WITHIN BURST

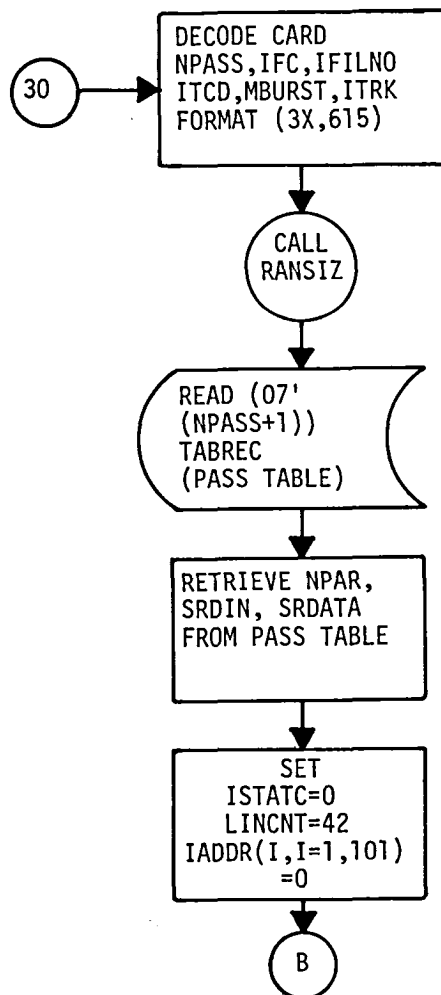
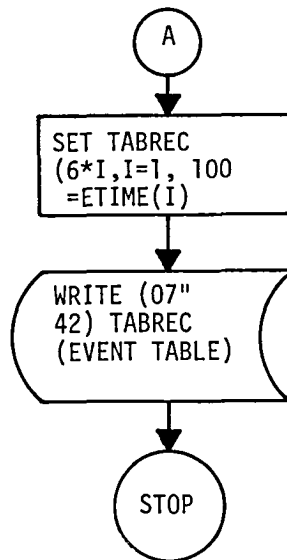
*****RESTRICTIONS -

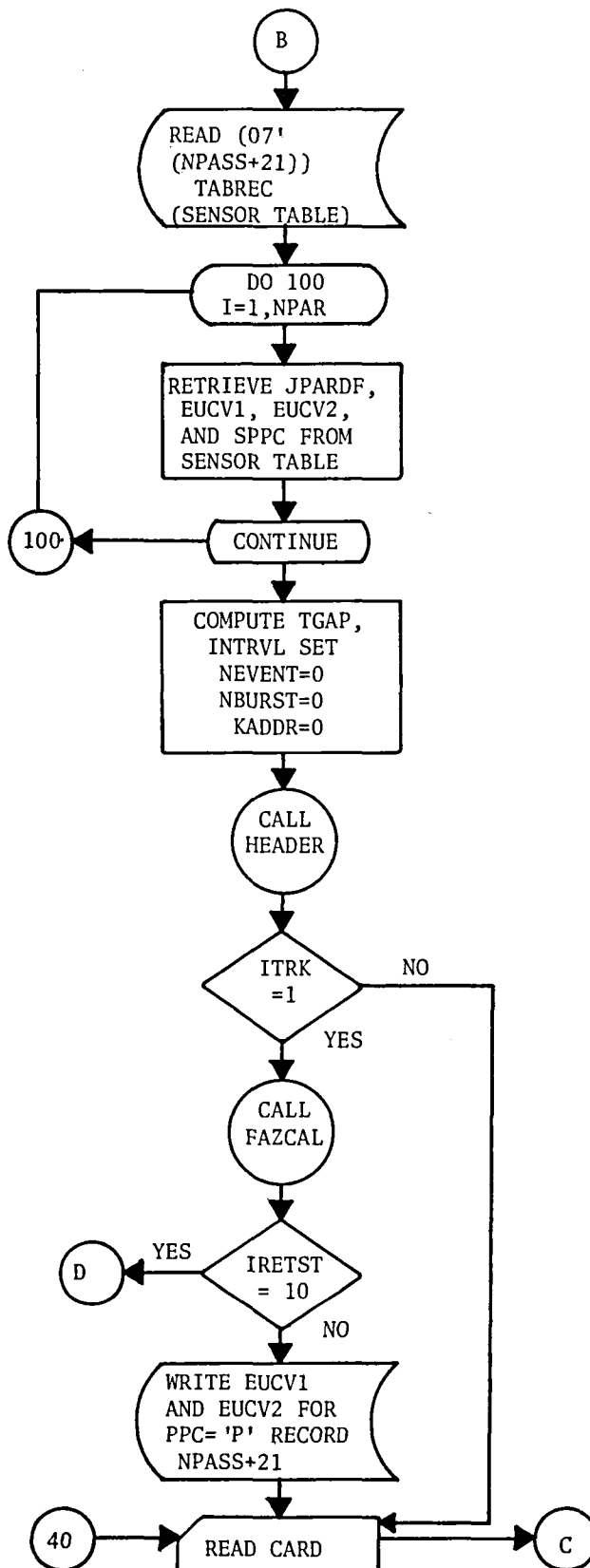
LIMIT OF 20 PASSES PER FLIGHT
LIMIT OF 40 PARAMETERS PER PASS
LIMIT OF 100 MANEUVERS
INPUT TAPES ARE STANDARD TELEVENT FORMAT (RESTRICTED BY
GFRAME MODULE)

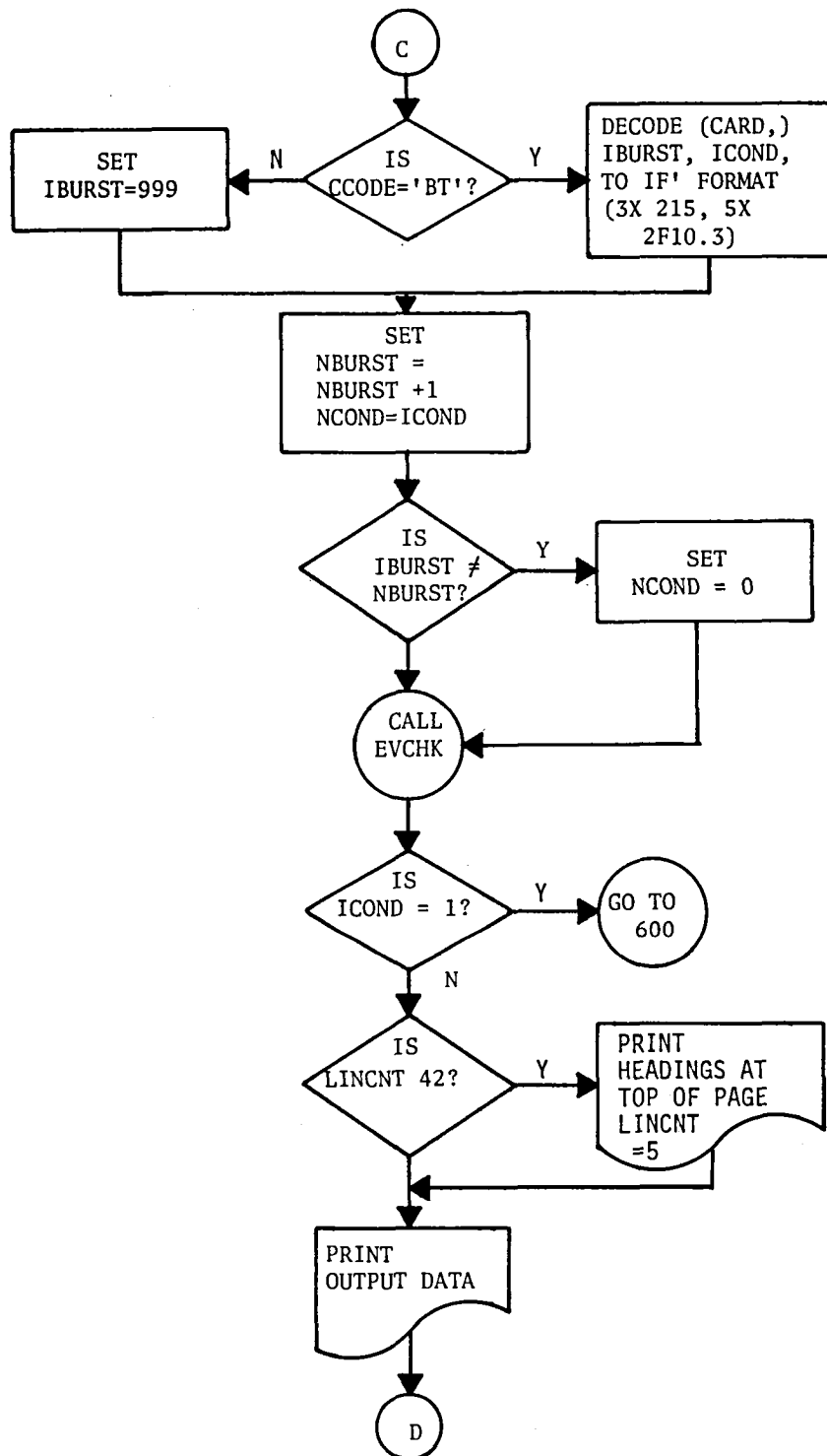
*****SUBPROGRAMS REQUIRED -

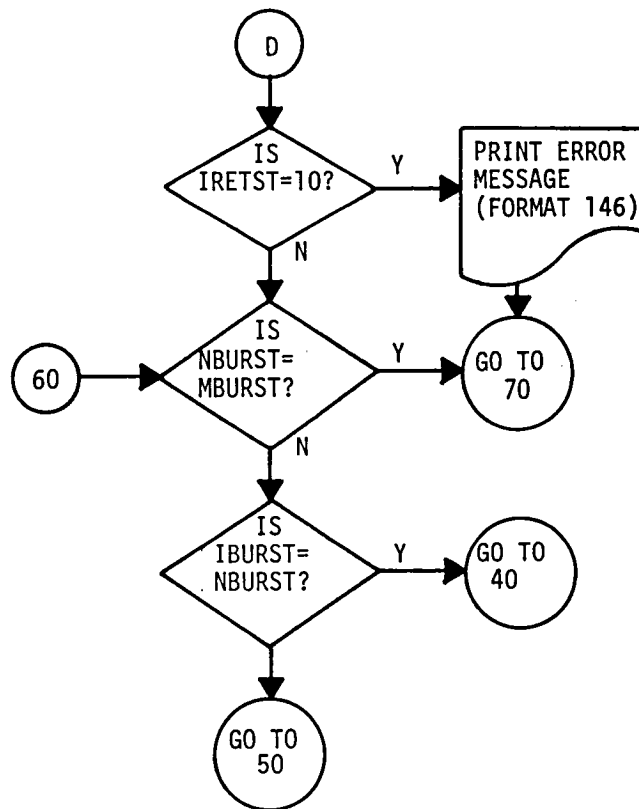
HEADER
 SFRAME
 HFRAME
EVCHK
 PCMRD
 GFRAME
 SFRAME
 TMSET
 FMRD
 GFRAME
 EPACK
STATCL
WRTRDF
EPACK

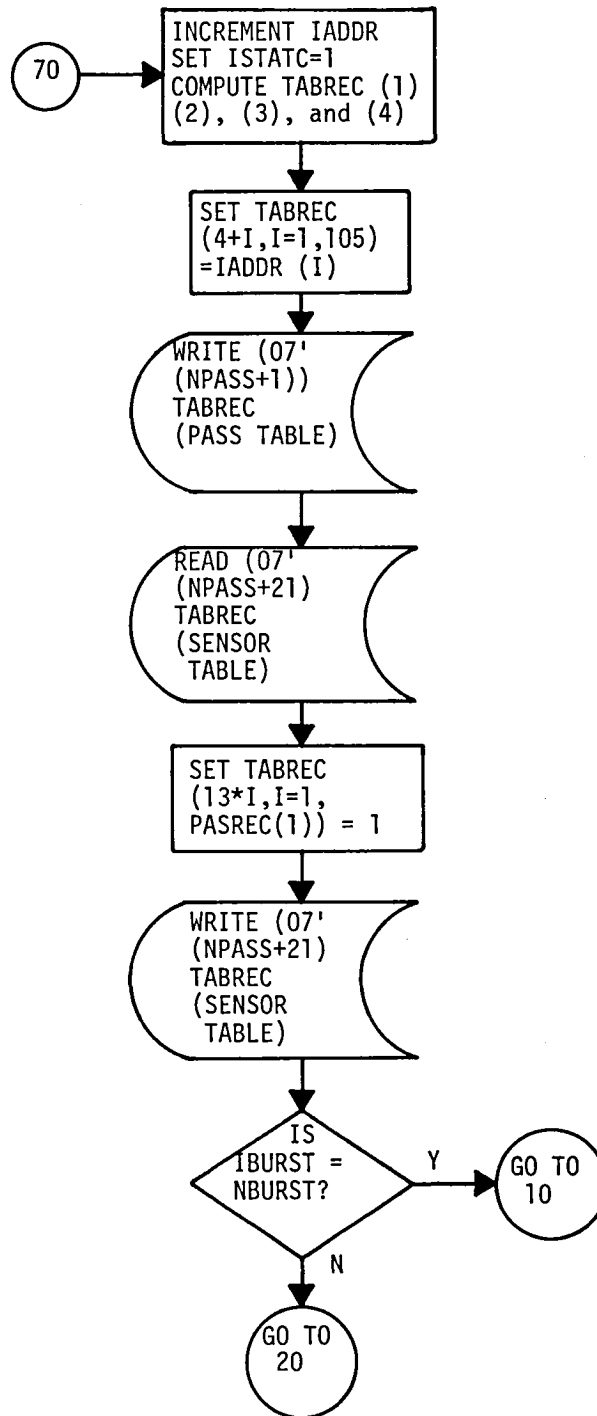












HEAD HEADER-INITIALIZE INPUT 6130-TAPE
*****SUBROUTINE HEADER*****

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN IV

*****MACHINE - HW 625/635

*****PURPOSE -
 INITIALIZE INPUT TAPE AND READ HEADER RECORD

*****METHOD -
 INITIALIZE TAPE BY CALLING SFRAME AND READ THE HEADER RECORD
 BY CALLING HFRAME.

*****INPUT -

 IFCD -FILE CODE OF INPUT TAPE

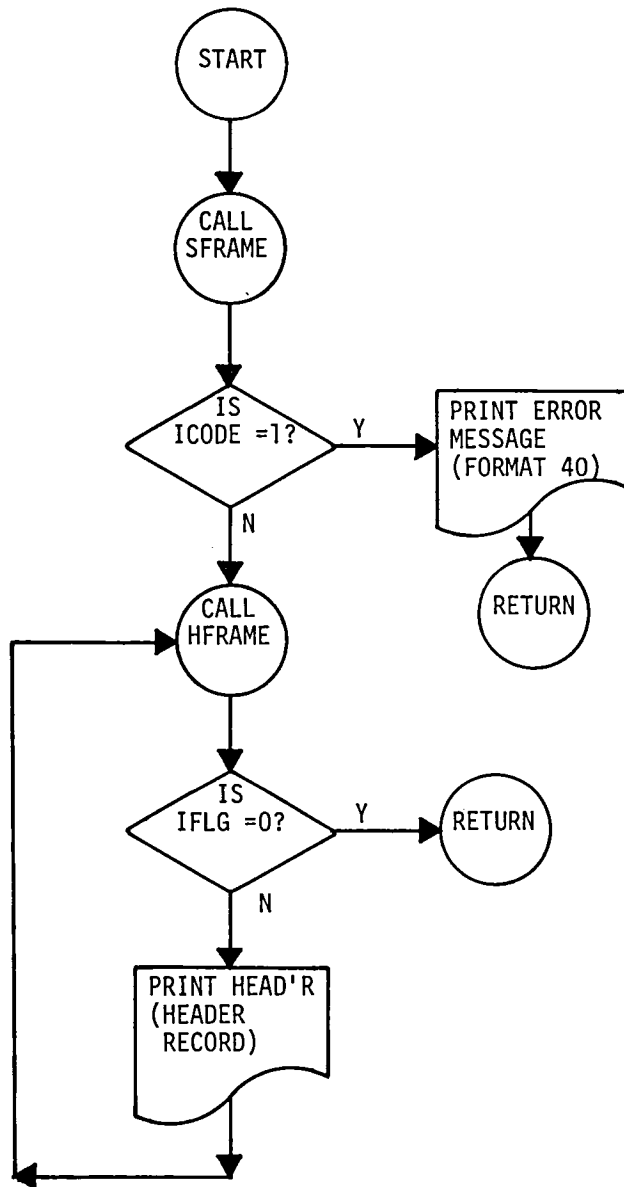
 IFL -LOGICAL FILE WHERE PASS = NPASS TO BE FOUND ON
 -INPUT TAPE

*****OUTPUT -

 HEADR -HEADER RECORD TO BE PRINTED

*****RESTRICTIONS -
 NONE

*****SUBPROGRAMS REQUIRED -
 SFRAME
 HFRAME



FAZCAL

*****SUBROUTINE FAZCAL*****

*****NASA WALLOPS VERSION OF MARCH 15,1978

*****LANGUAGE - FORTRAN IV

*****MACHINE - HONEYWELL 635

*****PURPOSE -

THIS ROUTINE PROCESSES PHASE CALIBRATION DATA.

*****METHOD -

THE FM TAPE MUST BE OF STANDARD TELEVENT FORMAT
BECAUSE DATA IS DECODED BY GFRAME MODULE.
THE STATUS OF EACH RECORD IS CHECKED FOR POSSIBLE
PARITY ON READ, AND END OF FILE DESIGNATOR.
ZERO DEGREE PHASE CALIBRATION IS COMPUTED AND
STORED IN ARRAY IAVG.
AVERAGE VALUE FOR ZERO DEGREES IS CALCULATED
AND STORED IN ARRAY IX0.
360 DEGREE PHASE CALIBRATION IS COMPUTED AND STORED
IN ARRAY IAVG.
AVERAGE VALUE FOR 360 DEGREES IS COMPUTED AND STORED
IN ARRAY IX1.
EUCV1 AND EUCV2 TERMS ARE COMPUTED AND STORED IN
ARRAYS EUCV1 AND EUCV2.

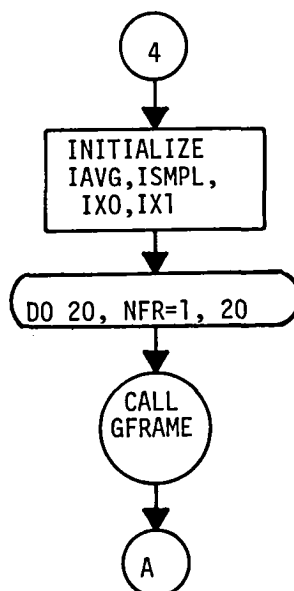
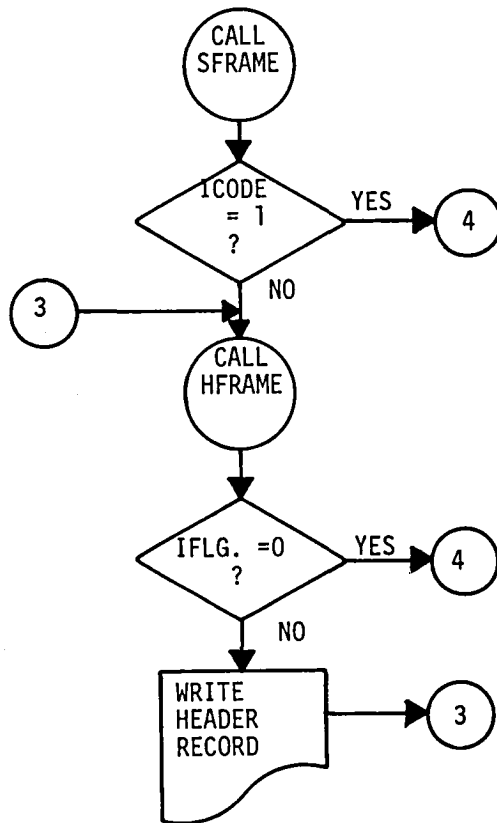
*****OUTPUT -

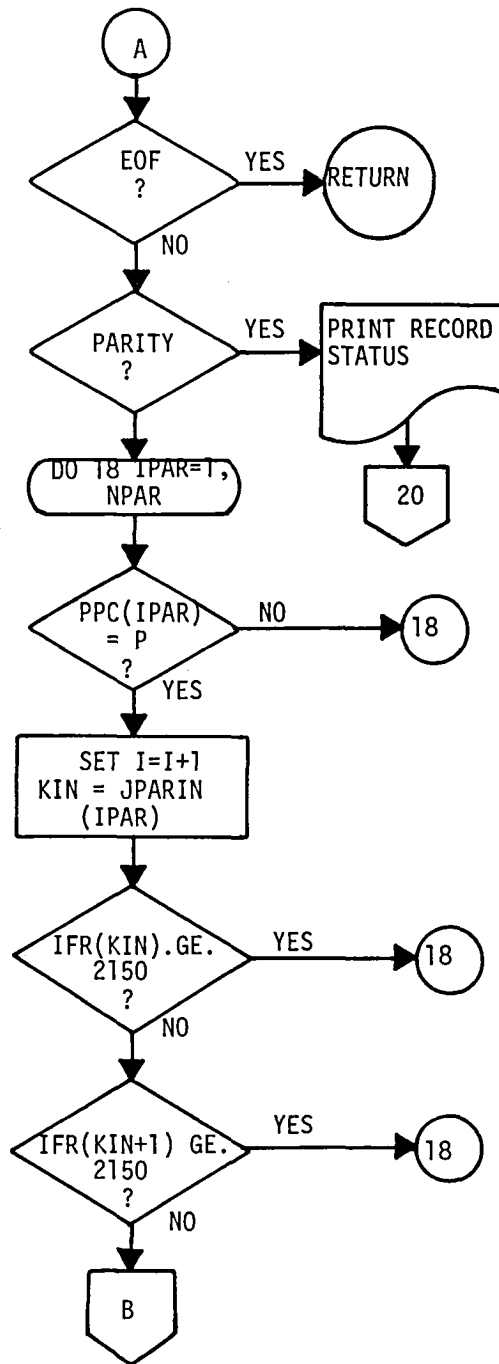
FILE NUMBER 06
CONSISTS OF -

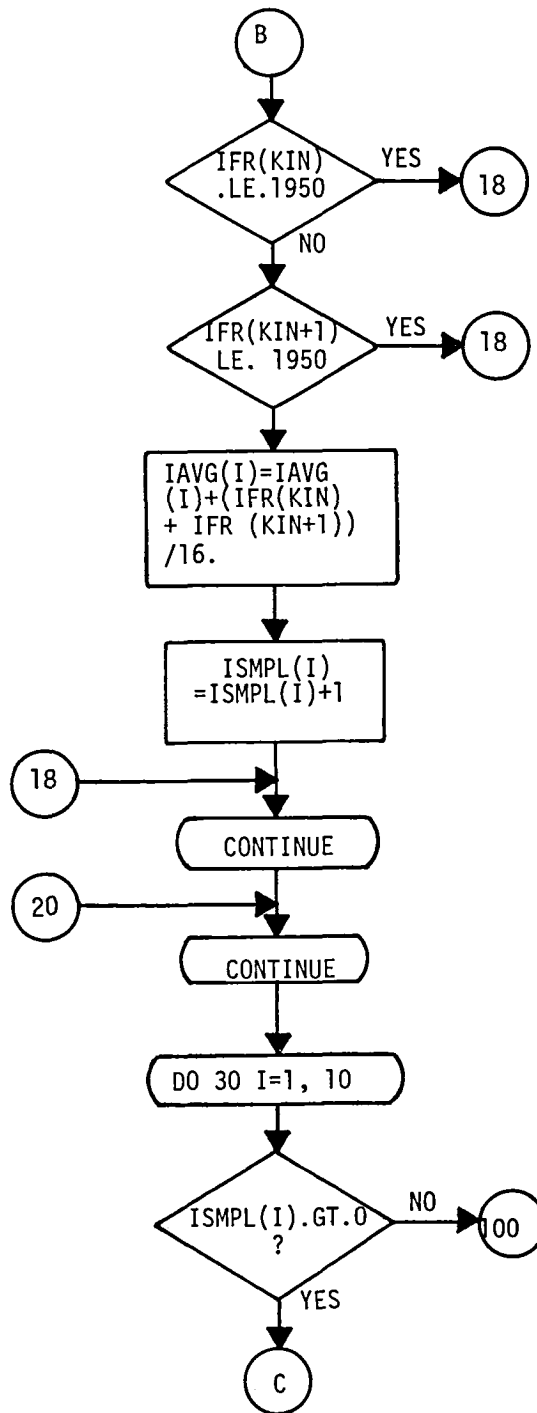
- SENSOR NUMBER
- ZERO DEGREE AVERAGE
- 360 DEGREE AVERAGE
- EUCV1 (DEFLECTION IN ENG. UNITS)
- EUCV2 (OFFSET IN ENG. UNITS)
- IRETST - READ STATUS OF FRAME
 - 1,2,OR 3 GOOD READ
 - 10= END OF FILE

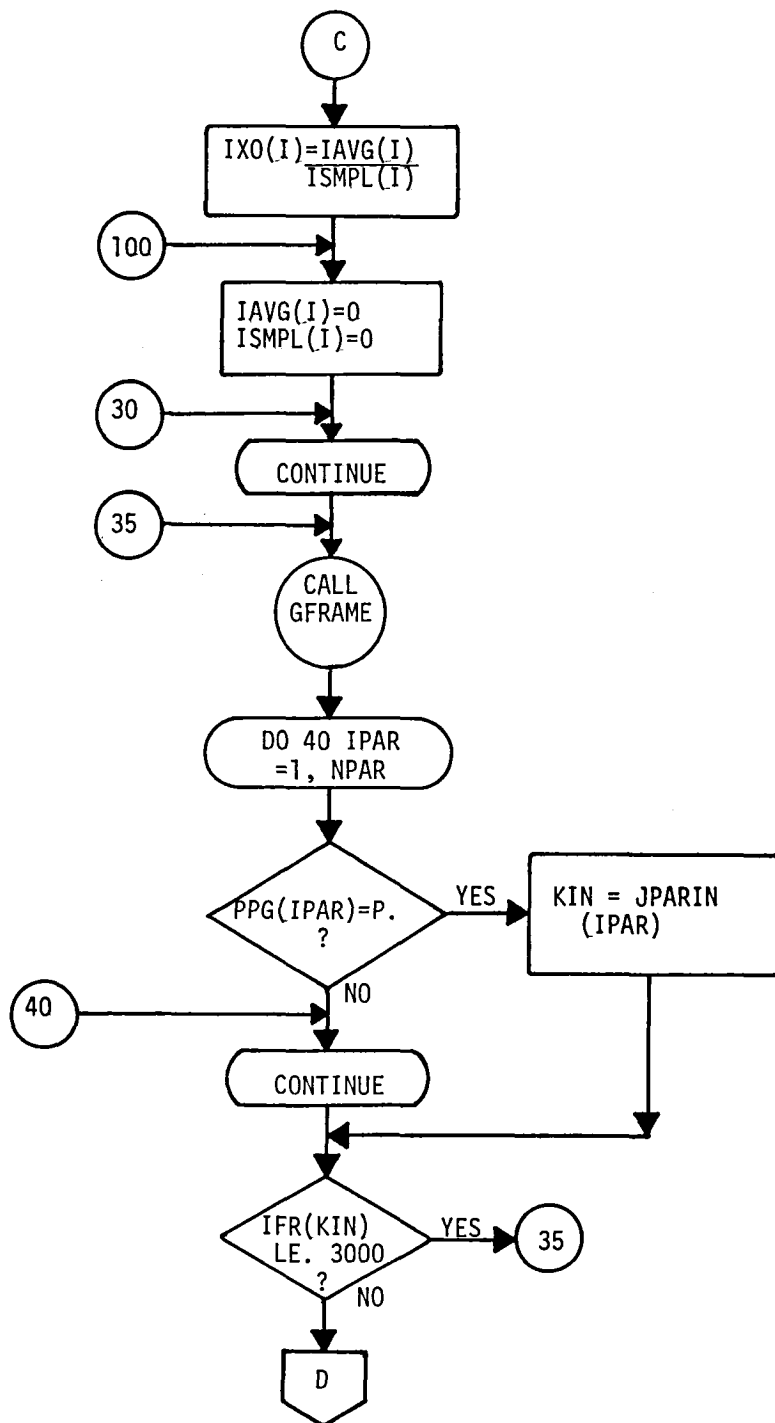
*****RESTRICTIONS - FM TAPE MUST BE STANDARD TELEVENT
FORMAT.

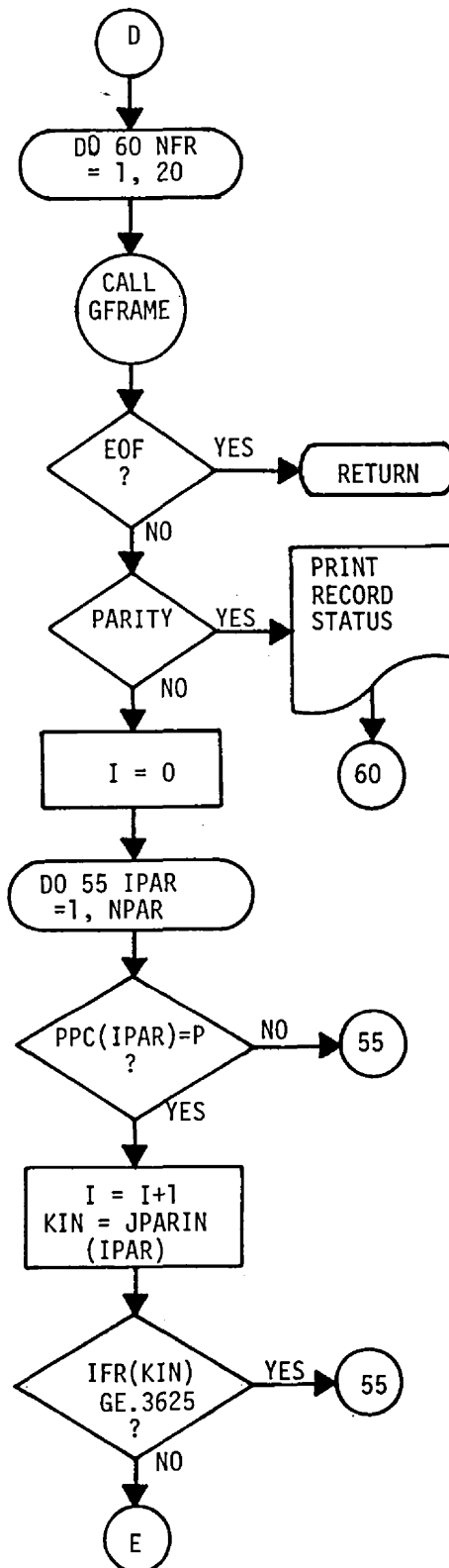
*****SUBPROGRAMS REQUIRED - GFRAME,HFRAME,SFRAME

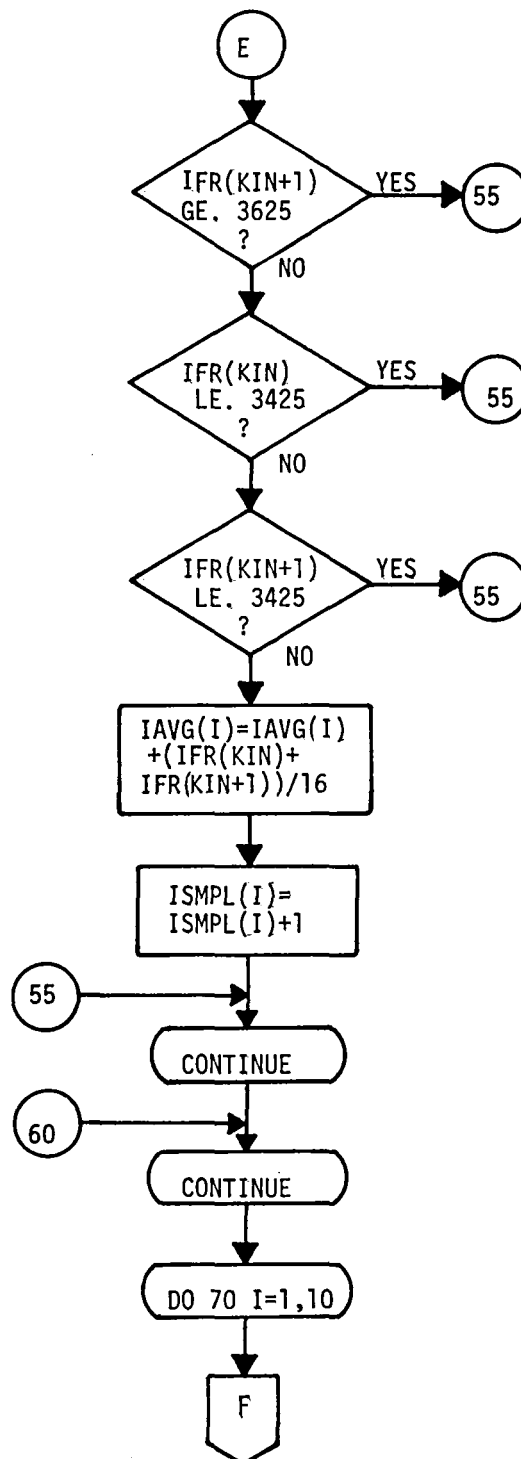


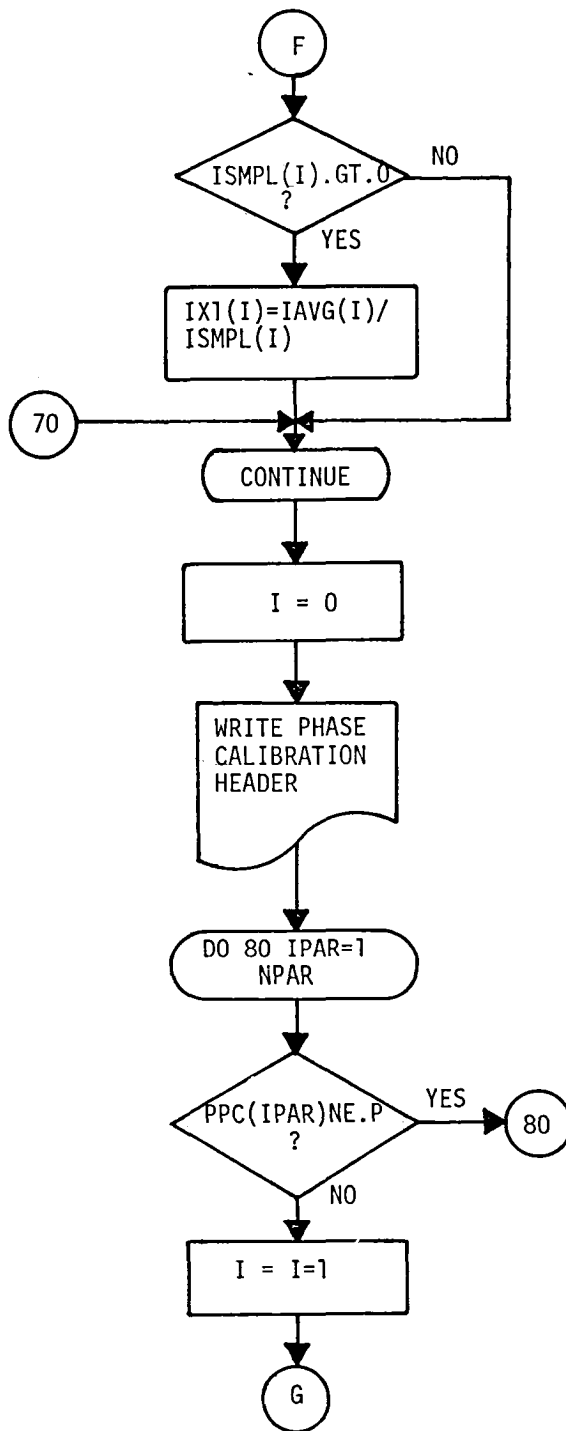


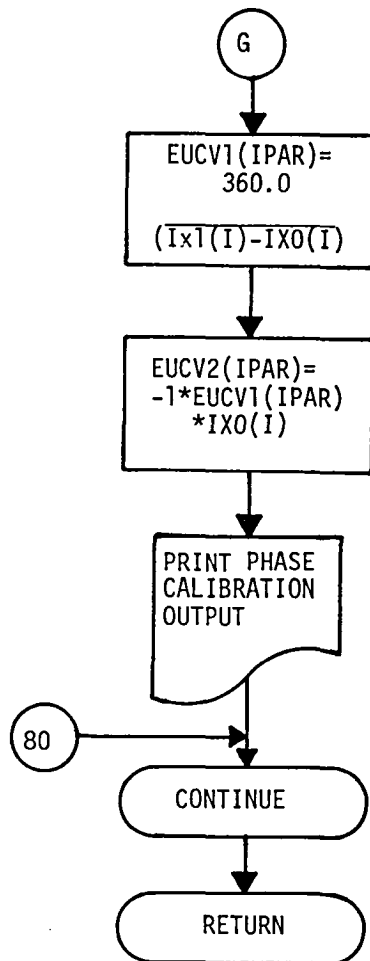












EVCH EVCHK-CORDINATE EVENTS
*****SUBROUTINE EVCHK*****

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN IV

*****MACHINE - HW 625/635

*****PURPOSE -
PROCESS A BURST OF DATA

*****METHOD -
BURST IS HANDLED ACCORDING TO ICOND FROM SCAN ROUTINE. UNDER
ICOND = 1 BURST IS READ UNTIL RUN TONE GOES OFF AND DATA IS
IGNORED. IF ICOND = 3 DATA RECORD AND STATISTICS ARE
REPRESENTED BY NULL VALUES. IF ICOND = 0 OR 2 DATA IS STORED
AND THEIR STATISTICS ARE TO BE COMPUTED.

METHOD OF PROCESSING DATA DEPENDS ON TYPE OF DATA BEING
PROCESSED (PCM OR FM).

PCM DATA MUST BE CHECKED FOR LOSS OF FRAME SYNC AND IT CAN BE
PROCESSED AT A SAMPLE RATE LOWER THAN THE ORIGINAL.

FM DATA HAS NO LOSS OF SYNC AND DATA IS PROCESSED AT THE
SAMPLE RATE AS RECEIVED. VIBRATORY AND STEADY COMPONENTS
MUST BE COMPUTED FROM INPUT PEAK AND VALLEY DATA IN FMRD.
PROCESSING OF DATA INCLUDES STORING DATA IN PACKED FORMAT
THROUGH WRTRDF ROUTINE. DATA IS PASSED TO STATCL ROUTINE FOR
COMPILE AND COMPUTATION OF STATISTICS. AT THE END OF EACH
DATA BURST FINAL STATISTICS ARE COMPUTED AND WRITTEN ONTO THE
STATISTICS FILE.

*****INPUT -

NPASS	-PASS NUMBER BEING PROCESSED
ICOND	-(SEE SCAN)
IBURST	-CARD INPUT BURST NUMBER
NEVENT	-MANEUVER NUMBER
TO	-BEGINNING TIME OF DATA BURST (SEC)
TF	-ENDING TIME OF DATA BURST (SEC)
ITCD	-(SEE SCAN)

TGAP	-RATIO OF 1. VS. INPUT SAMPLE RATE
INTRVL	-RATIO OF INPUT SAMPLE RATE VS. DATA FILE SAMPLE -RATE
IFCD	-FILE CODE OF INPUT TAPE
DTYP	-CODE TO DETERMINE IF CURRENT PASS OF DATA IS -PCM (DTYP = "X") OR FM (OTHER) (CHARACTER PORTION -OF INPUT SAMPLE RATE)

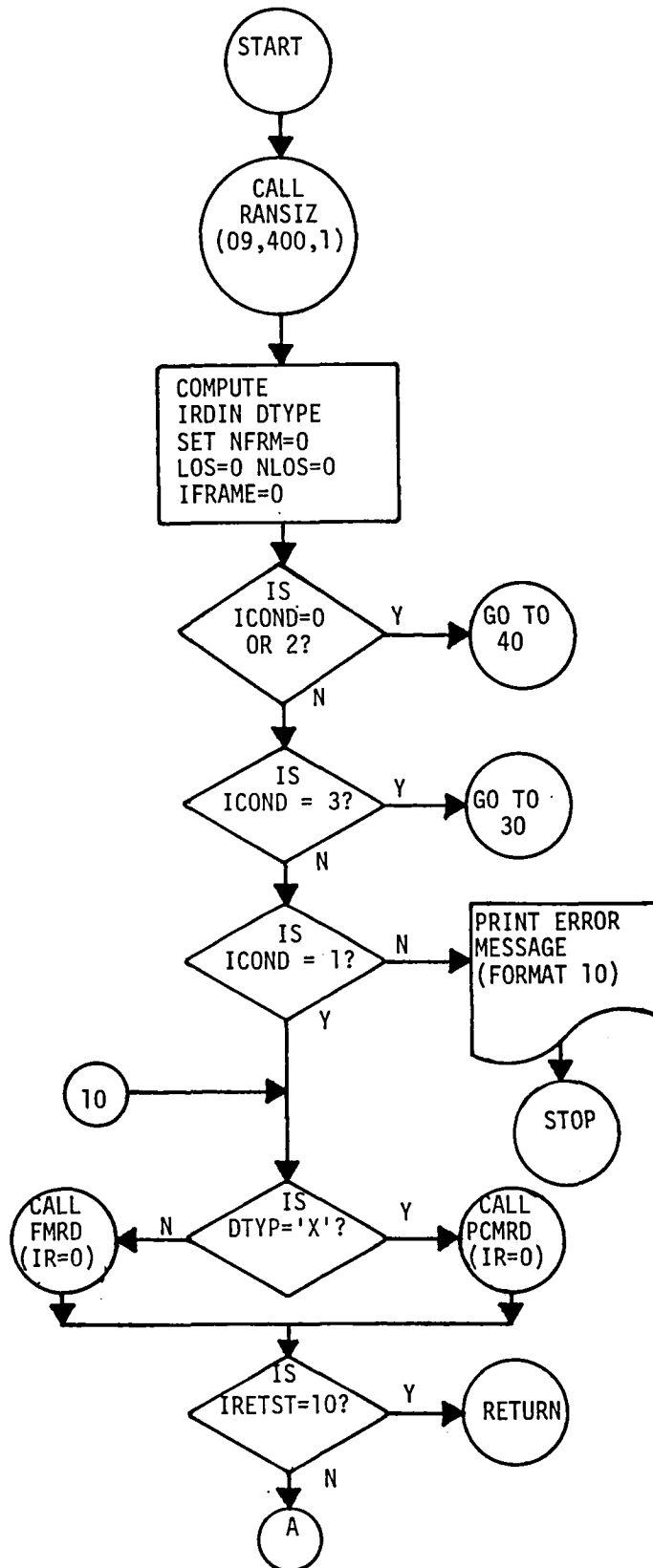
*****OUTPUT -

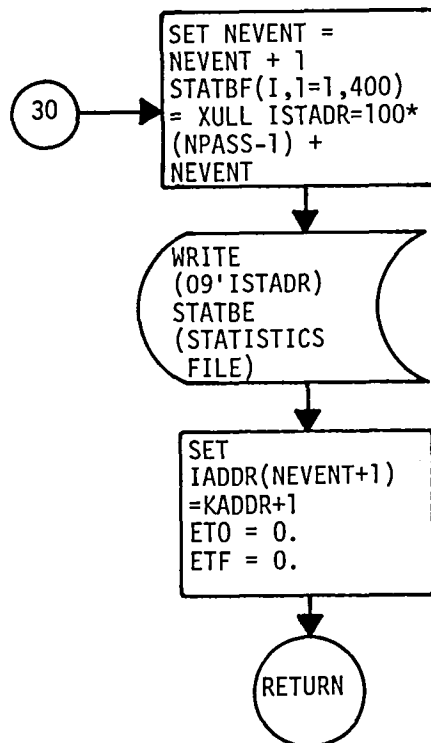
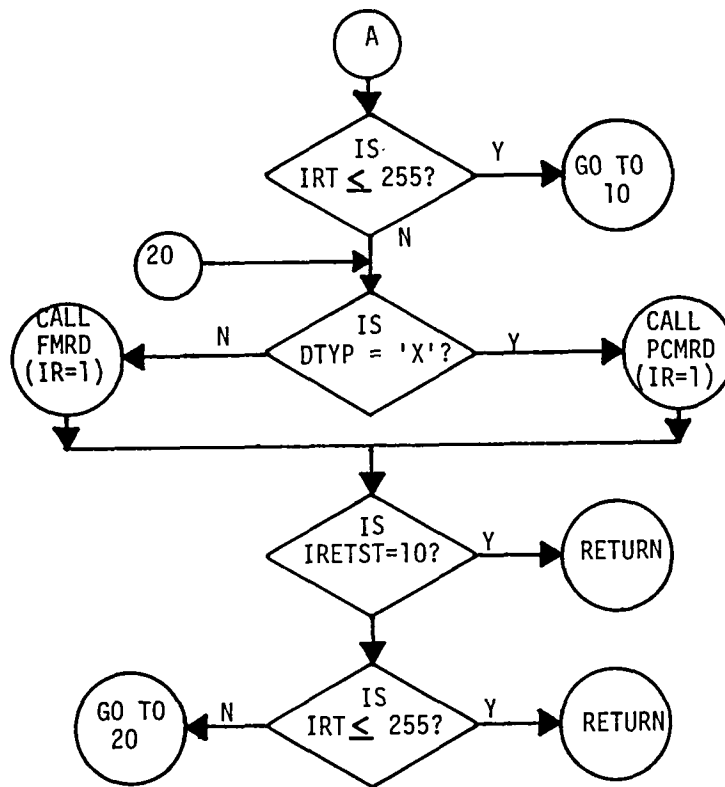
KADDR	-CURRENT ADDRESS OF DATA FILE RECORD FOR NPASS -(OUTPUT FROM WRTRDF)
IRETST	-TAPE STATUS AS RETURNED FROM GFRAME (SEE PCMRD -AND FMRD)
ETO	-BURST START TIME (OUTPUT FROM WRTRDF)
ETF	-BURST STOP TIME (OUTPUT FROM WRTRDF)
NFRM	-NUMBER OF FRAMES OF DATA WITHIN BURST (OUTPUT -FROM WRTRDF)
NLOS	-NUMBER OF LOSS OF SYNC'S WITHIN BURST
MODE	-(SEE STATCL AND WRTRDF)
LOS	-LOSS OF SYNC DETECTOR CODE -0, NO LOSS OF SYNC IN BURST -1, LOSS OF SYNC OCCURRED IN BURST

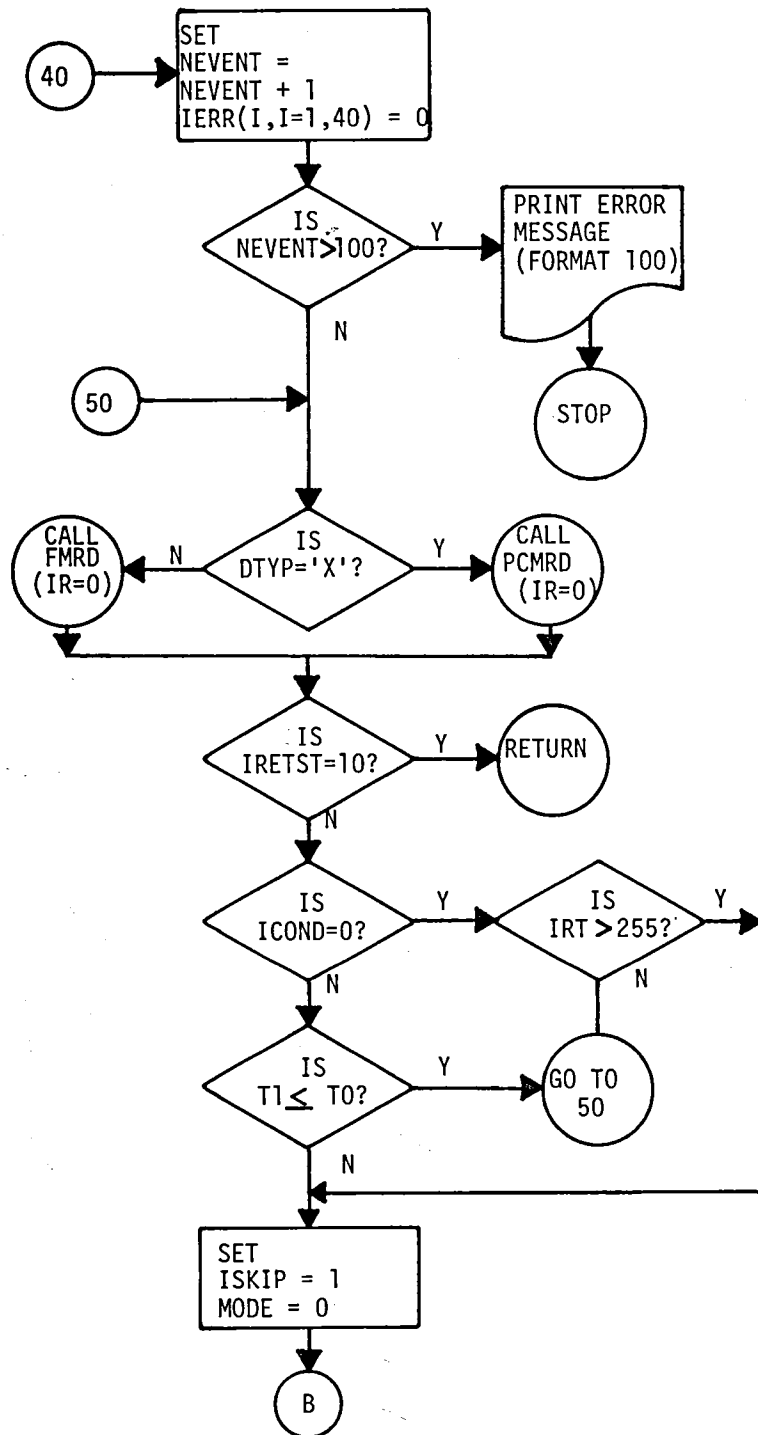
*****RESTRICTIONS -
SAME AS IN SCAN

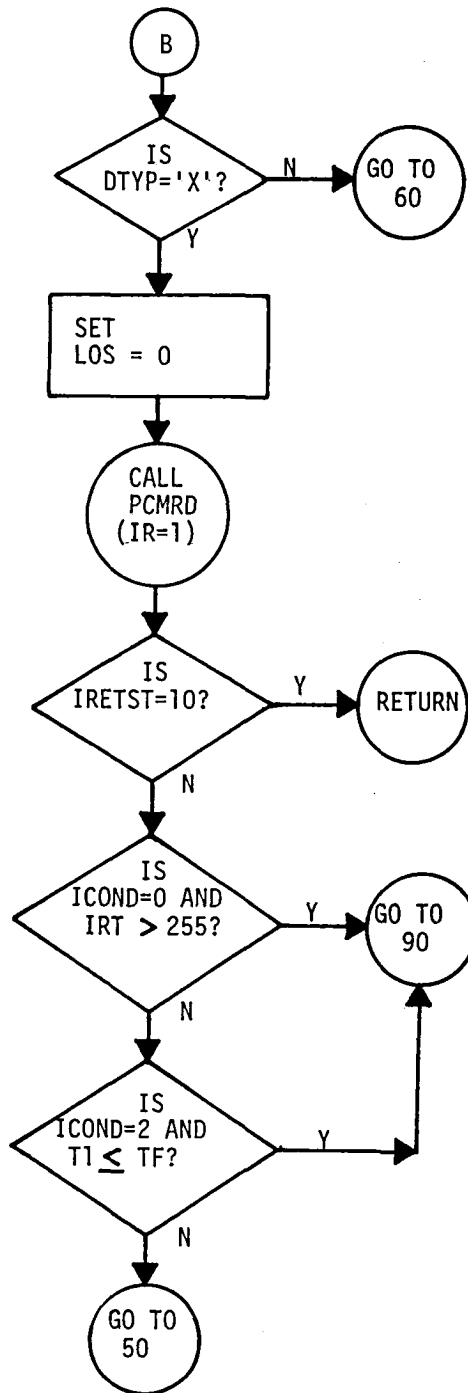
*****SUBPROGRAMS REQUIRED -

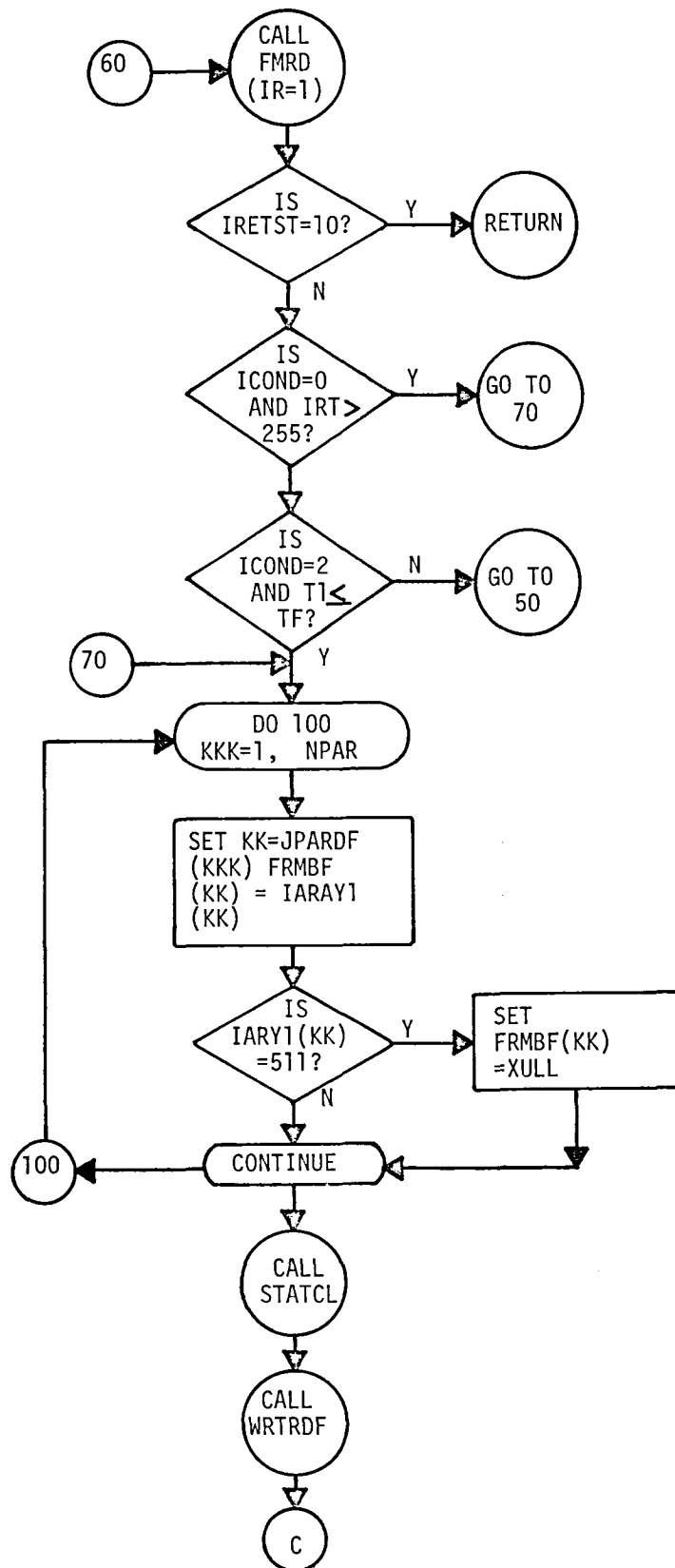
PCMRD	GFRAME SFRAME TMSET
FMRD	GFRAME EPACK
STATCL	
WRTRDF	

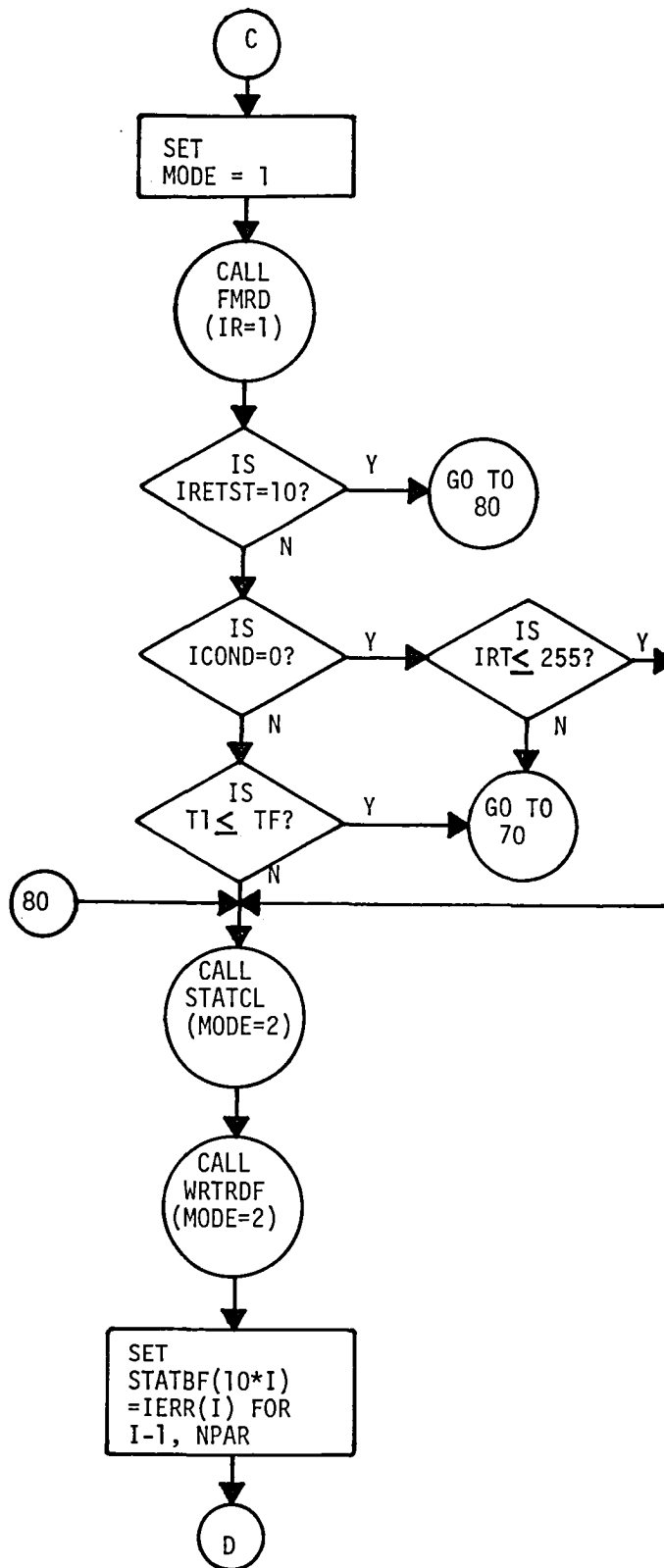


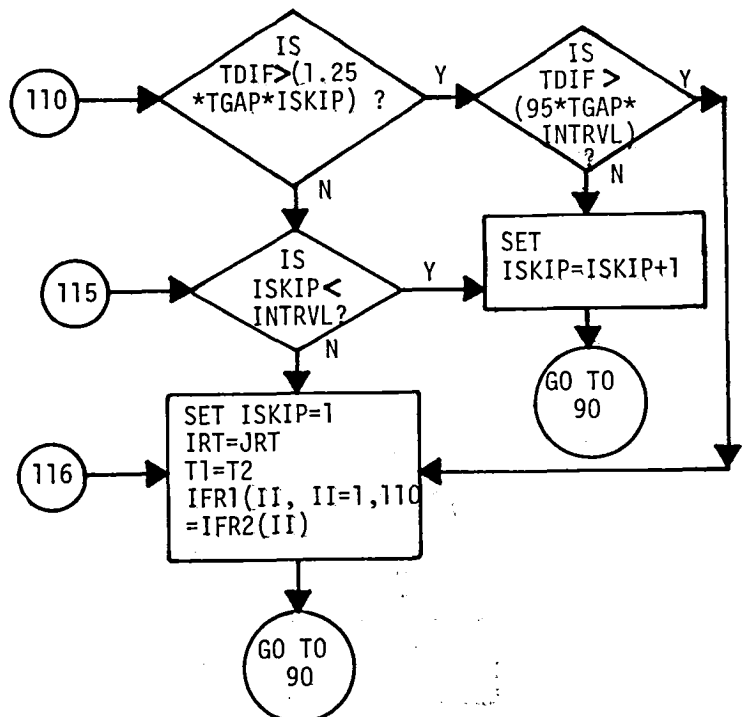
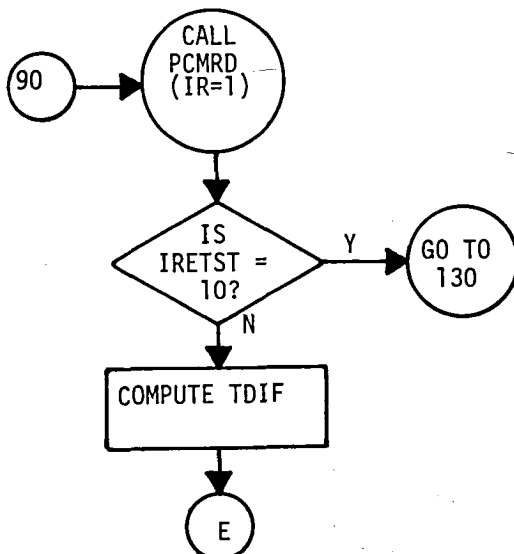
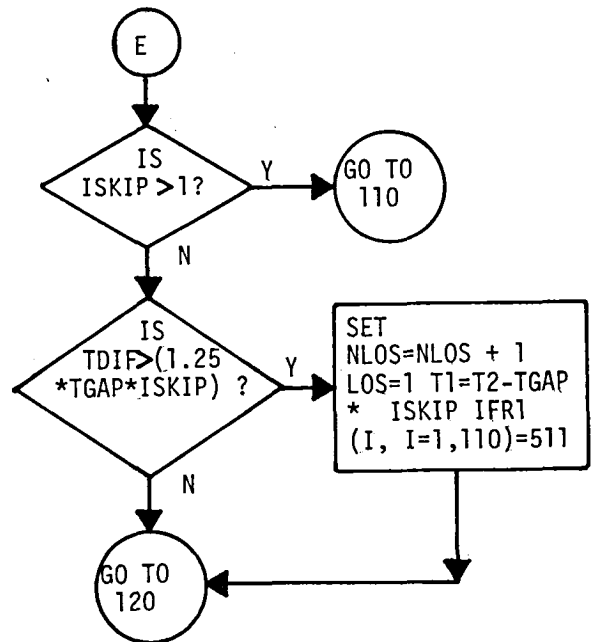
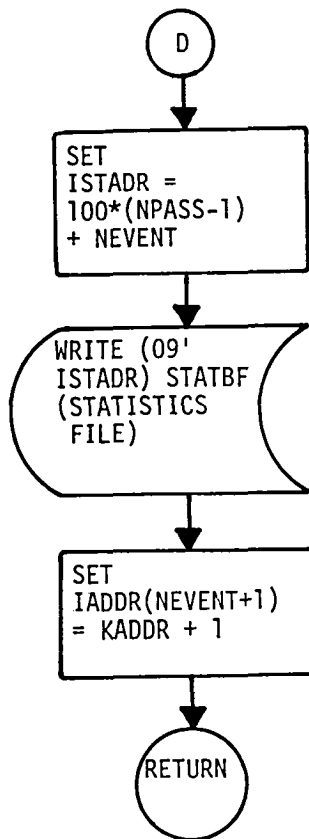


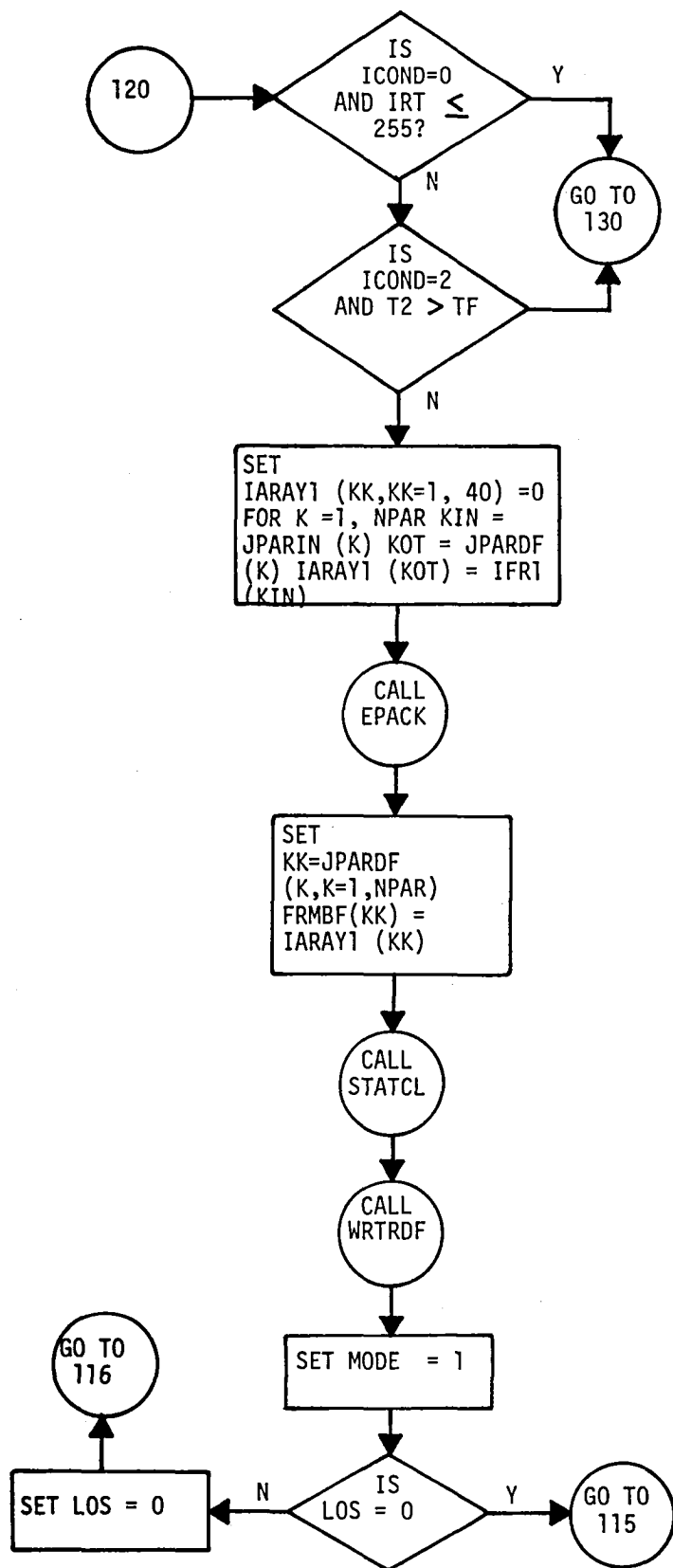


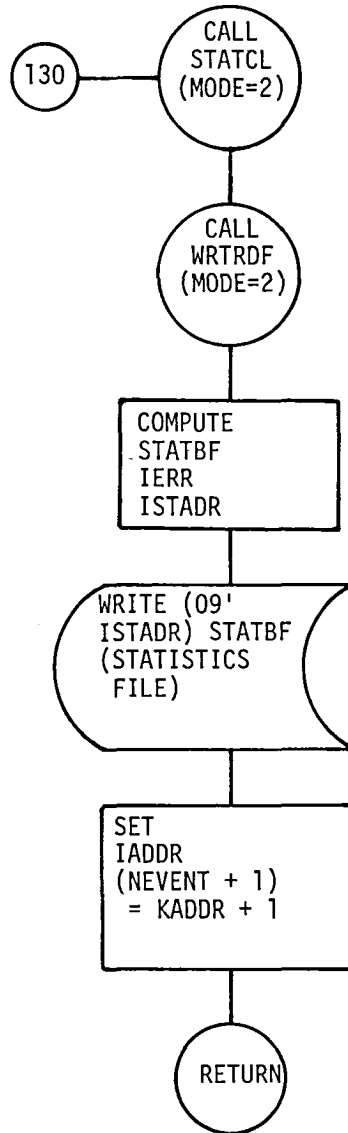












PCMR PCMRD-READ PCM DATA
*****SURROUTINE PCMRD*****

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN IV

*****MACHINE - HW 625/635

*****PURPOSE -
 THIS ROUTINE READS THE INPUT PCM TAPE OR TAPES AND RETURNS
 REQUIRED DATA.

*****METHOD -
 THE PCM TAPE MUST BE OF STANDARD TELEVENT FORMAT BECAUSE DATA
 IS DECODED BY GFRAME MODULE. IF TAPE IS MULTI-REEL,
 SEQUENTIAL TAPE IS INITIALIZED BY SFRAME BEFORE DECODED BY
 GFRAME.

 THE STATUS OF EACH RECORD IS CHECKED FOR POSSIBLE PARITY ON
 READ AND END OF FILE DESIGNATOR.

 GROUND STATION TIME IS COMPUTED FROM 5 WORDS OF TIME (ITIME)
 RETURNED BY GFRAME. AIRBOURNE TIME IS COMPUTED FROM WORDS 2
 THROUGH 6 OF THE DATA ARRAY (IFR) RETURNED BY GFRAME.

 THE RUN TONE IS FOUND IN IFR(110) AND ALTERED SO THAT A VALUE
 OF 256 REPRESENTS RUN TONE SIGNAL BEING ON.

*****INPUT -

 ITCD -CODE DESIGNATING WHICH TIME WORD TO USE
 --=0,AIRBOURNE TIME
 --=1,GROUND STATION TIME

 IR -CODE DESIGNATING STATUS OF BURST
 --=0,SEARCHING FOR BEGINNING OF NEXT BURST
 --=1,WITHIN A DATA BURST (RUN TONE IS ON OR STOP TIME
 - OF BURST HAS NOT BEEN REACHED)

 IFCD -FILE CODE OF INPUT TAPE

*****OUTPUT -

 T -TIME (GROUND STATION OR AIRBOURNE)

 IRT -RUN TONE
 --=256OR MORE,RUN TONE IS ON
 --=LESS THAN 256, RUN TONE IS OFF
 --=511, FULL SCALE

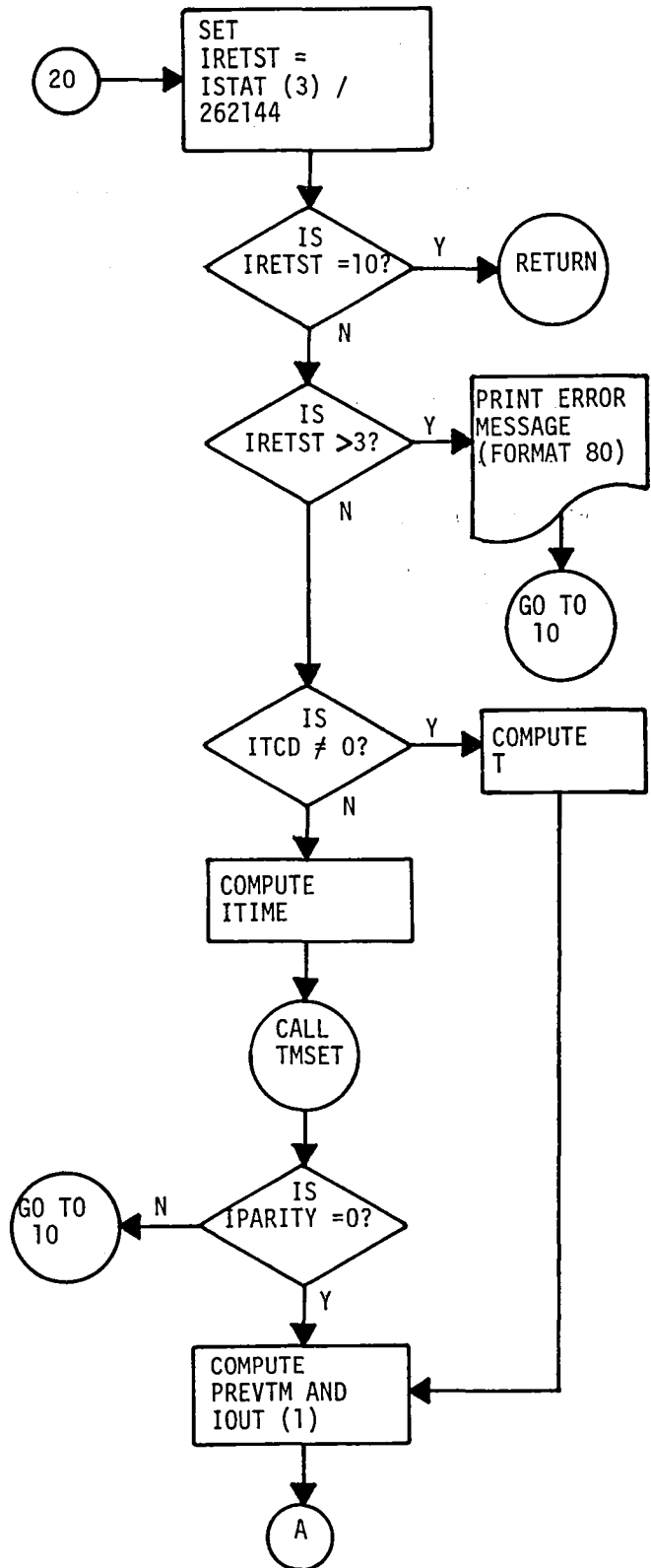
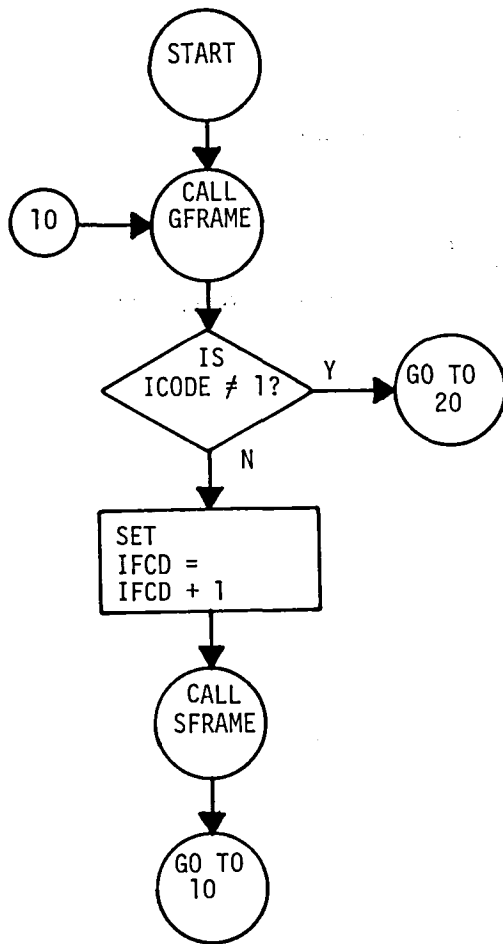
IRETST -READ STATUS OF FRAME
 -=1,2, OR 3,GOOD READ
 -=10,END OF FILE ON TAPE
 -=OTHER, ERROR ENCOUNTERED, DATA IGNORED

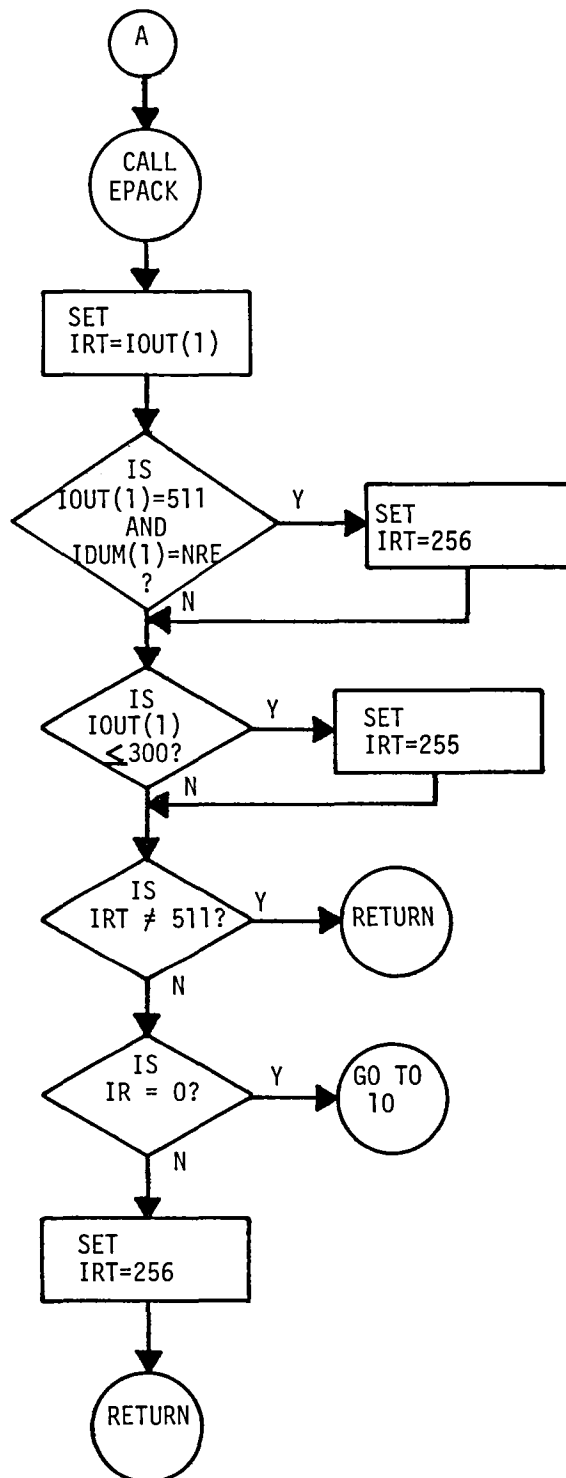
IFR -DECODED DATA ARRAY

ICODE -CODE TO DESIGNATE END OF TAPE
 -=0,END OF TAPE NOT REACHED
 -=1,END OF TAPE ENCOUNTERED, INITIALIZE SEQUENTIAL
 - TAPE

*****RESTRICTIONS -
 NONE

*****SUBPROGRAMS REQUIRED -
 GFRAME
 SFRAME
 TMSET





*****SUBROUTINE TMSET*****

PROGRAM IDENTIFICATION

PROGRAM NAME - TMSET
PROGRAM NO. - 1.1.2320
AUTHOR - DAVID L. DAVIS

COMPUTER - HW 625/635
MEMORY - 101 WORDS
PERIPHERALS - NONE
LANGUAGE - GMAP

PURPOSE

TMSET DECODES AND PARITY CHECKS
THE AIRBORNE TIME, AND RETURNS
IT AS A FLOATING POINT VALUE
IN TOTAL SECONDS.

METHOD

TIME IS CONVERTED TO TOTAL
MILLISECONDS, FLOATED, AND
DIVIDED BY 1000 TO GIVE TOTAL SECONDS.

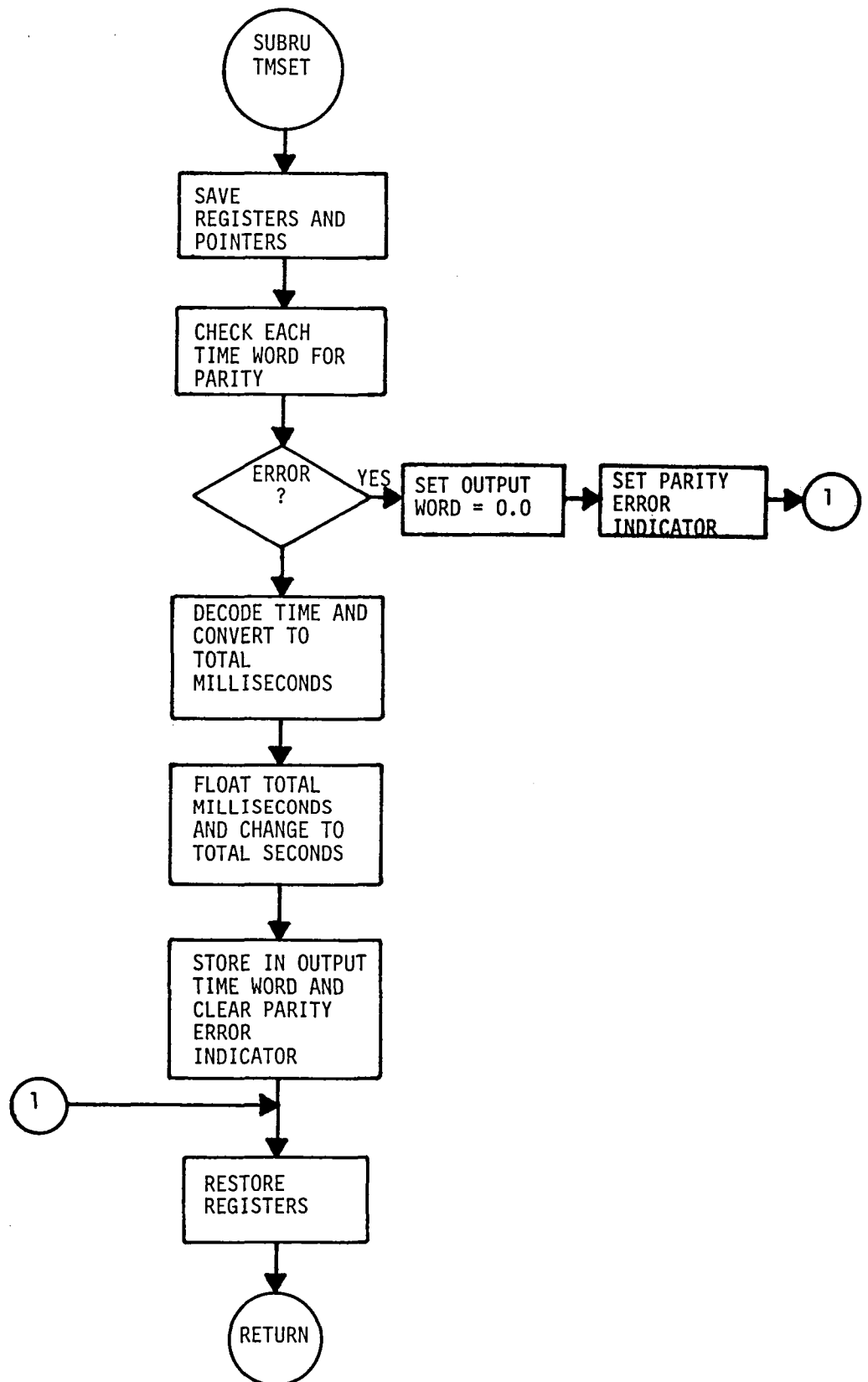
INPUT/OUTPUT

CALLING SEQUENCE<

CALL TMSET(A,B,C) WHERE

A = 5 WORD ARRAY OF INPUT TIME
B = OUTPUT TIME IN SECONDS (FLOATING POINT).
C = PARITY CHECK FLAG

IF C = #0# PARITY OK
C = #1# PARITY ERROR



*****SUBROUTINE EPACK*****

PROGRAM IDENTIFICATION

PROGRAM NAME - EPACK
PROGRAM NO. - 1.1.2320
AUTHOR - DAVID L. DAVIS

COMPUTER - HW 625/635
MEMORY - 105 WORDS
PERIPHERALS - NONE
LANGUAGE - GMAP

PURPOSE

EPACK EDITS AND PACKS A 40 WORD
INPUT ARRAY INTO A 10 WORD OUTPUT
ARRAY.

METHOD

METH

METHPCM DATA<

SYNC FLAG IS CHECKED. IF OUT OF SYNC
BIT 23 IN ALL WORDS OF THE STATUS
BUFFER IS SET TO A ONE (#1#), AND
THE OUTPUT BUFFER IS SET TO MAXIMUM
DATA VALUE. IF THE DATA IS IN SYNC,
PARITY IS THEN CHECKED. WHEN A PARITY
ERROR IS DETECTED, BIT 35 IN THE
CORRESPONDING STATUS WORD IS SET AND
MAXIMUM DATA VALUE IS INSERTED IN
THE PROPER POSITION OF THE OUTPUT
BUFFER. IF NO SYNC OR PARITY ERRORS
ARE DETECTED THE DATA RANGE IS CHECKED.
FOR DATA BETWEEN 0 AND 511 (EXCLUSIVE)
THE DATA VALUE IS MOVED TO THE PROPER
POSITION IN THE 10 WORD OUTPUT BUFFER.
WHEN DATA IS NOT WITHIN THIS RANGE,
BIT 29 IN THE CORRESPONDING STATUS
WORD IS SET AND THE DATA BITS ARE SET
TO ONES (#1#) IN BOTH THE INPUT AND
OUTPUT BUFFERS.

FM DATA<

SINCE THERE IS NO PARITY BIT WITH FM
DATA NO PARITY CHECK IS PERFORMED.
HOWEVER, ALL OTHER CHECKS ARE THE SAME
AS FOR PCM DATA.

INPUT/OUTPUT

CALLING SEQUENCE<

CALL EPACK(A,B,C,D,E) WHERE

A = FIRST WORD ADDRESS OF INPUT BUFFER
B = FIRST WORD ADDRESS OF STATUS BUFFER
C = FIRST WORD ADDRESS OF OUTPUT BUFFER
D = DATA SYNC FLAG
E = DATA TYPE

INPUT BUFFER - 40 WORD ARRAY WITH DATA IN
BITS 27 THRU 35 OF EACH WORD.

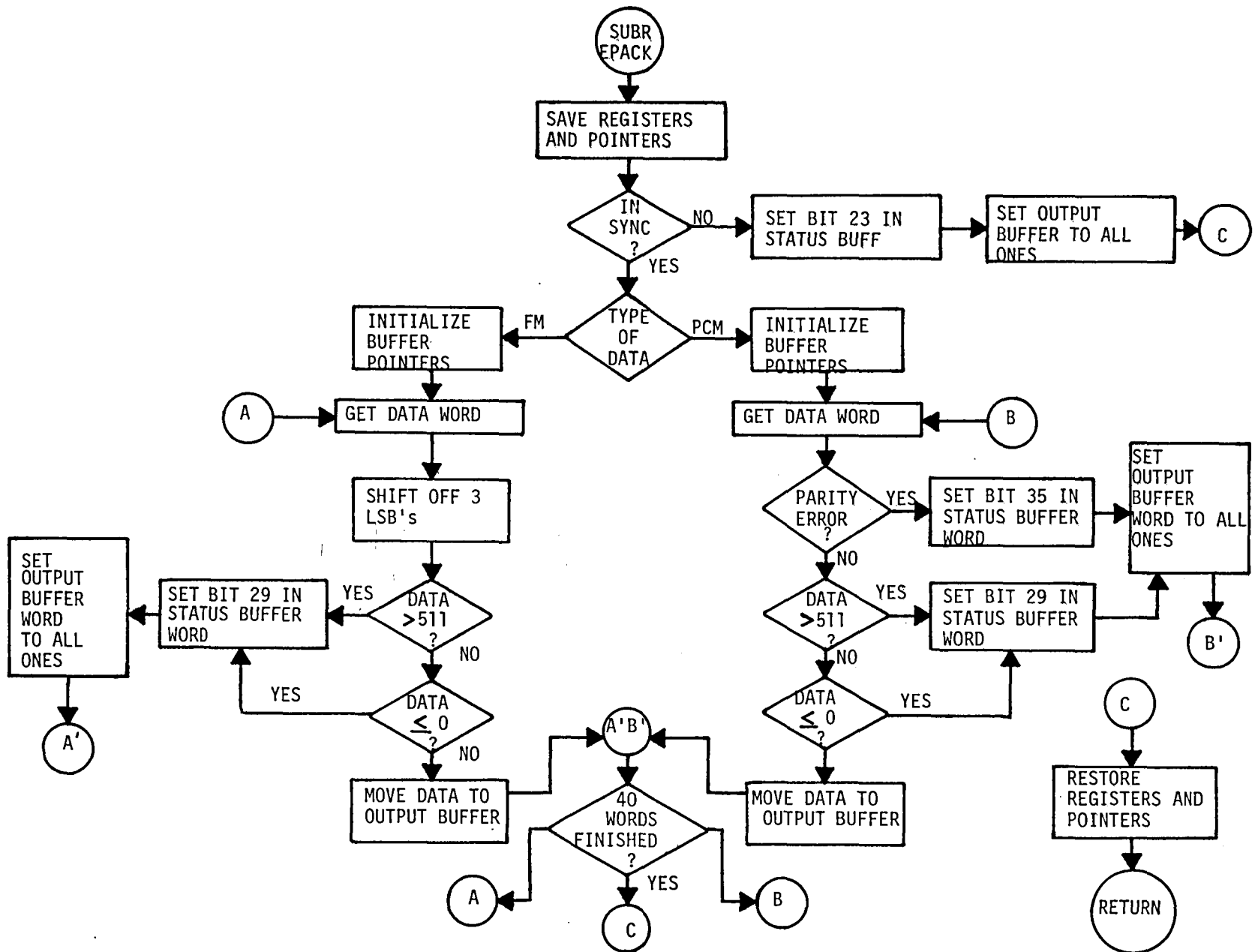
STATUS BUFFER - 40 WORD ARRAY WITH BITS
23, 29, AND 35 USED TO
DESCRIBE THE CONDITION OF
THE CORRESPONDING INPUT
BUFFER WORD.

BIT 23 = 1 - LOSS OF SYNC
BIT 29 = 1 - DATA RANGE ERROR
BIT 35 = 1 - PARITY ERROR

OUTPUT BUFFER - 10 WORD ARRAY WITH 4
9 BIT DATA VALUES PER
WORD.

DATA SYNC FLAG - 1 = LOSS OF SYNC
0 = SYNC

DATA TYPE FLAG - 1 = FM DATA
0 = PCM DATA



FMRD FMRD-READ FM DATA
*****SUBROUTINE FMRD*****

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN IV

*****MACHINE - HW 625/635

*****PURPOSE -
THIS ROUTINE READS THE INPUT FM TAPE AND RETURNS REQUIRED
DATA.

*****METHOD -
THE FM TAPE MUST BE OF STANDARD TELEVENT FORMAT BECAUSE DATA
IS DECODED BY GFRAME MODULE.

THE STATUS OF EACH RECORD IS CHECKED FOR POSSIBLE PARITY ON
READ.AND END OF FILE DESIGNATOR.

AIRBOURNE TIME IS THE ONLY TIME RECORDED AND IS COMPUTED FROM
5 WORDS OF TIME (ITIME).RETURNED BY GFRAME.

THE RUN TONE SIGNAL IS FOUND IN IFR (1) OF THE DATA ARRAY.

VIBRATORY AND STEADY COMPONENTS ARE COMPUTED FROM INPUT PEAK
AND VALLEY DATA.

*****INPUT -

IR	-CODE DESIGNATING STATUS OF BURST
	--=0,SEARCHING FOR BEGINNING OF NEXT BURST
	--=1,WITHIN A DATA BURST (RUN TONE IS ON OR STOP
	- TIME OF BURST HAS NOT BEEN REACHED)

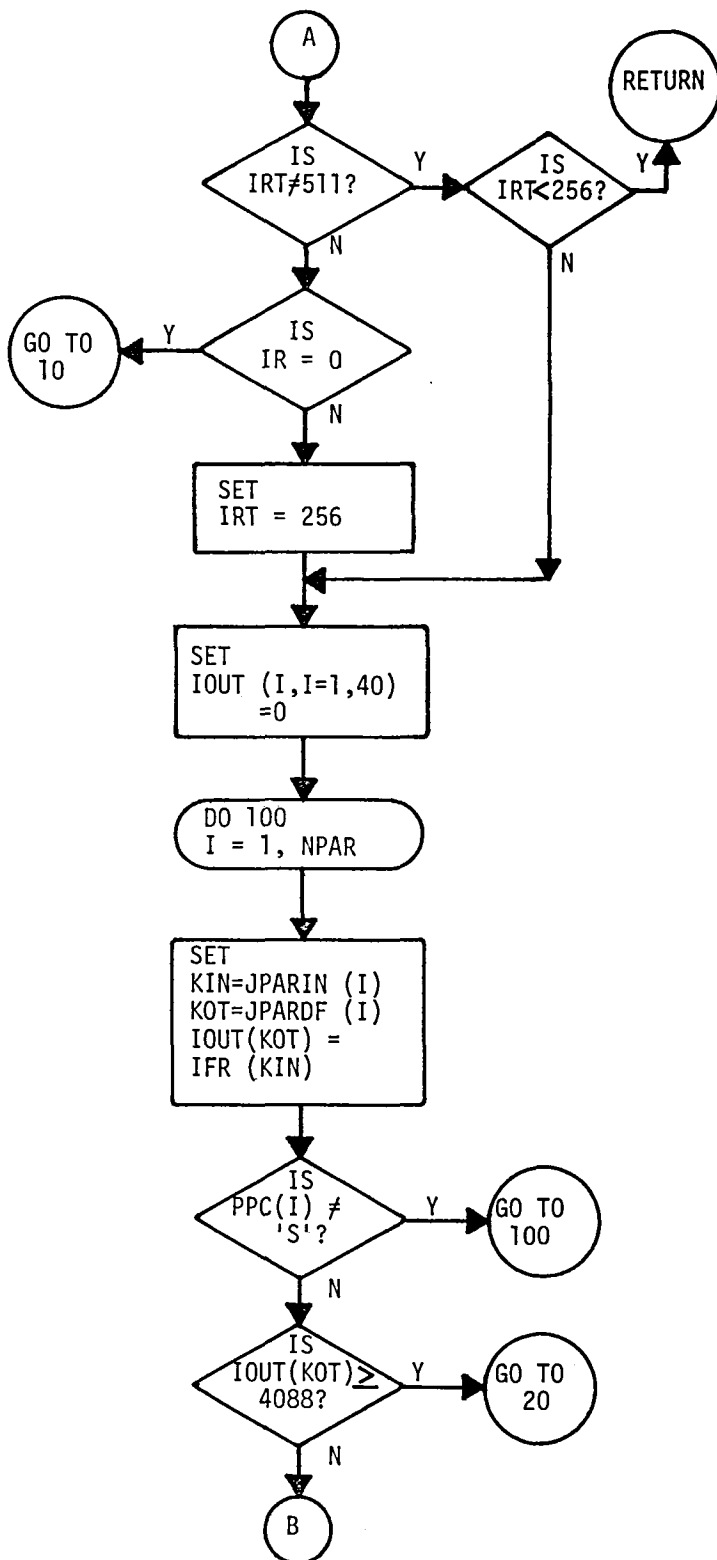
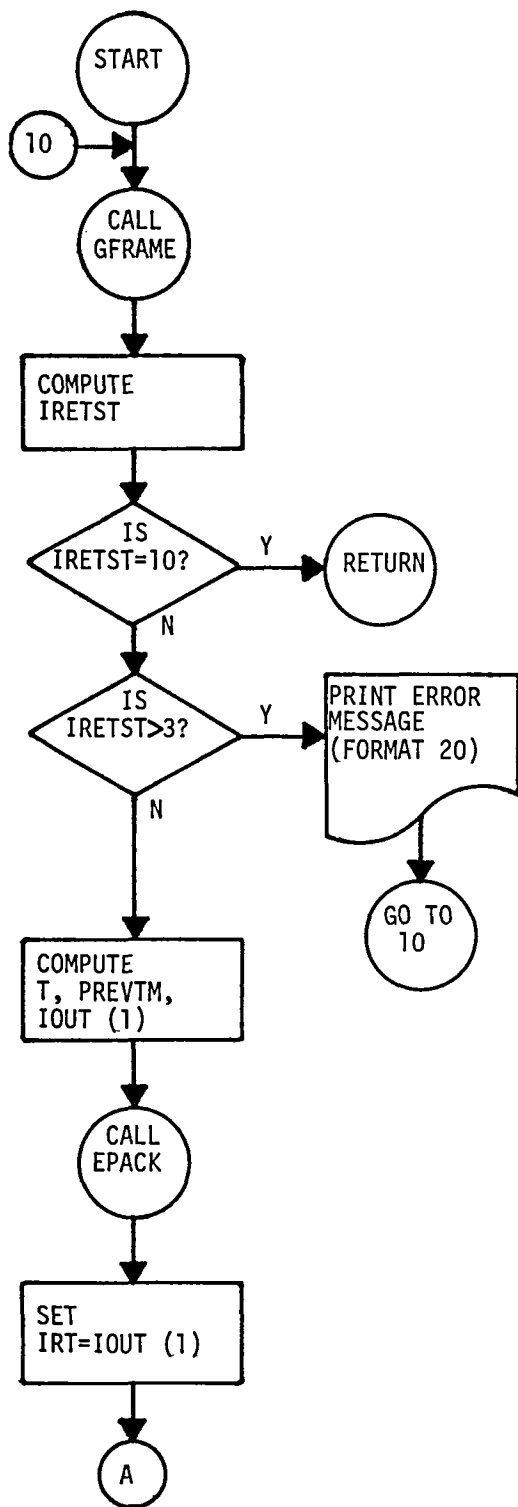
*****OUTPUT -

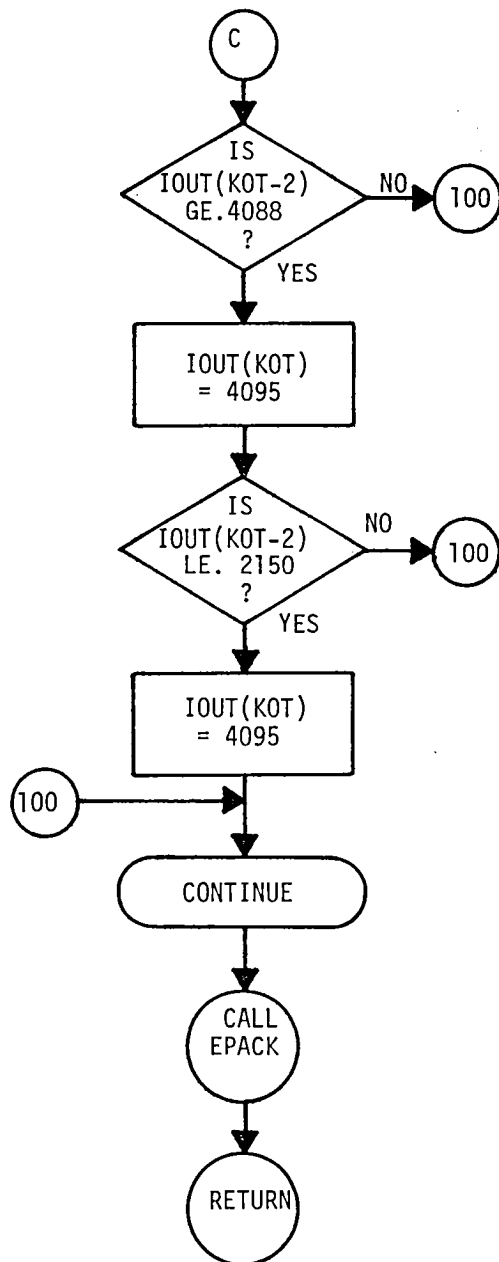
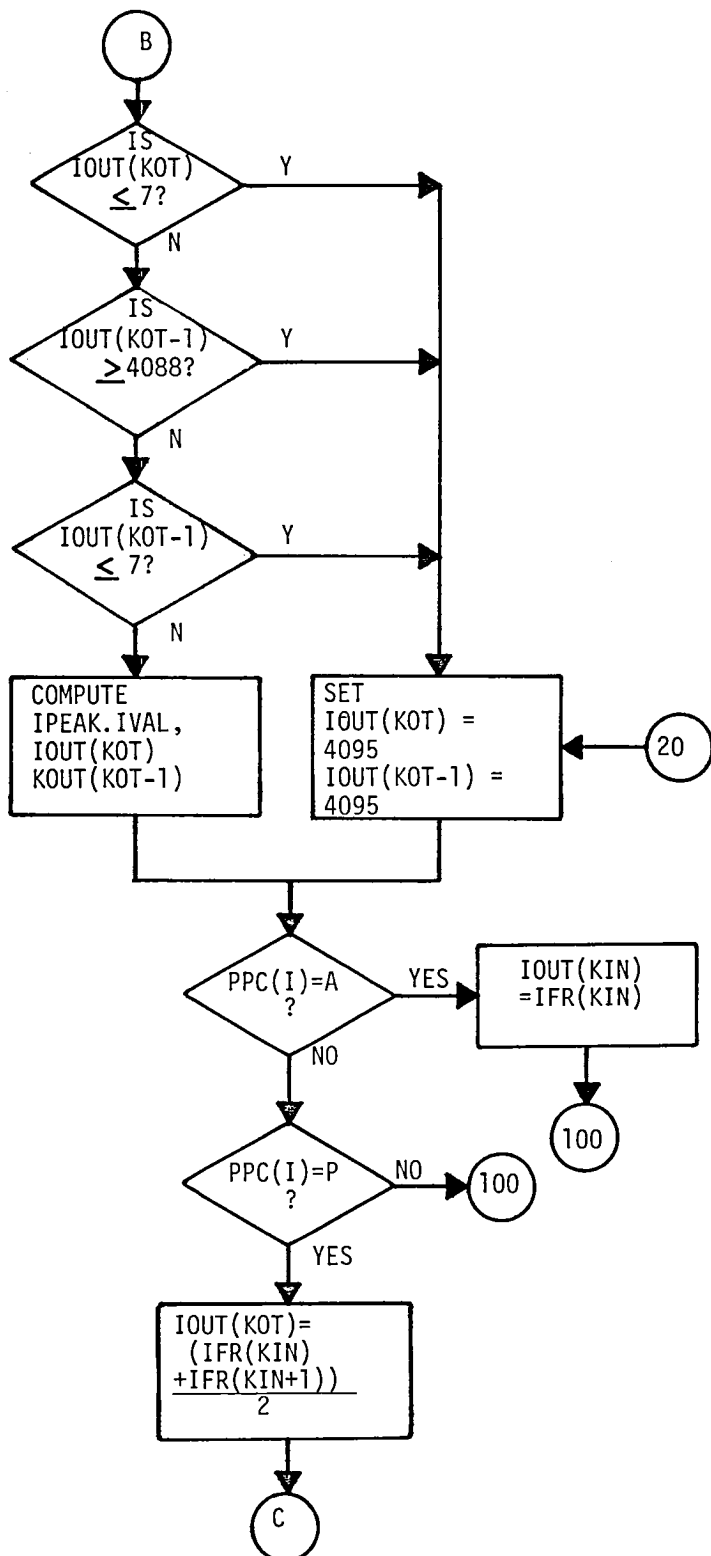
T	-TIME (AIRBOURNE TIME)
IRT	-RUN TONE
	--=511,FULL SCALE
	--=256 OR MORE, RUN TONE IS ON
	--=LESS THAN 256, RUN TONE IS OFF
IRETST	-READ STATUS OF FRAME
	--=1,2, OR 3,GOOD READ
	--=10,END OF FILE ON TAPE
	--=OTHER, ERROR ENCOUNTERED, DATA IGNORED

IOUT	-DECODED DATA ARRAY CONTAINING VIBRATORY AND -STEADY COMPONENTS
IERR	-ERROR RETURN FROM EPACK
IPCK	-PACKED DATA ARRAY FROM EPACK

*****RESTRICTIONS -
NONE

*****SUBPROGRAMS REQUIRED -
GFRAME
EPACK





STAT STATCL-COMPILE STATISTICS
*****SUBROUTINE STATCL*****

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN IV

*****MACHINE - HW 625/635

*****PURPOSE -
 THIS ROUTINE COMPILES AND COMPUTES STATISTICS AND OUTPUTS ONTO
 THE STATISTICS FILE.

*****METHOD -
 STATISTICS ARE ACCUMULATED DURING THE PROCESSING OF A DATA
 BURST. SUCH STATS ARE RUNNING SUM, RUNNING SUM OF SQUARES,
 MAX, MIN, AND BIN COUNT FOR 95 PERCENTILE OF VIBRATORY. AND
 AT THE COMPLETION OF EACH BURST, STATS ARE COMPUTED, STORED
 IN AN ARRAY AND OUTPUT ON STATISTICS FILE IN EVCHK.
 IF THERE IS ONLY ONE DATA POINT OR NO DATA POINTS FOR A BURST,
 NULLS ARE STORED IN THE STATISTICS FOR THAT BURST.

*****INPUT -

MODE	-CODE TO DESIGNATE DATA STATUS --=0, INITIALIZE STATISTICS ARRAY (FIRST FRAME OF - BURST) --=1, STATISTICS BEING ACCUMULATED --=2, FINALIZE STATISTICS (LAST FRAME OF BURST HAS - BEEN STORED)
FRMBF	-FLOATING POINT EQUIVALENT OF DATA ARRAY
NPAR	-NUMBER OF PARAMETERS IN PASS
PPC	-PRE-PROCESSING CODE OF SENSOR
LOC	-40-WORD ARRAY OF LOCATIONS WITHIN FRMBF FOR EACH -PARAMETER
STATBF	-400-WORD STATISTICS BUFFER WITH 10 WORDS FOR EACH -OF 40 PARAMETERS FOR BURST
STATBF(1)	-MAXIMUM
STATBF(2)	-CORRESPONDING VIBRATORY FOR MAXIMUM STEADY OR -CORRESPONDING STEADY FOR MAXIMUM VIBRATORY
STATBF(3)	-MINIMUM

STATBF(4) -CORRESPONDING VIBRATORY FOR MINIMUM STEADY OR
-CORRESPONDING STEADY FOR MINIMUM VIBRATORY

STATBF(5) -MEAN

STATBF(6) -STANDARD DEVIATION

STATBF(7) -95 PERCENTILE

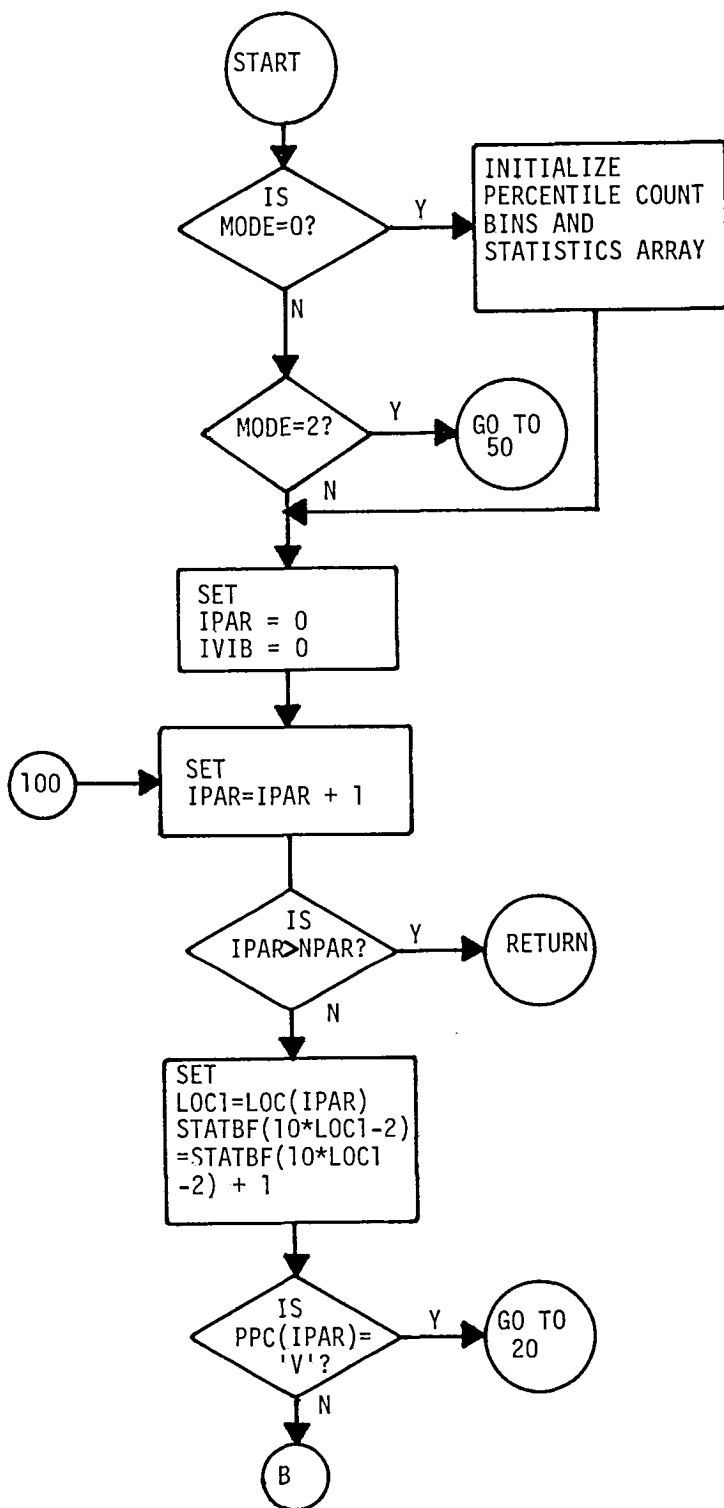
STATBF(8) -NUMBER OF POINTS IN BURST

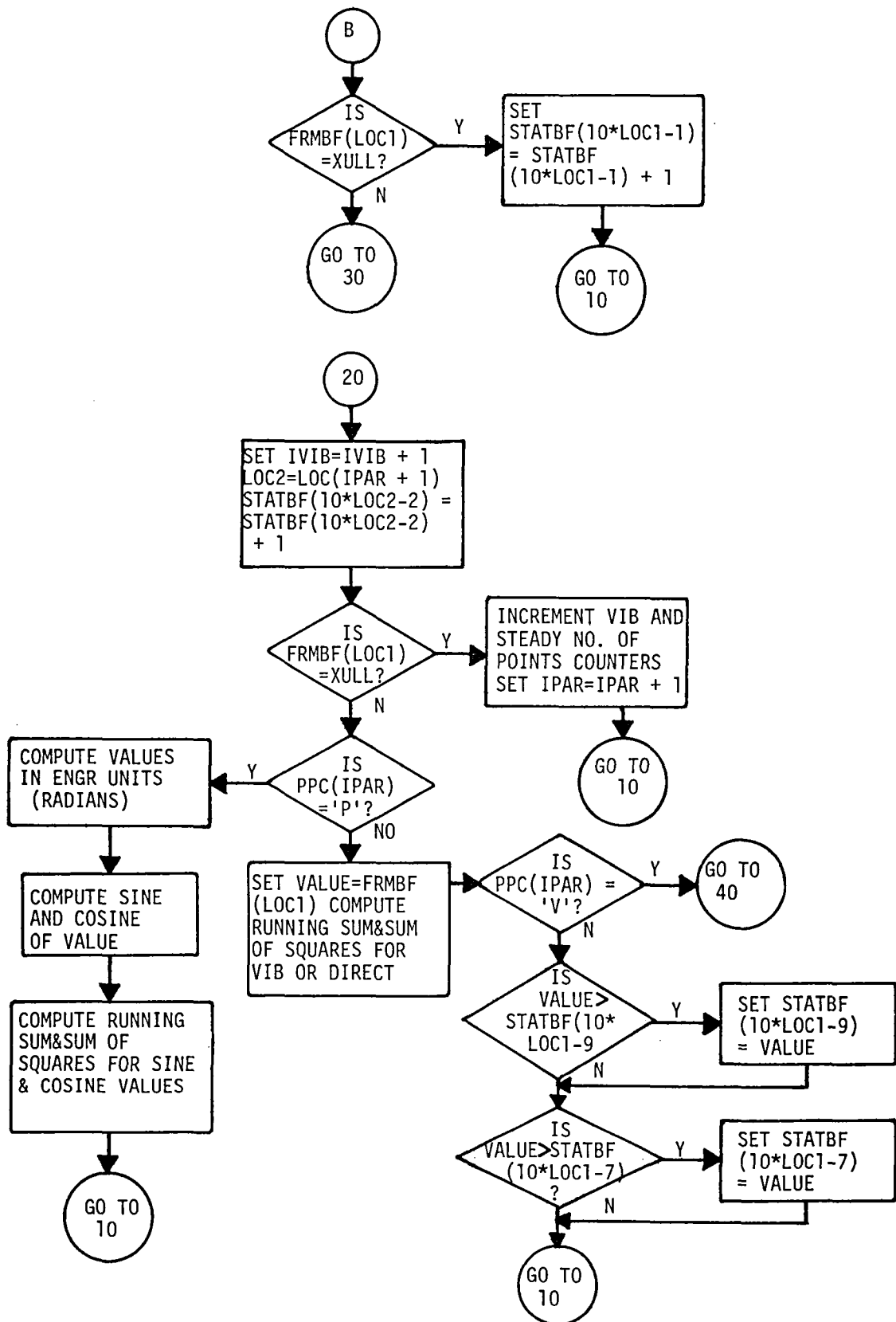
STATBF(9) -NUMBER OF ERROR POINTS

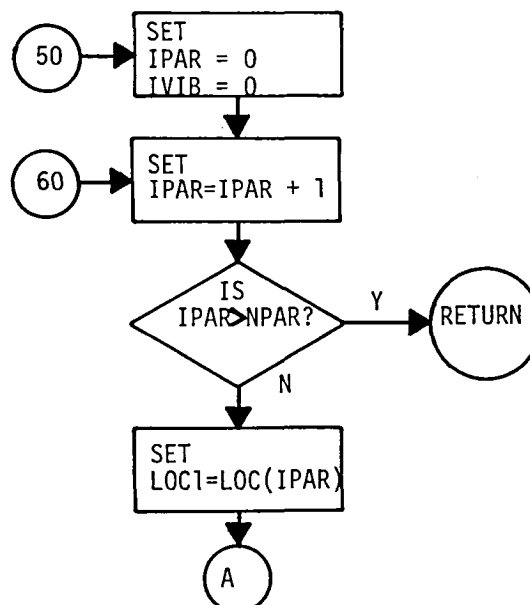
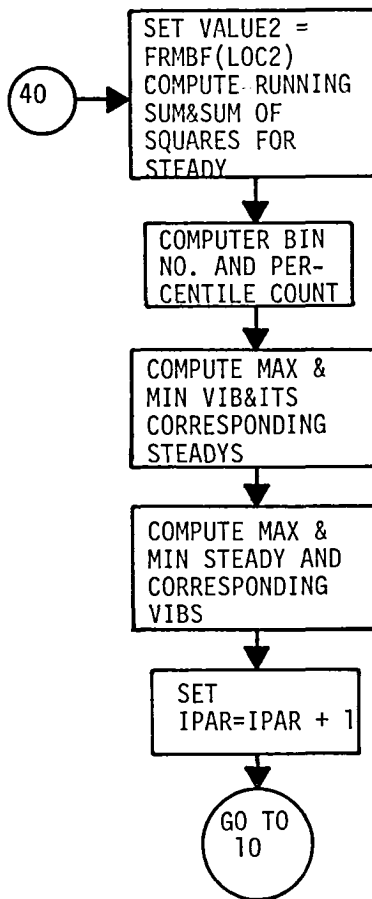
STATBF(10) -ERROR CODE (OUTPUT FROM EPACK)

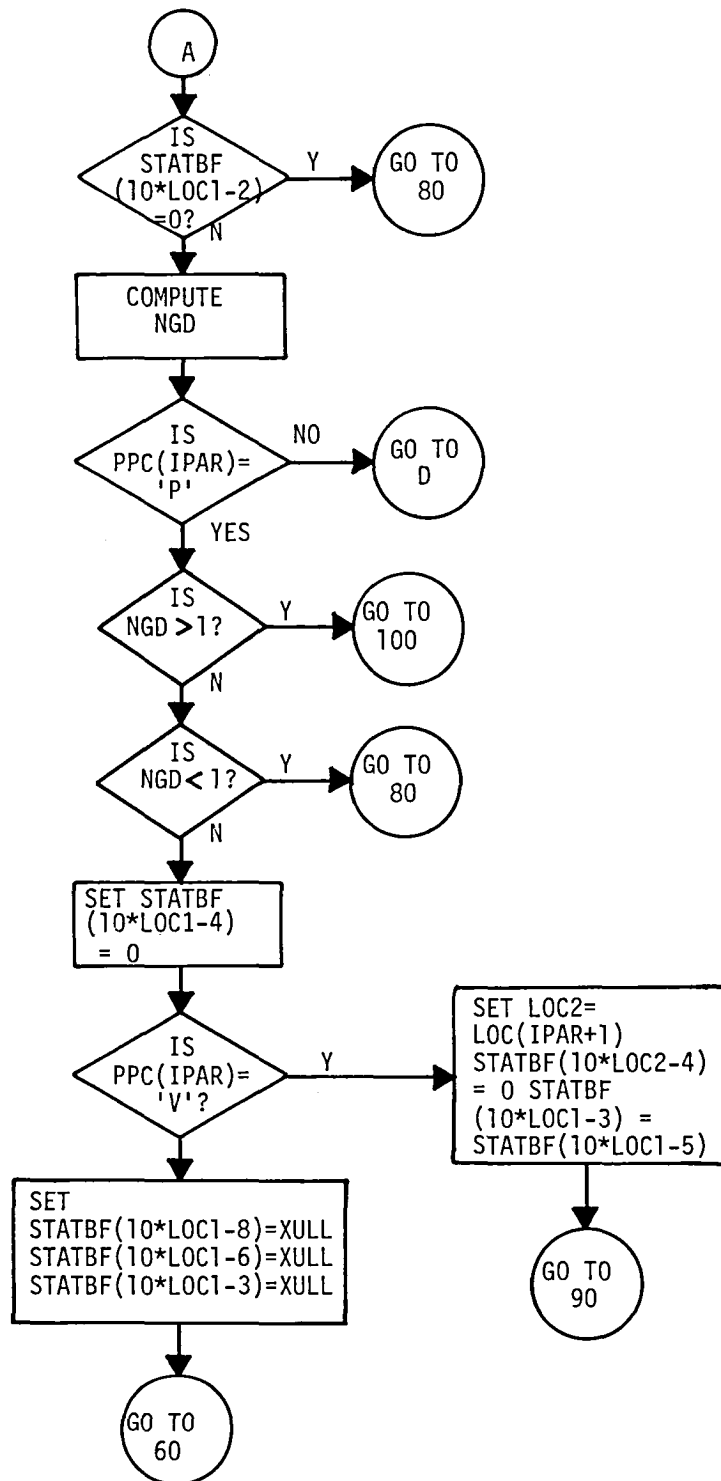
*****RESTRICTIONS -
NONE

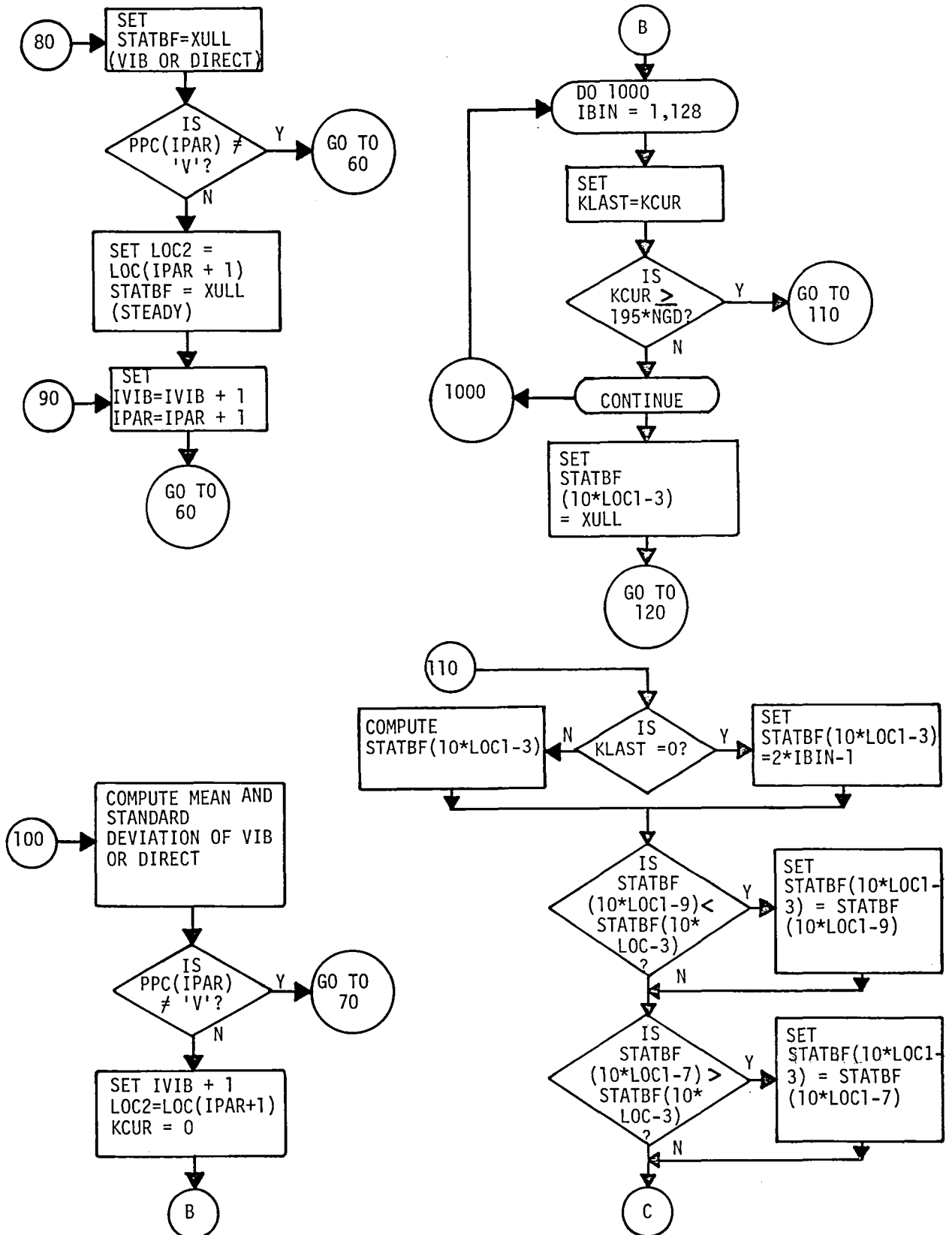
*****SUBPROGRAMS REQUIRED -
NONE

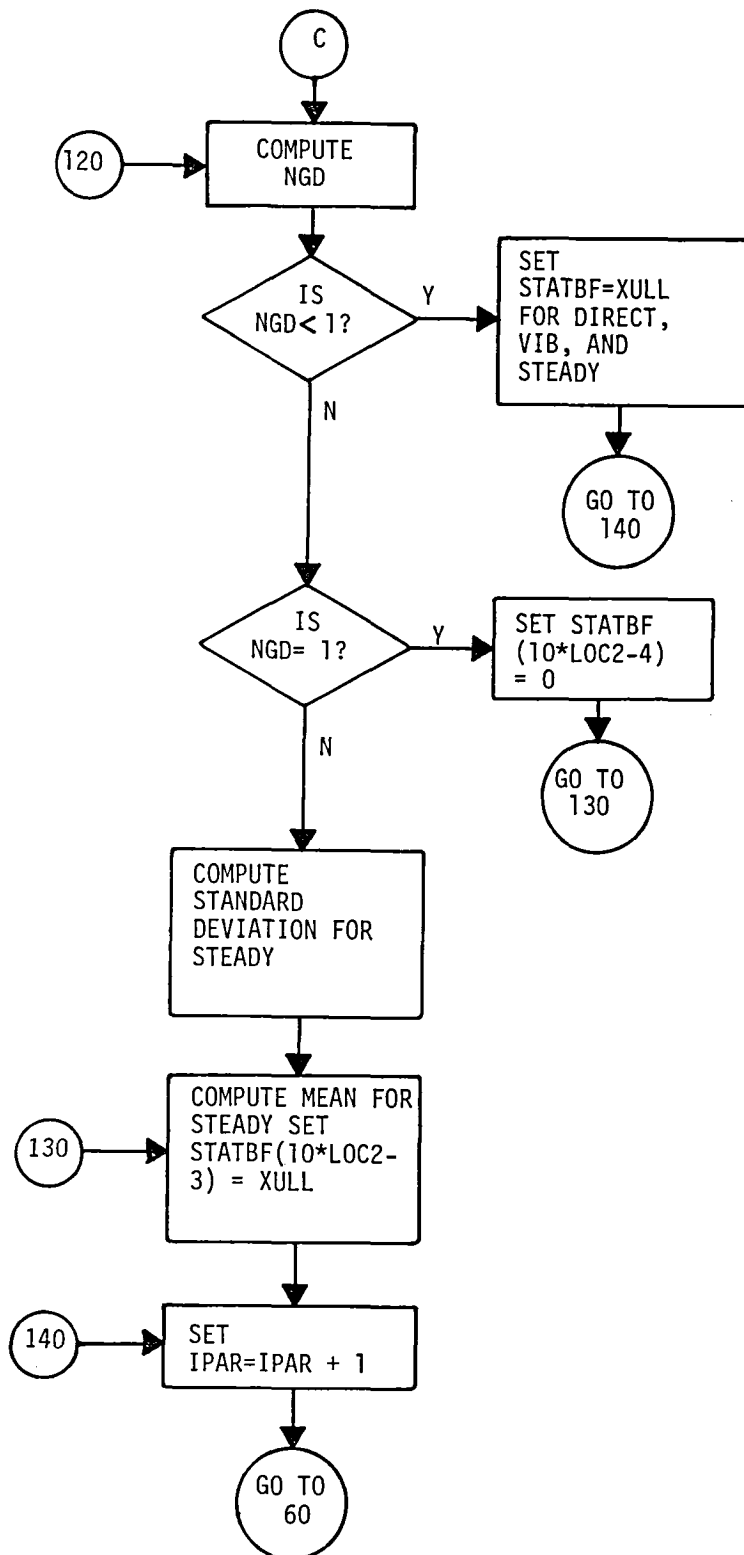


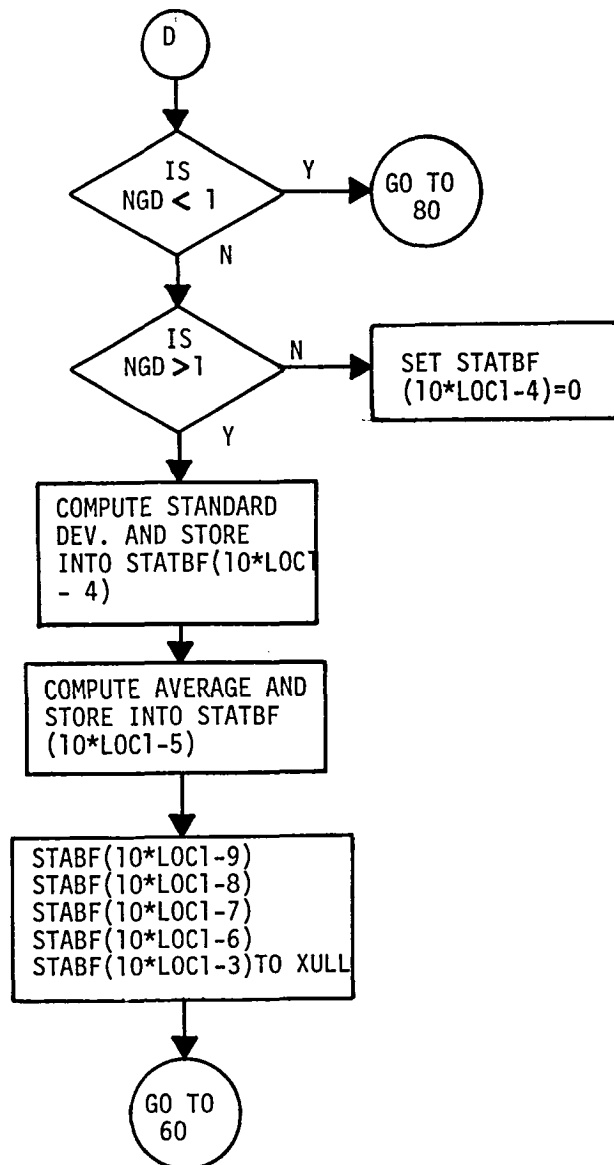












WRTR WRTRDF-OUTPUT DATA ON TAPE
*****SUBROUTINE WRTRDF*****

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN IV

*****MACHINE - HW 625/635

*****PURPOSE -
THIS ROUTINE OUTPUTS PASS DATA RECORDS ONTO PASS FILES.

*****METHOD -
TIME, PACKED DATA, EVENT NUMBER, AND NUMBER OF FRAMES FOR EACH
PASS ARE STORED INTO AN ARRAY AND OUTPUT ONTO A PASS FILE FOR
EACH PASS.

*****INPUT -

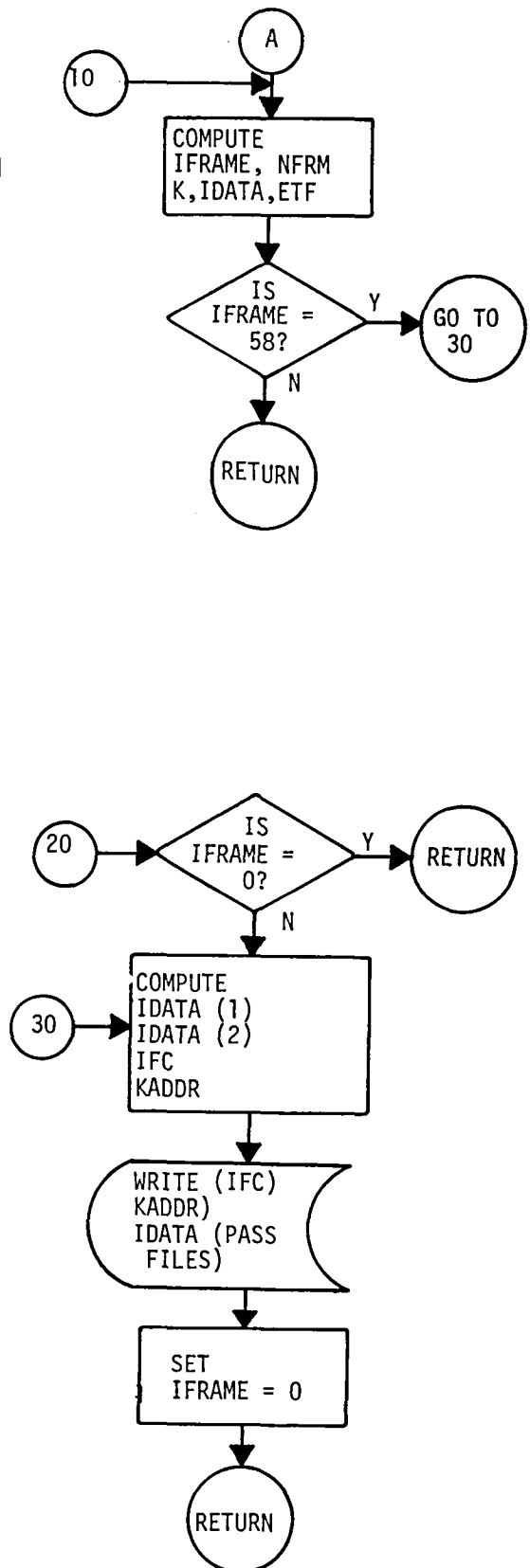
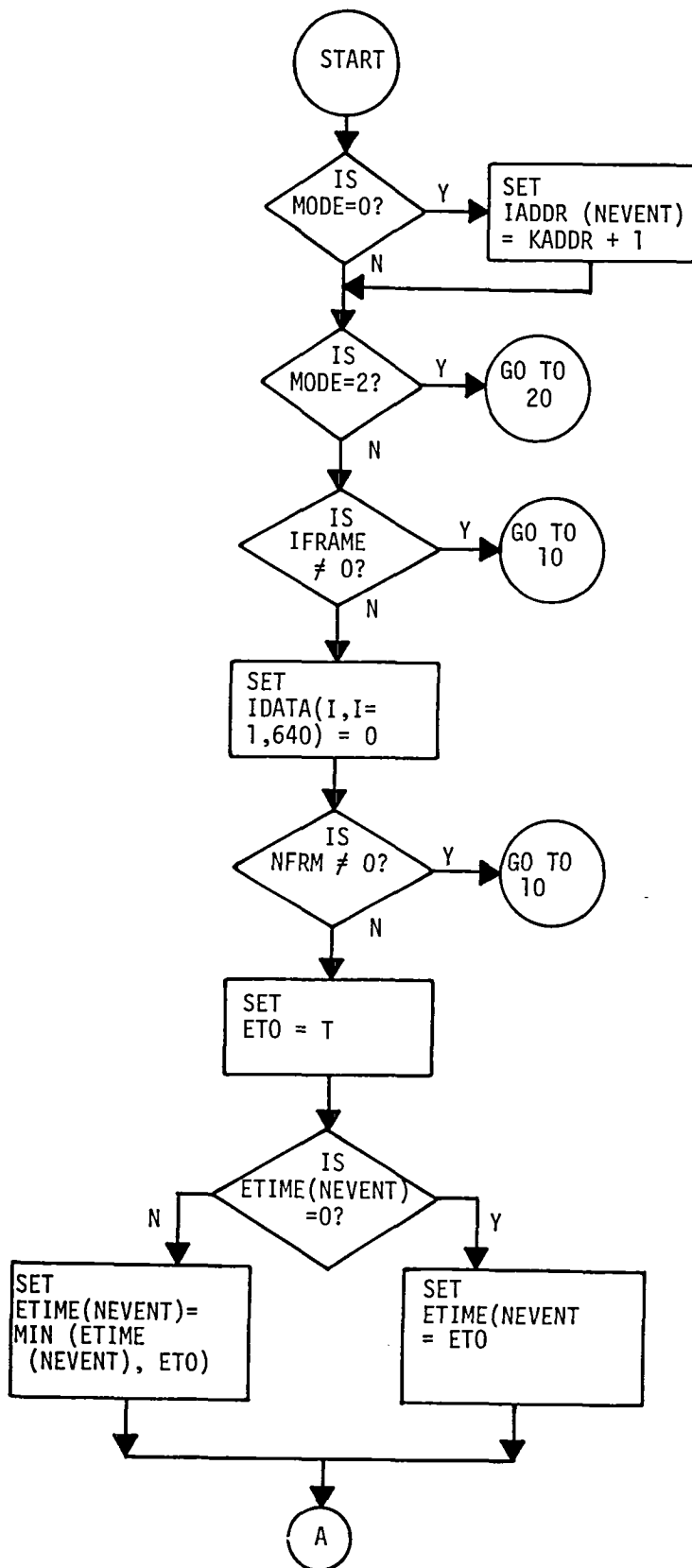
T	-TIME
IPCK	-PACKED DATA ARRAY FROM EPACK
NGVENT	-MANEUVER NUMBER
NPASS	-PASS NUMBER BEING PROCESSED
MODE	-CODE TO DESIGNATE DATA STATUS --=0, INITIALIZE BEGINNING OF DATA --=1, DATA BEING ACCUMULATED --=2, FINALIZE DATA

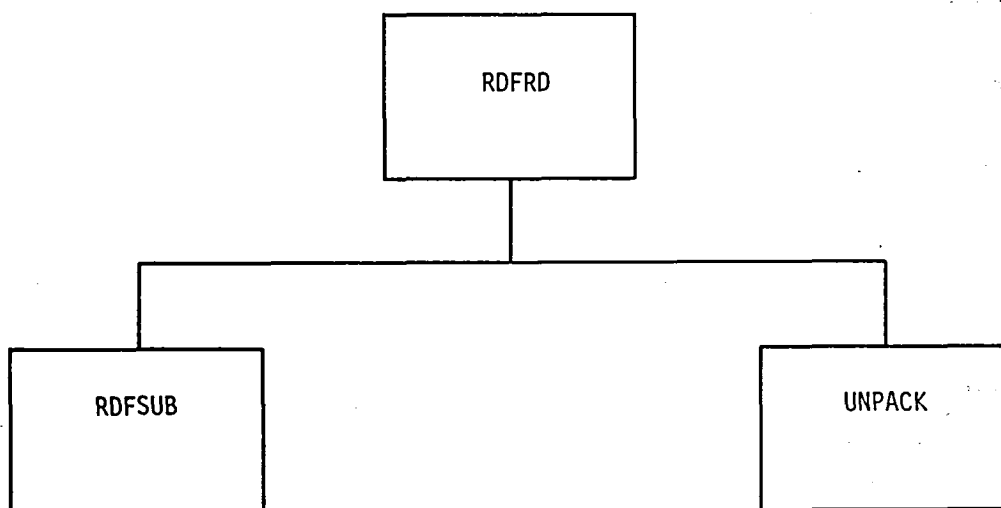
*****OUTPUT -

IFRAME	-COUNTER OF CURRENT FRAME POSITION ON OUTPUT DATA -FILE RECORD
KADDR	-CURRENT ADDRESS OF DATA FILE RECORD FOR NPASS
NFRM	-NUMBER OF FRAMES OF DATA FOR BURST
ETO	-START TIME OF BURST
ETF	-STOP TIME OF BURST
IDATA	-OUTPUT RECORD CONTAINING TIME, PACKED DATA, EVENT -NUMBER, AND NUMBER OF FRAMES FOR PASS

*****RESTRICTIONS -
NONE

*****SUBPROGRAMS REQUIRED -
NONE





RDFR RDFRD SUBROUTINE
*****SUBROUTINE RDFRD*****

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN Y

*****MACHINE - HW 625/635

*****PURPOSE -
THIS ROUTINE ACCESSES INFORMATION FROM RAW DATA FILES AND
RAW STATISTICS FILES AS PRODUCED THROUGH SCAN PROGRAM.

*****METHOD -
THIS ROUTINE WILL EXTRACT DATA FOR A GIVEN SET OF PARAMETERS
ACCORDING TO INPUT ARGUMENTS TO THIS ROUTINE AND RETURN THEM
TO THE CALLING ROUTINE.

*****INPUT -

ITOS	--0, WHEN INITIAL CALL WITH GIVEN SET OF PARAMETER SPECS WHICH MUST BE USED TO SEARCH SENSOR TABLE --1, WHEN PREVIOUS CALL WITH SAME SET OF PARAMETER SPECS HAS BEEN USED TO DEFINE TABLE OF SUBSCRITS ARGUMENT (TOS) THUS AVERTING SEARCH OF SENSOR TABLE
ITYPE	--0, DATA SAMPLES ARE BEING REQUESTED --1, STATISTICS ARE BEING REQUESTED --1, STATISTICS ARE BEING REQUESTED
ICONV	--0, RESULTS ARE TO BE IN RAW UNITS --1, RESULTS ARE TO BE IN ENGINEERING UNITS
IRUN	-RUN (EVENT) NUMBER REQUESTED
NPAR	-NUMBER OF PARAMETERS REQUESTED
NPAR	-NUMBER OF PARAMETERS REQUESTED
NAMES	-PARAMETER MNEMONICS
PPC	-PARAMETER PRE-PROCESSING CODES
SR	-PARAMETER SAMPLE RATE
ISMPL	-BEGINNING SAMPLE NUMBER REQUESTED, IF DATA
LSMPL	-ENDING SAMPLE NUMBER REQUESTED, IF DATA
ISZBUF	-SIZE OF OUTBUF

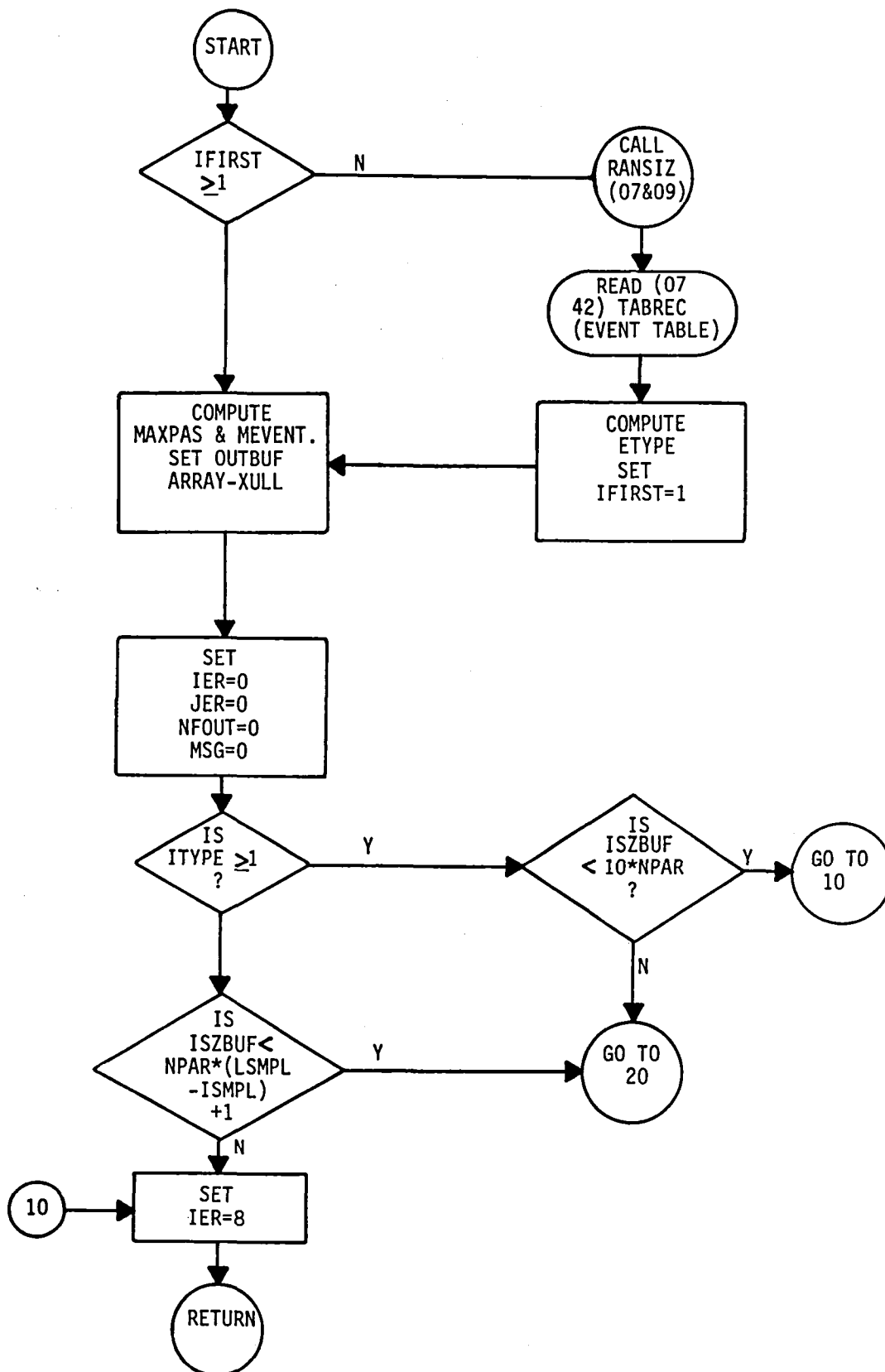
TOS -TABLE OF SUBSCRIPTS, 4 WORDS PER PARAMETER, BUILT
 -WITHIN ROUTINE WHEN ITOS = 0 FOR POSSIBLE
 -SUBSEQUENT CALLS WITH SAME SET OF PARAMETER SPECS
 TOS(1) -PASS NUMBER
 TOS(2) -ELEMENT NUMBER
 TOS(3) -A TERM
 TOS(4) -B TERM

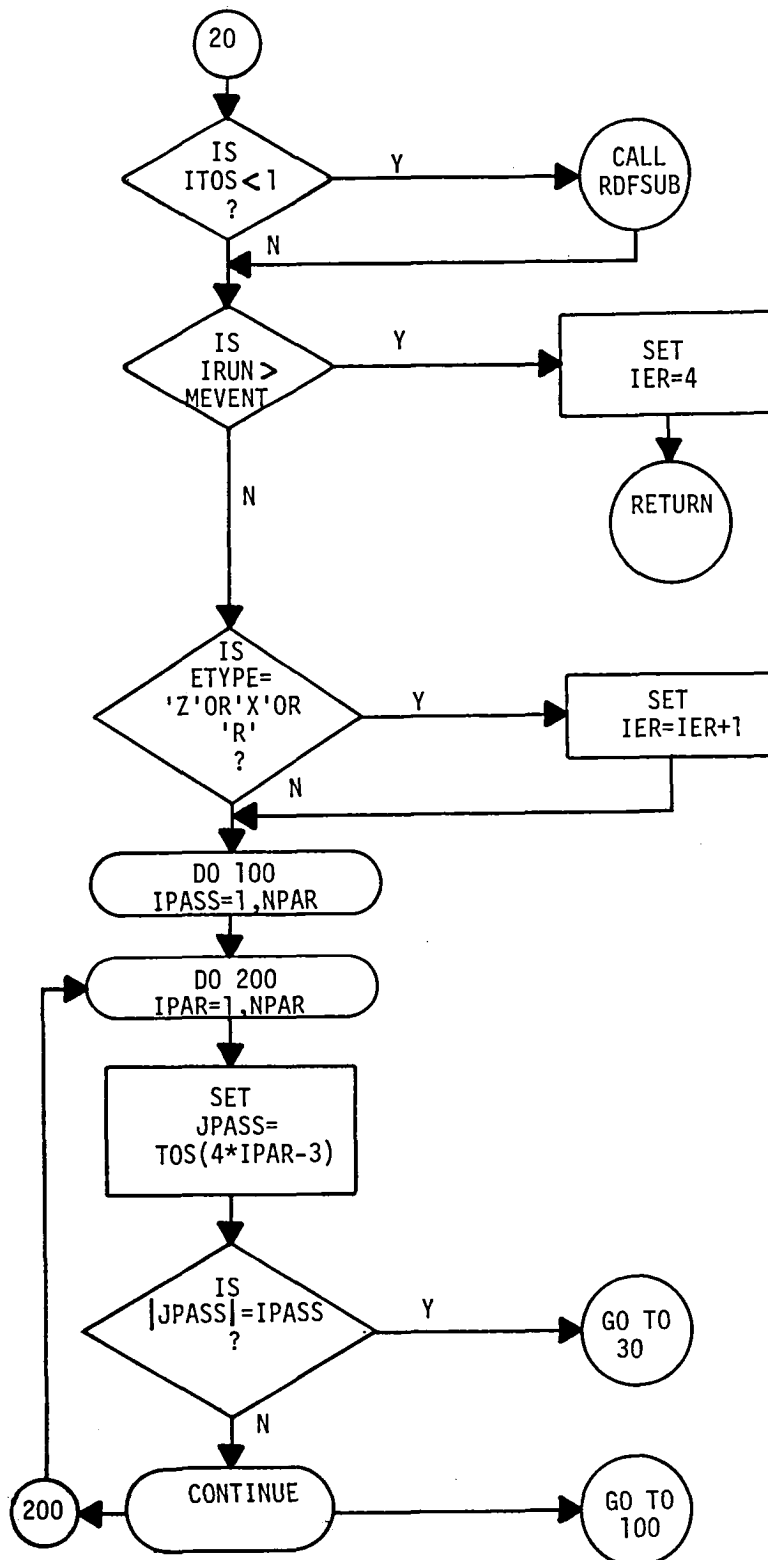
*****OUTPUT -

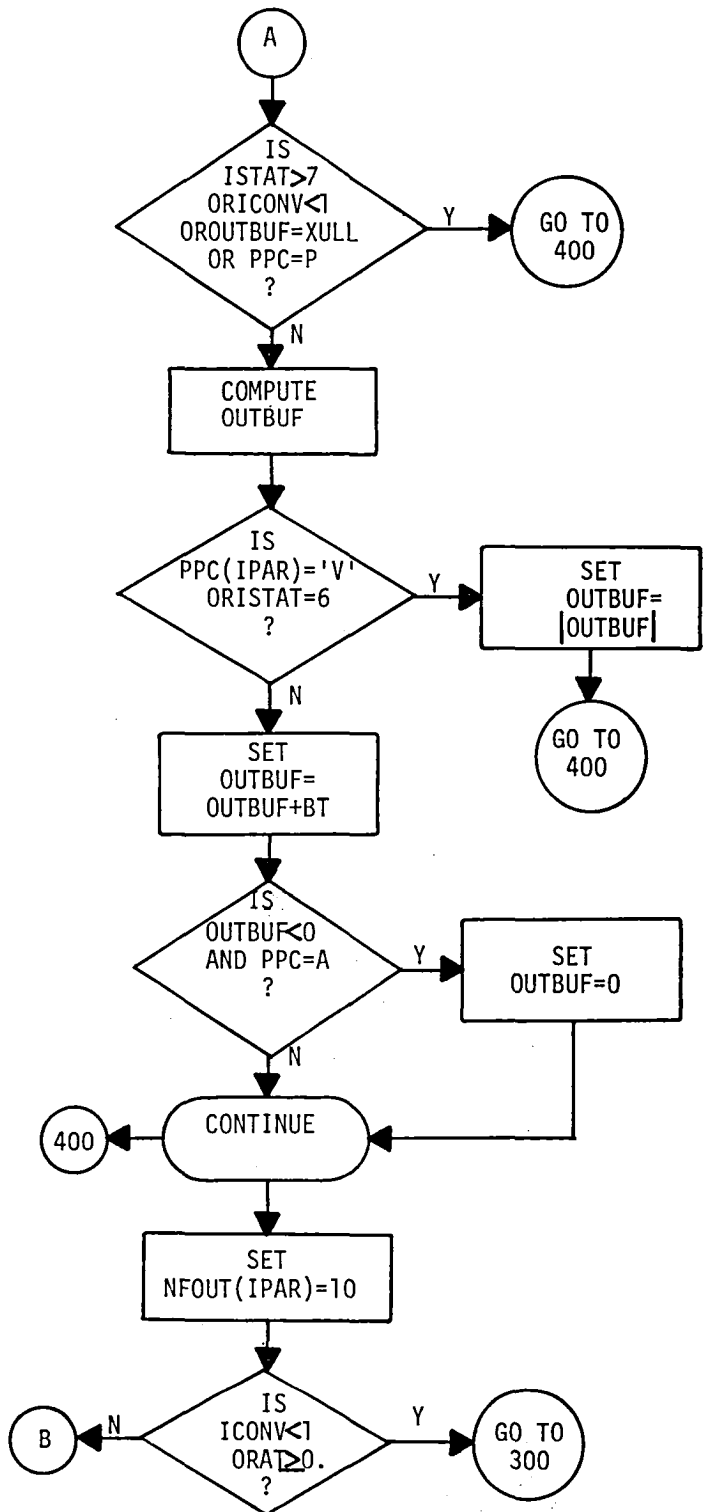
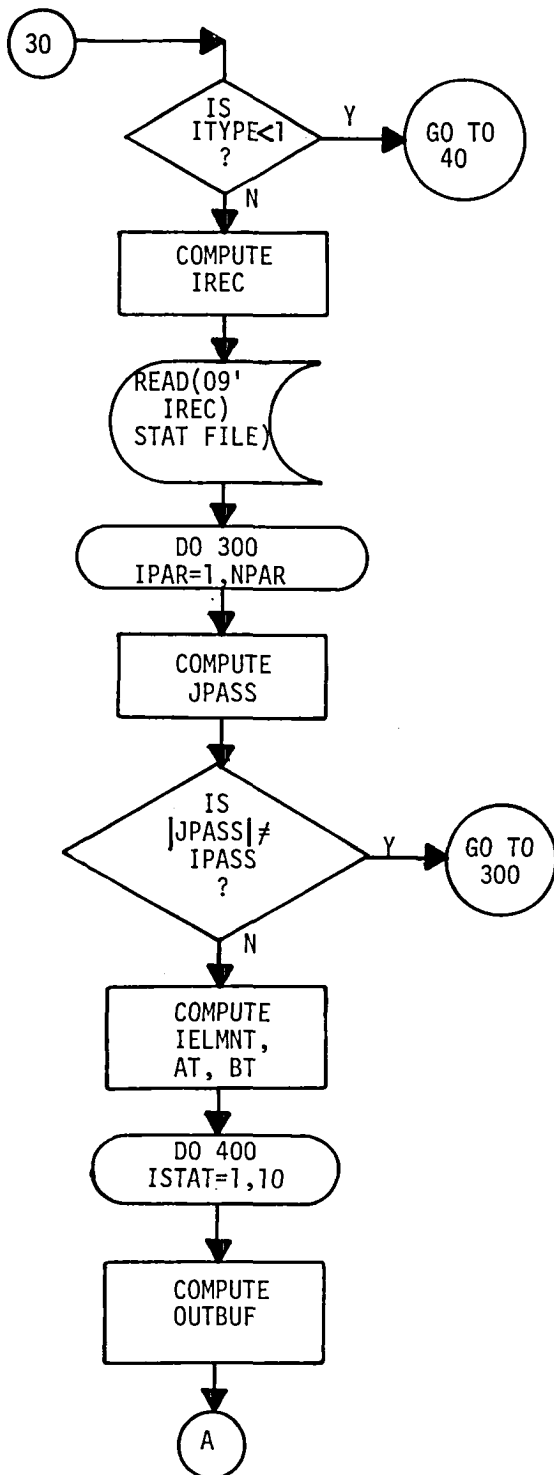
OUTBUF -OUTPUT BUFFER FOR DATA OR STATISTICS
 ISZBUF -SIZE OF OUTBUF
 NFOUT -OUTPUT ARRAY OF ACTUAL NUMBER OF FRAMES RETURNED
 -FOR EACH PARAMETER
 MSG -ARRAY OF OUTPUT PARAMETER MESSAGES WHEN ASKING
 -FOR DATA
 --0,NO ERRORS
 --1,LESS DATA RETURNED THAN REQUESTED BECAUSE
 - ENDING SAMPLE REQUESTED IS GREATER THAN LAST
 - SAMPLE AVAILABLE
 --2,BEGINNING SAMPLE REQUESTED IS GREATER THAN LAST
 - SAMPLE AVAILABLE
 IER -OUTPUT ERROR CODE DETERMINED AS THE SUM OF THE
 -FOLLOWING INDIVIDUAL CODES
 --0,NO ERRORS
 --1,CAL RUN REQUESTED
 --2,PARAMETER LEVEL ERRORS EXIST
 --4,NO SUCH RUN
 --8,BUFFER SIZE ERROR

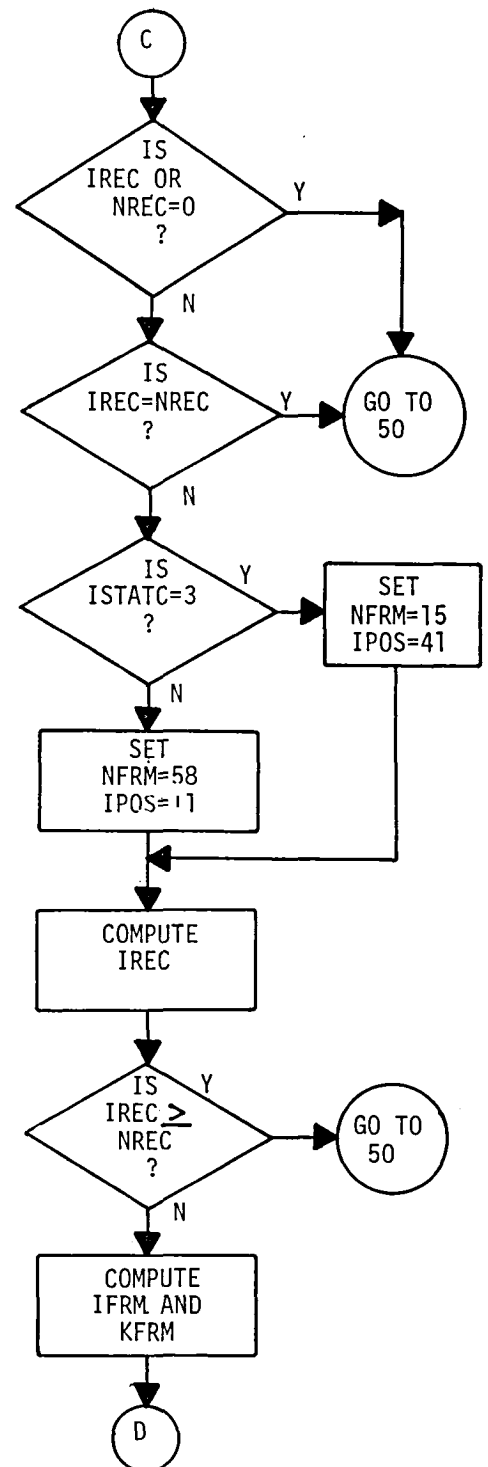
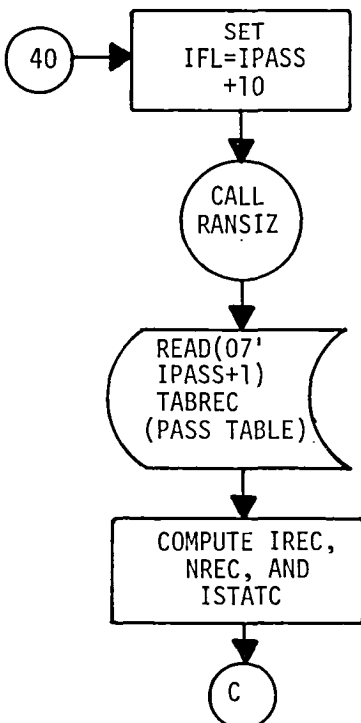
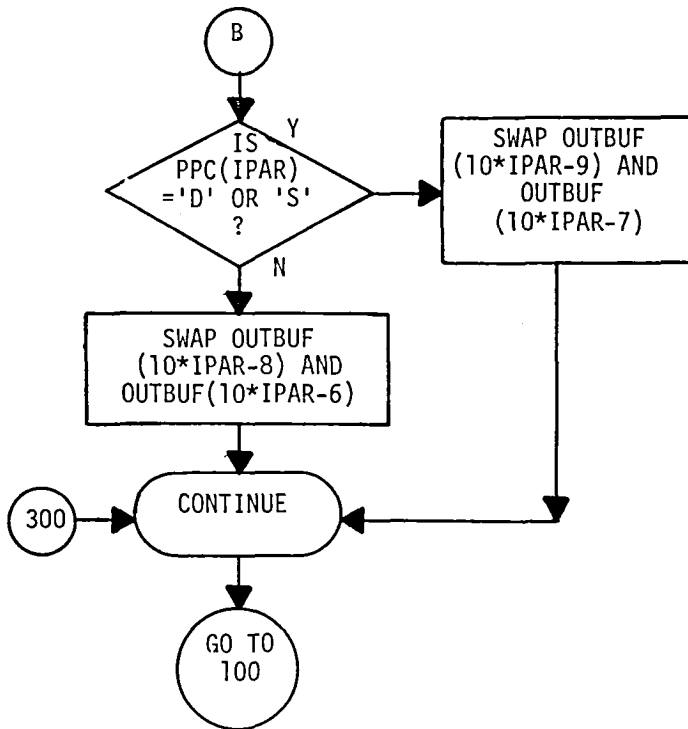
*****RESTRICTIONS -
 NONE

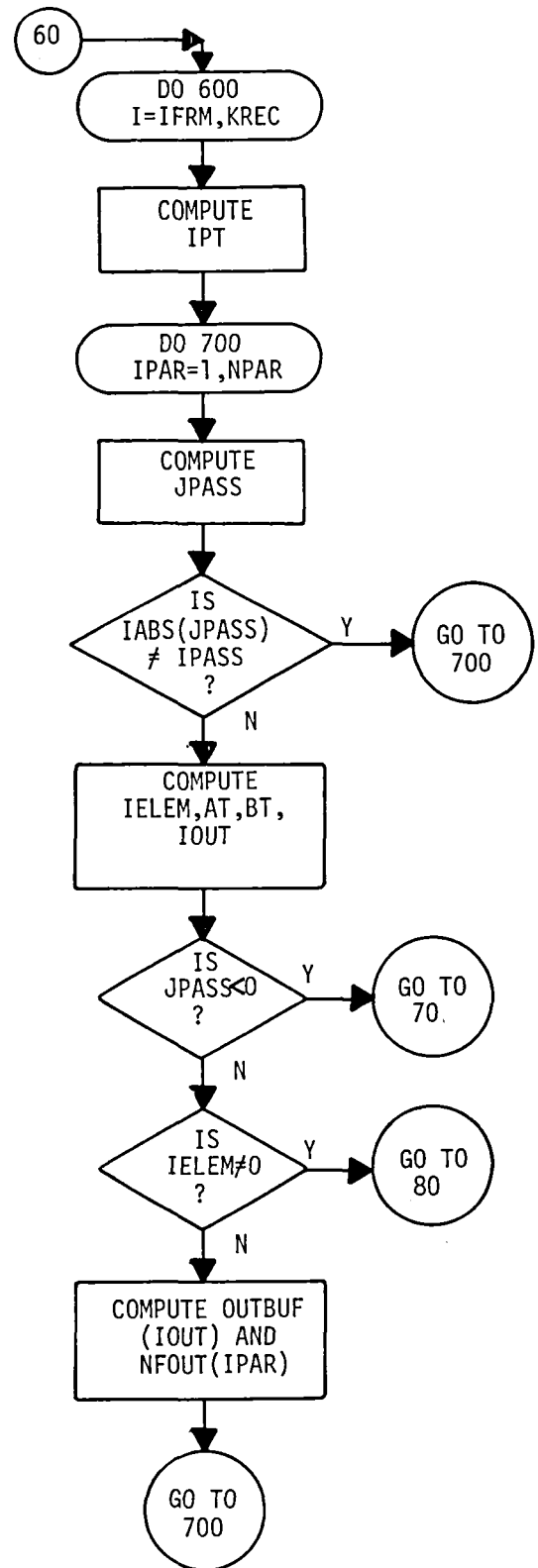
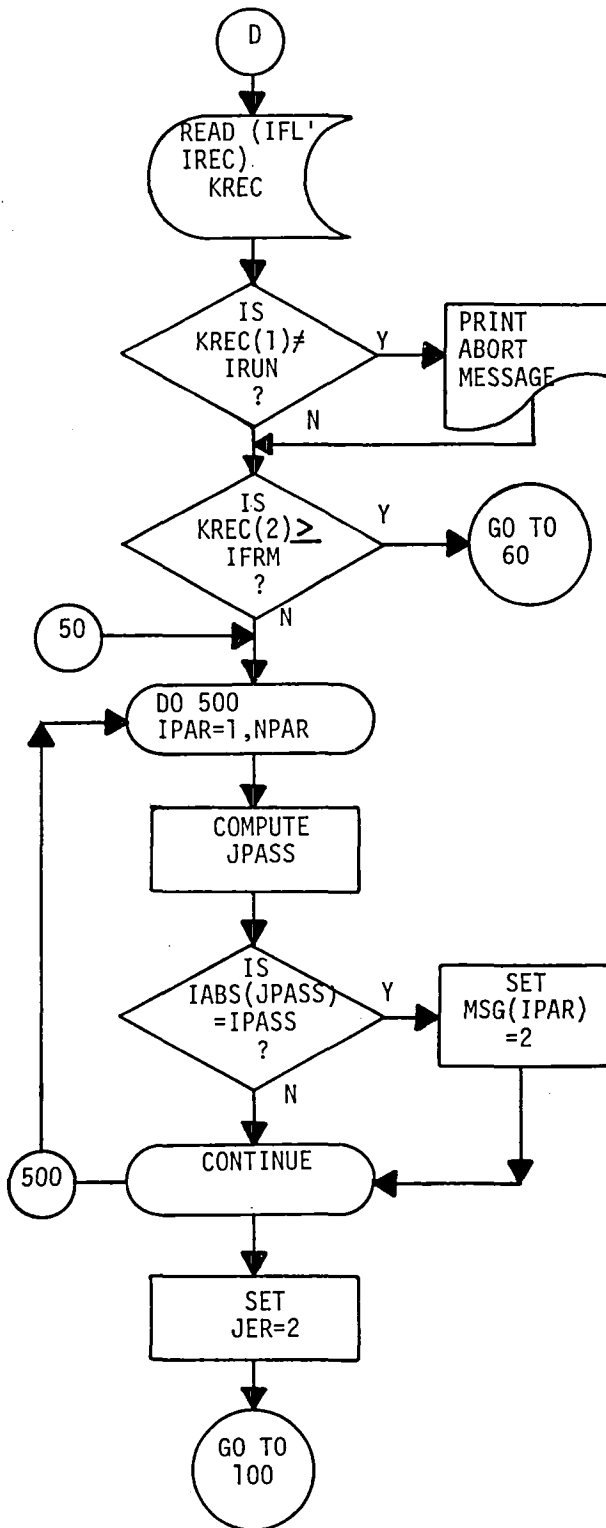
*****SUBPROGRAMS REQUIRED -
 RDFSUB
 UNPACK

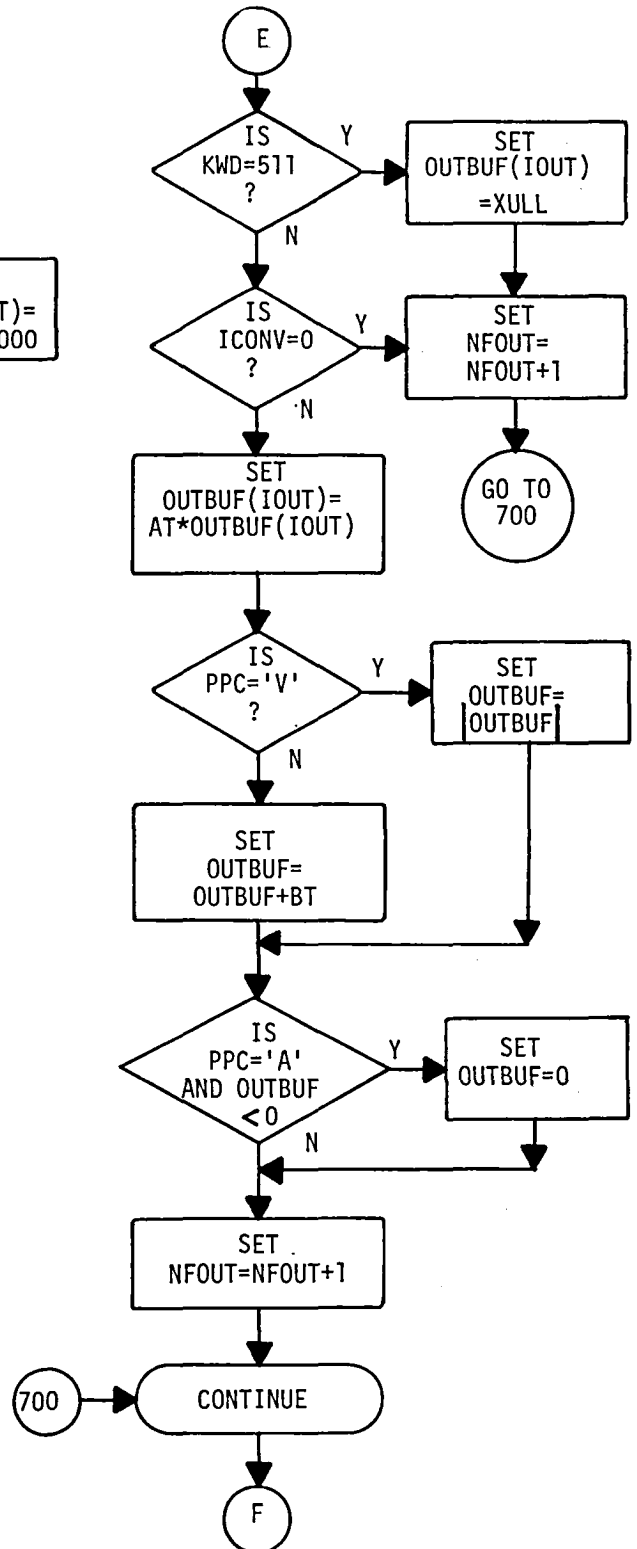
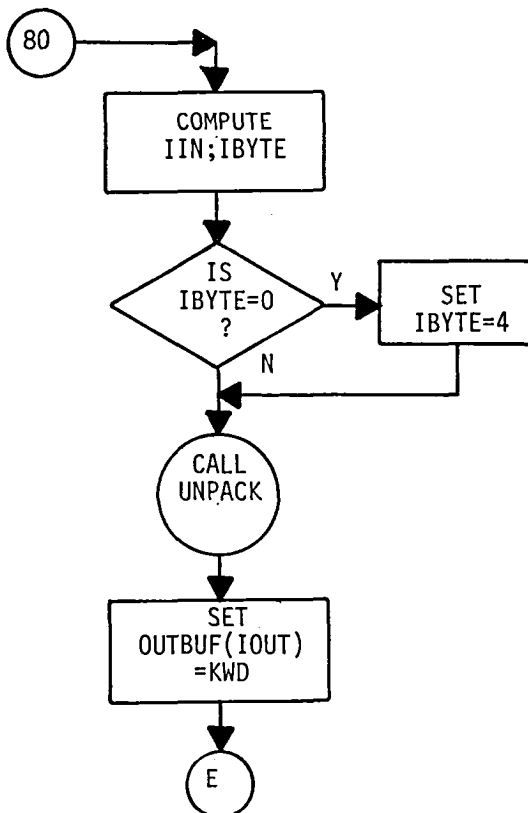
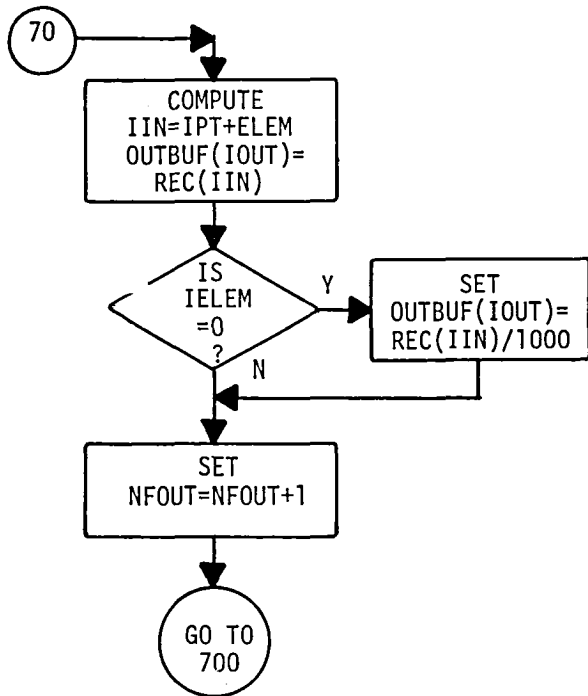


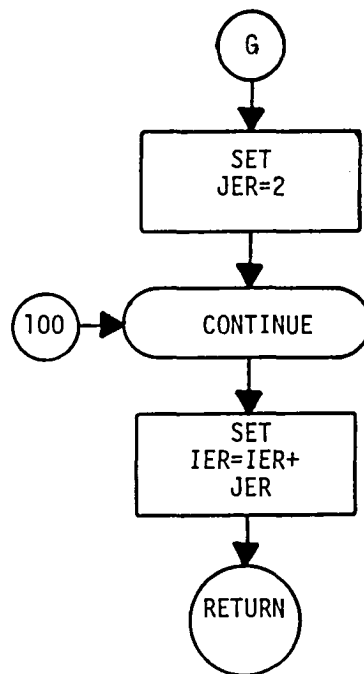
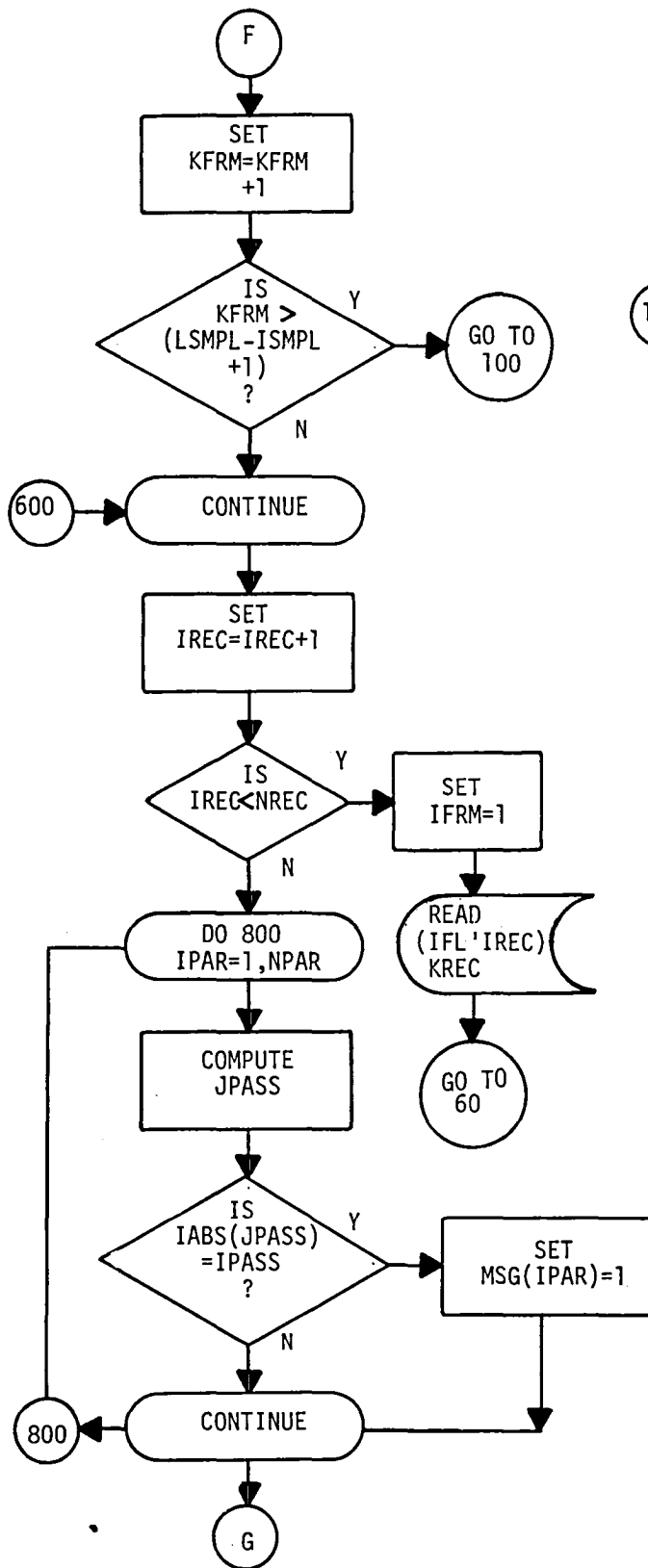












RDFS*****SUBROUTINE RDFSUB*****

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN Y

*****MACHINE - HW 625/635

*****PURPOSE -
BUILD A TABLE OF SUBSCRIPTS TO BE USED IN RDFRD.

*****METHOD -
GIVEN A SET OF NAMES, PPC, AND SR THE PASS AND SENSOR TABLES
ARE READ TO FIND WHICH PASS AND PARAMETER NUMBERS CORRESPOND.
THESE ARE OUTPUT TO THE SUBSCRIPT ARRAY (TOS) IN CONJUNCTION
WITH THE ENGINEERING UNIT CONVERSION FACTORS. IF A SEARCH
OF THE PASS AND SENSOR TABLES DOES NOT FIND A MATCH, TOS
VALUES ARE RETURNED AS ZEROES.

*****INPUT -

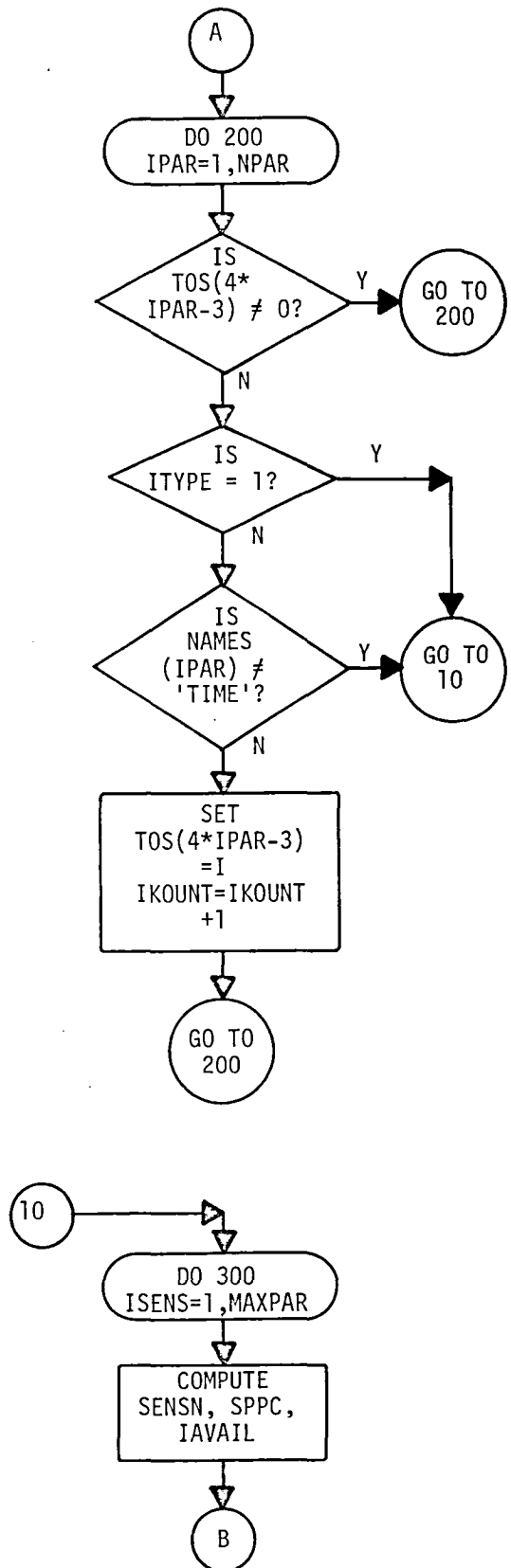
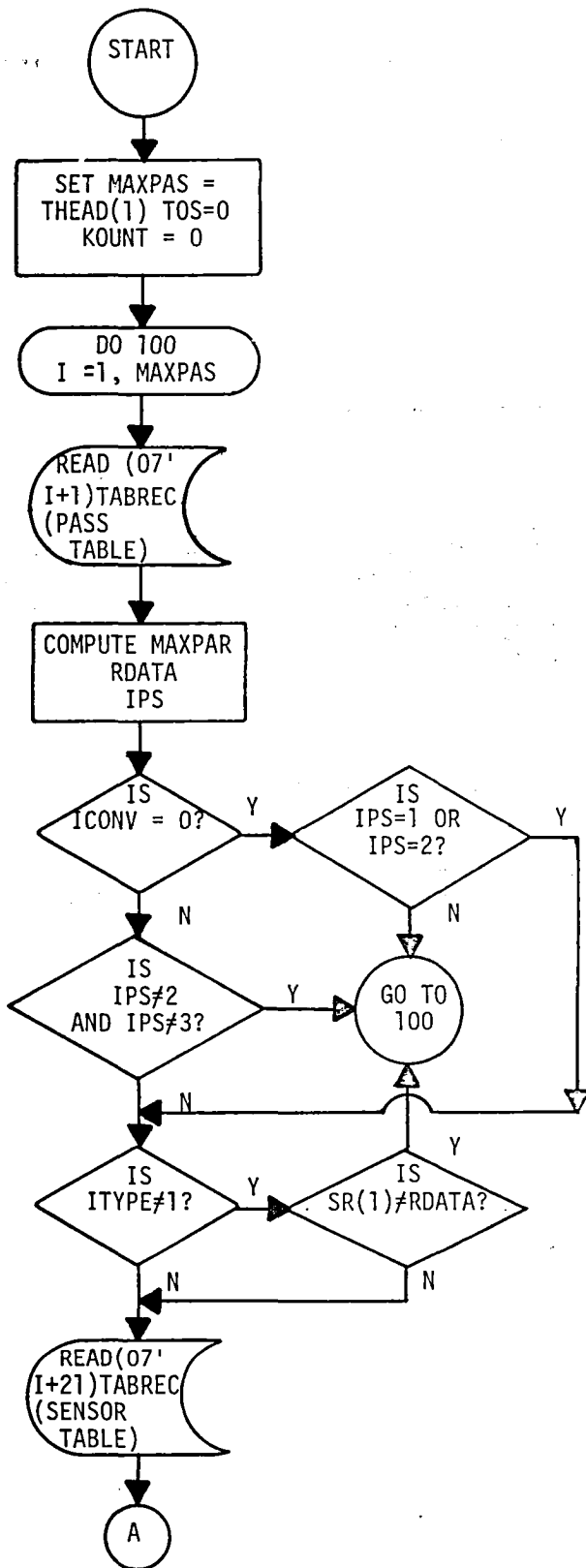
ITYPE	--0, DATA SAMPLES ARE REQUESTED --1, STATISTICS ARE REQUESTED
ICONV	--0, RESULTS ARE TO BE IN RAW UNITS --1, RESULTS ARE TO BE IN ENGINEERING UNITS
NPAR	-NUMBER OF PARAMETERS REQUESTED
NAMES	-PARAMETER MNEMONIC
PPC	-PARAMETER PRE-PROCESSOR CODE
SR	-PARAMETER SAMPLE RATE

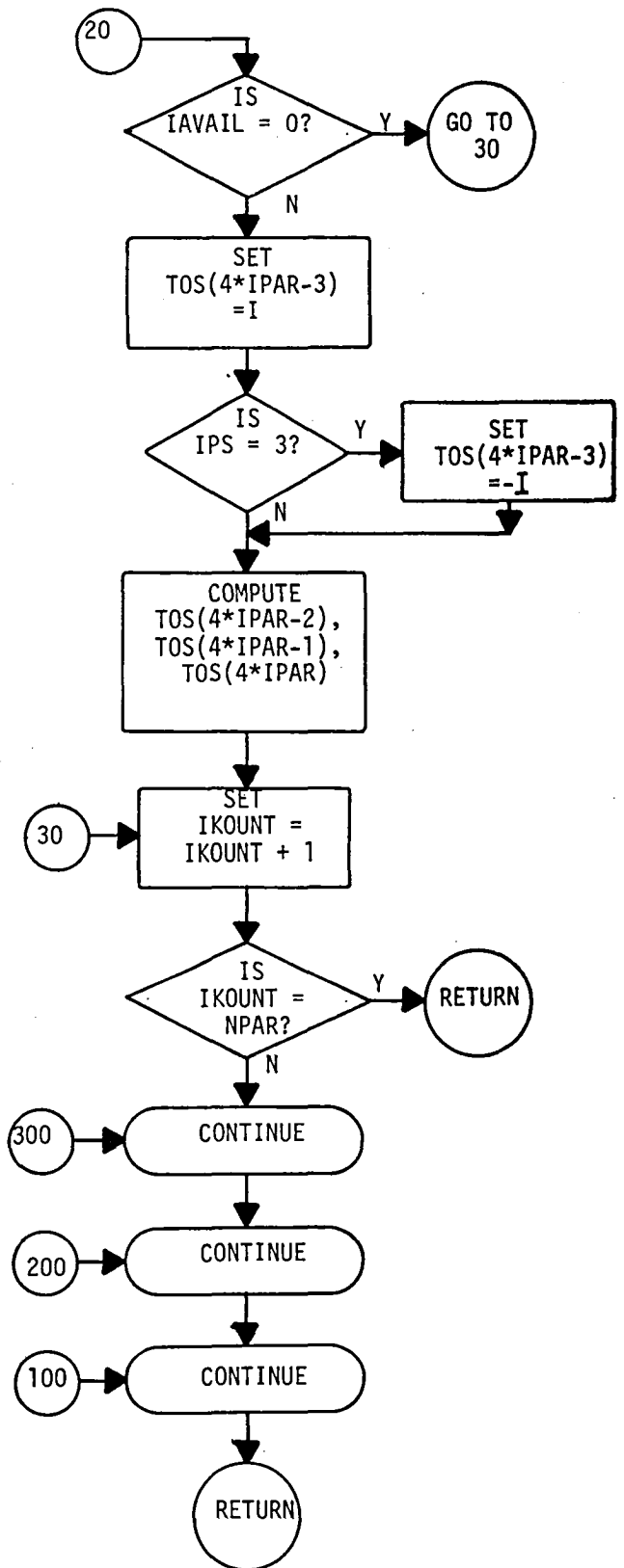
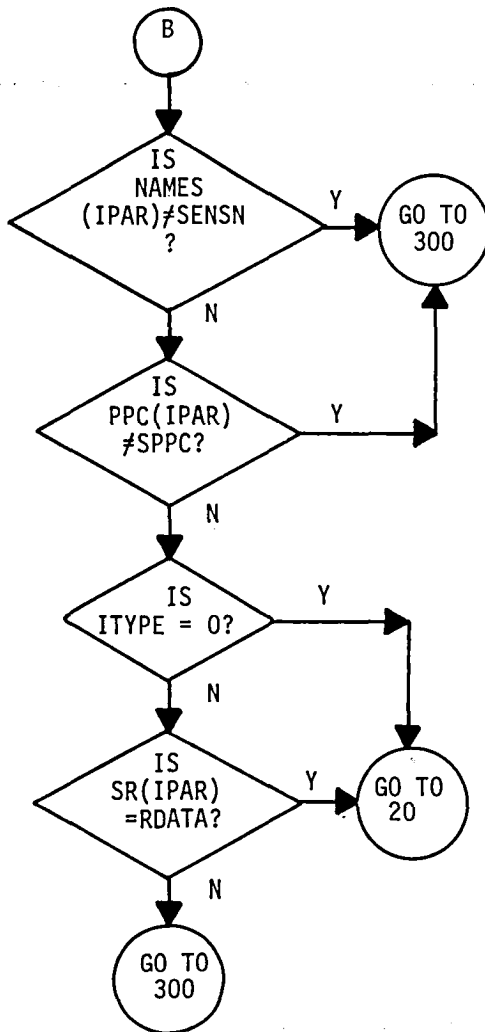
*****OUTPUT -

TOS	-(SEE RDFRD INPUT)
-----	--------------------

*****RESTRICTIONS -
NONE

*****SUBPROGRAMS REQUIRED -
NONE





***** SUBROUTINE UNPACK *****

PROGRAM IDENTIFICATION

PROGRAM NAME - UNPACK
PROGRAM NO. - 1.1.2320
AUTHOR - DAVID L. DAVIS

COMPUTER - HW 625/635
MEMORY - 70 WORDS
PERIPHERALS - NONE
LANGUAGE - GMAP

PURPOSE

TO UNPACK 40 DATA VALUES FROM
A 10 WORD ARRAY (4 DATA VALUES
PER WORD) IN A 40 WORD ARRAY
(ONE DATA VALUE PER WORD).

METHOD

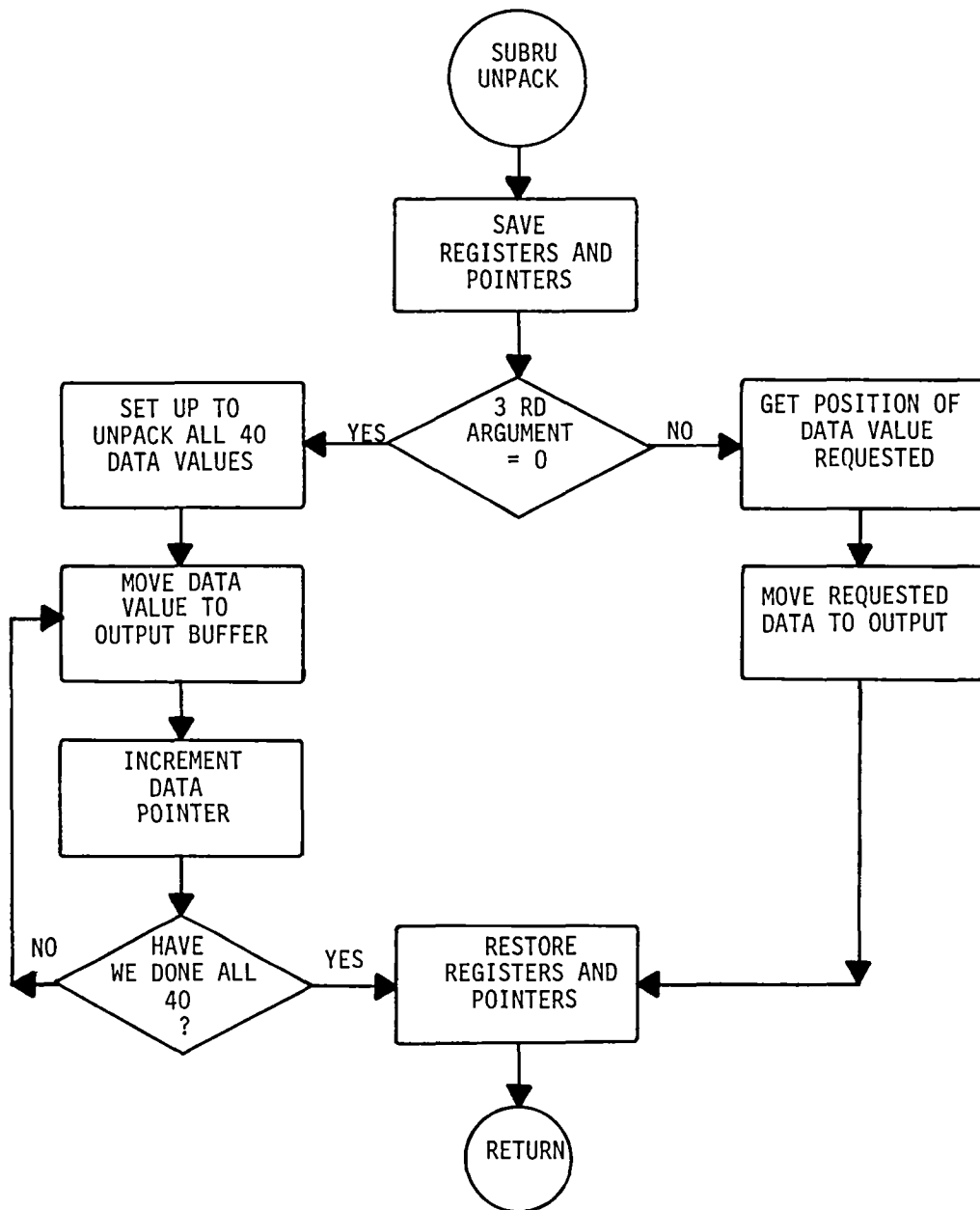
THE THIRD ARGUMENT IS EXAMINED
TO SEE IF ALL 40 DATA VALUES ARE
REQUESTED OR IF ONLY ONE IS REQUESTED.
THE SPECIFIED AMOUNT OF DATA IS THEN
MOVED TO THE OUTPUT BUFFER.

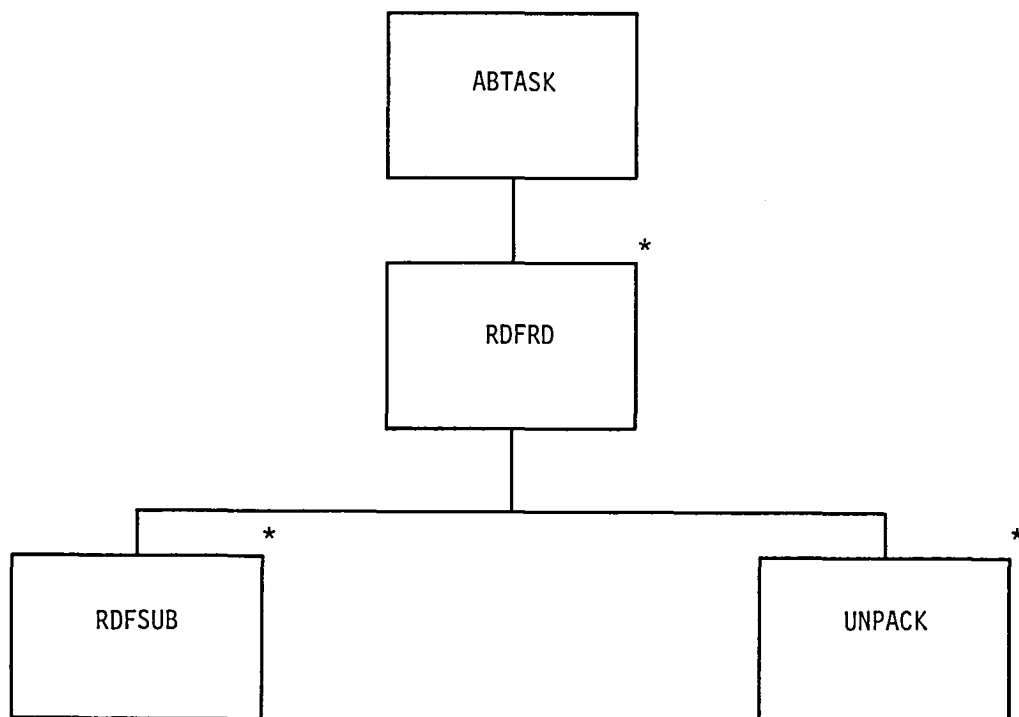
INPUT/OUTPUT

CALLING SEQUENCE<

CALL UNPACK(A,B,C) WHERE

A = FIRST WORD ADDRESS OF 10 WORD INPUT BUFFER
B = FIRST WORD ADDRESS OF 40 WORD OUTPUT
BUFFER IF C IS NON-ZERO, OR ONE WORD
BUFFER IF C IS ZERO.
C = CHARACTER POSITION INDICATOR (1 - 4)





*See Sub-program RDRD for Comments and Flowcharts

HIERARCHY CHART for AB PROGRAM

ABTASK

*****AB TASK*****

*****NASA WALLOPS VERSION OF AUG 19, 1977

*****LANGUAGE - FORTRAN Y

*****MACHINE - HONEYWELL 600 SERIES

*****PURPOSE

TO COMPUTE LINEAR COEFFICIENTS (SLOPE AND INTERCEPT)
FOR CONVERSION OF RAW UNITS TO ENGINEERING UNITS

*****METHOD

- A. HEADER AND CALRUN TABLES ARE READ
- B. PASS AND SENSOR TABLES ARE READ FOR EACH PASS
- C. STATUS IS CHECKED TO DETERMINE IF AB IS TO BE RUN
- D. STATISTICS ARE OBTAINED FROM FILE 09 THROUGH RDRFD
- E. CALTYP IS CHECKED AND A AND B ARE CALCULATED AS FOLLOWS

1. IF CALTYP = 1

A = EUCV1
B = EUCV2

2. IF CALTYP = 2

A = EUCV1/(EUCV2/100)*256
B = -A*256
UNLESS EUCV2 = 0
A = 1
B = 0

1. IF CALTYP = P

A = (EUCV1-EUCV2)/(RBAR-ZBAR)
B = EUCV1 - A*ZBAR

4. IF CALTYP = Z

A = EUCV1/(RBAR-ZBAR)
B = EUCV2 - A*ZBAR

5. IF CALTYP = X

A = EUCV1/(RBAR-ZBAR)
B = (PRE*XEBAR + POST*XTBAR)/(PRE + POST)
UNLESS POST AND PRE = 0
B = EUCV2 - A*XBAR

F. PERCENT FULL SCALE AND SHIFT ARE CALCULATED

G. DATA AVAILABILITY STATUS IS CHANGED TO 2

H. PASS AND SENSOR TABLES ARE UPDATED

*****INPUT - FROM FILE 07

HTAB(27)	HEADER TABLE - CONTAINS DATA IDENTIFYING FLIGHT
MAXPAS	MAXIMUM NUMBER OF PASSES - FROM HTAB
CTAB(120)	CALIBRATION RUN TABLE - CONTAINS RUN NUMBERS FOR SPECIFIED MANEUVER
ICTAB(120)	INTEGER REPRESENTATION OF CTAB
PTAB(600)	PASS TABLE - CONTAINS DATA CONCERNING EACH PASS
CPTAB(600)	CHARACTER REPRESENTATION OF PTAB
MAXPAR	NUMBER OF PARAMETERS IN PASS - FROM PTAB
ISTATC	DATA AVAILABILITY STATUS CODE - FROM PTAB 0 = DATA NOT AVAILABLE 1 = DATA AVAILABLE 2 = ARTASK COMPLETED 3 = OPTASK COMPLETED
STAB(600)	SENSOR TABLE - CONTAINS SENSOR INFORMATION
CSTAB(600)	CHARACTER REPRESENTATION OF STAB
CALADR(40)	CALABRATION ADDRESS FOR EACH PARAMETER
PPC(40)	PRE-PROCESSING CODE FOR EACH PARAMETER
CALTYP(40)	CALIBRATION TYPE FOR EACH PARAMETER
EUCV1(40)	FACTORY CALIBRATED A TERM FOR EACH PARAMETER
EUCV2(40)	FACTORY CALIBRATED B TERM FOR EACH PARAMETER

*****INPUT FROM FILE 09 THROUGH SUBROUTINE RDFRD

STATISTICS - AVERAGES AND STANDARD DEVIATIONS
OF RAW DATA

*****OUTPUT - TO FILE 07

A(40)	CALCULATED A TERM - WRITTEN ON SENSOR TABLE
B(40)	CALCULATED B TERM - WRITTEN ON SENSOR TABLE
AVG(40,6)	AVERAGES FOR SPECIFIED PARAMETER
STD(40,6)	STANDARD DEVIATIONS FOR SPECIFIED PARAMETER
IPCFS	PERCENT FULL SCALE

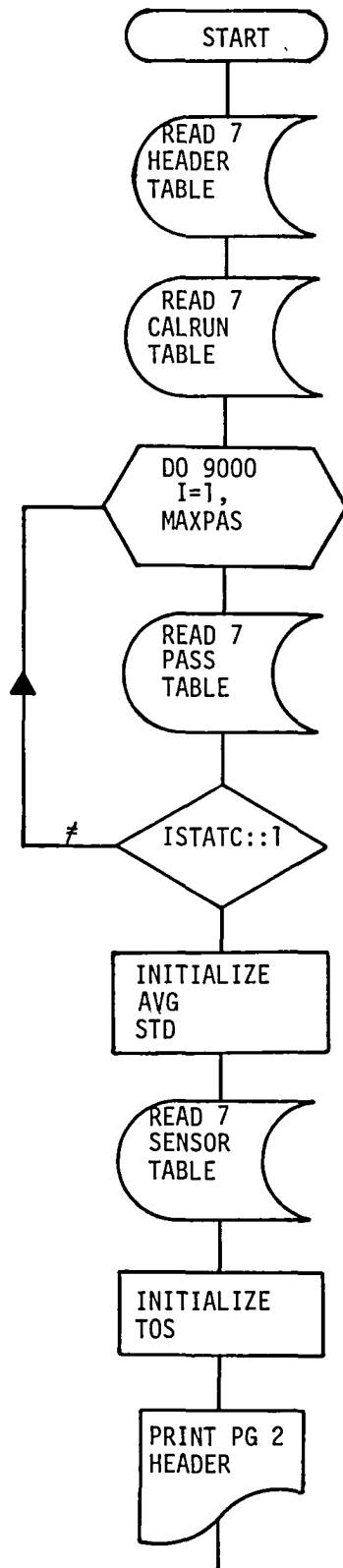
ISHFT

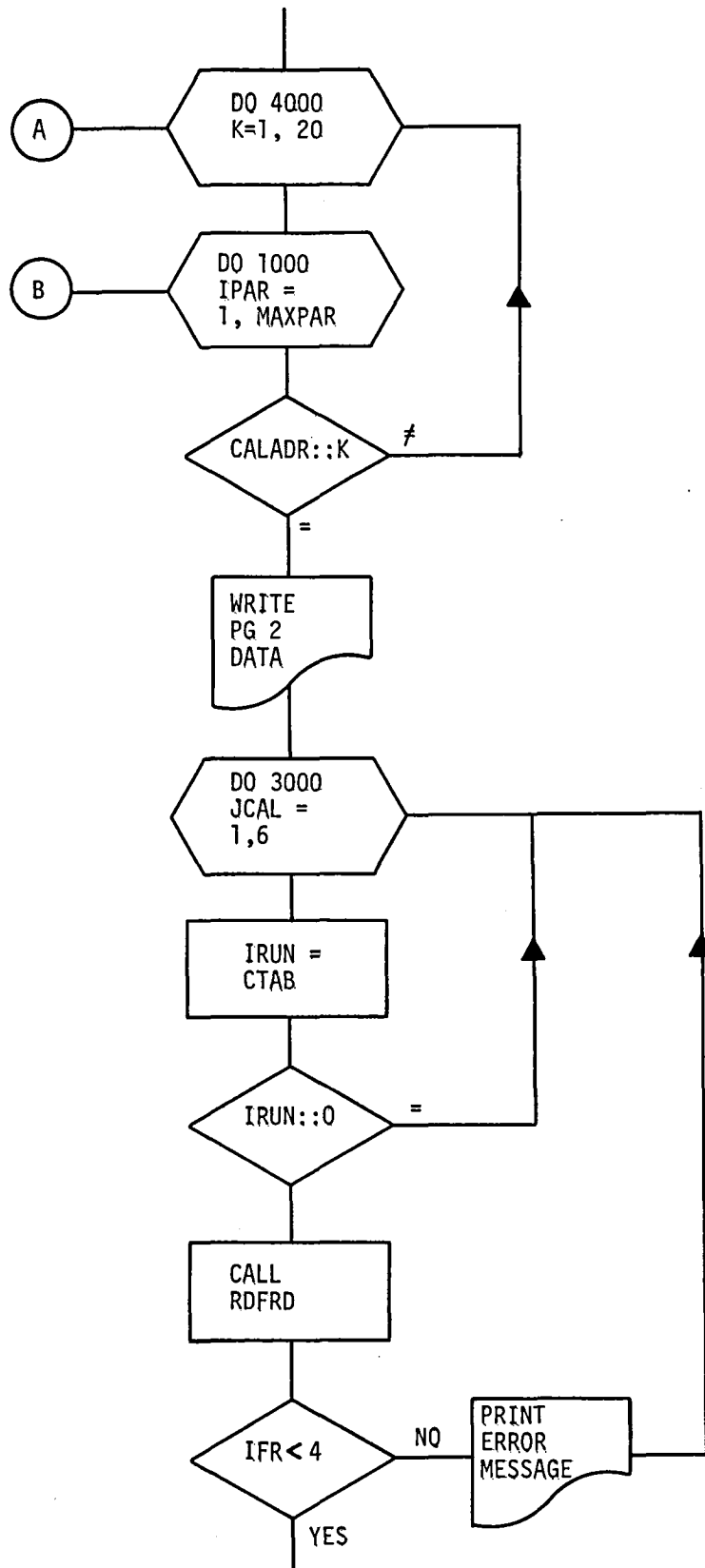
CHANGE IN IPCFS BETWEEN PRE AND POST

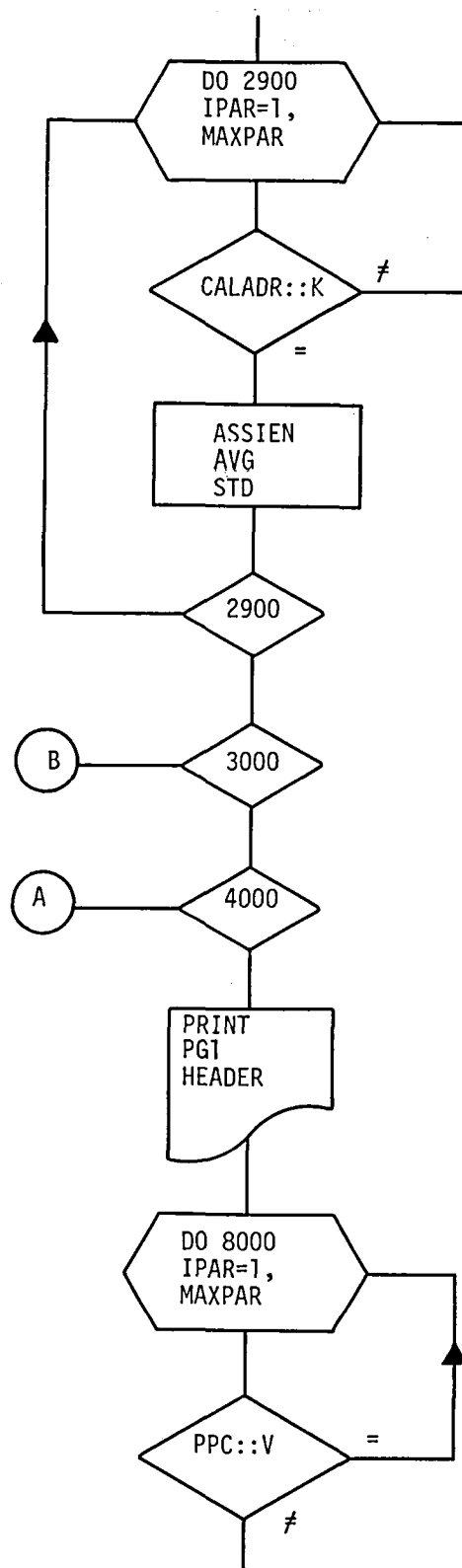
*****SURROUTINES REQUIRED

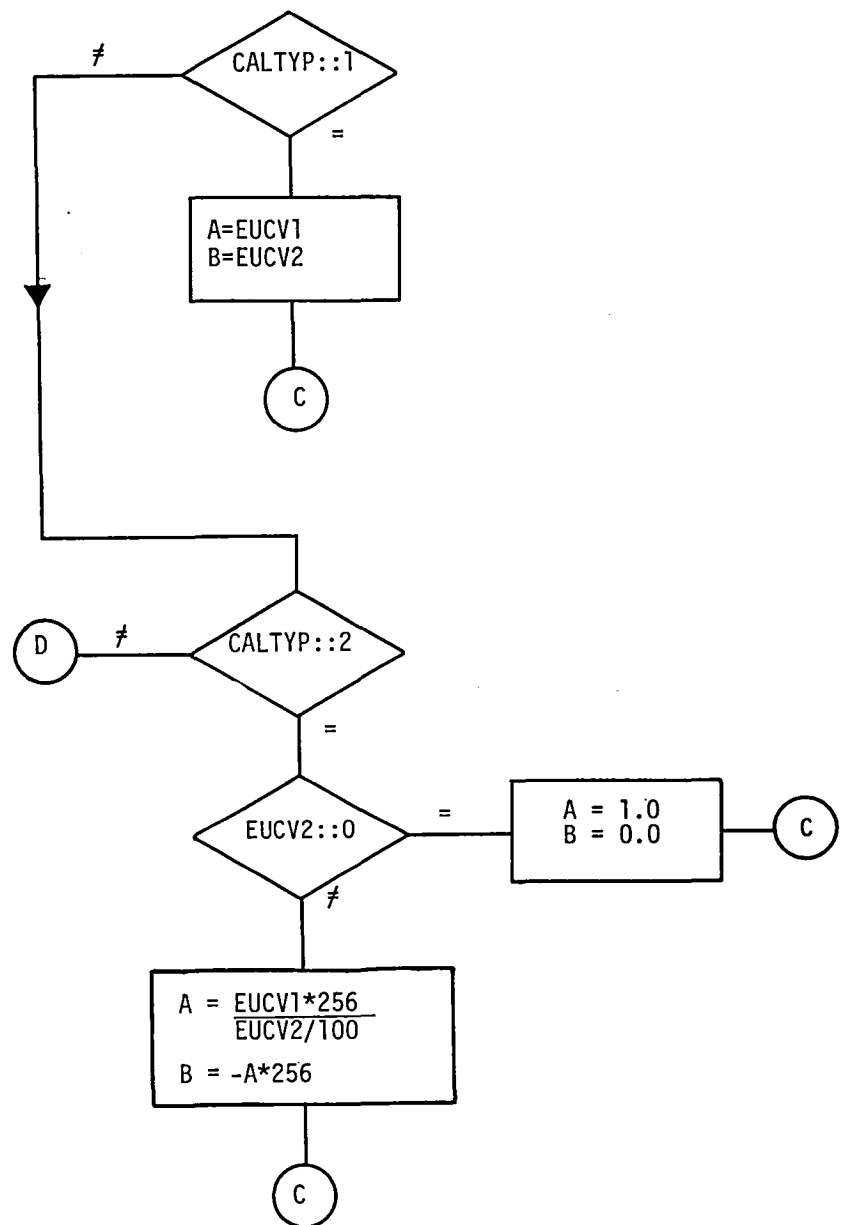
RDFRD

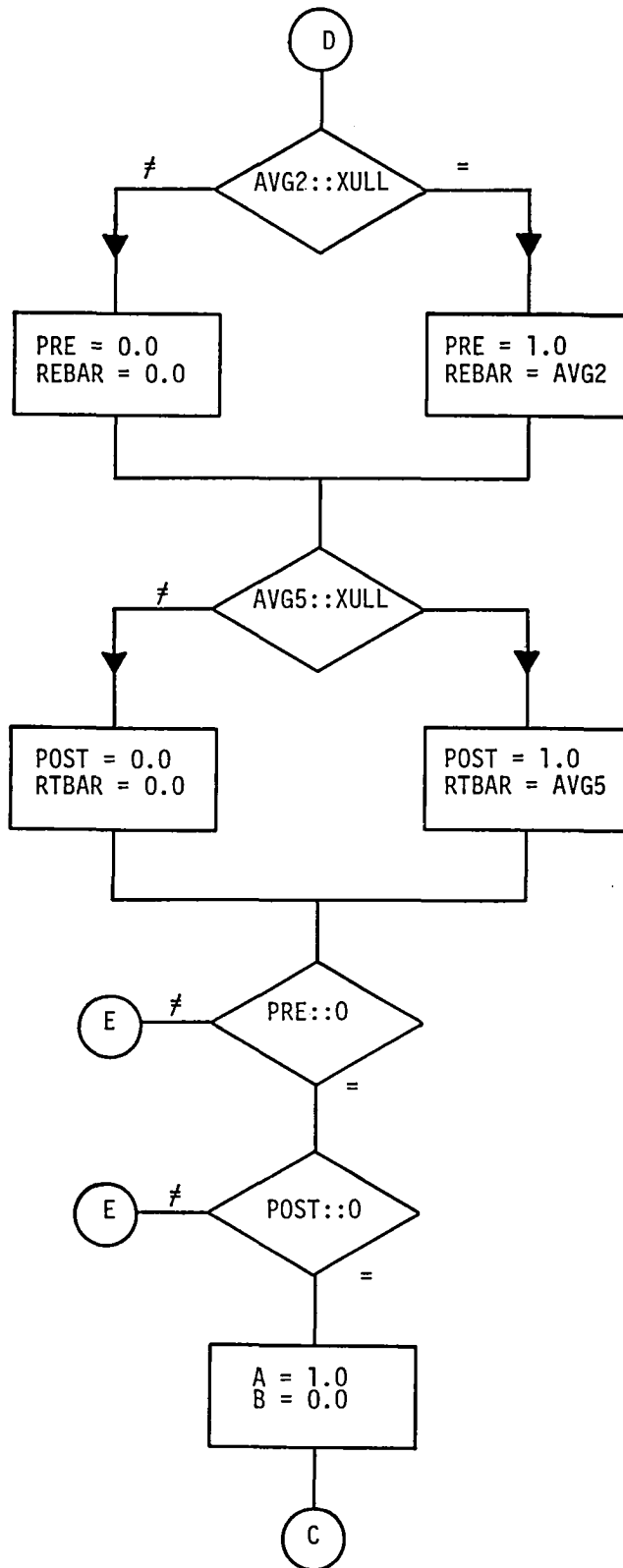
RDFSUB

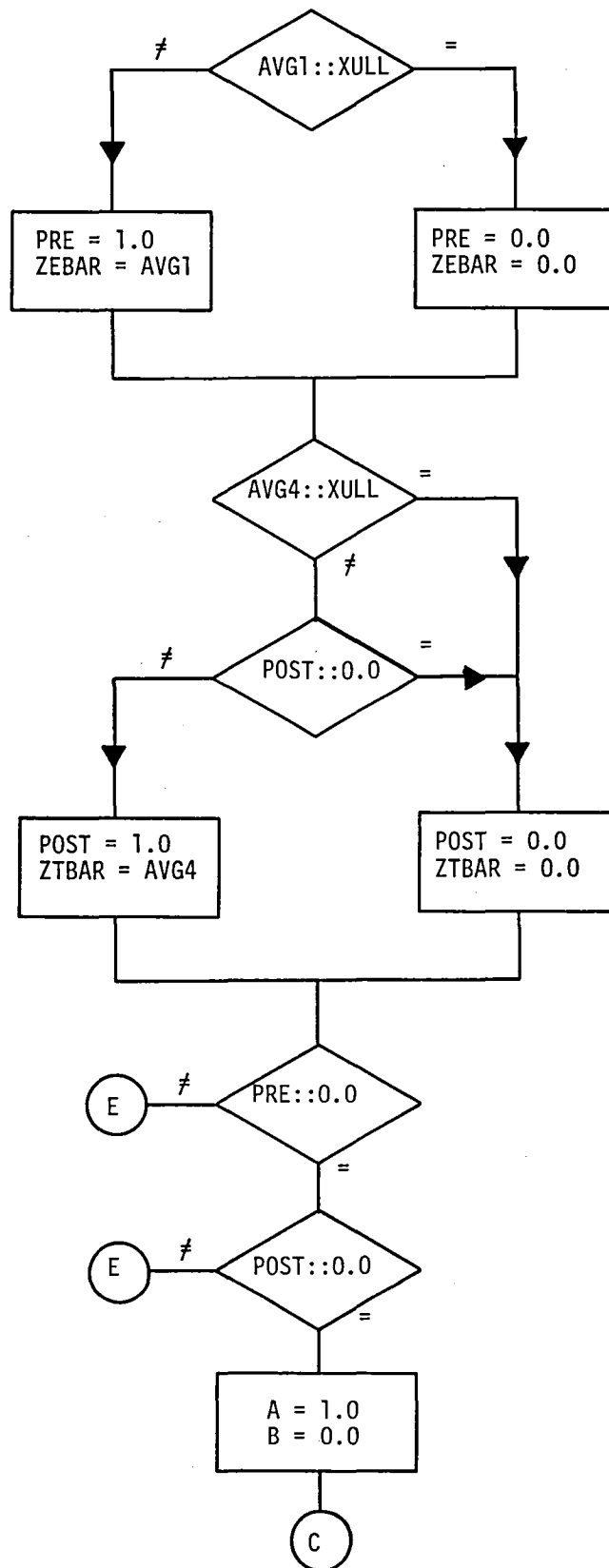


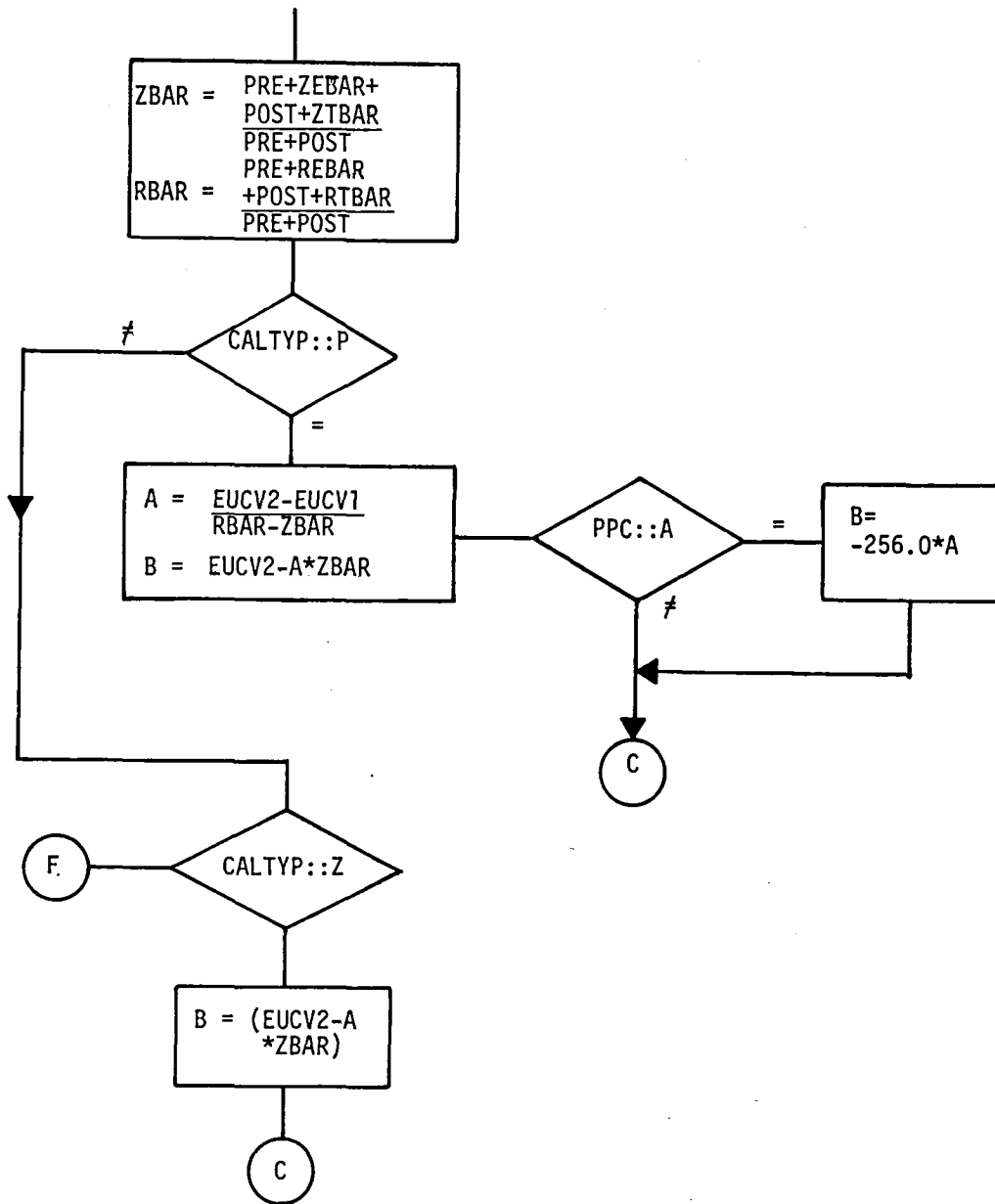


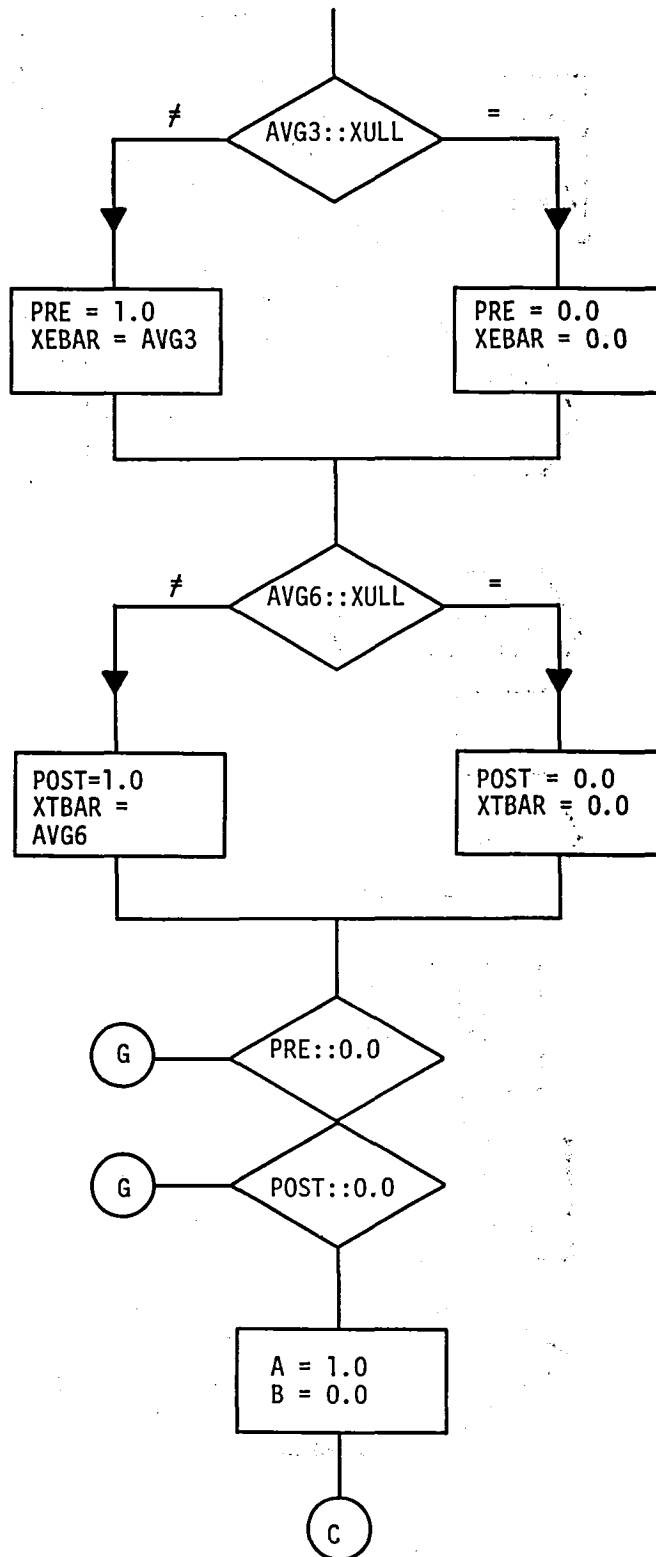


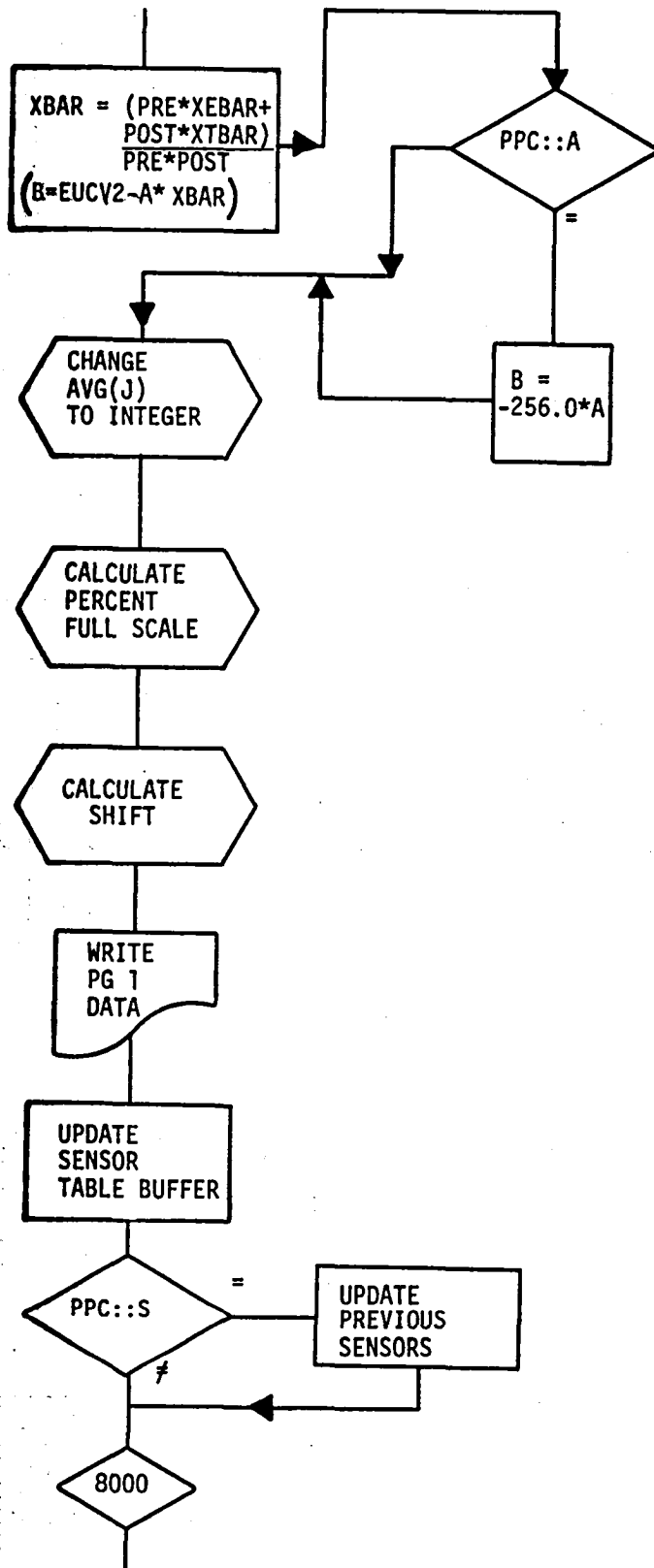


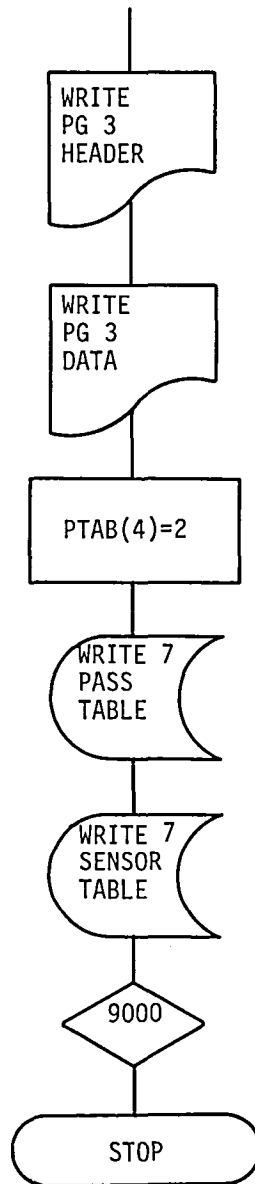


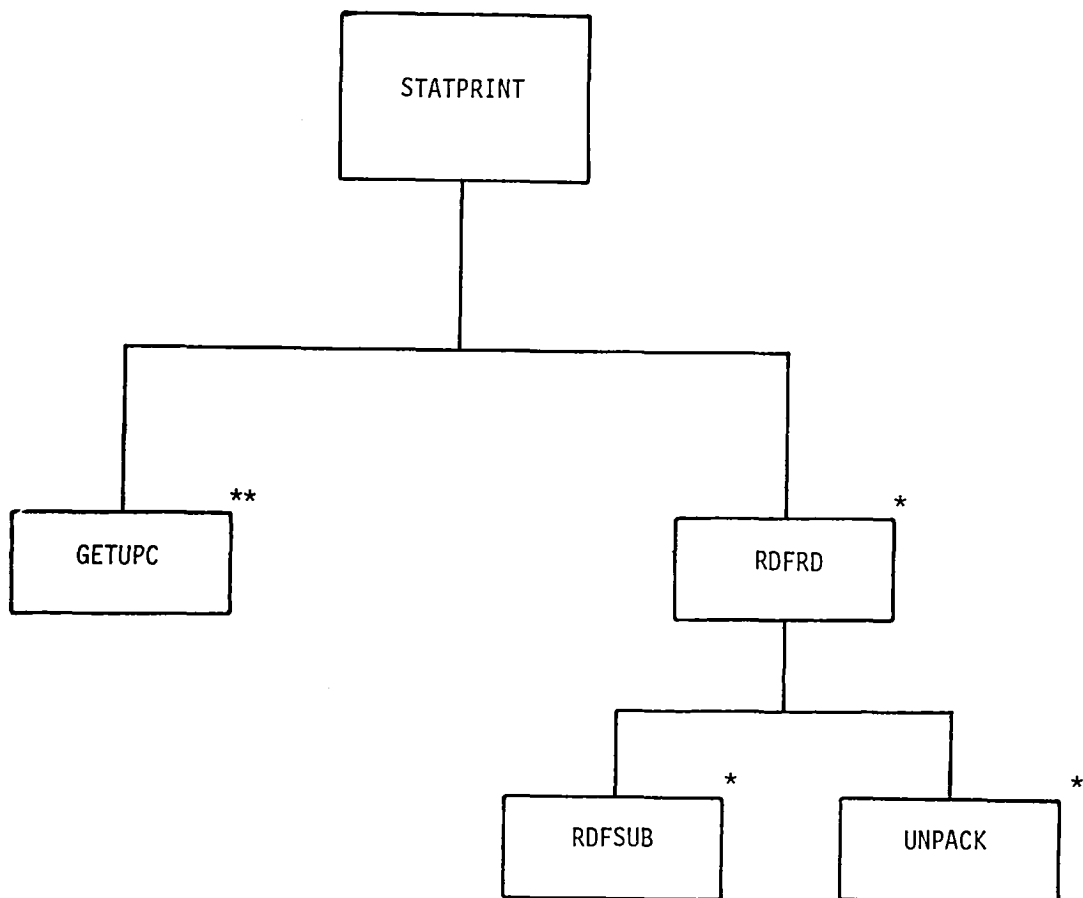












*See Sub-program RDFRD for Comments and Flowcharts

**See Program DATASK for Comments and Flowchart

HIERARCHY CHART For STATPRINT PROGRAM

STPRT STATISTICS PRINT-OUT
*****STATPRINT - PROGRAM NUMBER 1.1.2327

*****NASA WALLOPS VERSION OF 08/01/77

*****LANGUAGE - FORTRAN Y

*****MACHINE - HW 625/635

*****PROGRAM AUTHOR - JEANETTE WESSELLS

*****PURPOSE -

FOR ALL DATA? ALL DATA OF A GIVEN PASS? SELECTED PARAMETERS
FROM ANY PASS, GENERATE STATISTICS TABULATION ON ALL BURSTS
IN EITHER RAW UNITS OR ENGINEERING UNITS.

*****METHOD -

STATPRINT EXTRACTS STATISTICS FROM FILE AND PRODUCES PRINTED
OUTPUT OF COMPUTED MANEUVER STATISTICS INCLUDING MAXIMUM,
MINIMUM, AVERAGE, STANDARD DEVIATION, NO. OF POINTS, NO. OF
ERROR POINTS, AND ERROR CODE IN COLUMN FORMAT FOR EACH
PARAMETER.

THE AMOUNT OF OUTPUT IS CONTROLLED BY INPUT CARDS WHICH MAY
CONTAIN PASS NUMBER, MNEUMONIC NAME, PRE-PROCESSING CODE,
SAMPLE RATE FOR PARAMETER, AND UNITS DESIGNATOR CODE. THESE
INPUT CARDS CONTROL 3 MODES OF LOGIC<

MODE1 - IPASS, NAME, PPC ARE NOT SPECIFIED YIELDS LISTING OF
ALL PARAMETERS FOR ALL AVAILABLE PASSES

MODE2 - IPASS IS SPECIFIED YIELDS LISTING OF ALL PARAMETERS
FOR A GIVEN PASS

MODE3 - NAME, PPC, AND SR IS SPECIFIED YIELDS LISTING FOR
ONLY THAT PARAMETER

ALL INFORMATION IS IN EITHER RAW UNITS OR ENGINEERING UNITS
DEPENDING ON THE VALUE OF ICONV.

DATA IS ACCESSED THROUGH RDFRD MODULE.

*****SYSTEMS INPUT FILES -

FILE 05 = CARD READER

FILE 07 = TABLE FILE

FILE 09 = STATISTICS FILE

*****SYSTEMS OUTPUT FILES -

FILE 06 = PRINTER

FILE 07 = TABLE FILE

*****INPUT -

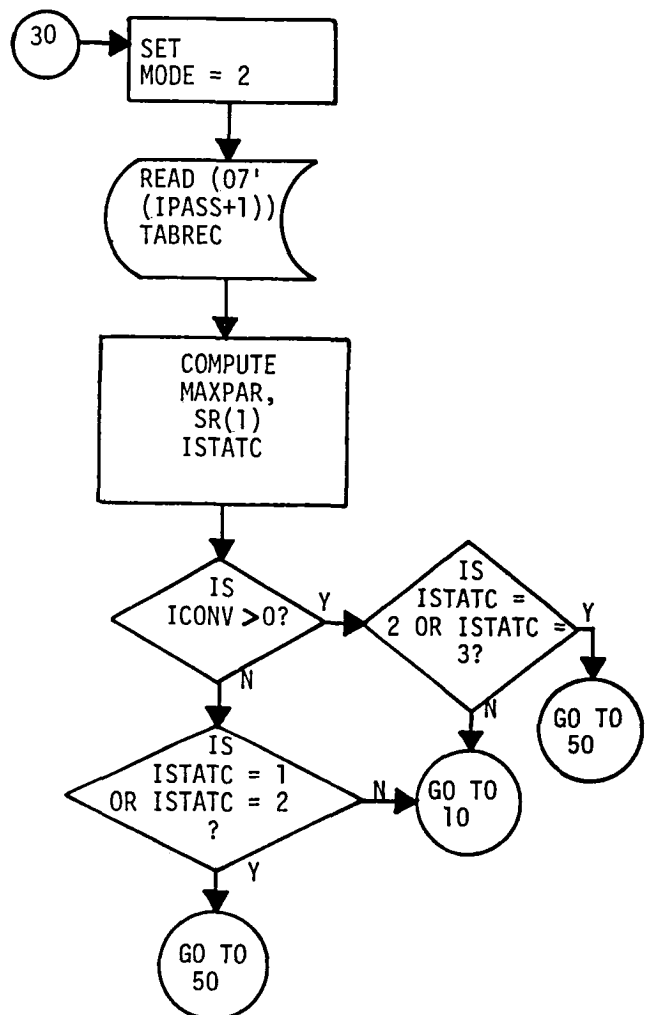
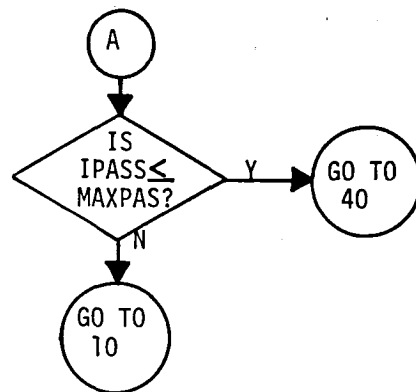
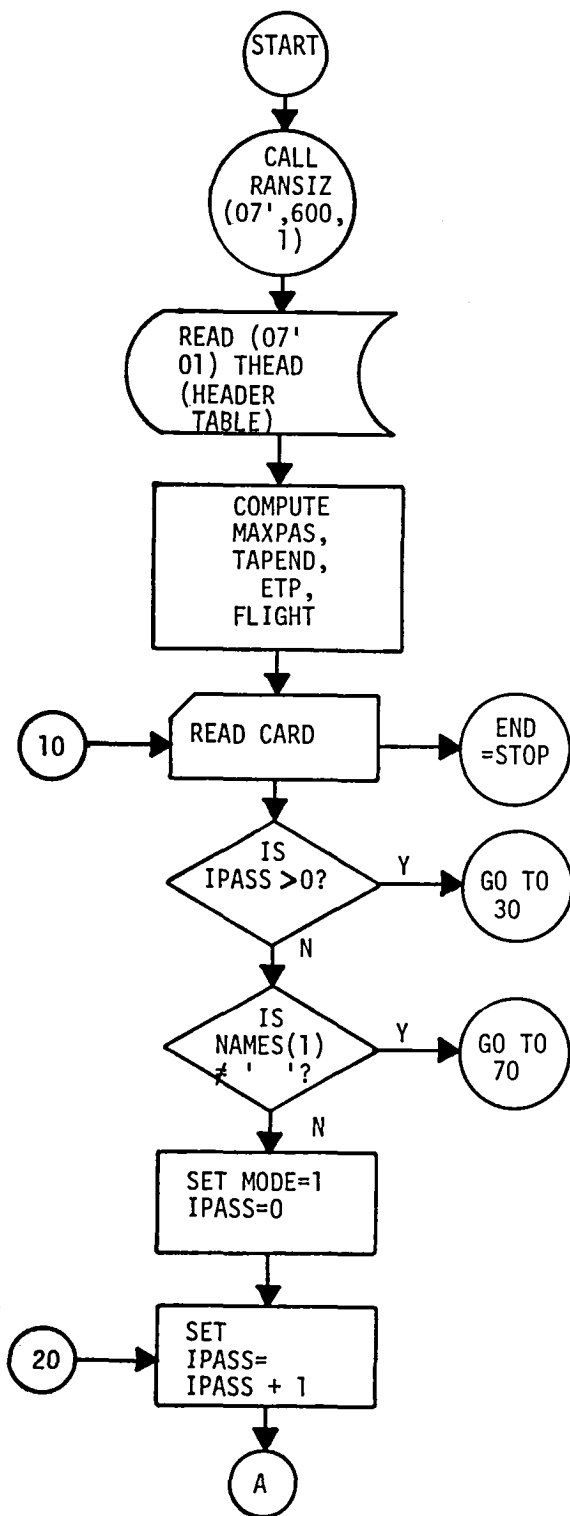
IPASS -PASS NUMBER (CARD INPUT)
NAMES -ARRAY OF PARAMETER MNEMONICS (CARD INPUT)
PPC -PARAMETER PRE-PROCESSING CODE
SR -PARAMETER SAMPLE RATE
ICONV -UNITS DESIGNATOR
 --=0,OUTPUT RAW UNITS
 --=1,OUTPUT ENGINEERING UNITS

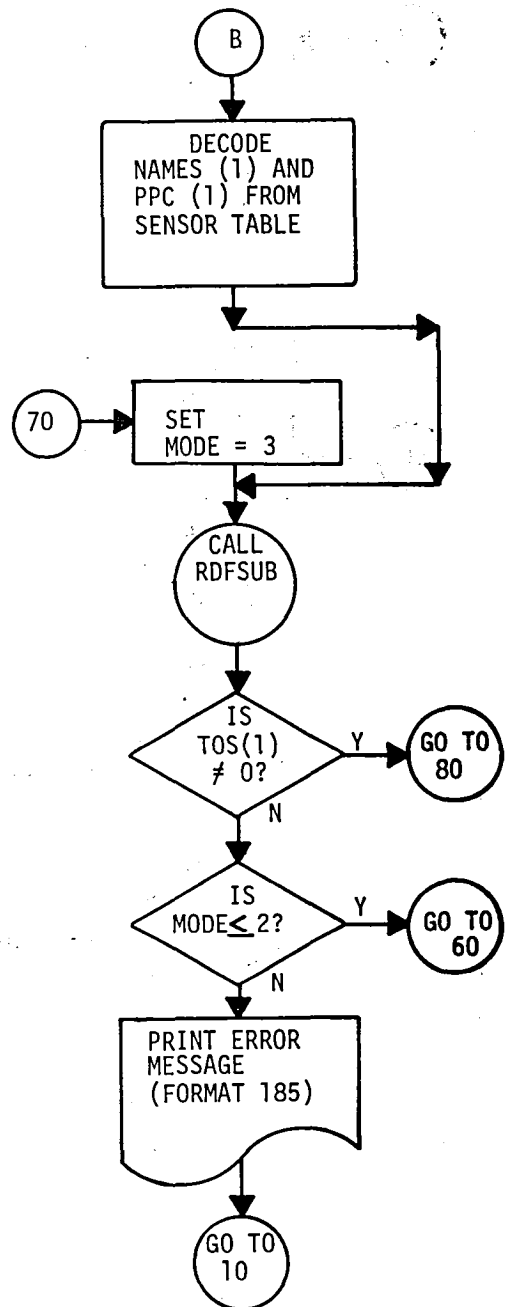
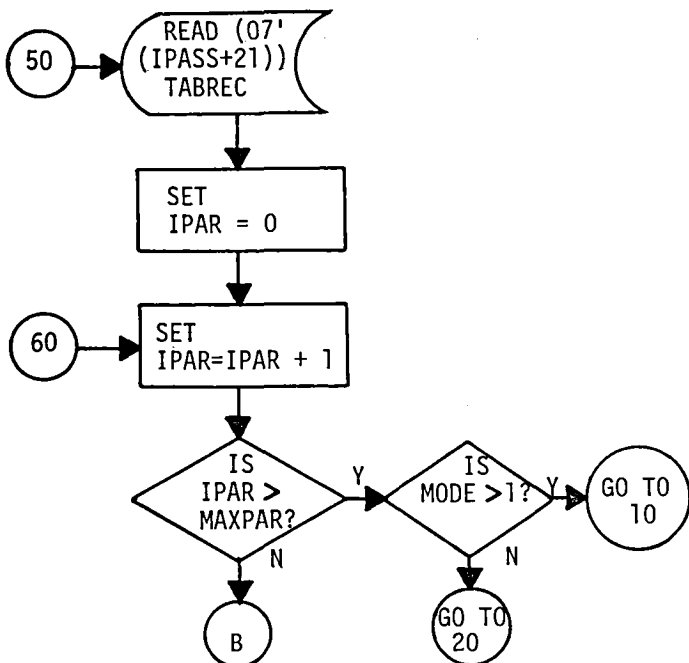
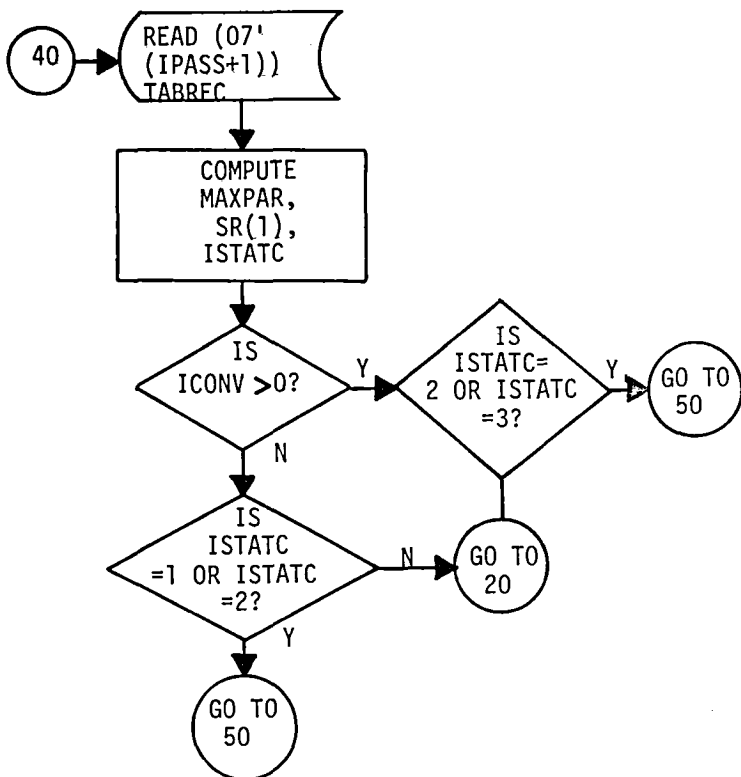
*****OUTPUT -

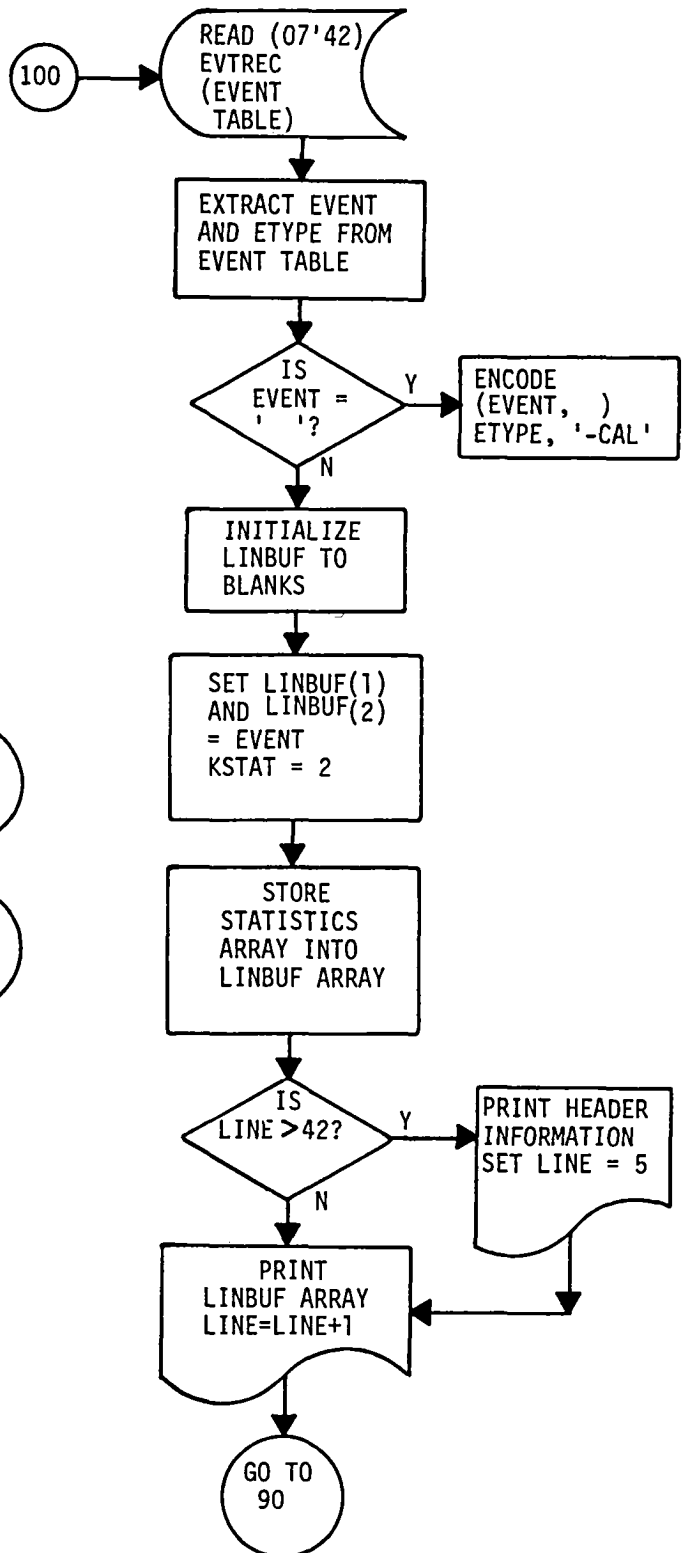
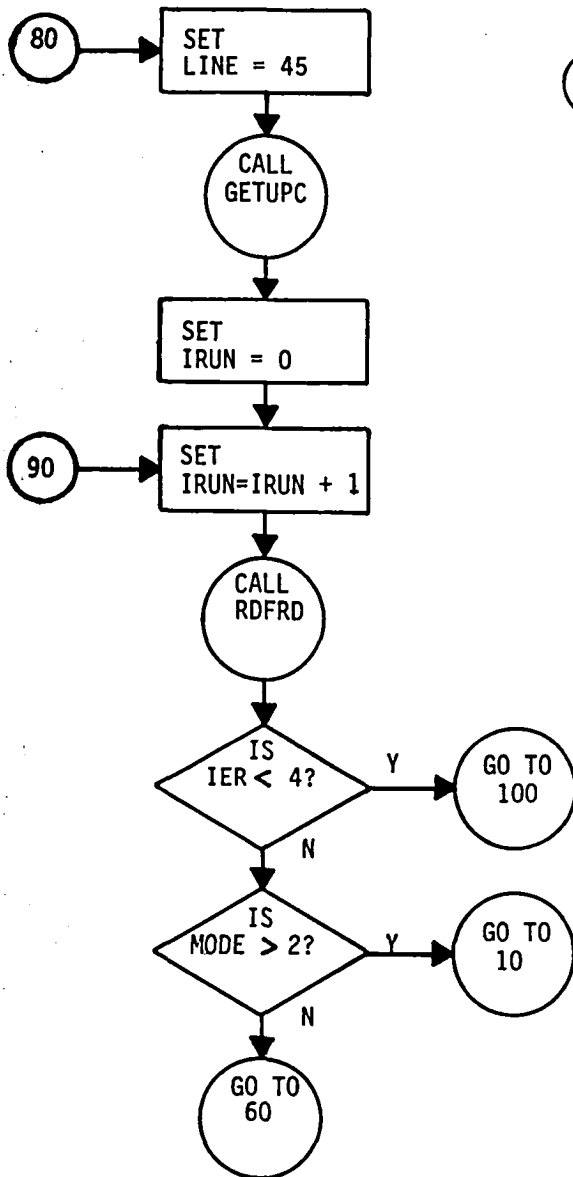
TAPENO -FLIGHT TAPE MNEMONIC
ETP -FLIGHT TEST PLAN NUMBER
FLIGHT -FLIGHT NUMBER
UNIT -OUTPUT IN RAW OR ENGINEERING UNITS
IPASS -PASS NUMBER
NAMES -PARAMETER MNEMONIC
PPC -PARAMETER PRE-PROCESSING CODE
SR -PARAMETER SAMPLE RATE
LTITL -LINE TITLE FOR SENSOR MNEMONIC
IRUN -RUN NUMBER
LINBUF -OUTPUT STATISTICS ARRAY
LINBUF(1) -MANEUVER NAME
LINBUF(2) -MANEUVER NAME
LINBUF(3) -MAXIMUM VALUE
LINBUF(4) -MINIMUM VALUE
LINBUF(5) -AVERAGE
LINBUF(6) -STANDARD DEVIATION
LINBUF(7) -95 PERCENTILE
LINBUF(8) -NUMBER OF POINTS
LINBUF(9) -NUMBER OF ERROR POINTS
LINBUF(10) -TYPE OF ERROR CODE
 --=000100,LOSS OF SYNC ERROR
 --=000010,FULL SCALE ERROR
 --=000001,PARITY ERROR

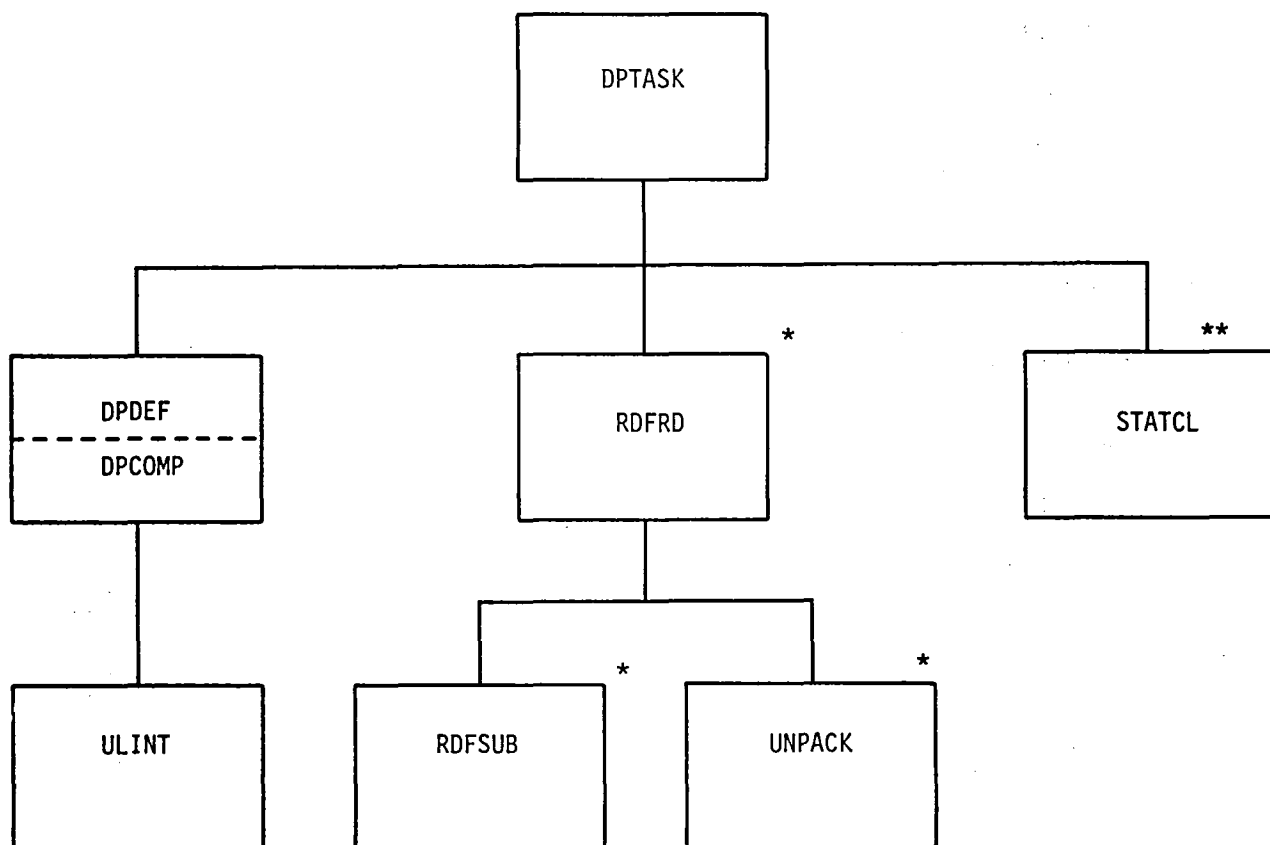
*****RESTRICTIONS -
NONE

*****SUBPROGRAMS REQUIRED -
RDFRD
RDFSUB
UNPACK
GETUPC









*See Sub-program RDFSUB for Comments and Flowcharts
**See Program SCAN for Comments and Flowcharts

HIERARCHY CHART for DPTASK PROGRAM

DPTK SUBROUTINE DPTASK

SUBROUTINE DPTASK

*****DPTASK*****

PROGRAM IDENTIFICATION

PROGRAM NAME ----- DPTASK
PROGRAM NUMBER ----- 112338
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW625/635
MEMORY ----- ALL FILES OPEN(23K)
PERIPHERALS ----- CARD READER, DISC , PRINTER
LANGUAGE ----- HW6000 FORTRAN/FORTY

PURPOSE

THE PURPOSE OF THIS PROGRAM IS TO COMPUTE DERIVED PARAMETERS FROM PARAMETERS PREVIOUSLY SPECIFIED IN A FRAME OF DATA AND TO WRITE THESE DERIVED PARAMETERS ON A DATA FILE.

METHOD

A SUBROUTINE WITH TWO ENTRY POINTS IS REQUIRED.

1. CALL DPDEF - THIS IS AN INITIALIZATION CALL TO BE MADE ONCE PRIOR TO BEGINNING EACH DP PASS. ITS PROCESS IS TO DEFINE FOR THE DPComp ROUTINE WHAT PASS IS TO BE PROCESSED AND IN RETURN IT WILL RETURN TO THE CALLING PROGRAM A LIST OF SPECIFICATIONS FOR THE PARAMETERS THAT IT WILL BE NEEDING AND FOR THE PARAMETERS IT WILL BE GENERATING.

2. CALL DPComp - THIS ENTRY IS MADE FOR EACH FRAME OF DATA.

A SUBROUTINE ULINT IS ALSO REQUIRED TO PERFORM UNIVARIATE LINEAR INTERPOLATION.

INPUT/OUTPUT

- IPASS - A NOMINAL PASS NO. TO BE PROCESSED. THIS IS THE ONLY INPUT ARGUMENT TO THIS ENTRY. IT IS THE NOMINAL PASS NO. AS OPPOSED TO THE ACTUAL PASS NO. IN THAT A VALUE OF 1 WILL INDICATE THE FIRST DP PASS EVEN THOUGH THE ACTUAL PASS NO. MAY BE SOMETHING OTHER THAN 1. A VALUE OF 2 WILL INDICATE THE SECOND DP PASS ETC. IF THE PASS NO. SPECIFIED DOES NOT EXIST THIS ARGUMENT WILL BE RETURNED TO THE CALLING PROGRAM AS A ZERO INDICATING THAT DP IS COMPLETE.
- NOPF - THE NO. OF VALUES THAT ARE REQUIRED FROM THE ONCE PER FLIGHT SECTION OF THE HEADER TABLE.
- IOFPLC - AN ARRAY OF ONCE PER FLIGHT ENTRY NOS. NOPF IN LENGTH, DEFINING WHICH ONCE PER FLIGHT VALUES WILL BE NEEDED.
- NSTREQ - THE NO. OF PARAMETER STATISTICS WHICH MAY BE REQUIRED.
- ISTAT - AN ARRAY WITH NSTREQ ENTRIES EACH OF WHICH WILL BE A NUMBER FROM 1 TO 10 INDICATING THE STATISTIC ELEMENT WHICH WILL BE REQUIRED.

STPAR - AN ARRAY WITH NSTREQ ENTRIES EACH OF WHICH IS A
 PARAMETER MNEMONIC INDICATING THE PARAMETER WHOSE
 STATISTIC WILL BE REQUIRED.
 STPPC - AN ARRAY WITH NSTREQ ENTRIES EACH OF WHICH IS A PPC
 CORRESPONDING TO THE MNEMONICS OF THE ABOVE ARGUMENT.
 STSR - AN ARRAY WITH NSTREQ ENTRIES EACH OF WHICH IS A
 SAMPLE RATE CORRESPONDING TO THE MNEMONIC ABOVE.
 NPAREQ - THE NO. OF PARAMETERS THAT WILL BE REQUIRED AS INPUT
 ON A FRAME BY FRAME BASIS.
 SR - THE SAMPLE RATE OF THE PARAMETER REQUIRED ON A FRAME
 BASIS. THIS WILL ALSO BE THE SR OF THE PARAMETERS TO
 BE COMPUTED ON A FRAME BASIS.
 PARNAM - AN ARRAY OF NPAREQ LENGTH DEFINING THE MNEMONICS OF
 THE PARAMETERS THAT WILL BE NEEDED AS INPUT ON A
 FRAME BASIS.
 PPC - AN ARRAY OF NPAREQ LENGTH DEFINING THE CORRESPONDING
 PRE-PROCESS CODES FOR THE ABOVE PARAMETERS.
 NPOUT - THE NO. OF PARAMETERS THAT WILL BE COMPUTED FOR THIS
 PASS ON A FRAME BASIS.
 PAROT - AN ARRAY OF LENGTH NPOUT CONTAINING THE MNEMONICS OF
 THE PARAMETERS THAT WILL BE GENERATED ON A FRAME BASIS.
 PPCOT - AN ARRAY OF LENGTH NPOUT CONTAINING THE PRE-PROCESS
 CODES FOR THE ABOVE PARAMETERS.
 ITRANS - = ZERO IF STEADY STATE CONDITION, ONE IF TRANSIENT
 CONDITION
 ISTFRM - = ZERO IF THIS FRAME IS THE FIRST FRAME IN THE BURST
 = ONE IF NOT FIRST FRAME OF BURST
 OPFVAL - ARRAY OF ONCE PER FLIGHT VALUES, NOPF IN LENGTH
 STVAL - ARRAY OF STATISTIC VALUES, NSTREQ IN LENGTH
 PARVAL - ARRAY OF INPUT FRAME VALUES, NPAREQ IN LENGTH
 DPVAL - ARRAY OF DP VALUES RETURNED TO CALLING PROGRAM,
 NPOUT IN LENGTH

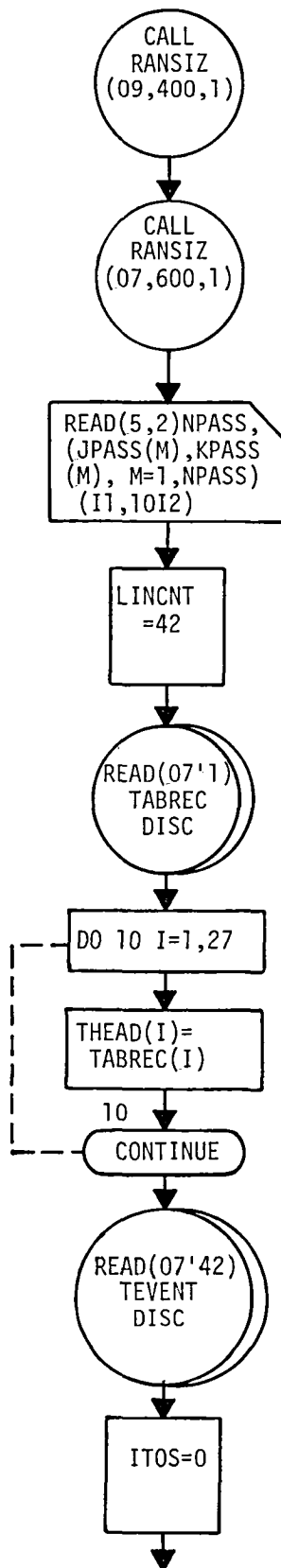
CALLING SEQUENCE

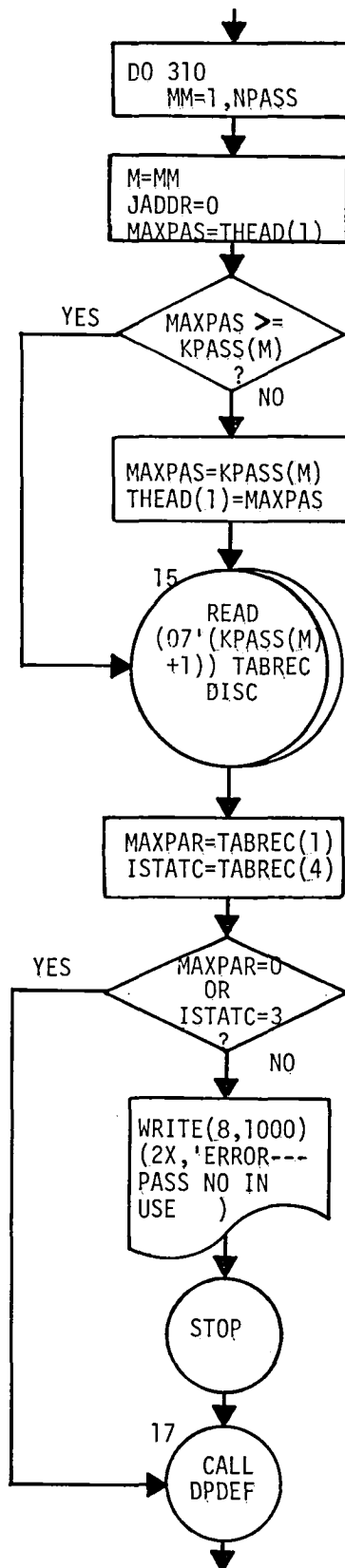
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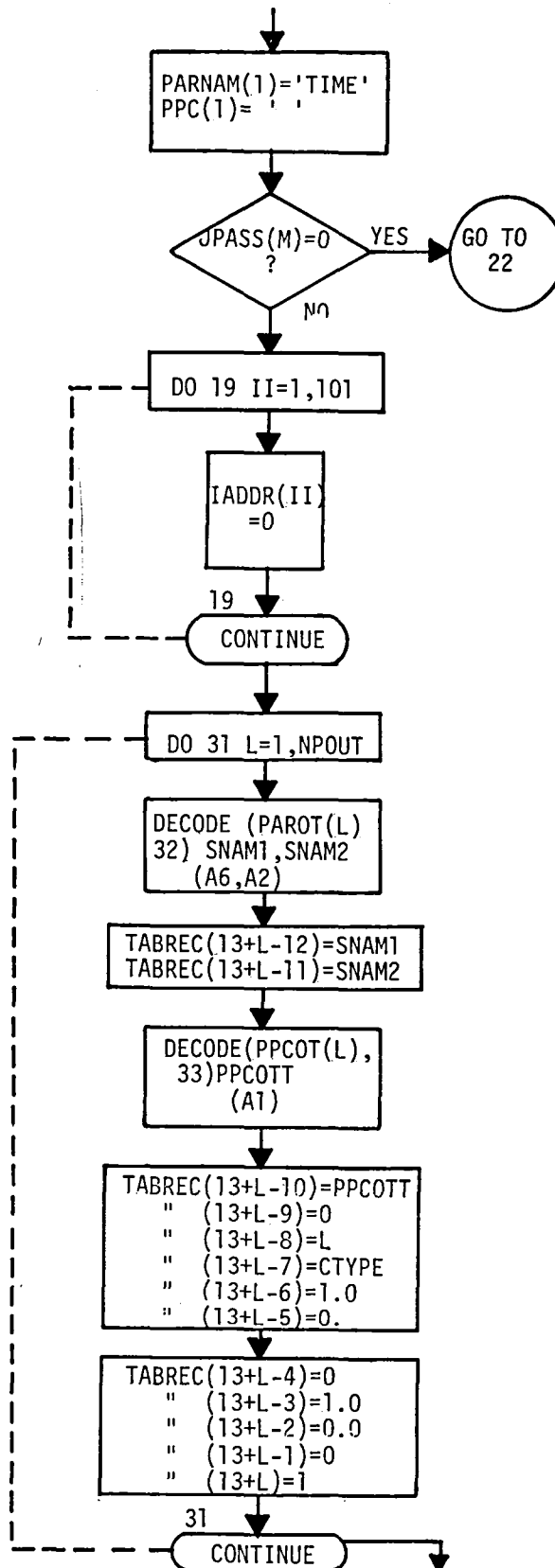
CALL DPDEF(IPASS,NOPF,IOPFLC,NSTREQ,ISTAT,STPAR,STPPC,STSR,
           NPAREQ,SR,PARNAM,PPC,NPOUT,PAROT,PPCOT)
CALL RDFRD(ITOST,1,1,IRUN,NSTREQ,STPAR,STPPC,STSR,0,0,OUTBUF,
           (10*NSTREQ),TOSTAT,NFOUT,MSG,IER)
CALL DPCOMP(ITRANS,0,OPFVAL,STVAL,PARVAL,DPVAL)
CALL RDFRD(ITOS,0,1,IRUN,(NPAREQ+1),PARNAM,PPC,SR,ISMPL,NSMPL,
           PARVAL,(15*(NPAREQ+1)),TOS,NFOUT,MSG,IER)
CALL DPCOMP(ITRANS,ISTFRM,OPFVAL,STVAL,VALIN,DPVAL)
CALL STATCL(ISTFRM,DPVAL,NPOUT,PPCOT,EUCV1,EUCV2,LOCOT,STATBF)
CALL STATCL(2,IFRMBF,NPOUT,PPCOT,EUCV1,EUCV2,LOCOT,STATBF)
  
```

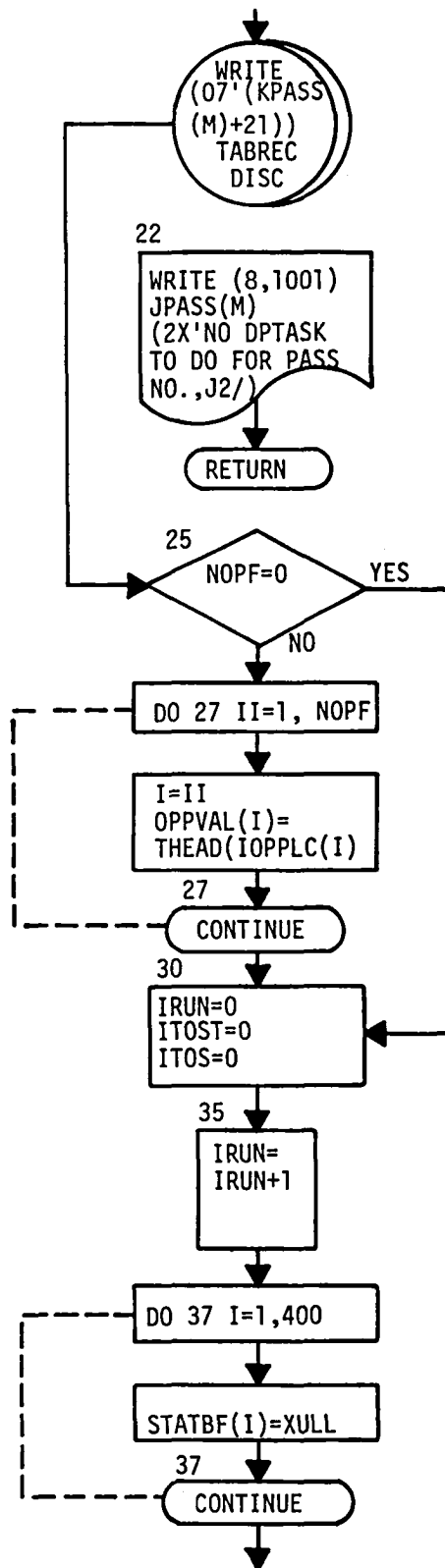
COMMON AREAS
 TABL1/THAD

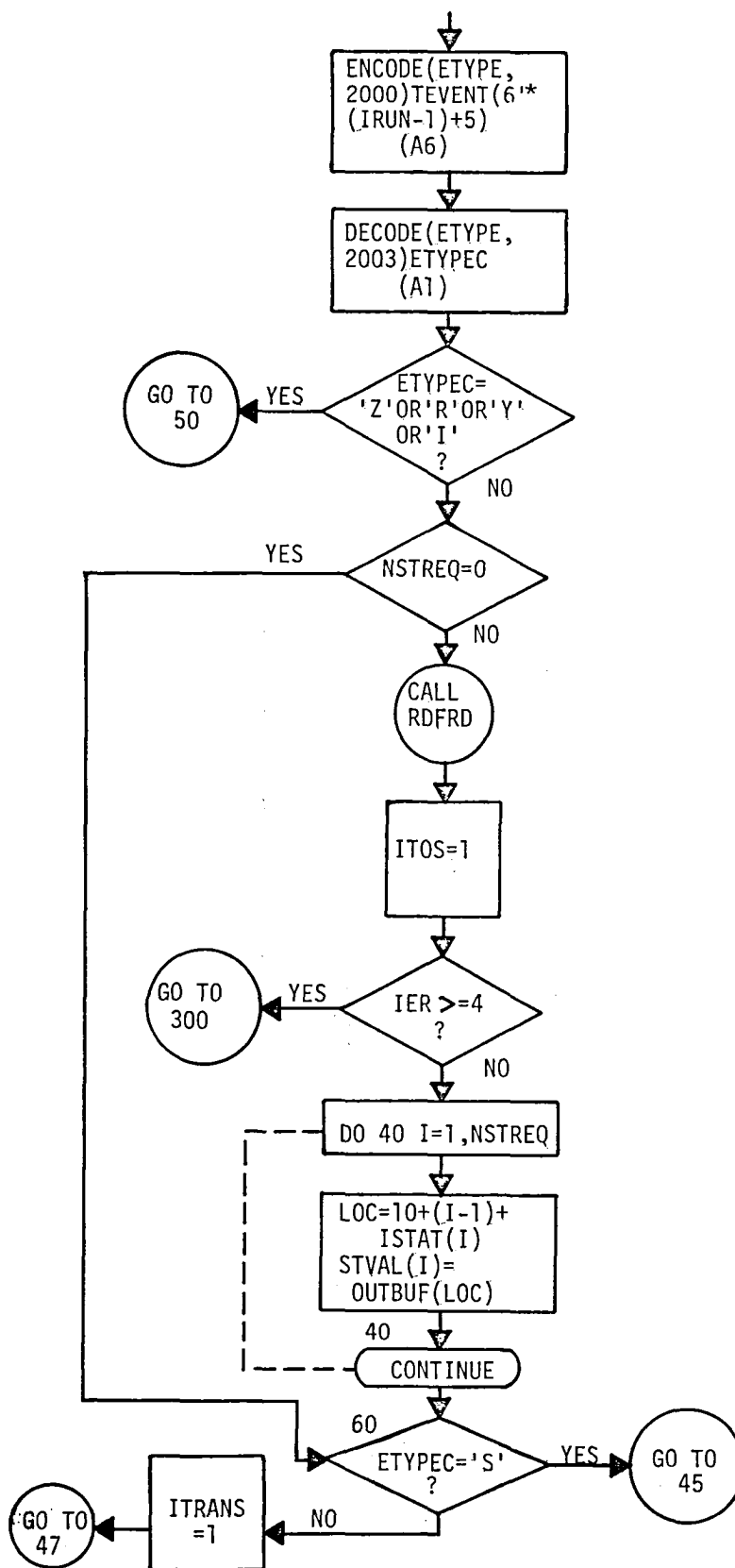
SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS ,
 FILE DESCRIPTIONS OR FOR ANY OTHER SPECIFIC INFORMATION)

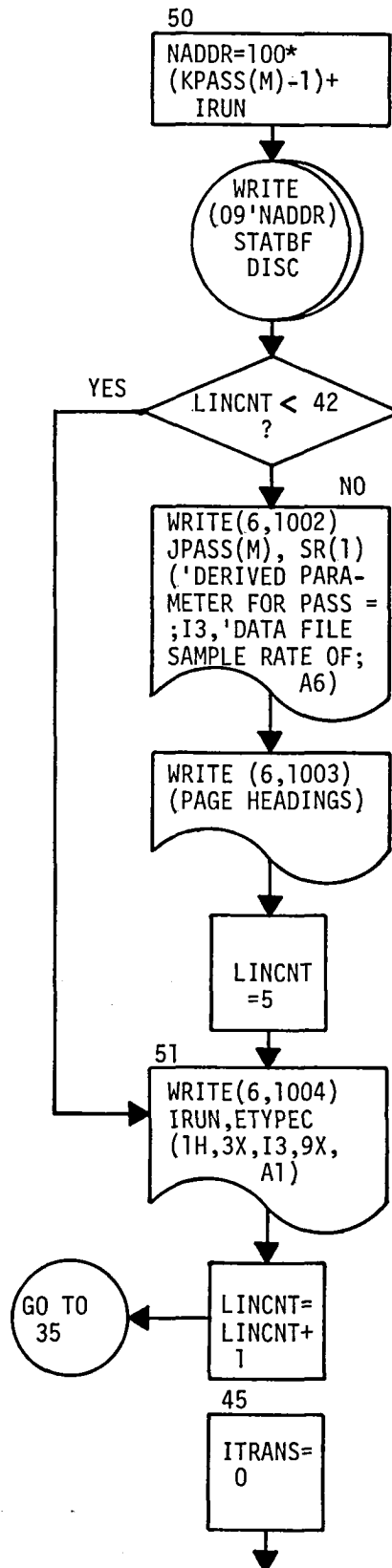


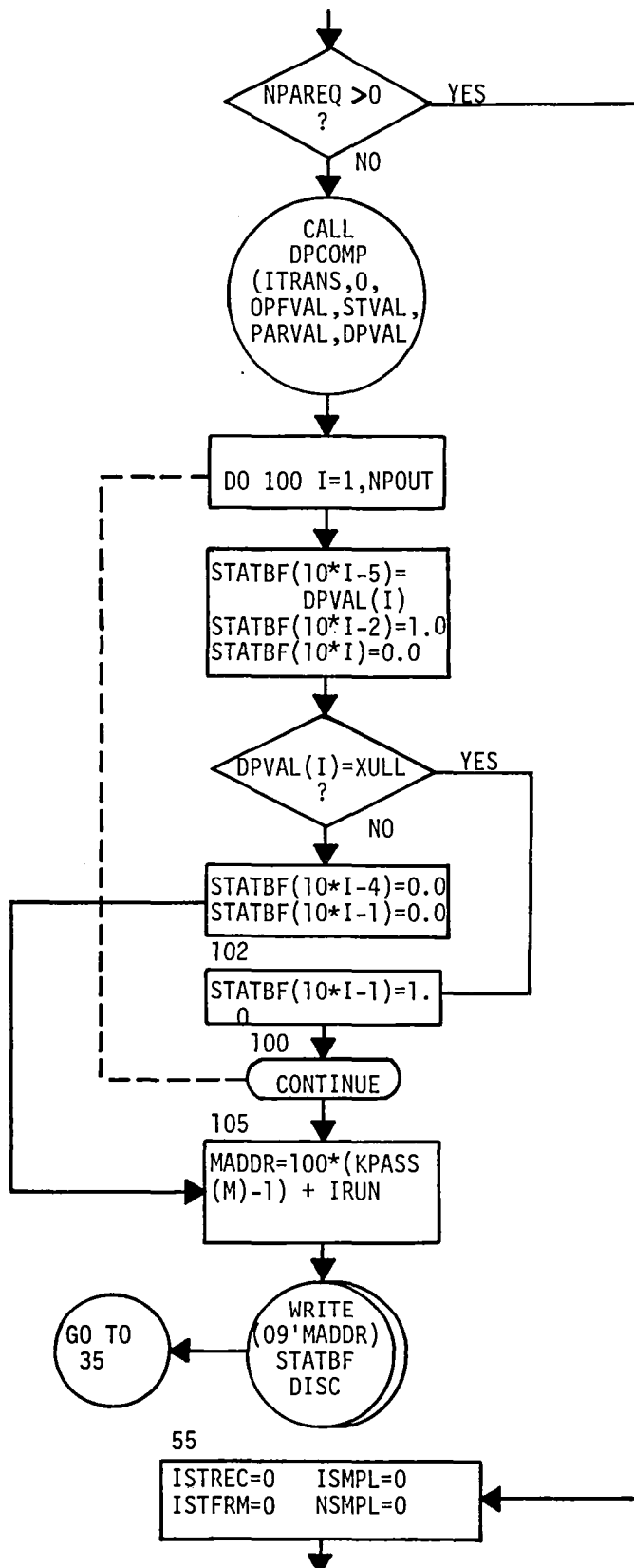


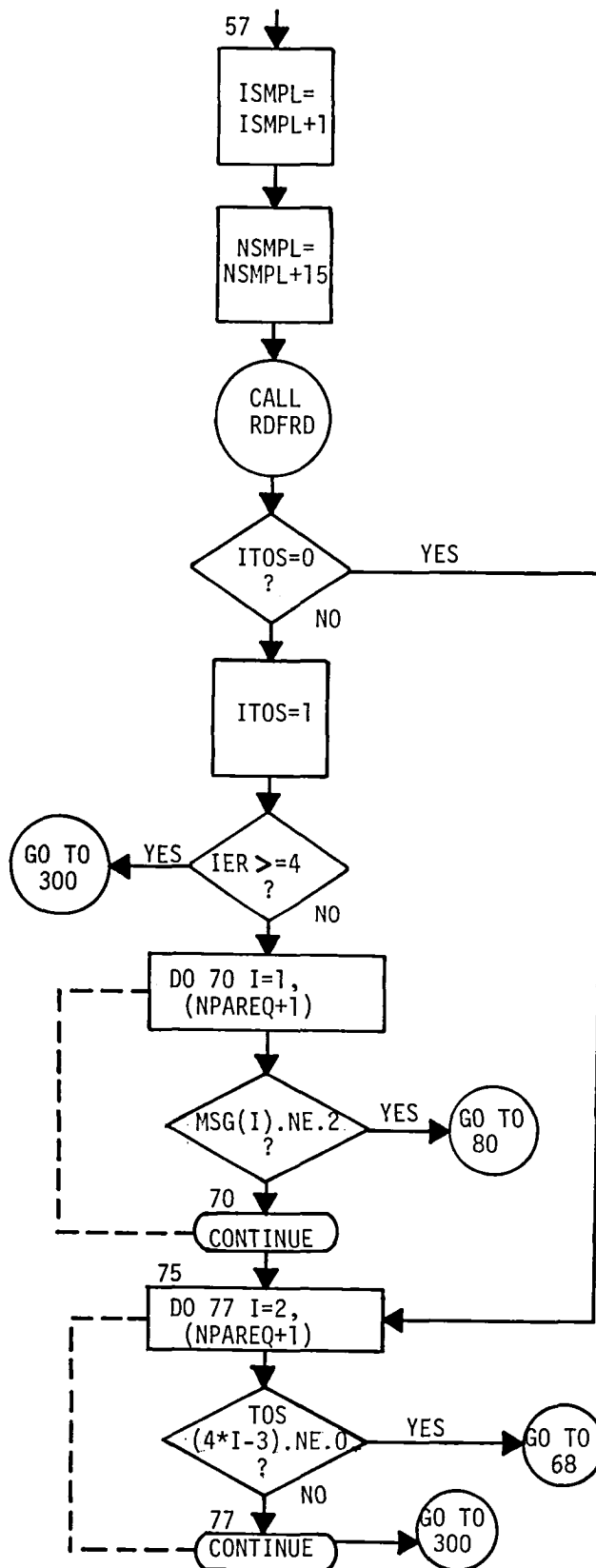


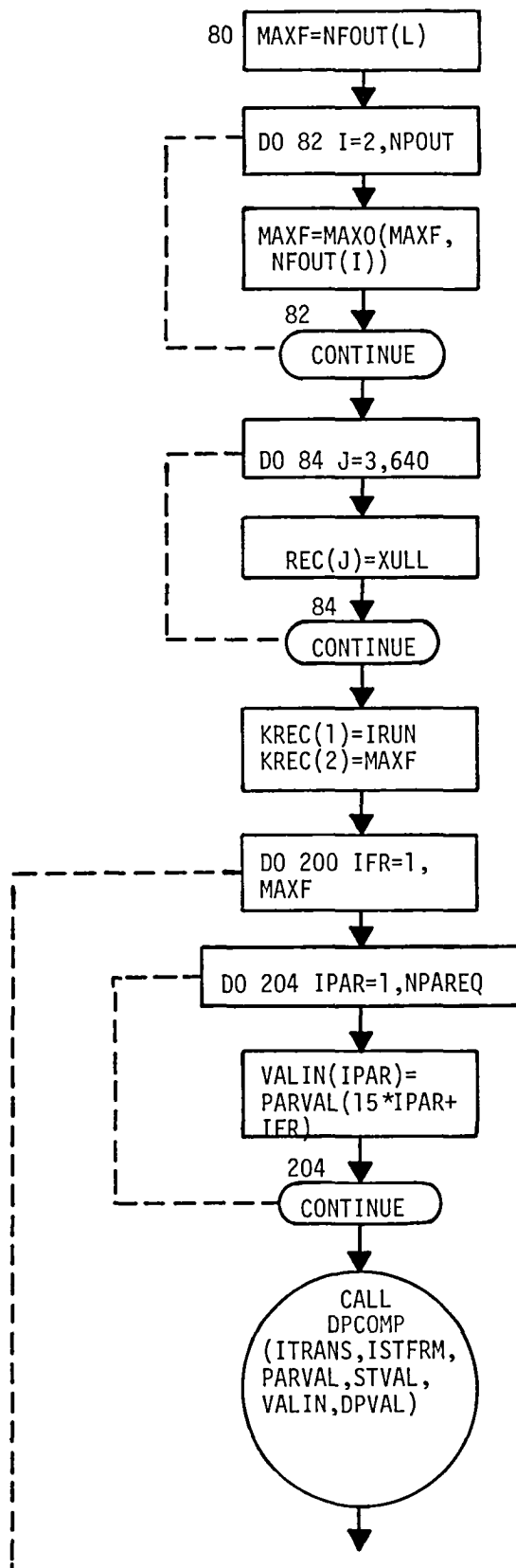


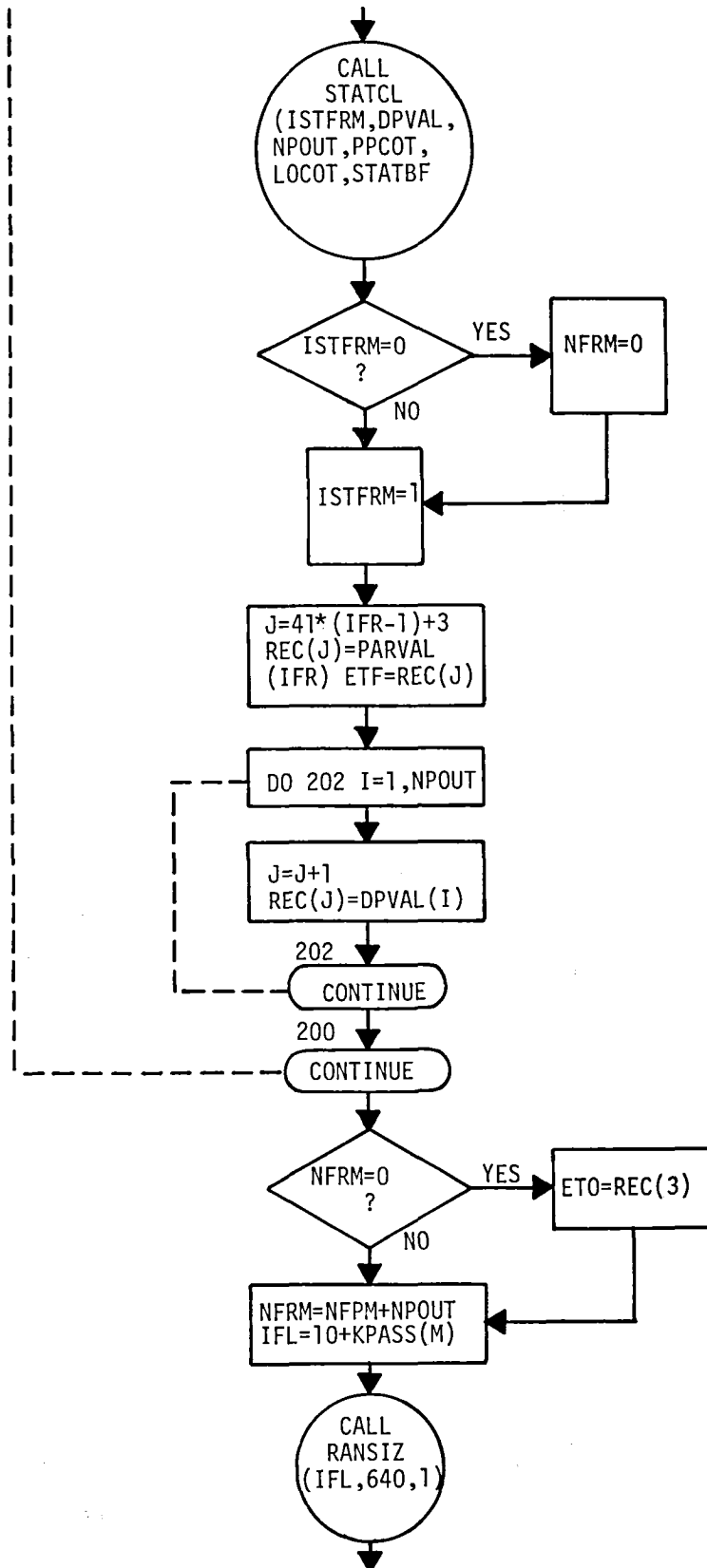


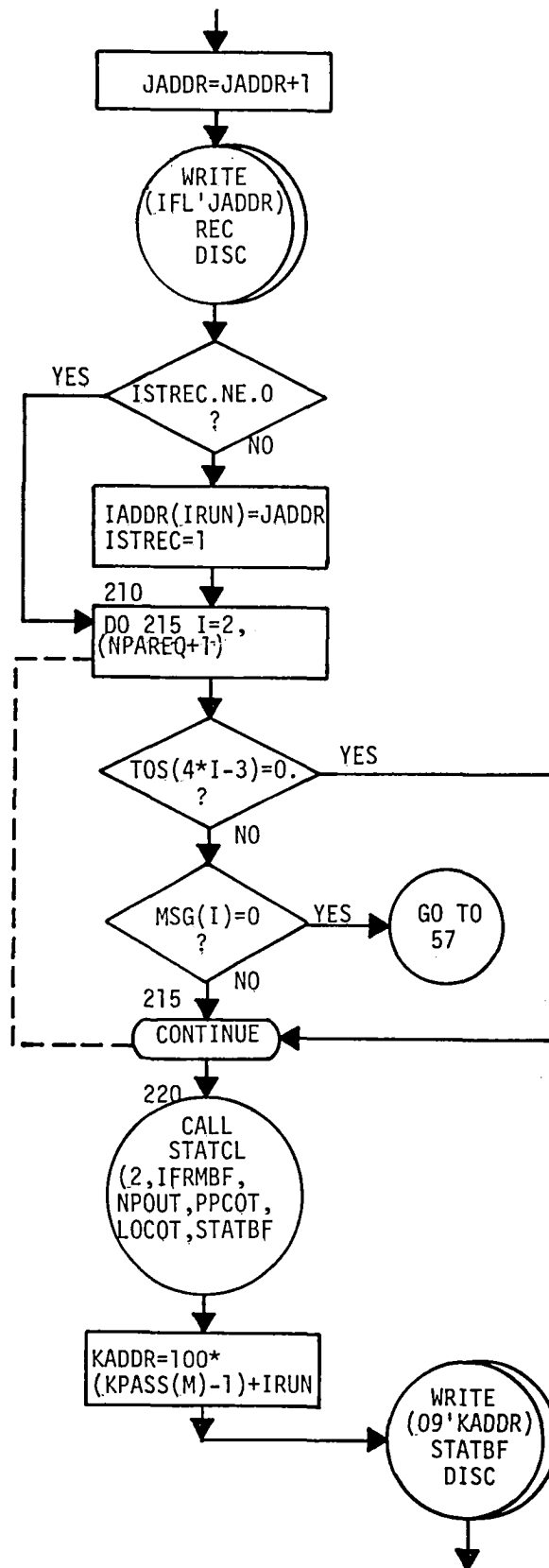


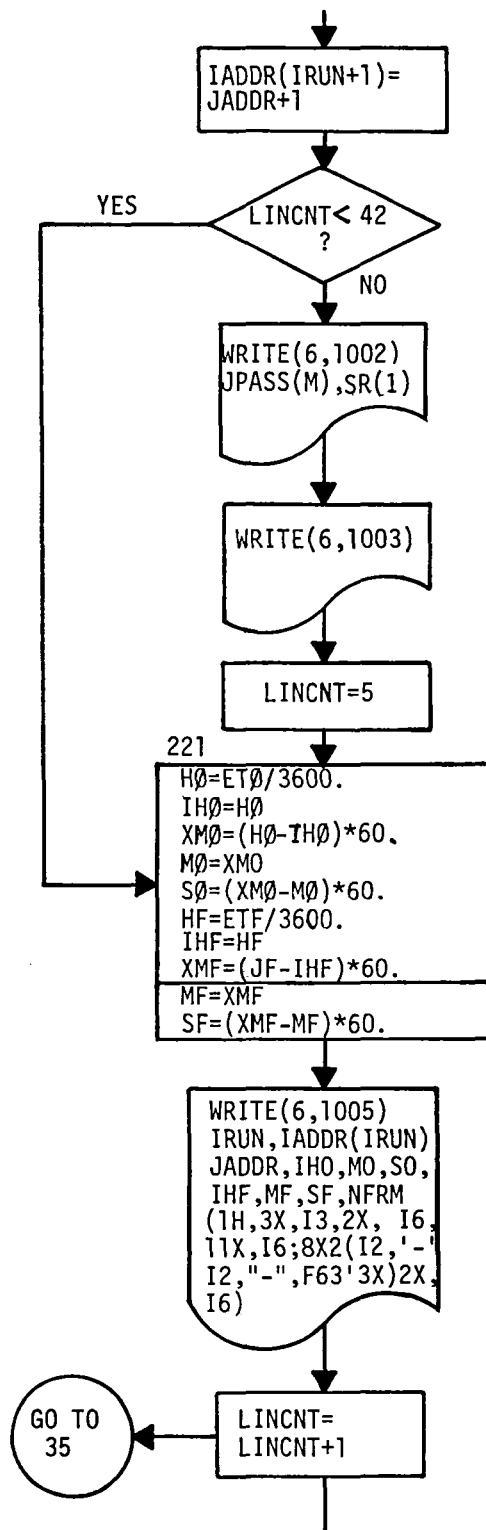


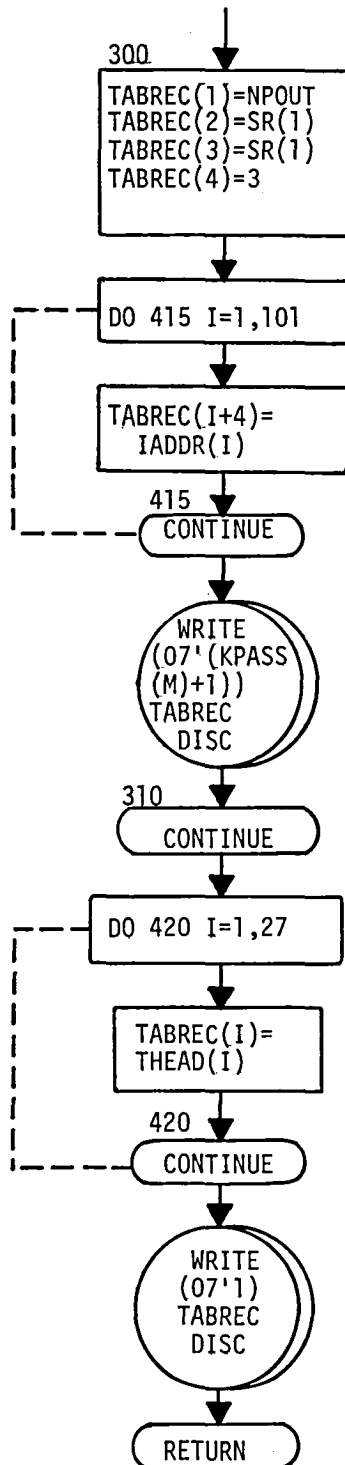












DPDE SUBROUTINE DPDEF

SUBROUTINE DPDEF(IPASS,NOPF,IOPFLC,NSTREQ,ISTAT,STPAR,STPPC,STSR,
1 NPAREQ,SR,PARNAM,PPC,NPOUT,PAROT,PPCOT)
*****SUBROUTINE DPDEF--ENTRY POINT DPCOMP*****

PROGRAM IDENTIFICATION

PROGRAM NAME ----- DPDEF (ENTRY DPCOMP)
PROGRAM NUMBER ----- 112338
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW625/635
MEMORY -----
PERIPHERALS -----
LANGUAGE ----- HW6000 FORTRAN/FORTY

PURPOSE

THIS IS AN INITIALIZATION CALL TO BE MADE ONCE PRIOR TO
BEGINNING EACH DP PASS. ITS PURPOSE IS TO DEFINE FOR THE DP
COMPUTE ROUTINE WHAT PASS IS TO BE PROCESSED AND IN RETURN
IT WILL RETURN TO THE CALLING PROGRAM A LIST OF SPECIFICATIONS
FOR THE PARAMETERS THAT IT WILL BE NEEDING AND FOR THE
PARAMETERS IT WILL BE GENERATING.

THE ENTRY TO DPCOMP IS MADE FOR EACH FRAME OF DATA.

METHOD

ASSUMPTIONS

ONCE PER FLIGHT VALUES REQUIRED

ETP - LOCATION 16
ESGW - LOCATION 17
ESCG - LOCATION 18
KPR - LOCATION 19
HPC - LOCATION 20
MRC - LOCATION 21
R - LOCATION 22
RT - LOCATION 23
GT - LOCATION 24
GTS - LOCATION 25
RELHU - LOCATION 26
FHBOOM - LOCATION 27

STATISTICS REQUIRED

ITATBOOM	VIPBOOM	HB00M	NO1QPCT
NO2QPCT	NO1NFPCT	NO2NFPCT	NR
MRQ1	TRQ	LOADFACT	

MEASUREMENTS REQUIRED AS INPUT ON A FRAME BASIS

ITATBOOM	VIPBOOM	HB00M	HEAD180	NO1QPCT
NO2QPCT	NO1NFPCT	NO2NFPCT	LOADFACT	MRQ1
TRQ	NR	TRIMPIT	MRLIFTA	MRLIFTB
MRLIFTC	MRLIFTD	ISAFAPR	ISOFAPR	ISAFBPR
XMSNSGT	AILPOSR			

PARAMETERS GENERATED FOR OUTPUT TO RDRD

VITBOOM	VCASBOOM	VEIBOOM	FATBOOM	VTRROOM
TATBOOM	HDBOOM	OMEGAR	OMEGATR	MU
MACHA	NO1SHP	NO2SHP	HPT	CPTC
HPMR	CPM	HPTR	CPTAIL	HPS
CPT	YAWFTRM	FX	FY	FZ
MX	MY	MZ	AILPOSP	

VARIABLE NAMING CONVENTION

FIRST LETTER X = TEMPORARY VARIABLE GENERATED WITHIN
DPCOMP BUT WHICH ARE NOT RETURNED TO
THE CONTROL PROGRAM AND ONCE PER FLIGHT
VALUES FED IN FROM THE HEADER TABLE
FIRST LETTER Q = VARIABLES CONTAINING STATISTICS VALUES
FED IN FROM THE CONTROL PROGRAM
FIRST LETTER Z = VARIABLES CONTAINING SENSOR VALUES FED IN
FROM THE CONTROL PROGRAM ON A FRAME BASIS

INPUT/OUTPUT

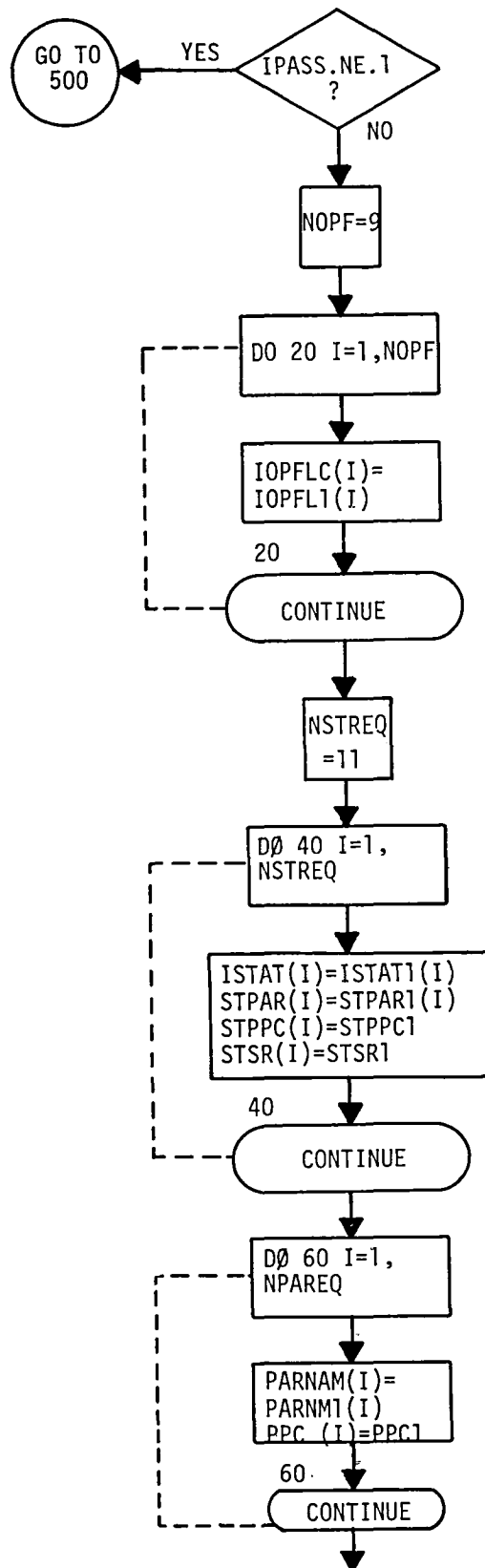
SEE CALLING ROUTINE FOR ARGUMENT DEFINITIONS

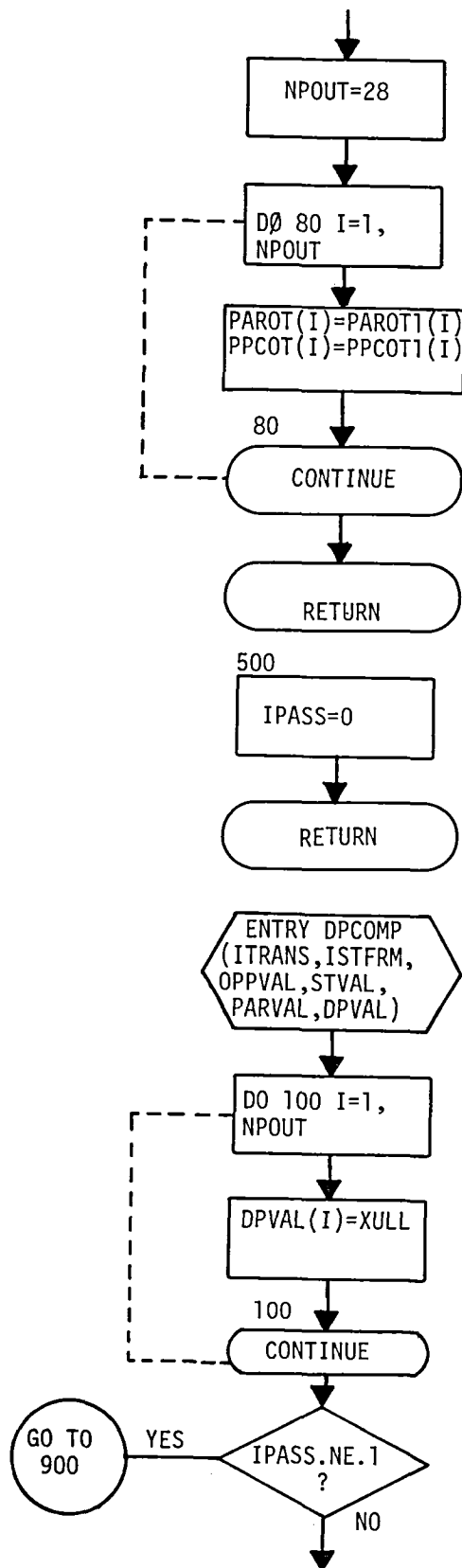
CALLING SEQUENCE

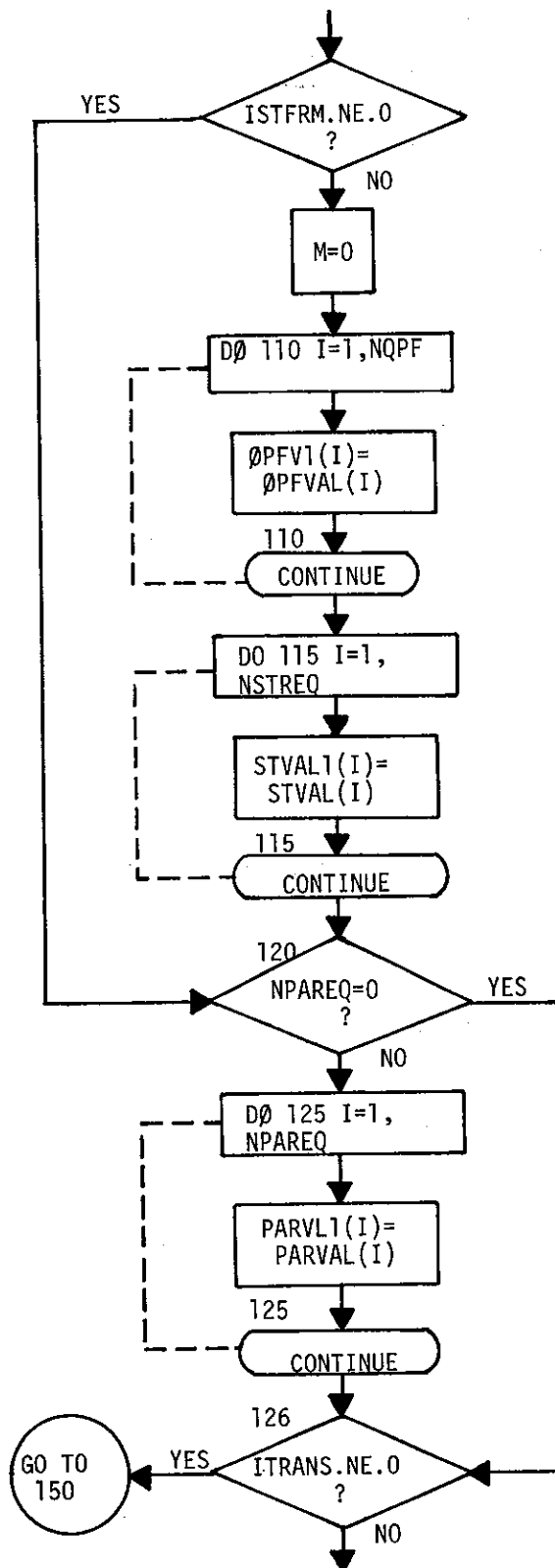
CALL ULINT(VIASN,VIASC ,VIT,VCAS,DUM)

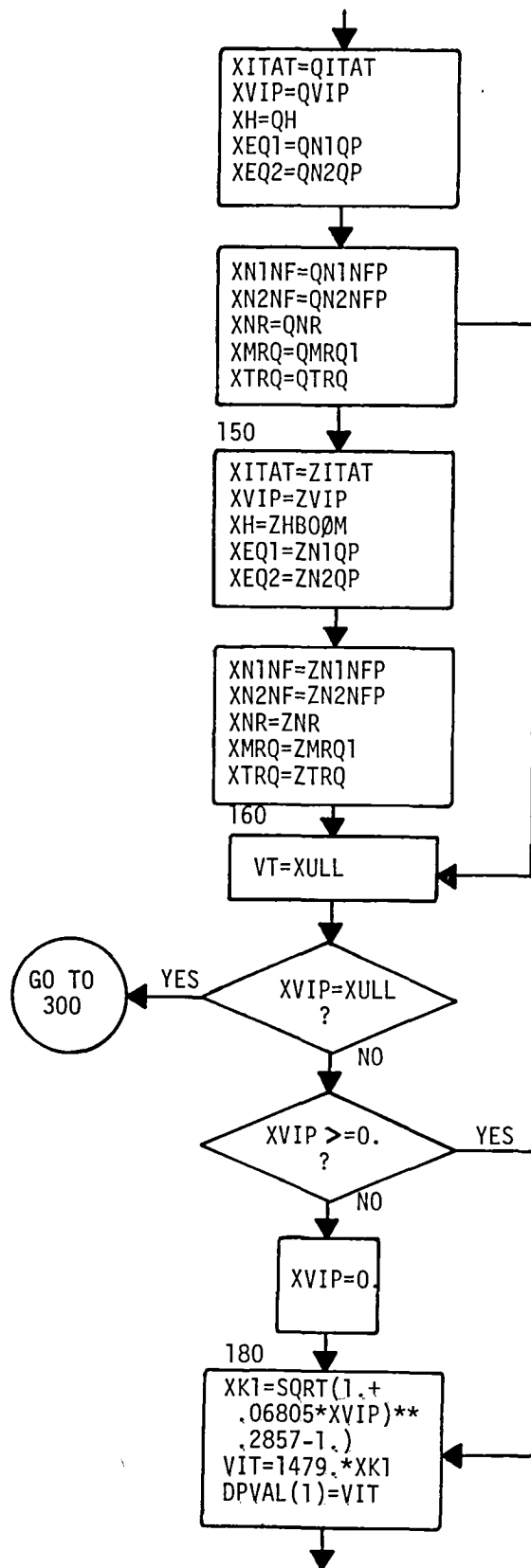
COMMON AREAS

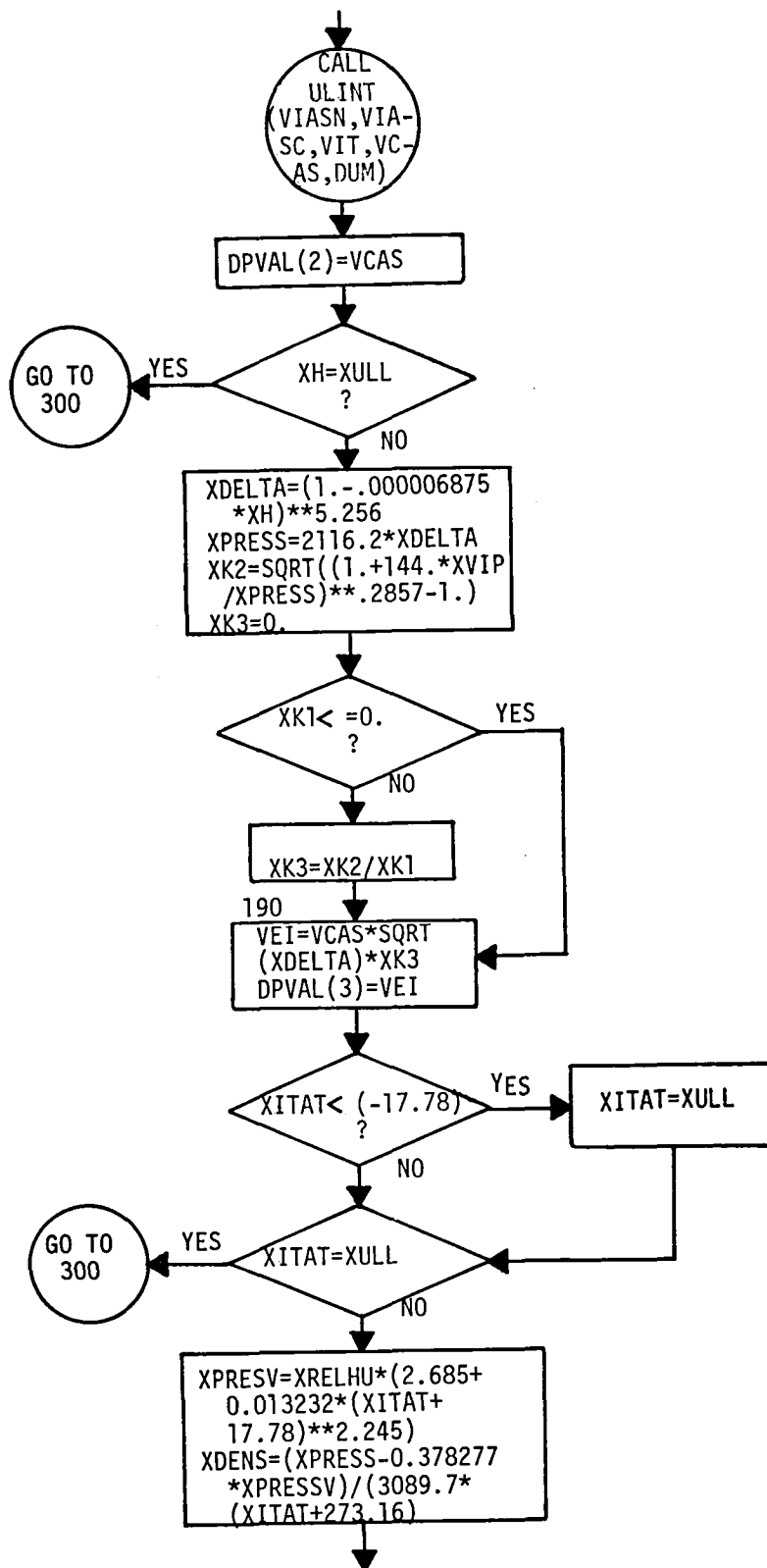
SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS ,
FILE DESCRIPTIONS OR FOR ANY OTHER SPECIFIC INFORMATION)

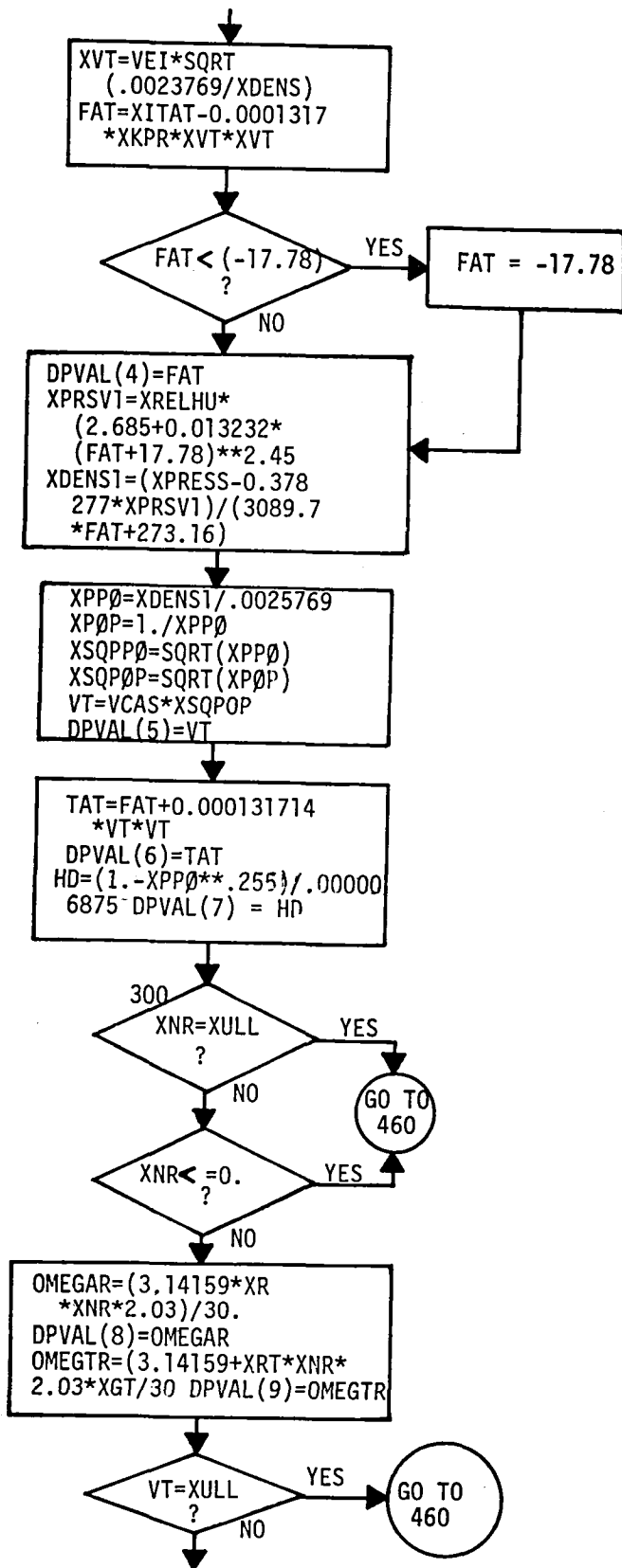


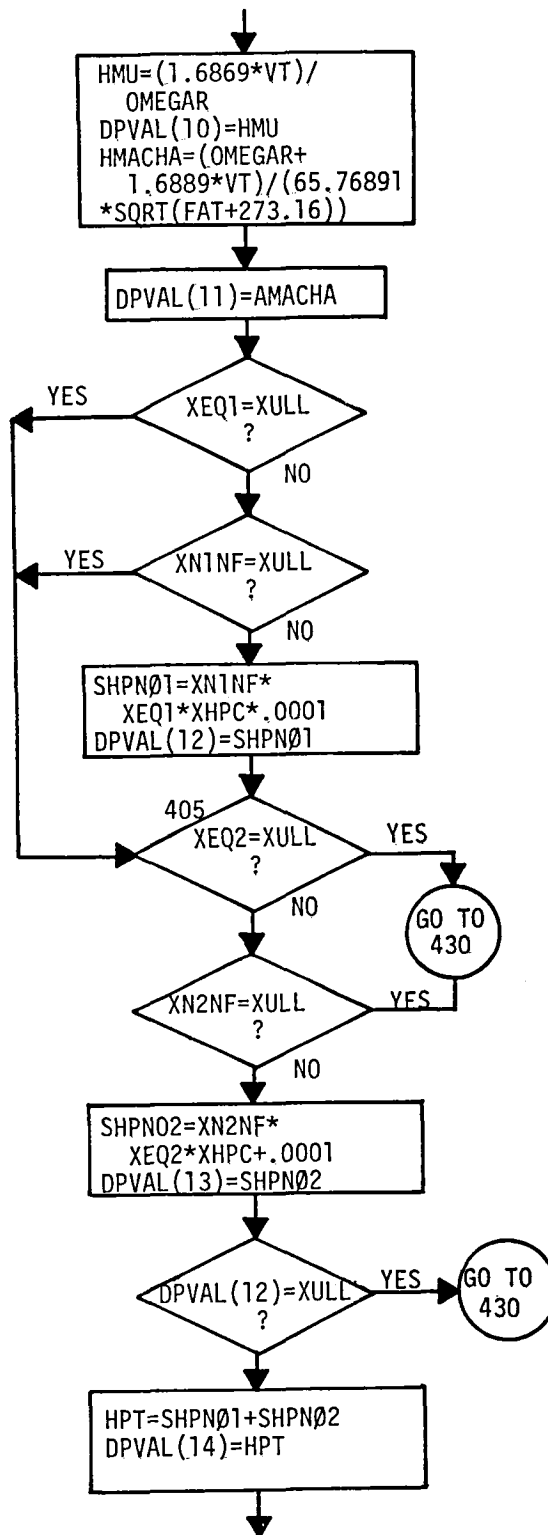


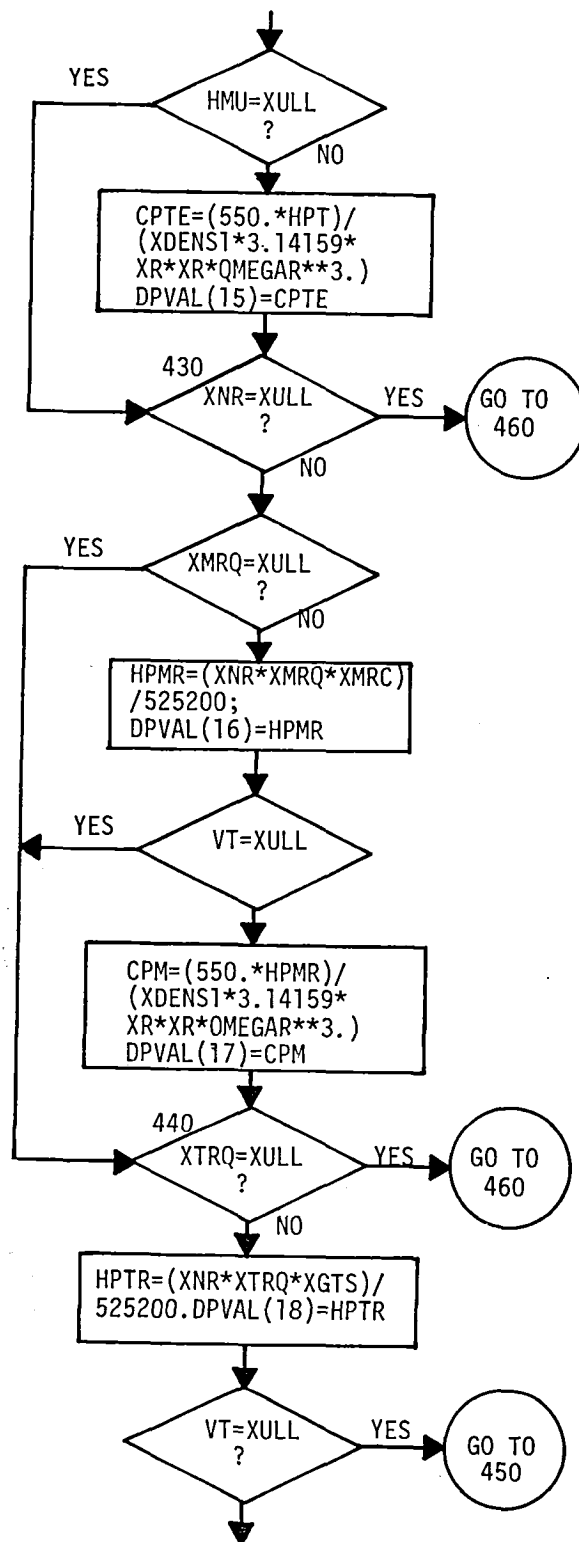


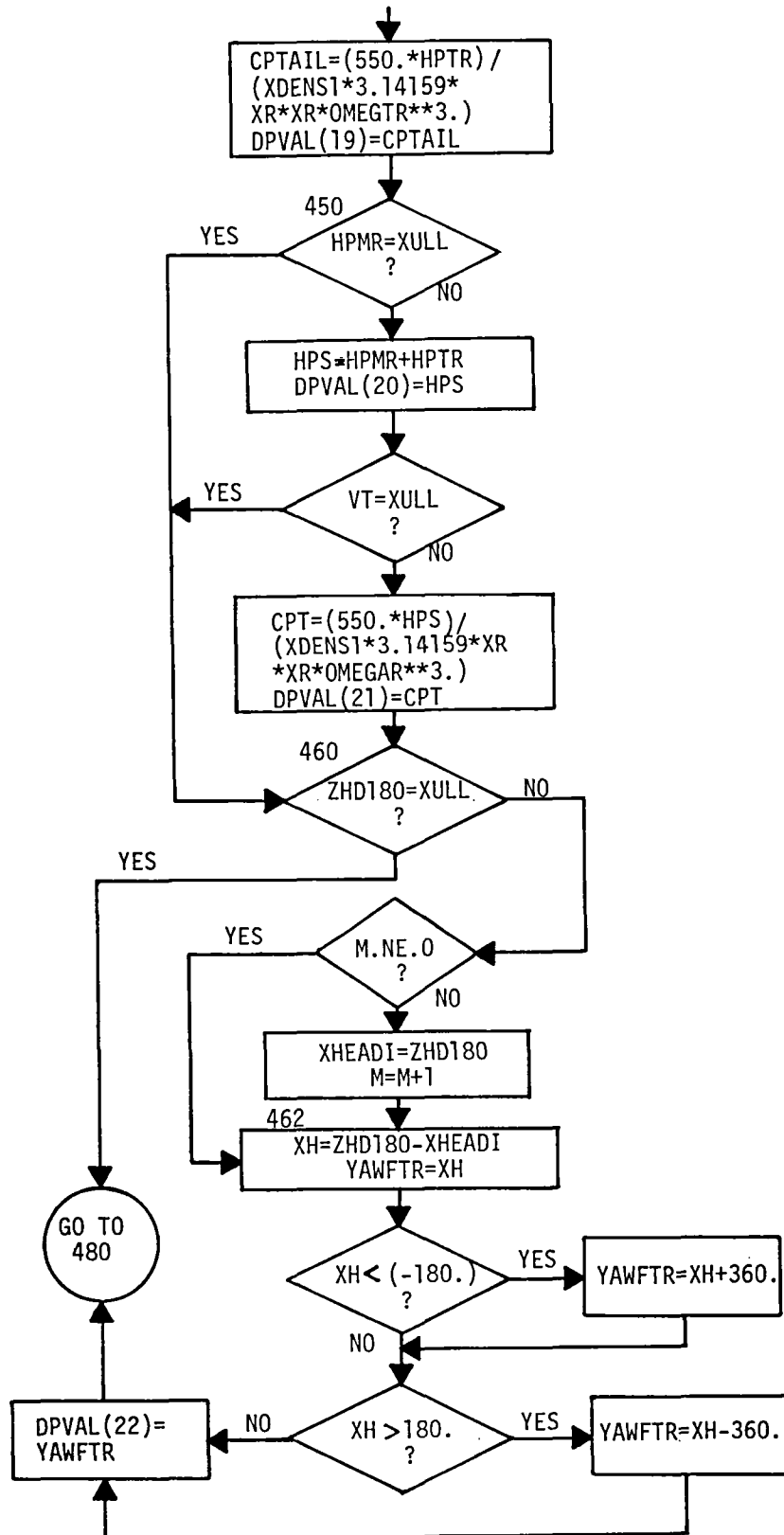


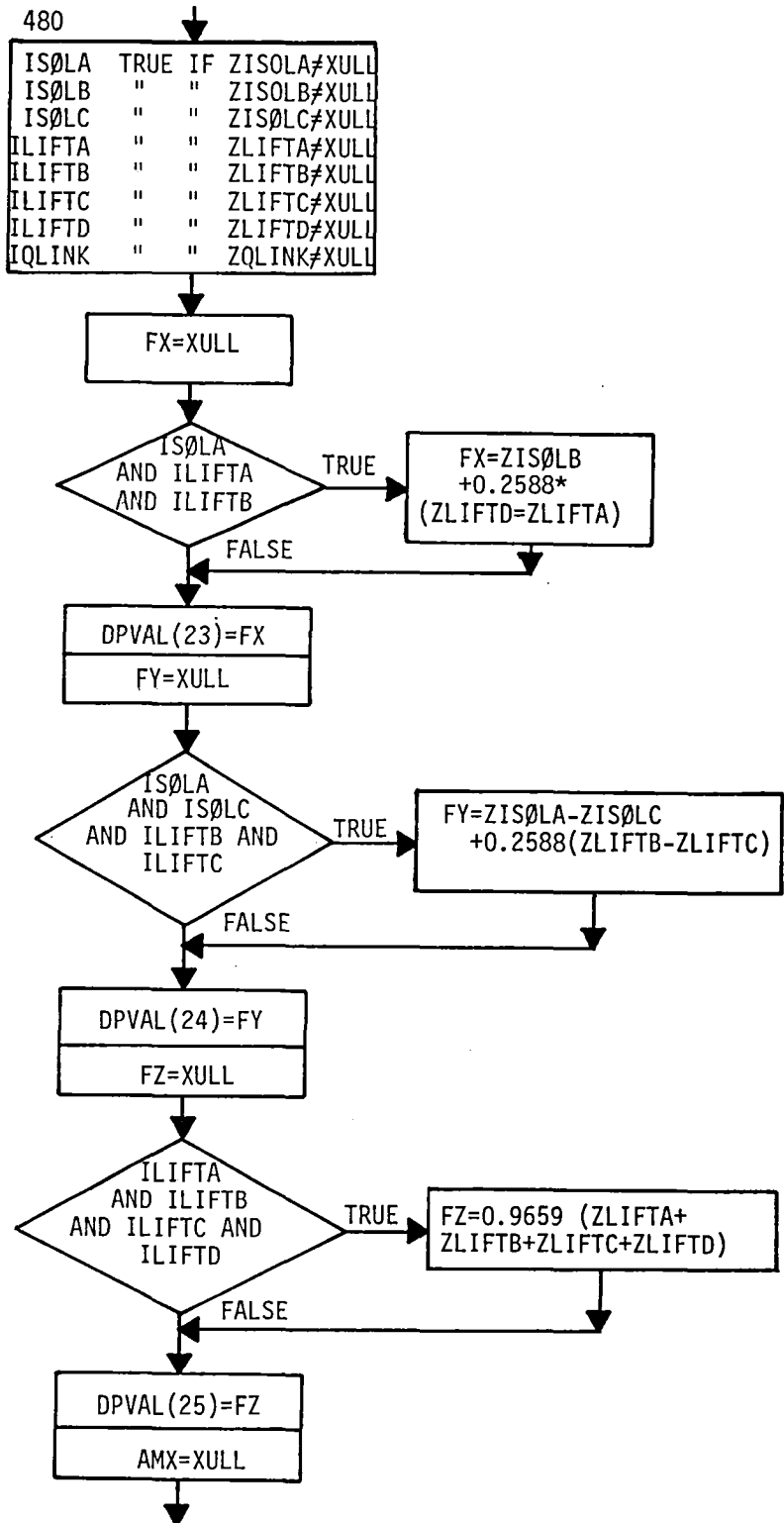


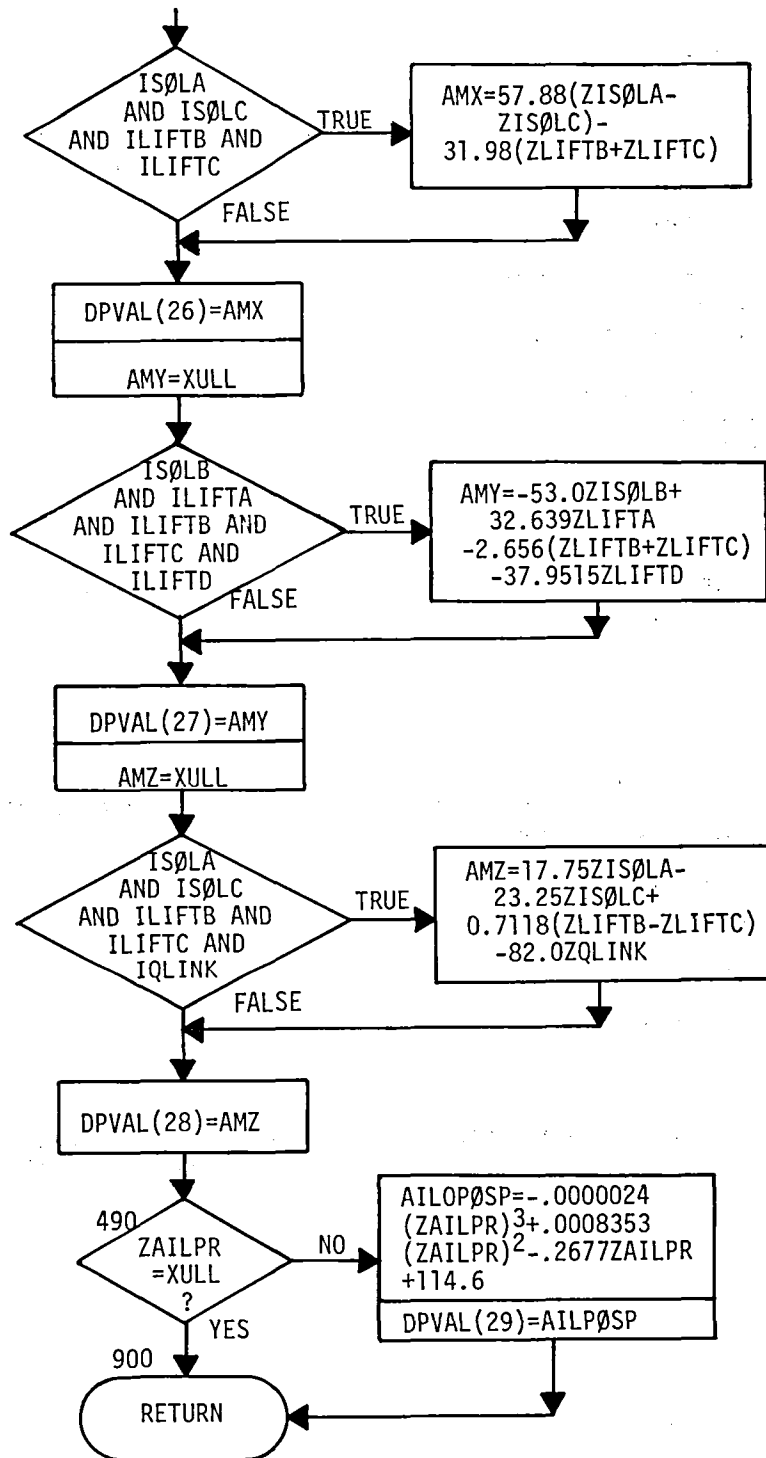












ULIN SUBROUTINE ULINT(CN,C,X,Z,ZX)

SUBROUTINE ULINT(CN,C,X,Z,ZX)

*****SUBROUTINE ULINT*****

PROGRAM IDENTIFICATION

PROGRAM NAME ----- ULINT
PROGRAM NUMBER ----- 112338
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW625/635
MEMORY -----
PERIPHERALS -----
LANGUAGE ----- HW6000 FORTRAN/FORTY

PURPOSE

SUBROUTINE CALLED BY DPCOMP TO PERFORM UNIVARIATE LINEAR
INTERPOLATION.

METHOD

INPUT/OUTPUT

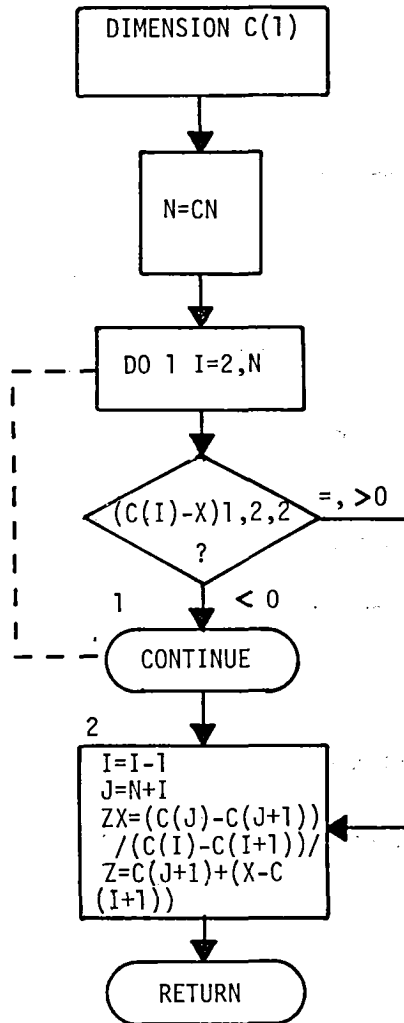
CN - NO. OF X VALUES IN C
C - TABLE OF VALUES (CN X'S (MONOTONICALLY INCREASING) .
FOLLOWED BY CN Y'S)
X - INPUT X VALUES
Z - RETURNED Z VALUE
ZX - RETURNED SLOPE

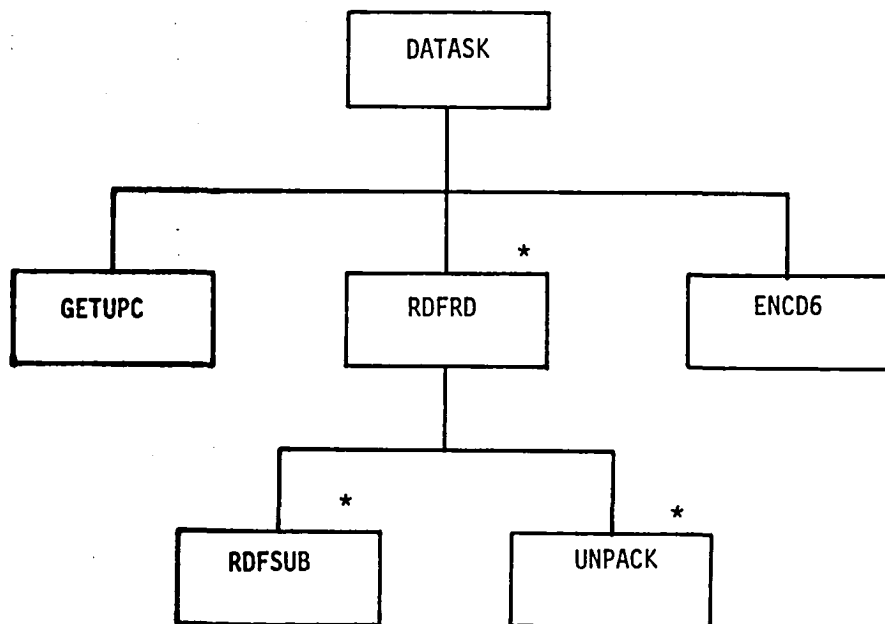
CALLING SEQUENCE

CALL ULINT(CN,C,X,Z,ZX)

COMMON AREAS

SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS ,
FILE DESCRIPTIONS OR FOR ANY OTHER SPECIFIC INFORMATION)





*See Sub-program RDFRD for Comments and Flowcharts

HIERARCHY CHART for DATASK PROGRAM

DATAK SUBROUTINE DATAK

SUBROUTINE DATAK

*****DATAK*****

PROGRAM IDENTIFICATION

PROGRAM NAME ----- DATAK
PROGRAM NUMBER ----- 112320
AUTHOR ----- TERRY D SOMMERS

COMPUTER ----- HW-625/635
MEMORY ----- ALL FILES OPEN(16K)
PERIPHERALS ----- CARD READER,DISC,PRINTER
LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

TO GENERATE A DATA ANALYSIS REPORT TO BE USED BY
ENGINEERS FOR DETERMINING FLIGHT CONDITIONS AND
DATA VALIDITY.

METHOD

READ CARDS CONTAINING SENSOR NAME,PRE-PROCESSING CODE
AND SAMPLE RATE. READ IN SPECIFIC EVENT UNLESS ALL EVENTS
ARE TO BE USED. GET CORRESPONDING DATA FROM STATISTICS FILE 09
AND OUTPUT VALUES IN REPORT FORM.

INPUT/OUTPUT

THEAD - HEADER TABLE ARRAY
TABREC - ARRAY FOR A 600 WORD RECORD
HEAD - A 4 X 12 ARRAY CONTAINING INFORMATION TO BE PRINTED AS
THE PAGE HEADER. 4 INPUT CARDS PUNCHED IN COLUMNS 1-72.
NRUN - COUNTER FOR EVENT NUMBER
CDIM - CARD IMAGE OF GROUPED PARAMETER NAMES, PRE-PROCESSING CODE
AND SAMPLE RATE OR EVENT NUMBERS.
MODE - CODE SET TO INFORM PROGRAM IF ALL NON-CAL EVENTS ARE
TO BE PROCESSED OR RUNS NAMED ON INPUT CARDS ARE TO
BE PROCESSED.
 MODE = 1 - PROCESS ALL NON-CAL EVENTS
 MODE = 2 - PROCESS ONLY THOSE SPECIFIED INPUTS
JRUN - INPUT RUN NUMBERS
IPAGE - CONTROLS INPUT OF PARAMETER NAMES, PPC'S AND SR'S FOR
PROGRAM LOGIC.
 IPAGE = 0 - UNTIL FIRST OR NEXT "PAGE" CARD IS FOUND
 IPAGE = 1 - WHEN "PAGE" CARD IS FOUND
 IPAGE = 2 - IF PARAMETER CARDS TERMINATED BY
 A NEW "PAGE" CARD
 IPAGE = 3 - IF PARAMETER CARDS TERMINATED WHEN
 18 PARAMETER CARDS HAVE BEEN READ
 IF PARAMETER CARDS TERMINATED BY "END" CARD
NAMES - PARAMETER MNEMONICS(NPAR IN LENGTH) MAX 18
PPC - PRE-PROCESSING CODE(NPAR IN LENGTH) MAX 18
SR - SAMPLE RATE(NPAR IN LENGTH) MAX 18

NPAR - NUMBER OF PARAMETERS COUNTED ON PROCESSING CARD
 INPUT OF PARAMETERS
 TOS - TABLE OF SUBSCRIPTS DETERMINED FOR EACH PARAMETER
 THRU SUBROUTINE RDFSUB
 TOS(4*I-3) - PASS NO. FOR PARAMETER "I"
 TOS(4*I-2) - OFFSET POSITION OF PARAMETER IN
 DATA FILE FRAME FOR PARAMETER "I"
 TOS(4*I-1) - COMPUTED "A" TERM FOR PARAMETER "I"
 TOS(4*I) - COMPUTED "B" TERM FOR PARAMETER "I"
 JINDEX - INTEGER TO USE IN SUBROUTINE ENCD6 FOR ARRANGING
 THE OUTPUT STATISTICS INTO AN AESTHETIC FORM FOR
 PRINTING
 CHBUFF - A 6 CHARACTER WORD OUTPUT FROM SUBROUTINE ENCD6
 THAT CONTAINS THE EDITED OUTPUT STATISTICS DATA
 VALUE - THE PARTICULAR STATISTIC DATA VALUE SENT TO ENCD6 FOR
 EDITING INTO THE CHBUFF WORD
 FOR PPC=S = D OR S VALUE = AVERAGE
 FOR PPC = V VALUE = 95 PERCENT
 COLTIT - ARRAY OF INFORMATION ON EACH PARAMETER NAME FOR
 PRINTING THE COLUMN TITLES OF REPORT
 CTITL - COLUMN TITLES AS DEFINED IN SUBROUTINE GETUPC FOR
 EACH PARAMETER
 LTITL - LINE TITLES AS DEFINED IN SUBROUTINE GETUPC FOR
 EACH PARAMETER (NOT USED IN THIS ROUTINE)
 LINCNT - LINE COUNTER TO DETERMINE WHEN NEW PAGE HEADINGS
 ARE TO BE PRINTED
 OUTBUF - 400 WORD BUFFER CONTAINING ONE RECORD OF STATISTICS
 DATA READ FROM THE STATISTICS FILE 09
 LINRUF - ARRAY OF CHBUFF'S ARRANGED IN OUTPUT FORM
 EVENT - EVENT NAME FOR EVENT = IRUN

CALLING SEQUENCE

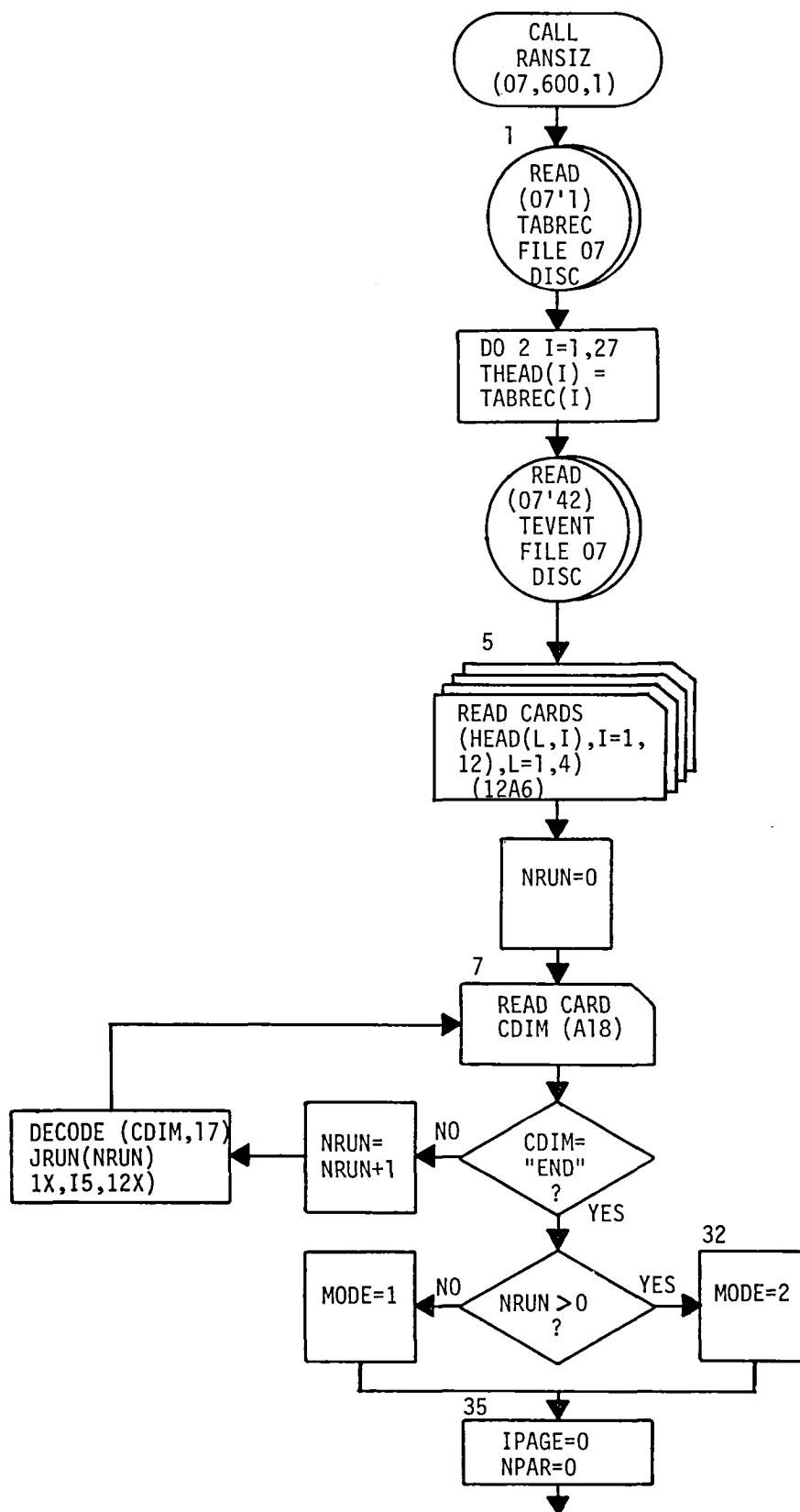
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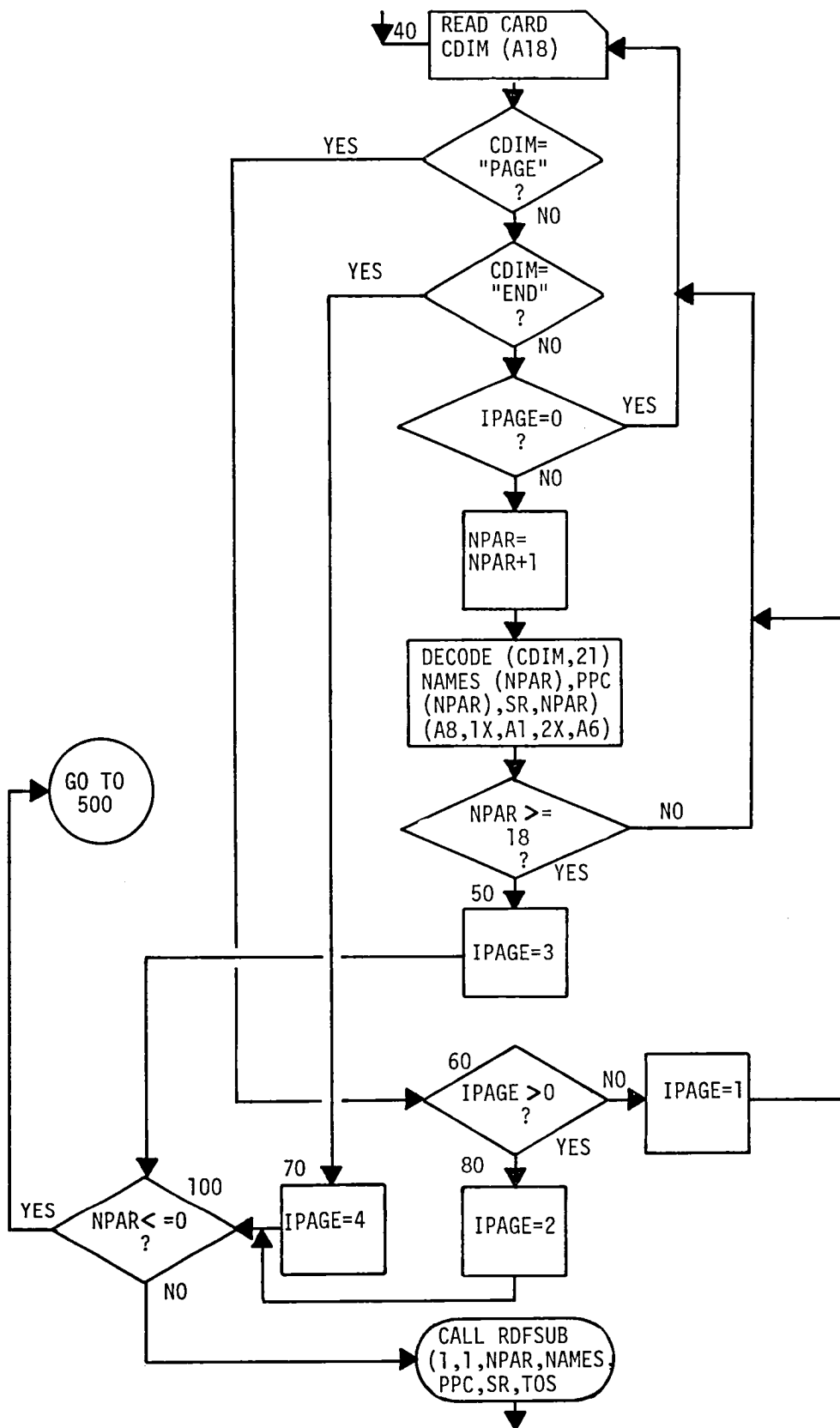
CALL RDFSUB(1,1,NPAR,NAMES,PPC,SR,TOS)
CALL GETUPC(NAMES(IPAR),PPC(IPAR),JINDEX(IPAR),CTITL,LTITL)
CALL RDFRD(1,1,1,IRUN,NPAR,NAMES,PPC,SR,ISMPL,LSMPL,
           OUTBUF,180,TOS,NFOUT,MSG,IER)
CALL ENCD6(VALUE,JINDEX(IPAR),CHBUFF)
  
```

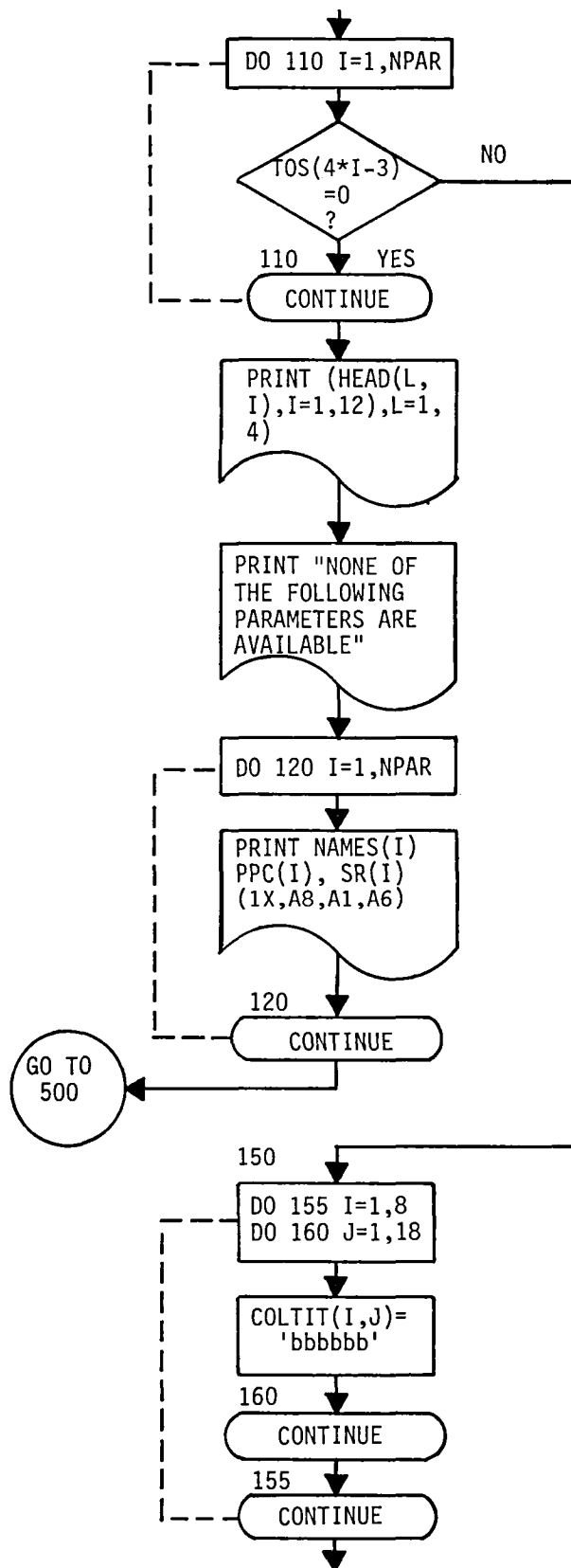
COMMON AREAS

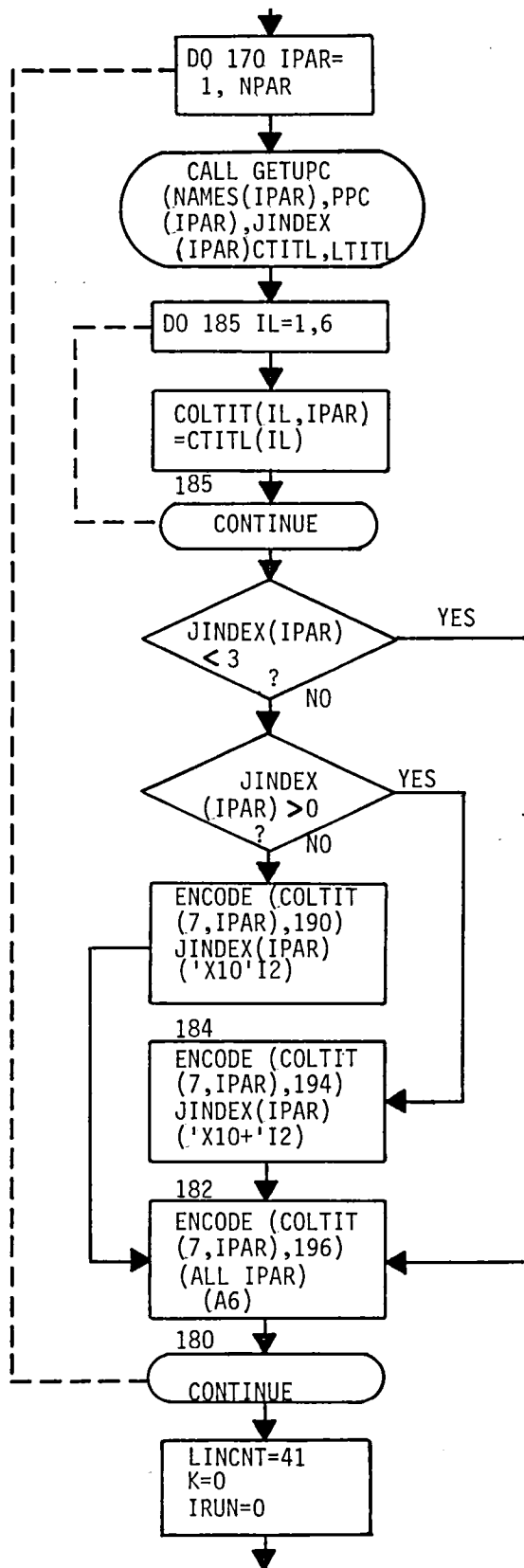
/TABL1/THEAD

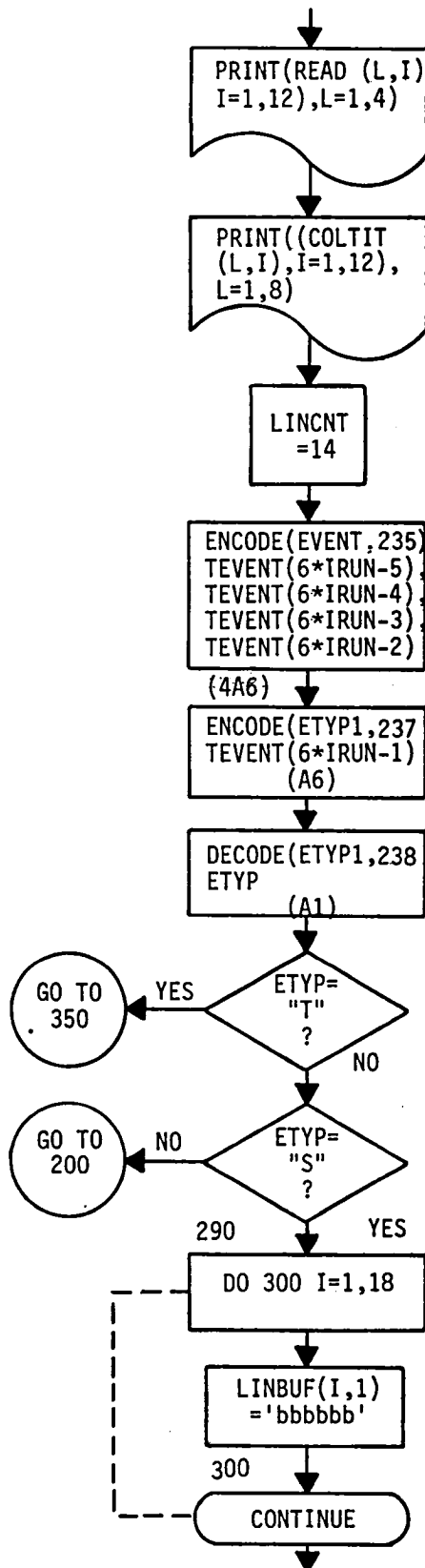
SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS
 FILE DESCRIPTIONS OR FOR ANY OTHER SPECIFIC INFORMATION.

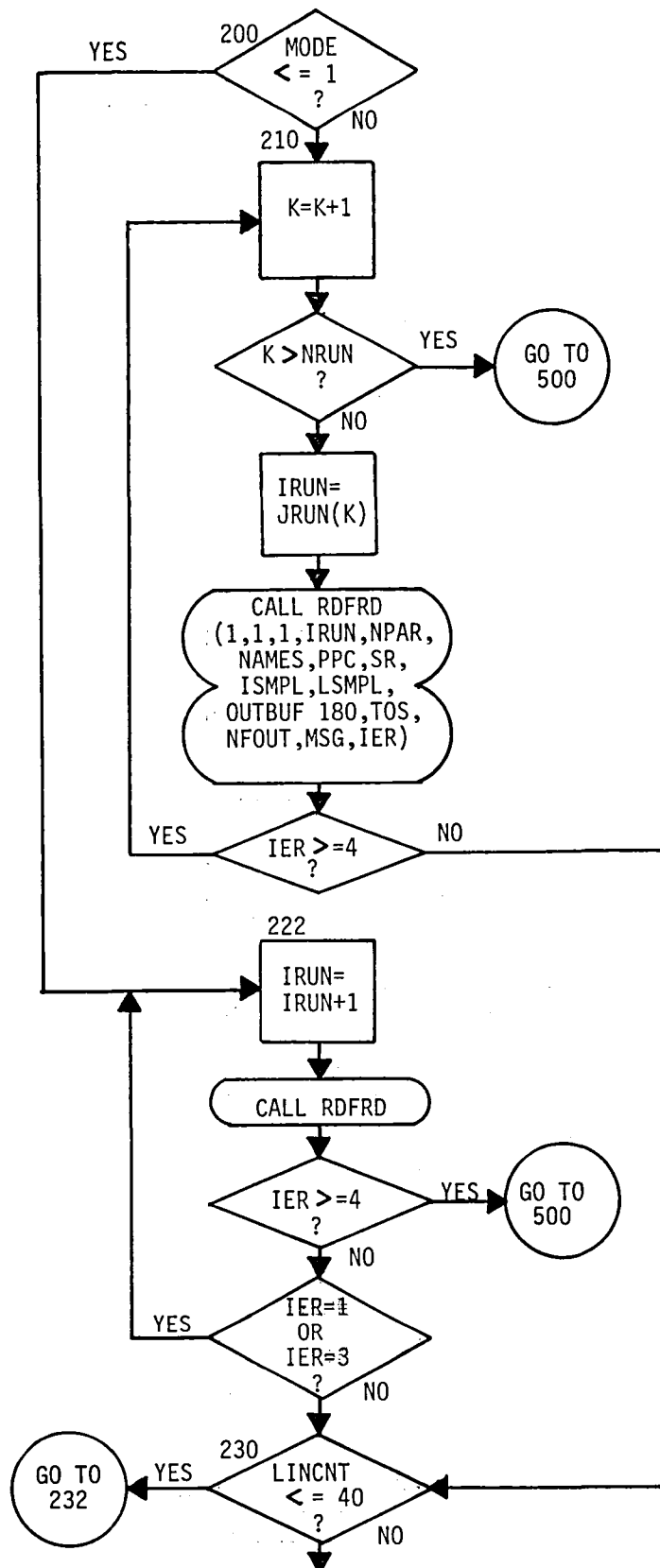


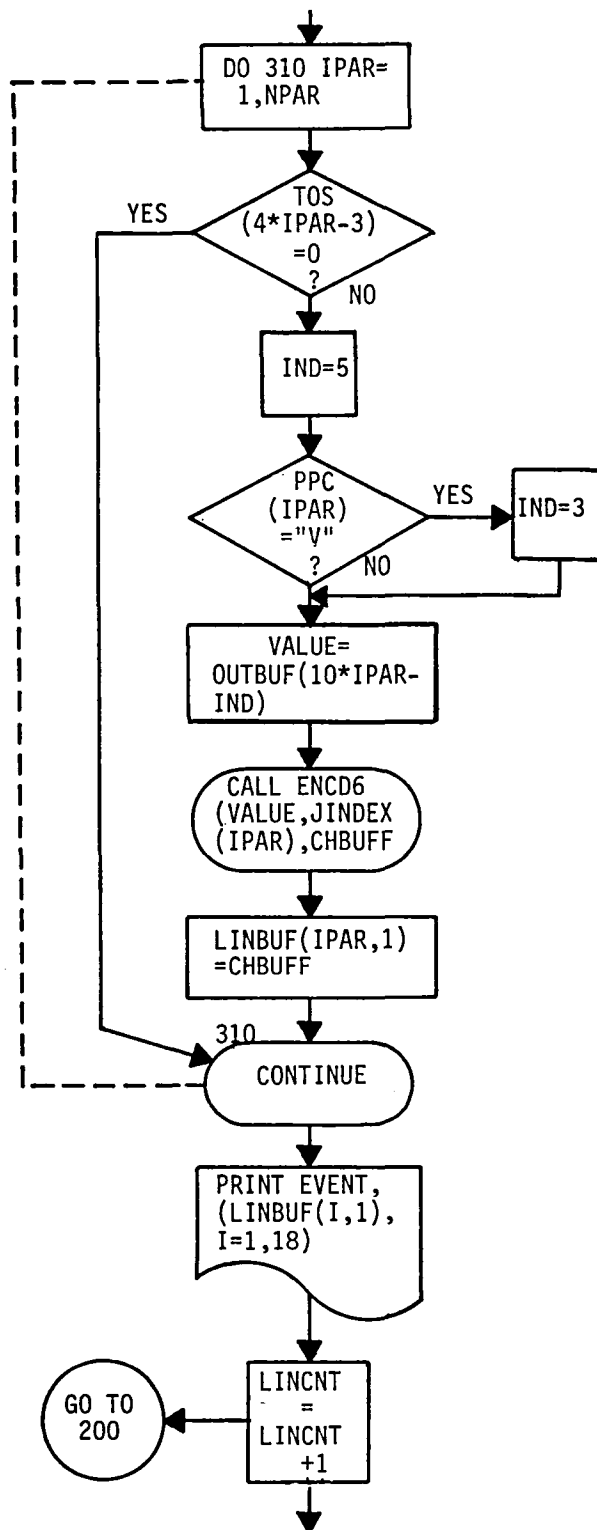


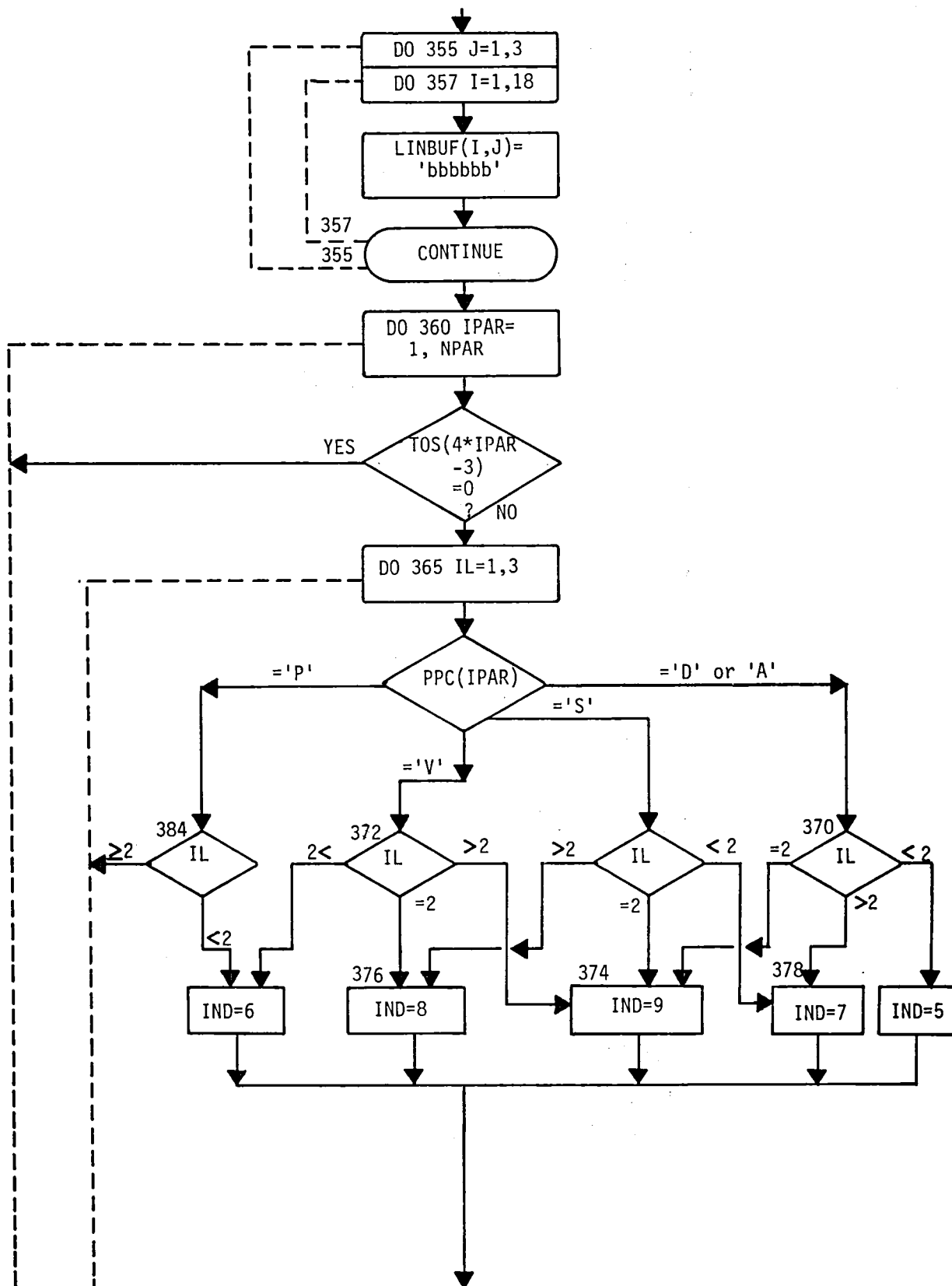


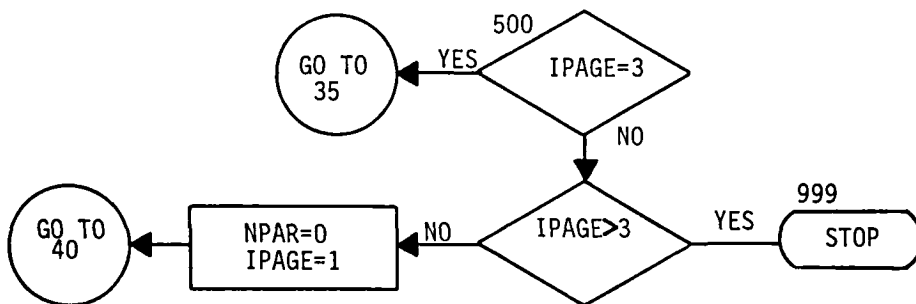
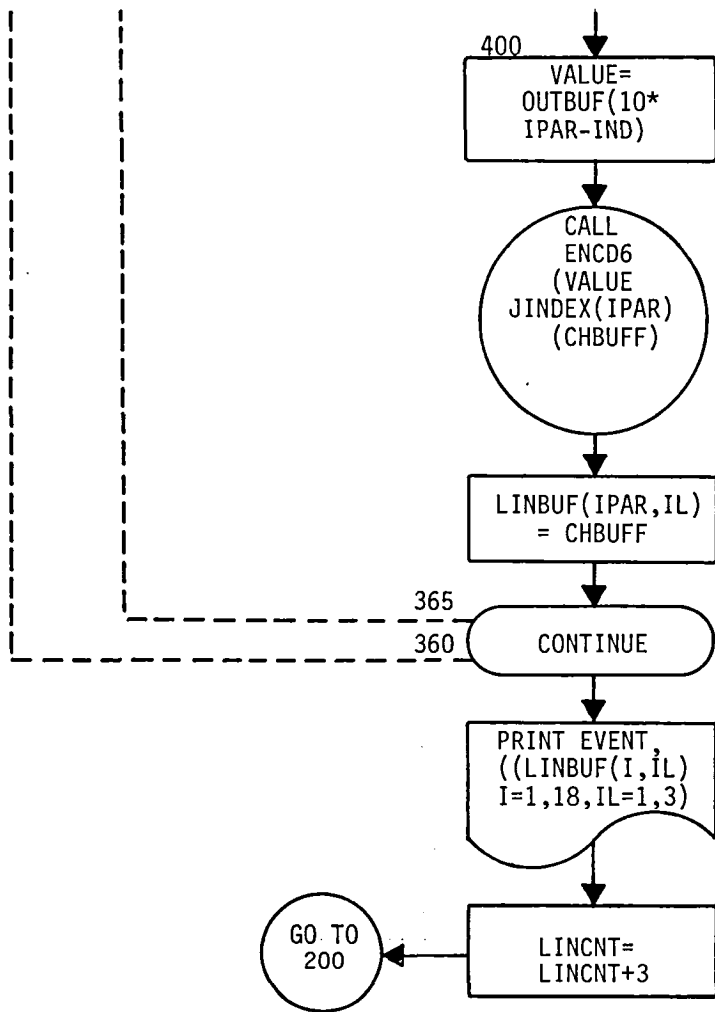












GETUPC

SUBROUTINE GETUPC (NAME, PPC, JINDEX, CTITL, LTITL)

***** SUBROUTINE GETUPC *****

PROGRAM IDENTIFICATION

PROGRAM NAME - GETUPC
PROGRAM NO. - 1.1.2320
AUTHOR - DAVID L. DAVIS

COMPUTER - HW 625/635
MEMORY -
PERIPHERALS - DISC SUBSYSTEM
LANGUAGE - HW 6000 FORTRAN

PURPOSE

TO LOCATE ON THE UPC FILE AND RETURN TO
A CALLING PROGRAM VARIOUS SPECIFICATIONS
FOR A USER REQUESTED PARAMETER. IF THE
REQUESTED PARAMETER CANNOT BE FOUND, ARTIFICIALLY
BUILT SPECIFICATIONS WILL BE RETURNED.

METHOD

THE UPC FILE IS SEARCHED FOR A MATCH ON
CONCATENATED NAME AND PRE-PROCESSING CODE.
IF SUCCESSFUL THOSE RESULTS WILL BE
RETURNED. IF NO MATCH IS FOUND THEN
ARTIFICIALLY GENERATED RESULTS WILL BE
RETURNED.

INPUT/OUTPUT

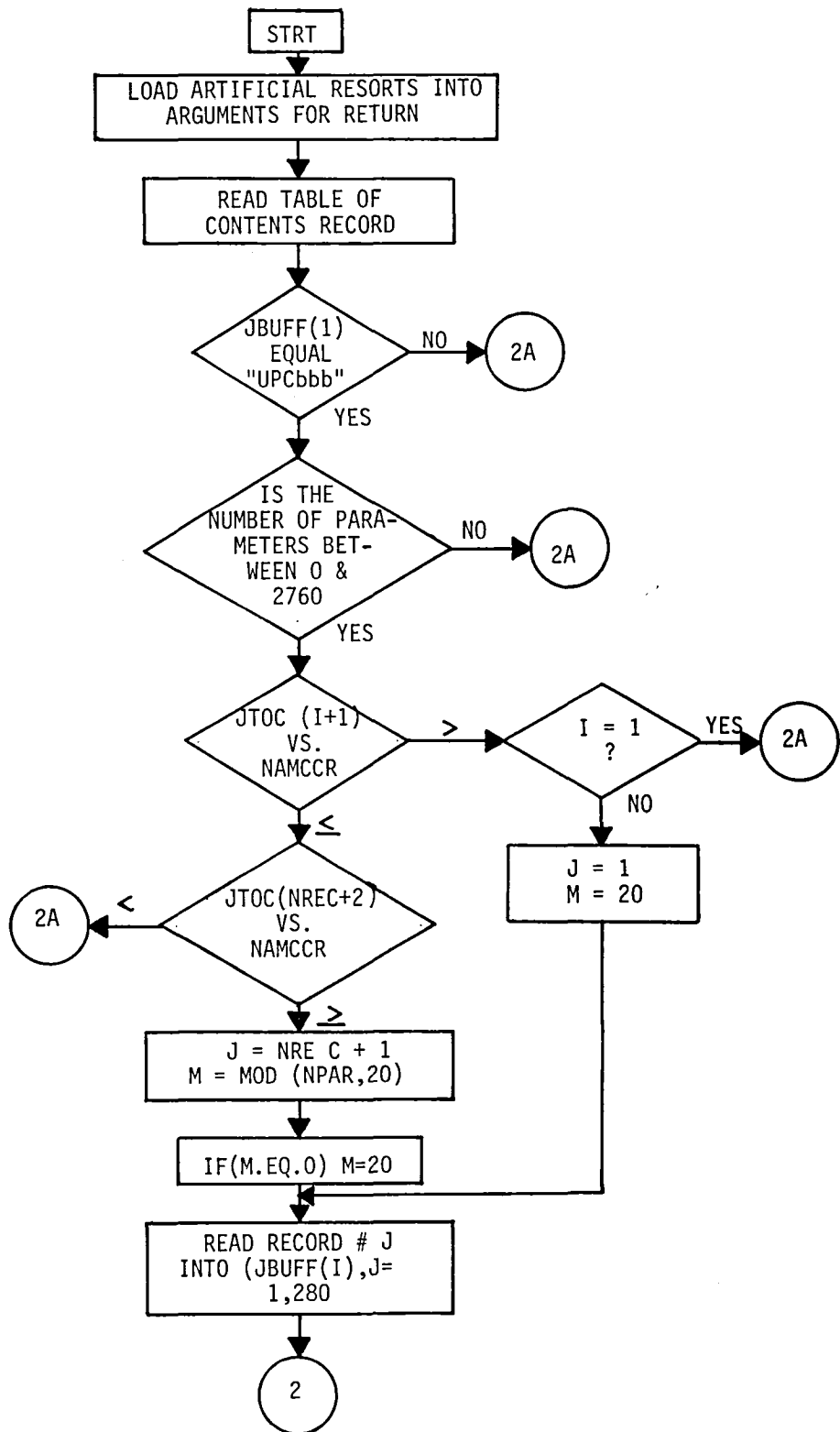
CALLING SEQUENCE

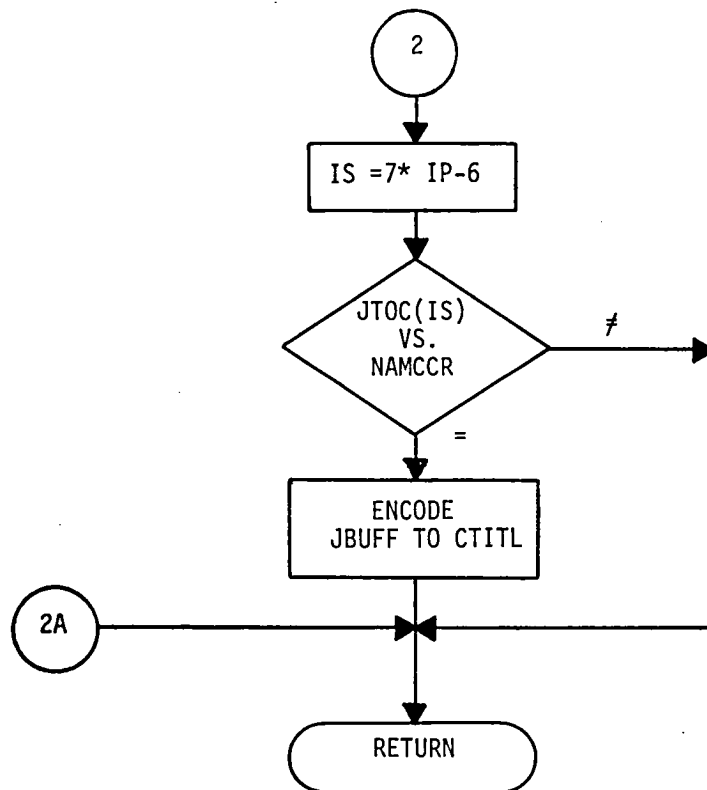
CALL GETUPC(NAME,PPC,JINDEX,CTITL,LTITL) WHERE

NAME - INPUT ARGUMENT CONTAINING CONCATENATED NAME
PPC - INPUT ARGUMENT CONTAINING PRE-PROCESSING CODE
JINDEX - OUTPUT ARGUMENT FOR INDEX INFO.
CTITL - OUTPUT ARGUMENT FOR COLUMN TITLE INFO.
LTITL - OUTPUT ARGUMENT FOR LINE TITLE INFO.

FILE DESCRIPTIONS

SEE DOCUMENTATION FOR ROUTINE #UPCGEN# FOR
COMPLETE DESCRIPTION OF THE #UPC# FILE.





ENCD SUBROUTINE ENCD6(VALUE,JINDEX,CHBUFF)

*****SUBROUTINE ENCD6*****

PROGRAM IDENTIFICATION

PROGRAM NAME ----- ENCD6
PROGRAM NUMBER ----- 112320
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW-625/635
MEMORY -----
PERIPHERALS -----
LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

ROUTINE ENCODES VALUE IN 6 CHARACTER FIELD WITH FORMAT
DETERMINED BY READOUT PRECISION CODE NUMRER, JINDEX.
SCIENTIFIC NOTATION USED IF IABS(JINDEX) GE. 3.

METHOD

CHECK FOR NULL VALUE. CHECK FOR JINDEX BEING GE. 3.
REFORMAT VALUE ACCORDING TO JINDEX VALUE. RETURN
TO DATASK ROUTINE.

INPUT/OUTPUT

XULL - NULL VALUE EQUAL TO 037677777777
JINDEX - INTEGER TO USE IN SUBROUTINE ENCD6 FOR ARRANGING
THE OUTPUT STATISTICS INTO AN AESTHETIC FORM FOR
PRINTING
CHBUFF - A 6 CHARACTER WORD OUTPUT FROM SUBROUTINE ENCD6
THAT CONTAINS THE EDITED OUTPUT STATISTICS DATA
VALUE - THE PARTICULAR STATISTIC DATA VALUE SENT TO ENCD6 FOR
EDITING INTO THE CHBUFF WORD
FOR PPC'S = D OR S VALUE = AVERAGE
FOR PPC = V VALUE = 95 PERCENT

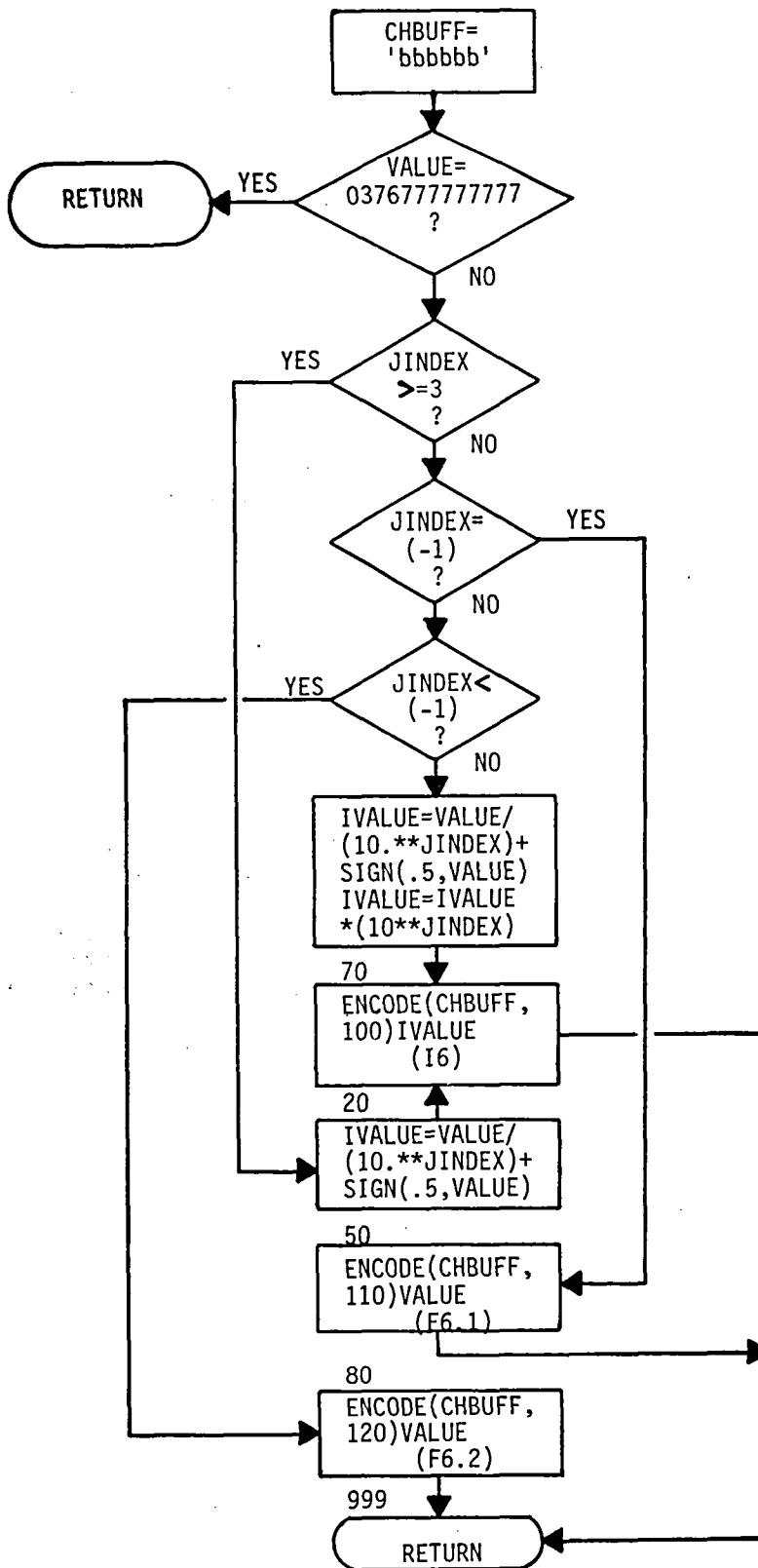
CALLING SEQUENCE

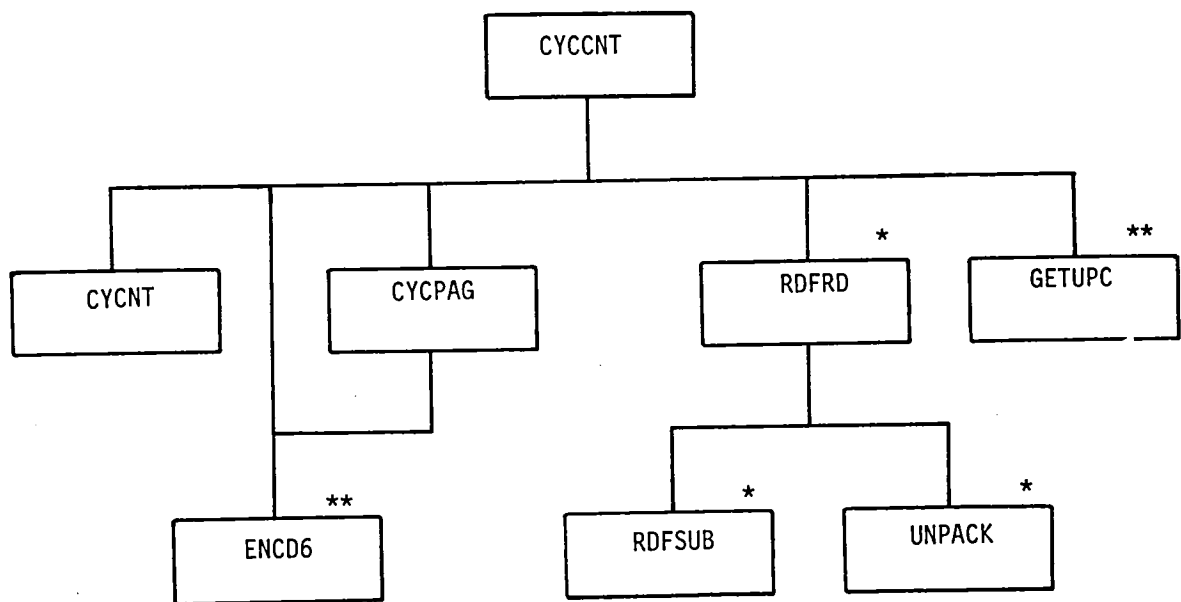
CALL ENCD6(VALUE,JINDEX,CHBUFF)

COMMON AREAS

NONE

SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR
SPECIFIC INFORMATION.





*See Sub-program RDFRD for Comments and Flowcharts
**See Program DATASK for Comments and Flowcharts

HIERARCHY CHART for CYCLE COUNTS PROGRAM

CCNT SUBROUTINE CYCCNT

SUBROUTINE CYCCNT

PROGRAM IDENTIFICATION

PROGRAM NAME ----- CYCCNT
PROGRAM NUMBER ----- 112336
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW625/635
MEMORY ----- ALL FILES OPEN (20K)
PERIPHERALS ----- CARD READER,DISC,PRINTER
LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

TO PROCESS VIBRATORY COMPONENT OF PEAK STRESS CONVERTER FOR A SELECTED PARAMETER AND EVENT COMBINATION SO AS TO OBTAIN A COUNT OF THE NUMBER OF VIBRATORY CYCLES WHICH OCCUR IN EACH OF 8 CLASS INTERVALS. ALSO COMPUTED ARE THE ABSOLUTE MAXIMUM LEVEL AND ABSOLUTE MINIMUM LEVEL EXPERIENCED DURING THE EVENT FOR FM DATA ONLY.

METHOD

TWO METHODS OF EVENT SELECTION ARE IMPLEMENTED

1. ALL NON-CALIBRATION EVENTS
2. USER SPECIFIED EVENTS

THREE METHODS OF PARAMETER SELECTION ARE IMPLEMENTED

1. ALL AVAILABLE VIBRATORY PARAMETERS
2. ALL AVAILABLE VIBRATORY PARAMETERS ON A USER SPECIFIED PASS
3. USER SPECIFIED VIBRATORY PARAMETERS

IN ALL OF THE ABOVE THE CONCERN LEVEL GREATER THAN 0 MUST BE PRESENT ON THE SENSOR FILE OR THE PARAMETER WILL BE BYPASSED.

ASSUMPTIONS

1. VIBRATORY CANNOT EXIST WITHOUT CORRESPONDING STEADY.
2. VIBRATORY CANNOT BE A DERIVED PARAMETER.
3. STATS CANNOT EXIST WITHOUT DATA
4. ON ANY FRAME, IF VIBRATORY IS NULL, STEADY IS ALL NULL.

INPUT/OUTPUT

THEAD - HEADER TABLE ARRAY
TABREC ARRAY FOR A 600 WORD RECORD
TEVENT - EVENT ARRAY
NAME - SENSOR NAME
SR - SAMPLE RATE
PPC - PRE-PROCESSING CODE
IPASS - PASS NUMBER
MAXPAS - MAXIMUM NUMBER OF PASSES
CONLVL - CONCERN LEVEL

IENT - INITIAL DATA POINT
 LEN - LAST DATA POINT
 ISMPL - INITIAL SAMPLE
 LSMPL - LAST SAMPLE
 ABSMAX - ABSOLUTE MAXIMUM DATA POINT
 ABSMIN - ABSOLUTE MINIMUM DATA POINT
 FLTMAX - MAXIMUM DATA POINT
 FLTMIN - MINIMUM DATA POINT

CALLING SEQUENCE

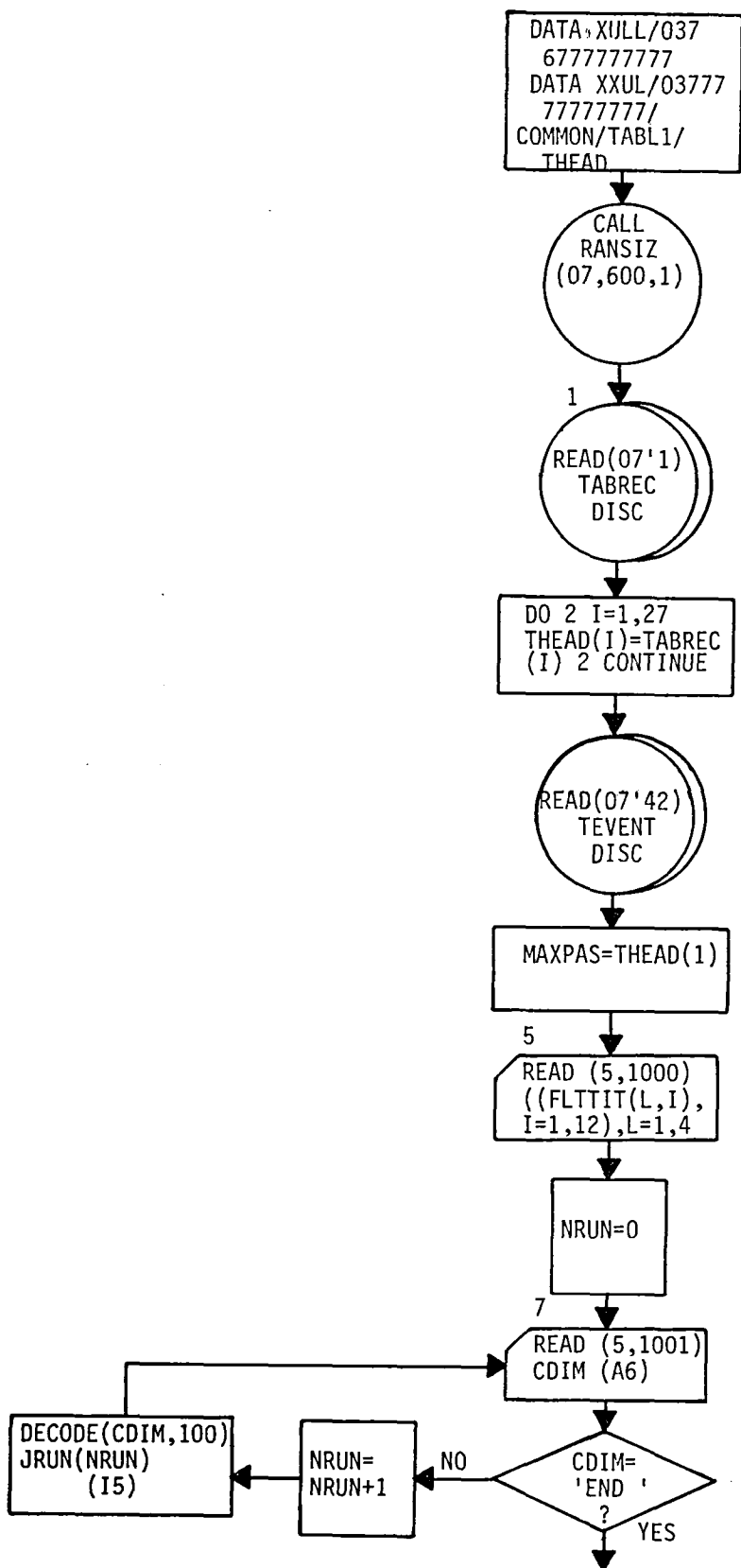
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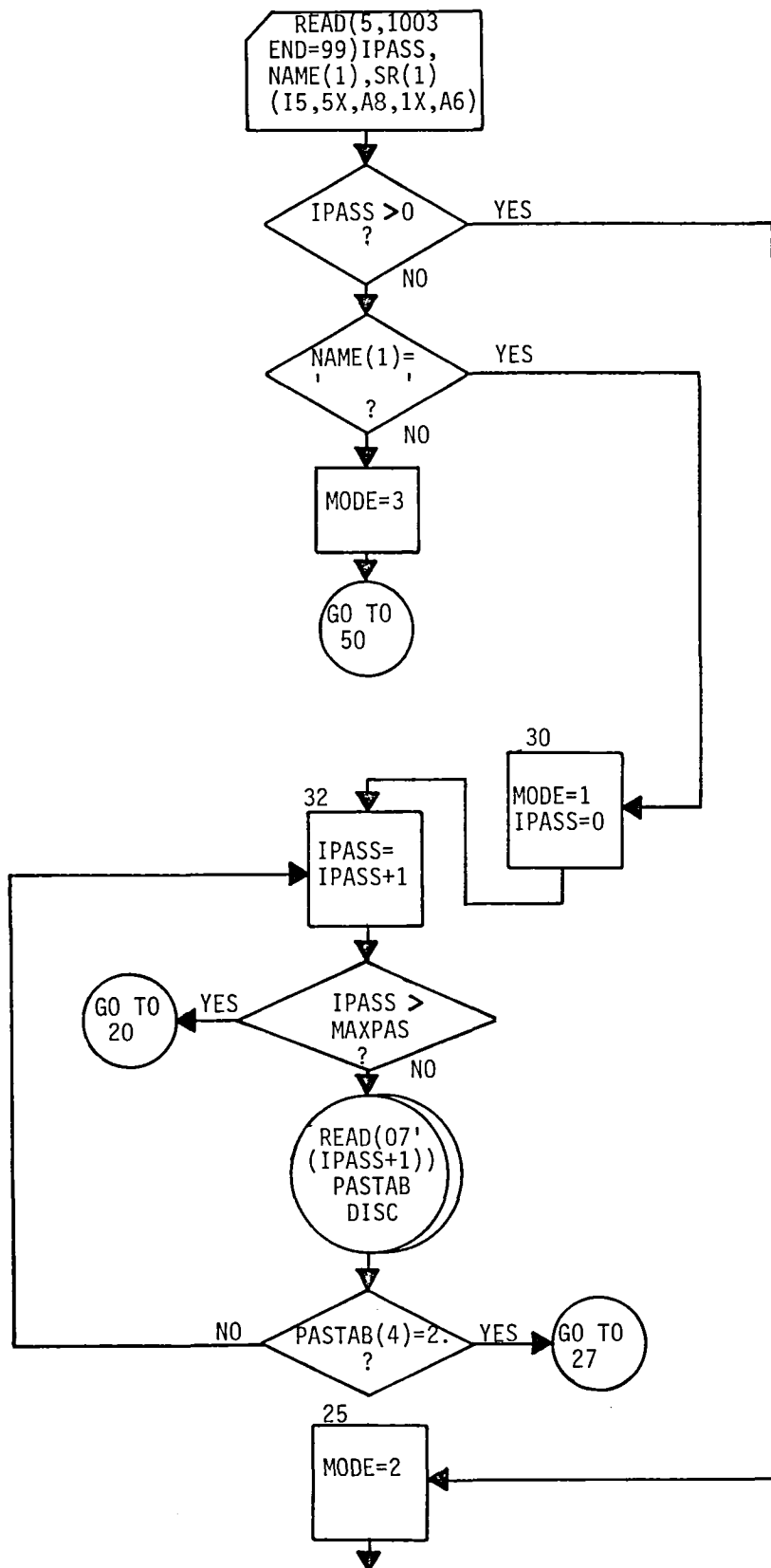
CALL RDFSUB(0,1,2,NAME,PPC,SR,TOS)
CALL GETUPC(NAME(1),PPC(1),JINDEX,CTITL,LTITL)
CALL RDRFD(1,1,1,IRUN,2,NAME,PPC,SR,ISMPL,LSMPL,OUTBUF,20,
          TOS,NFOUT,MSG,IER)
CALL ENCD6(OUTBUF(N),JINDEX,LINBUF(N))
CALL RDRFD(1,0,1,IRUN,2,NAME,PPC,SR,ISMPL,LSMPL,OUTBUF,2*LEN,
          TOS,NFOUT,MSG,IER)
CALL CYCNT(IENT,NFRM,OUTBUF(1),OUTBUF(LEN+1),CONLVL,CYCINT,
          ABSMAX,ABSMIN,NGD)
CALL CYCPAG(FLTTIT,LTITL,SR(1),JINDEX,CONLVL)
  
```

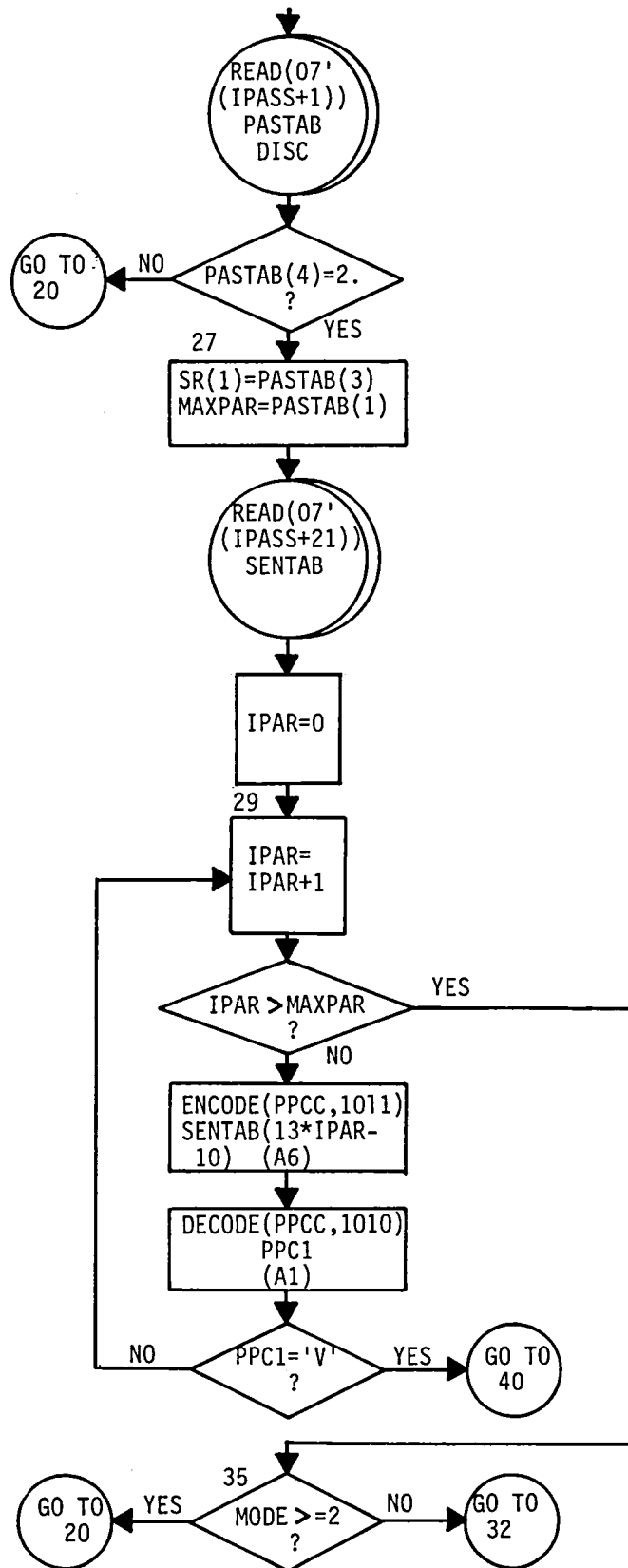
COMMON AREAS

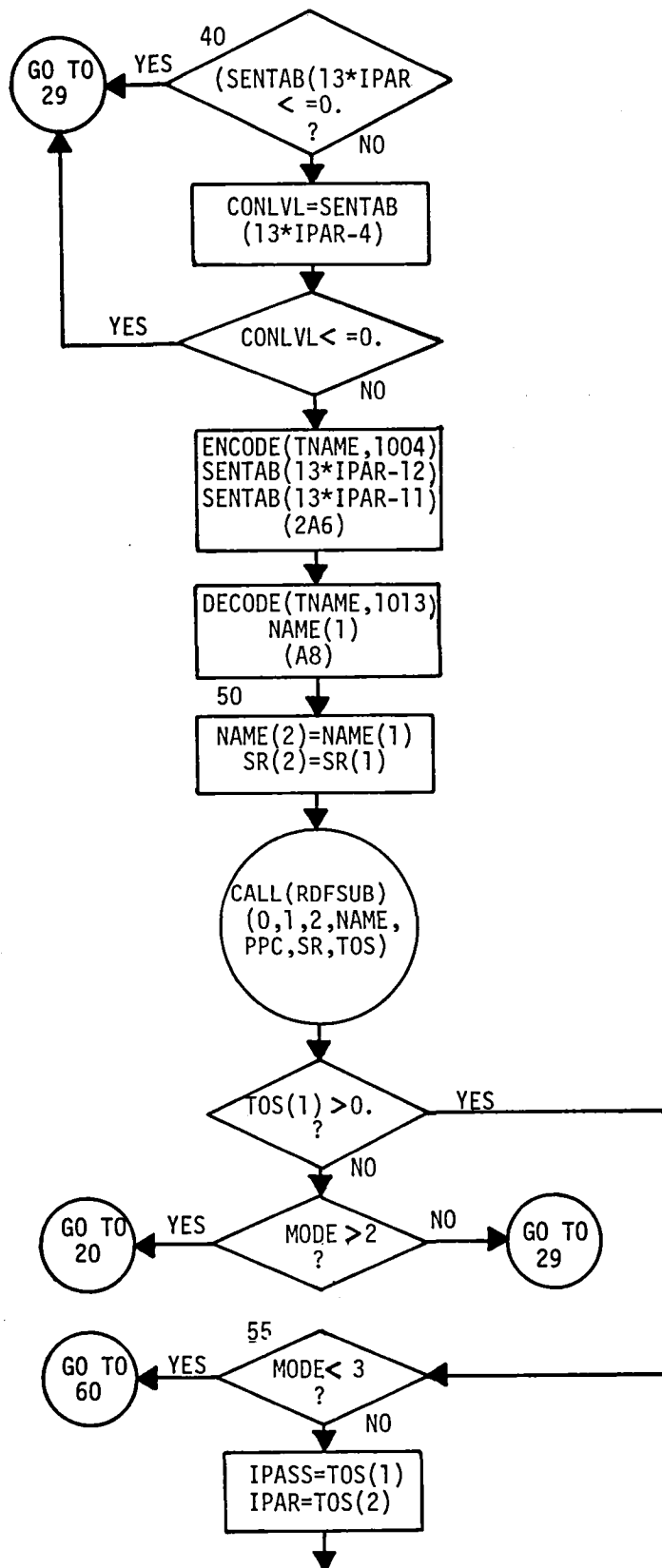
/TABL1/THEAD

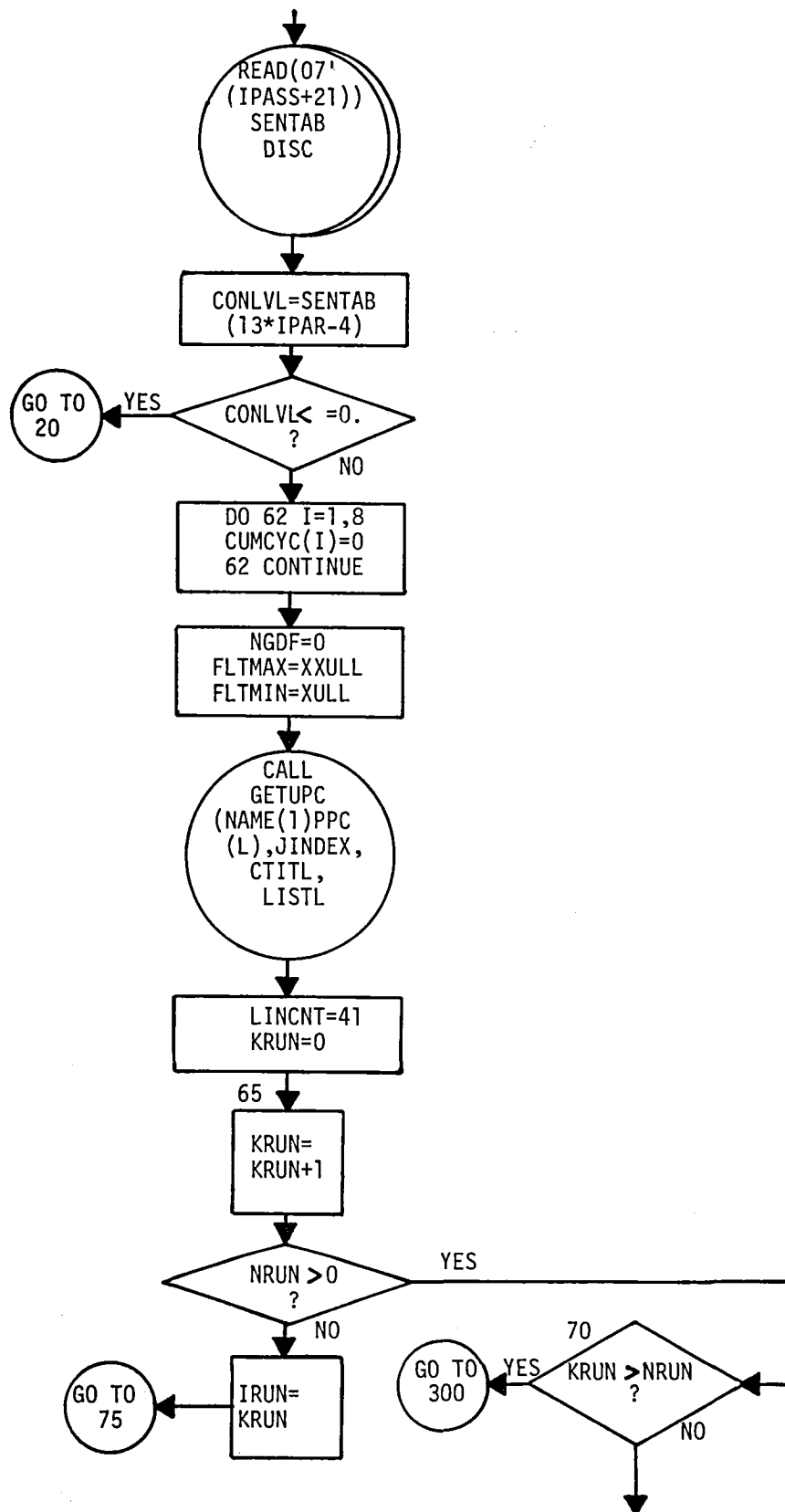
SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS,
FILE DESCRIPTIONS OR FOR ANY OTHER SPECIFIC INFORMATION.

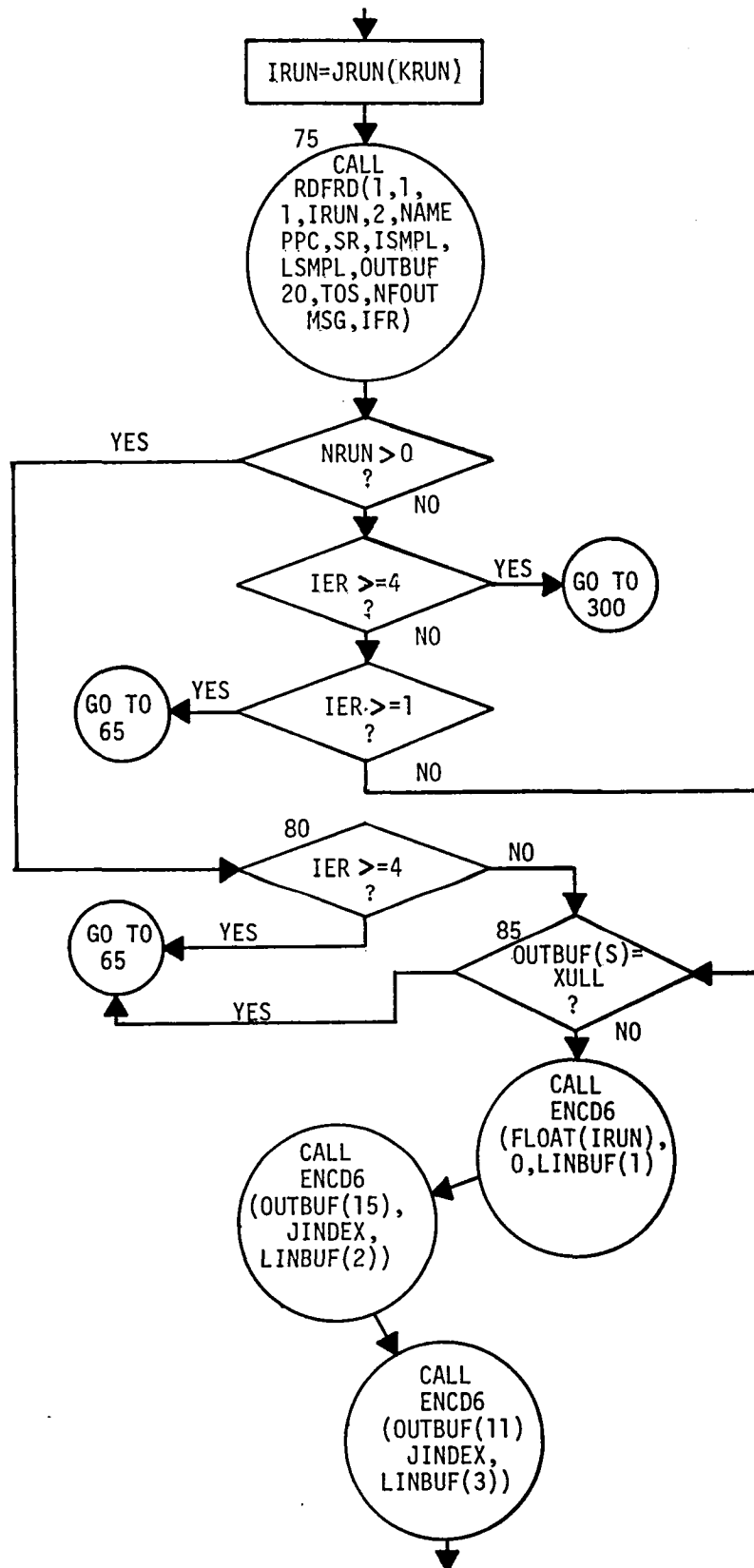


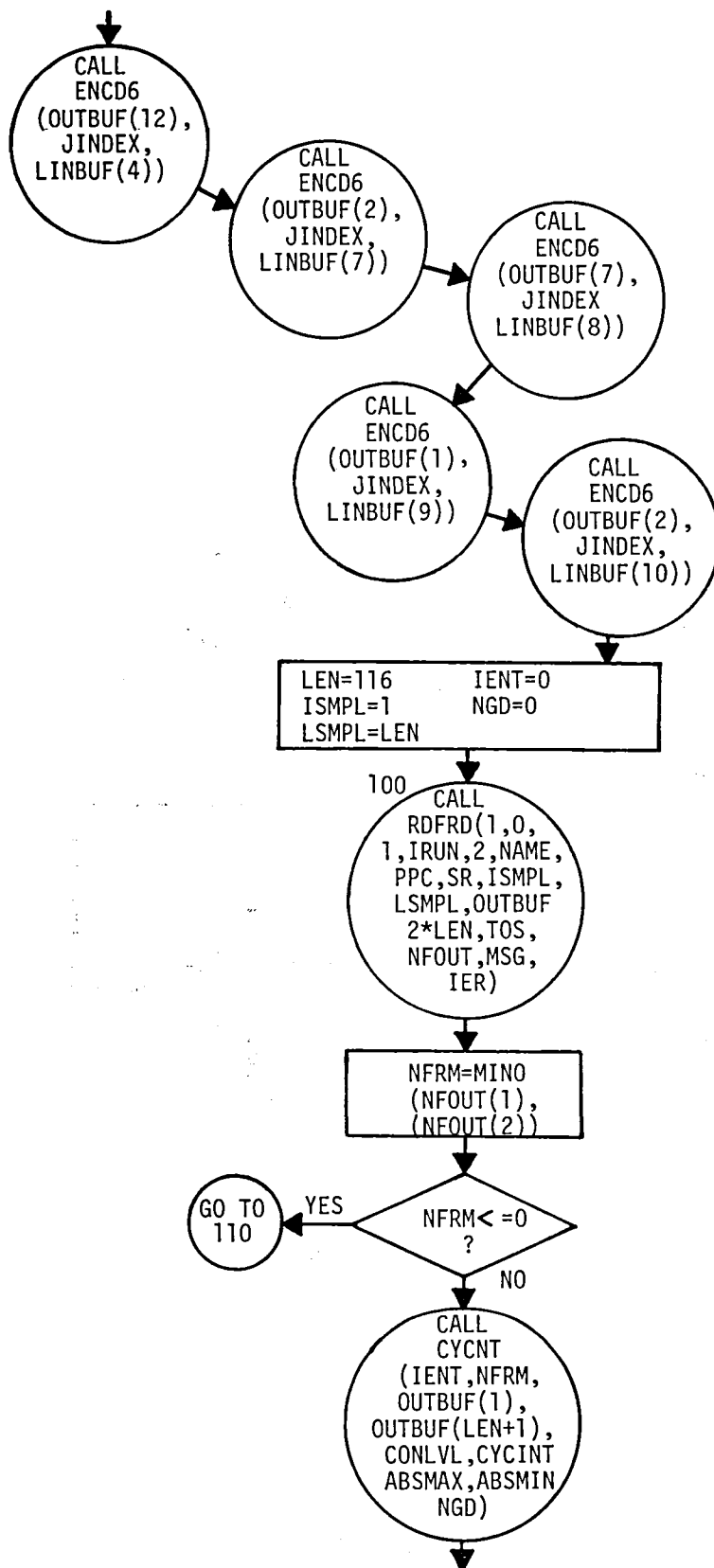


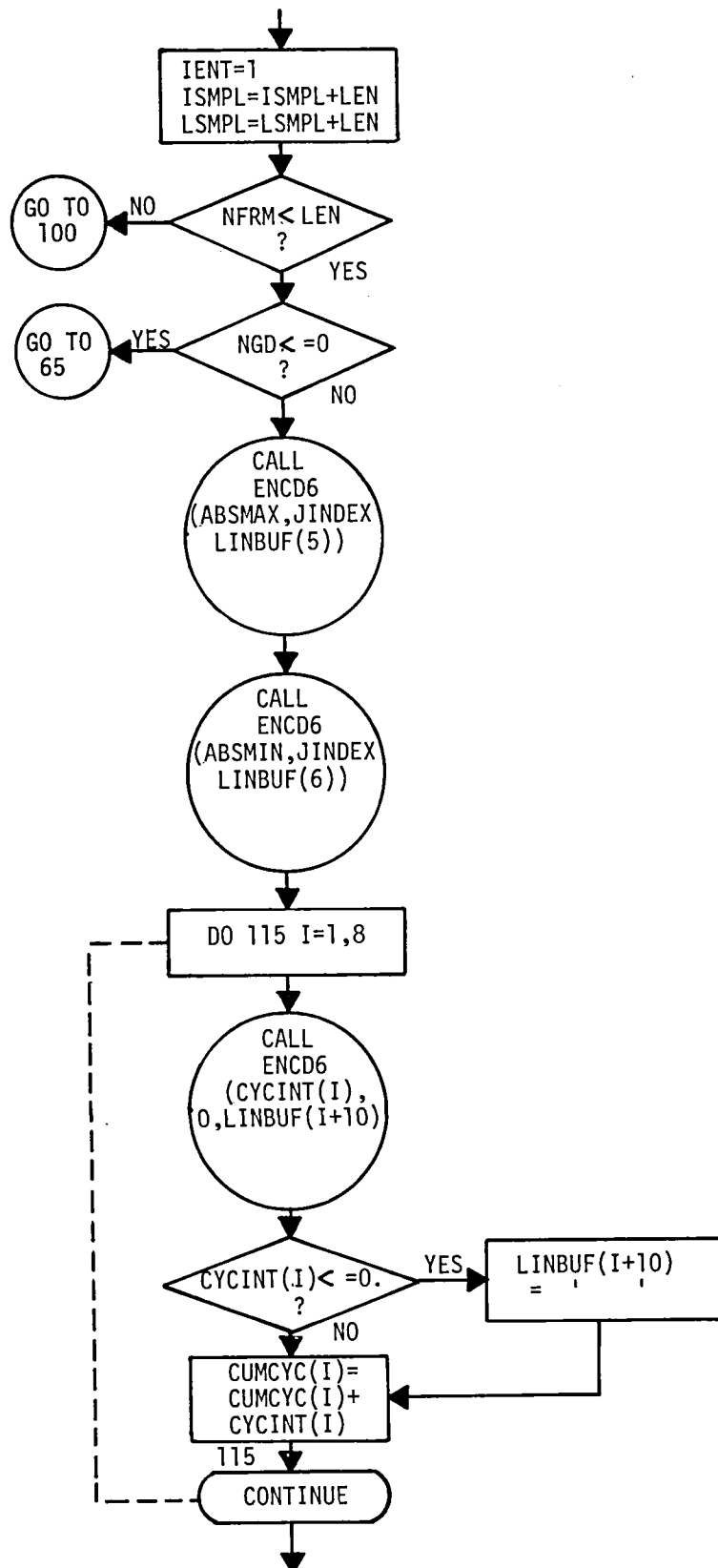


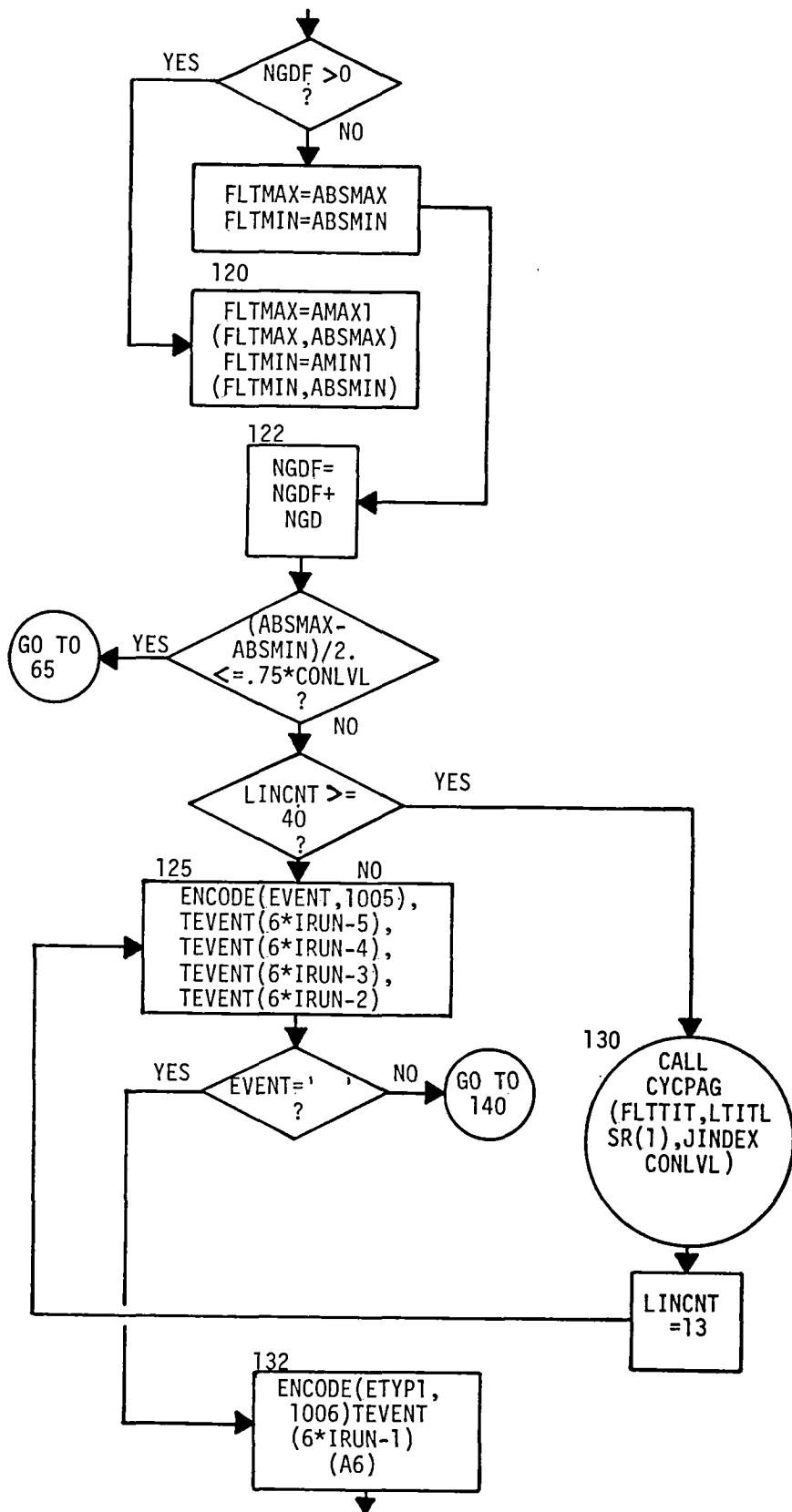


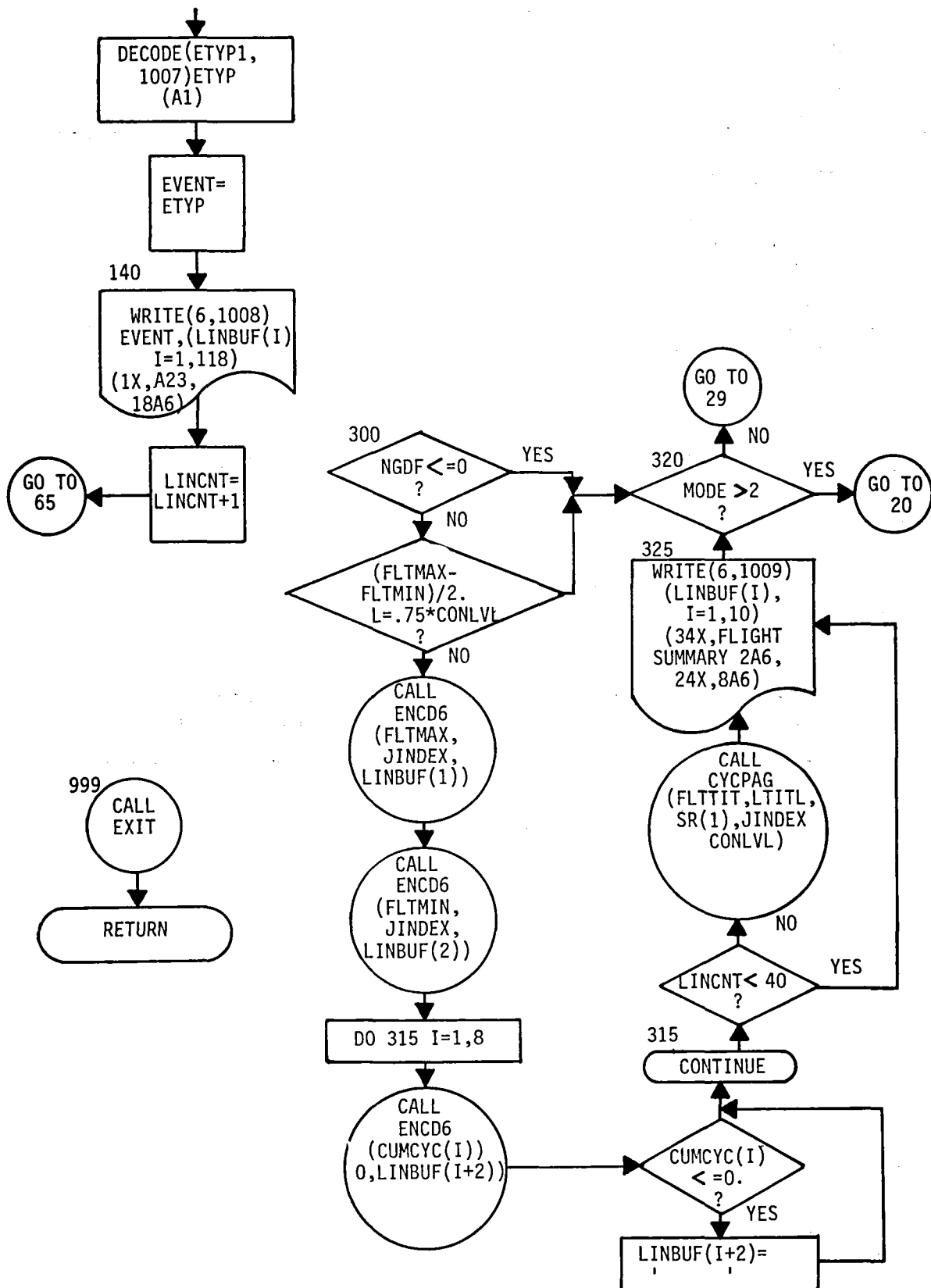












CYCT SUBROUTINE CYCNT

SUBROUTINE CYCNT(IENT,NPT,DATAV,DATAS,CONLVL,CYCINT,
1 ARSMAX,ARSMIN,NGD)

*****SUBROUTINE CYCNT*****

PROGRAM IDENTIFICATION

PROGRAM NAME ----- CYCNT
PROGRAM NUMBER ----- 112336
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW625/635
MEMORY -----
PERIPHERALS -----
LANGUAGE ----- HW 6000 FORTRAN/FORTY

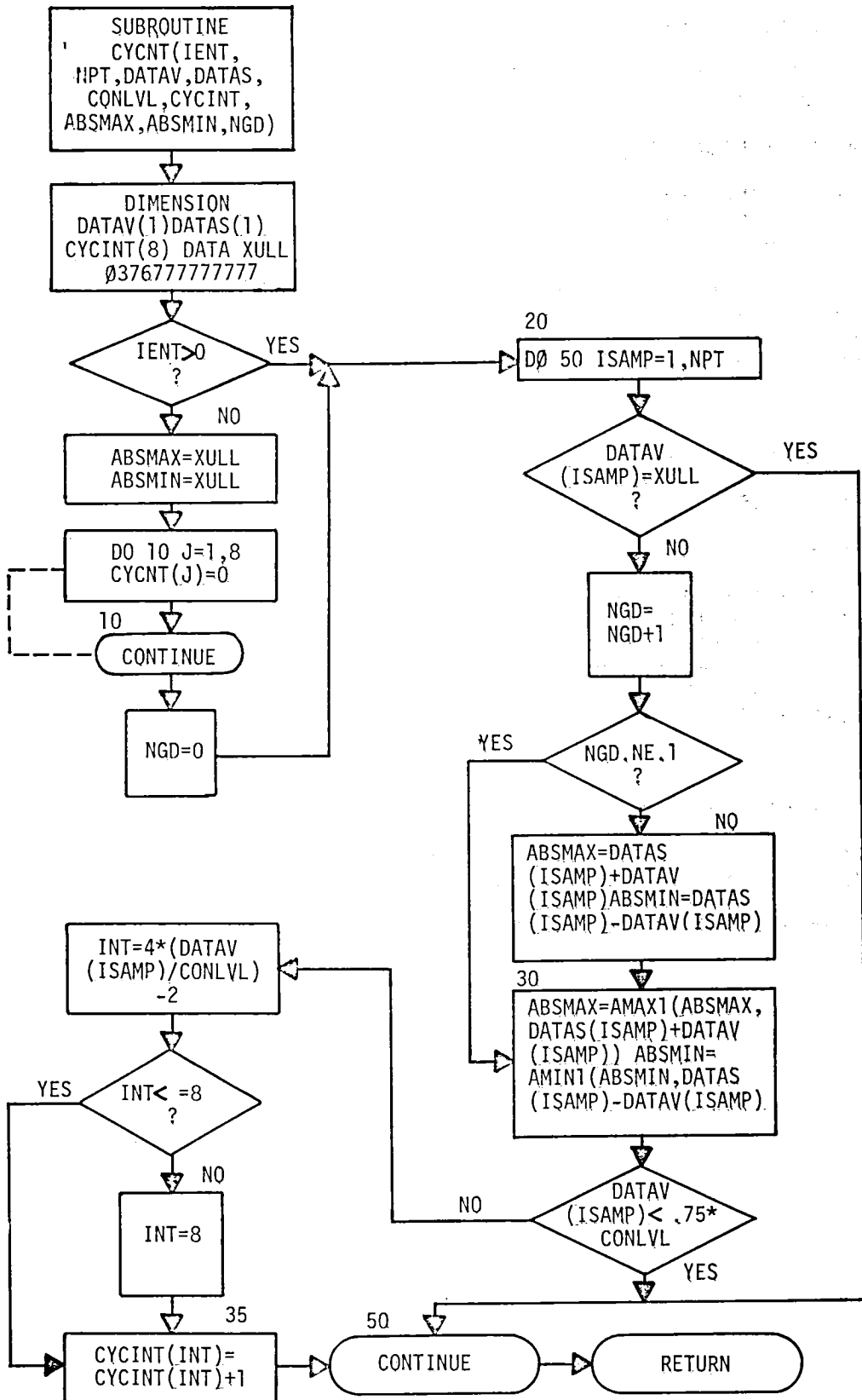
PURPOSE

TO DETERMINE THE ABSOLUTE MAXIMUM AND MINIMUM DATA
VALUES AND TO COMPUTE CONCERN LEVEL.

INPUT/OUTPUT

ARSMAX - ABSOLUTE MAXIMUM DATA VALUE
ARSMIN - ABSOLUTE MINIMUM DATA VALUE
DATAV - VIBRATORY DATA
DATAS - STEADY DATA
XULL - NULL VALUE

SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS,
FILE DESCRIPTIONS OR FOR ANY OTHER SPECIFIC INFORMATION.



CYPC SUBROUTINE CYCPAG

SUBROUTINE CYCPAG(FLTTIT,LTITL,SR,JINDEX,CONLVL)

*****SUBROUTINE CYCPAG*****

PROGRAM IDENTIFICATION

PROGRAM NAME ----- CYCPAG
PROGRAM NUMBER ----- 112336
AUTHOR ----- TERRY D. SOMMERS

COMPUTER ----- HW625/635
MEMORY -----
PERIPHERALS -----
LANGUAGE ----- HW 6000 FORTRAN/FORTY

PURPOSE

TO GENERATE REPORT OF VIBRATORY CYCLE COUNT SHOWING
VIBRATORY AND STEADY DATA, PERCENT OF CONCERN LEVEL,
ABSOLUTE LEVELS FOR EACH MANEUVER.

INPUT/OUTPUT

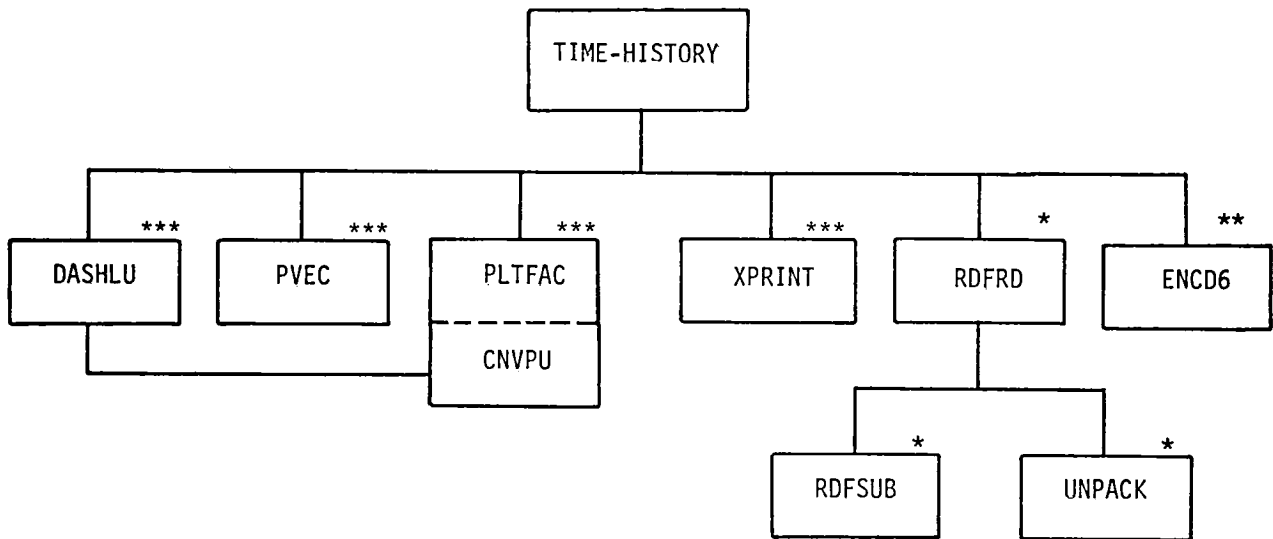
FLTTIT - FLIGHT TITLE
LTITL - LINE TITLE
JINDEX - INTEGER TO USE IN SUBROUTINE ENCD6 FOR
ARRANGING THE OUTPUT STATISTICS INTO AN
AESTHETIC FORM FOR PRINTING
CONLVL - CONCERN LEVEL

CALLING SEQUENCE

CALL ENCD6(CONLVL,JINDEX,CLEV)

SEE PROGRAM DOCUMENTATION ON FILE AT CAS FOR CARD FORMATS,
FILE DESCRIPTIONS OR FOR ANY OTHER SPECIFIC INFORMATION.





- * See Sub-program RDRD for Comments and Flowcharts
- ** See Program DATASK for Comments and Flowcharts
- *** Comments and Flowcharts not available for these modules

HIERARCHY CHART For THPLOT PROGRAM

TIMHIS TIME-HISTORY - RSRA PLOT PROGRAM
TIMHIS NASA WALLOPS VERSION OF 8-15-77

LANGUAGE FORTRAN V (FORTY)

MACHINE - GE-625

METHOD - PROGRAM USES CALCOMP SUBROUTINES ON FILE IN SYSTFM
TO COMMUNICATE WITH PLOTTER HARDWARE. TIMHIS OUTPUTS
A STANDARD LABELLED TAPE AT A DENSITY OF 5568PI.

PURPOSE - TO PLOT RSRA DATA

DESCRIPTION OF TASK INPUT CARDS

		GENERAL TITLE CARD
COLS.	FORMAT	DESCRIPTION
2-73	12A6	THIS TITLE IS PLACED AT THE TOP OF ALL PLOT PAGES.
PLOT ROW LABELS CARD		
COLS.	FORMAT	DESCRIPTION
5	I1	RT. ADJUSTED PGF NO.(=1,9)
10	I1	RT. ADJUSTED ROW NO.(=1,4)
29-46	3A6	18 CHARACTER BOT LINE OF ROW LABEL(RITE-MOST)
11-28	3A6	18 CHARACTER TOP LINE OF ROW LABEL(LEFT-MOST)
29-46	3A6	18 CHARACTER BOT LINE OF ROW LABEL(RITE-MOST)

A CARD WITH A ZERO IN COL. 5 TERMINATES READING OF THESE CARDS
MAXIMUM NUMBER OF ROW LABEL CARDS =9 PGF"S * 4 ROWS = 36 CARDS

PARAMETER SPECIFICATION CARDS(2 CARDS/PARAMETER)

COLS.	FORMAT	DESCRIPTION
CARD NO.1		
1- 8	A8	LEFT ADJUSTED MNEMONIC OF PARAMETER
9	A1	PRE-PROCESSING CODE LETTER
10-11	BLANK	
12-14	A3	SAMPLE RATE CODE
15-18	BLANK	
19-36	3A6	18 CHARACTER AXIS LABEL (TOP LINE)
37-54	3A6	18 CHARACTER AXIS LABEL (BOT LINE)
55-58	A4	4 CHAR. DIRECTION NOTE FOR TOP OF SCALE
59-62	A4	4 CHAR. DIRECTION NOTE FOR BOT OF SCALE
63-64	I2	PARAMETERS PLOT POSITION ON PGF NO. 1
65-66	I2	PARAMETERS PLOT POSITION ON PGF NO. 2
67-68	I2	PARAMETERS PLOT POSITION ON PGF NO. 3
69-70	I2	PARAMETERS PLOT POSITION ON PGF NO. 4
71-72	I2	PARAMETERS PLOT POSITION ON PGF NO. 5
73-74	I2	PARAMETERS PLOT POSITION ON PGF NO. 6
75-76	I2	PARAMETERS PLOT POSITION ON PGF NO. 7
77-78	I2	PARAMETERS PLOT POSITION ON PGF NO. 8
79-80	I2	PARAMETERS PLOT POSITION ON PGF NO. 9

PARAMETER PLOT POSITIONS ARE

ROW	COL	POSITION NO
1	1	1
1	2	2
1	3	3
2	1	4
2	2	5
2	3	6
3	1	7
3	2	8
3	3	9
4	1	10
4	2	11
4	3	12

TWO PARAMETERS MUST NOT
OCCUPY THE SAME POSITION
ON A PGF.

CARD 2

1-10 F10 RANGE OF PRIMARY SCALE IN E.U. (BOT TO TOP)
 11-20 F10 VALUE AT BOTTOM OF PRIM. SCALE
 21-30 F10 RANGE OF SECONDARY SCALE IN E. U. (BOT TO TOP)
 31-40 F10 VALUE AT BOTTOM OF SECON. SCALE.
 41-42 I2 * SCALE PRECISION INDEX NO.
 43-44 I2 ** OPTION FLAG TO REFERENCE (BIAS) ALL VALUES TO THE
 * A PLUS SIGN OR NONE INDICATE INTEGER SCALING.
 A NEG SIGN INDICATES SCALES LT 0
 A NEG N INDICATES N DECIMAL PLACE ACCURACY.
 ** FIRST NON-NULL VALUE. FLAG IS ON IF IT=1
 UP TO 40 PARAMETERS MAY BE DEFINED FOR PLOTTING.
 PRIMARY SCALE WILL BE USED IF 80 PRCT. OF THE DATA CAN BE
 CONTAINED WITHIN IT. IF 20 PRCT OF THE DATA EXCEEDS THE PRIM
 SCALE, THEN THE SECOND. WILL BE USED. (20 PCNT OF DATA POINTS)
 A CARD WITH BLANKS IN COLS. 1-8 WILL TERMINATE READING OF THESE
 CARDS.

HEADING LABEL CARDS

COLS.	FORMAT	DESCRIPTION
5	I1	HEADING NO
6-13	A8	LINE 1 CHARACTER STRING
14-21	A8	LINE 2 CHARACTER STRING
22-29	A8	LINE 3 CHARACTER STRING

FROM ONE TO EIGHT HEADINGS MAY BE IDENTIFIED
 ANY MAY BE SKIPPED
 A ZERO IN COL. 5 END READING HEADING LABEL CARDS.

BURST SELECTION CARDS (2 CARDS PER BURST)

COLS.	FORMAT	DESCRIPTION
-------	--------	-------------

CARD 1

1- 5	I5	BURST NO TO BE PROCESSED
6-10	I5	PGF NO TO BE USED FOR THIS BURST
11-20	F10	START TIME OF PLOTS IN SECONDS INTO THE EVENT
21-30	F10	STOP TIME OF PLOTS IN SECONDS INTO THE EVENT
31-78	8A6	MANEUVER TITLE (PLACED AT TOP OF PLOT)
79-80	I2	OPTION FLAG TO PRINT DATA TO BE PLOTTED (ON IF =1)

CARD 2

1-10	A10	LINE 4 CHARACTER STRING HEADING 1
11-20	A10	LINE 4 CHARACTER STRING HEADING 2
21-30	A10	LINE 4 CHARACTER STRING HEADING 3
31-40	A10	LINE 4 CHARACTER STRING HEADING 4
41-50	A10	LINE 4 CHARACTER STRING HEADING 5
51-60	A10	LINE 4 CHARACTER STRING HEADING 6
61-70	A10	LINE 4 CHARACTER STRING HEADING 7
71-80	A10	LINE 4 CHARACTER STRING HEADING 8

A CARD WITH A ZERO IN COL. 5 ENDS READING ALL CARDS.

INPUT VARIABLES

CARD INPUTS

ALLPLT	*6 (12)	72 CHARACTER TITLE FOR DISPLAY AT TOP OF ALL PLOTS
BOT	(40,2)	2 POSSIBLE SCALE BOTTOM VALUES FOR ALL PARAMS DEFINED
CDBUFF	*6 (14)	LOCAL ENCODE/DECODE BUFFER FOR ARRANGING TEXTS
IBNAME	*8 (40)	MNEMONICS OF ALL PARAMETERS DEFINED
IRPP	*1 (40)	PRE PROCESS CODES OF ALL PARAMETERS DEFINED
IRSR	*6 (40)	SAMPLE RATES OF ALL PARAMETERS DEFINED
JDELTA	(40)	FLAG TO PLOT VALUE MINUS FIRST SAMPLE
JINDEX	(40)	PRECISION CODE FOR EACH PARAMETER DEFINED
KGRP	(40,9)	POSITION INDEX NO /PGF/PARAM
MASLAB	*6 (6,9,4)	MAIN AND SUB TITLES FOR EACH ROW
REGTIT	*6 (8)	48 CHARACTER REGIME TITLE
SCNOTE	*6 (40,2)	(2) 4 CHAR DIRECTION PLOT SCALE NOTES
SLP	(40,2)	2 POSSIBLE SCALE RANGES
YTITL	*6 (6,40)	36 CHARACTER PARAMETER TITLE (MAIN + SUB)
IGRP		PLOT GROUP FORMAT NO BEING EXECUTED
IRUN		RUN NUMBER BEING PLOTTED
TIMEL		TIME INTO RUN AT WHICH DATA PRESENTATION IS TO BEGIN
TIMEL		TIME INTO RUN AT WHICH DATA PRESENTATION IS TO END

VARIABLES CALCULATED WITHIN PROGRAM

ACNAME	*8 (2)	MNEMONIC OF PARAMETER BEING PROCESSED + TIME
ACPP	*1 (2)	PRE PROCESS CODE OF PARAMETER BEING PROCESSED + TIME
ACSR	*6 (2)	SAMPLE RATE OF PARAMETER BEING PROCESSED + TIME
DX	(6)	LOCAL PEN INCREMENTS IN X DIRECTION
DY	(6)	LOCAL PEN INCREMENTS IN Y DIRECTION
LEGEND	*6 (3,2)	TEXT FOR "SOLID LINE","SHORT DASH","LONG DASH"
OUTBUF	(232)	ACCESS RUFFER (116 FRAMES OF DATA/PARAM + TIME)
PCTBD	(2)	0/0 OF SCALE UTILIZATION FOR EACH POSSIBLE PLOT SCALE
PCTGD	(2)	0/0 OF SCALE UTILIZATION FOR EACH POSSIBLE PLOT SCALE
TRASE	(3)	TIME SCALE MULTIPLIERS (1.5, 3.0, 6.0)
TOS	(8)	TABLE OF SUBSCRIPT VECTOR USED BY RDFSUB + RDFRD
DATAFST		FIRST NON-NULL VALUE OF THE PARAMETER BEING PLOTTED
DATMIN		MINIMUM DATA VALUE OF THE PARAMETER BEING PLOTTED
DATMAX		MAXIMUM DATA VALUE OF THE PARAMETER BEING PLOTTED
IRS		BEGINNING FRAME NO. IN SEGMENTED ACCESS OF RUN
ICOL		COLUMN INDEX NO.
IES		ENDING FRAME NO. IN SEGMENTED ACCESS OF RUN
IFLACT		FRAME NO. INTO BURST WHERE PLOT WILL BEGIN FOR THIS PARAMETER
IFLACT		FRAME NO. INTO BURST WHERE PLOT WILL END FOR THIS PARAMETER
IPTR1		SUBSCRIPT OF OUTBUF FOR GIVEN FRAME OF PARAMETER BEING PLOTTED
IPTR		SUBCRIPT OF OUTBUF FOR GIVEN FRAME OF TIME
IROW		ROW INDEX NO (1-4)

ITPCD PRECISION CODE INDEX FOR TIME SCALE
 LCHAN PLOT-POSITION INDEX NO.(1-12)
 LEN THE NUMBER OF FRAMES THAT CAN BE ACCESSED AT A TIME
 LL PLOT SCALE FLAG =1,PRIMARY, =2,SECONDARY
 NCHAND NO OF PARAMETERS DEFINED IN ENTRY TO PRIMEP
 NFRM NO OF FRAMES ACTUALLY ACCESSED DURING GIVEN CALL TO RDRD
 NGD NO OF NON-NULL FRAMES AVAILABLE FOR THIS PARAMETER
 PMN MINIMUM PARAMETER VALUE PERMITTED ON PLOT SURFACE
 PMX MAXIMUM PARAMETER VALUE PERMITTED ON PLOT SURFACE
 POR PARAMETER VALUE AT BOTTOM EDGE OF GRID (Y=0.0 CM)
 SBOTX SCALE VALUE AT BOTTOM END
 SEGDN LENGHT IN CM OF DASH LINE TO BE DRAWN
 SLPACT PLOT SCALE CHOSEN FOR PARAMETER IN ENG. UNITS/CM
 STOPX SCALE VALUE AT TOP END
 SV LOCAL VARIABLE USED IN GENERATION OF TIME SCALE
 TMN MINIMUM TIME VALUE PERMITTED ON PLOT SURFACE
 TMX MAXIMUM TIME VALUE PERMITTED ON PLOT SURFACE
 TOR TIME VALUE AT PLOT ORIGIN (X=0.0 CM)
 TSLP CHOSEN PLOT RATE FOR TIME SCALE (SECS/CM)
 TSPAN REQUESTED TIME SPAN = (TIME1-TIME1)
 TSPAN1 CHOSEN LENGHT OF TIME SCALE IN SECS
 XOFFS1 X POSITION IN CM FROM ORIGIN FOR A GIVEN COLUMN Y AXIS
 YOFFS1 Y POSITION

OUTPUT
 PARAMETERS OUTPUT BY PROGRAM

OUTBUF(232), MAY BE PRINTED ON LISTING
 X,Y,XOFF1,YOFF1 PEN POSITIONS

SUBROUTINES USED BY TIMHIS

PLOTS - A CALCOMP ROUTINE TO INITIALIZE CALCOMP PACKAGE
 CALLING SEQUENCE
 CALL PLOTS(ARG1,ARG2,ARG3)
 ARG1-IBUF-NAME OF OUTPUT BUFFER
 ARG2-1000-SIZE OF IBUF
 ARG3-50-OUTPUT TAPE FILE (STD FORMAT)

FACTOR - A CALCOMP ROUTINE TO SCALE PLOT POSITIONS
 CALLING SEQUENCE
 CALL FACTOR(ARG)
 ARG-0.3937-CONVERTS PEN DISPLACEMENTS FROM METRIC TO
 INCHES FOR METRIC PAPER. INPUTS ARE METRIC

SYMBOL-A CALCOMP ROUTINE TO PLOT ALPHANUMERIC INFORMATION
 CALLING SEQUENCE
 CALL SYMBOL(ARG1,ARG2,ARG3,ARG4,ARG5,ARG6)
 ARG1- - X START POSITION
 ARG2- - Y START POSITION
 ARG3- - SIZE OF CHARACTERS
 ARG4- - ALPHANUMERICS TO PLOT
 ARG5- - HORIZONTAL OR VERTICAL ALIGNMENT
 0.0 FOR HORIZONTAL, 90.0 FOR VERTICAL
 ARG6 - NUMBER OF CHARACTERS TO BE PLOTTED

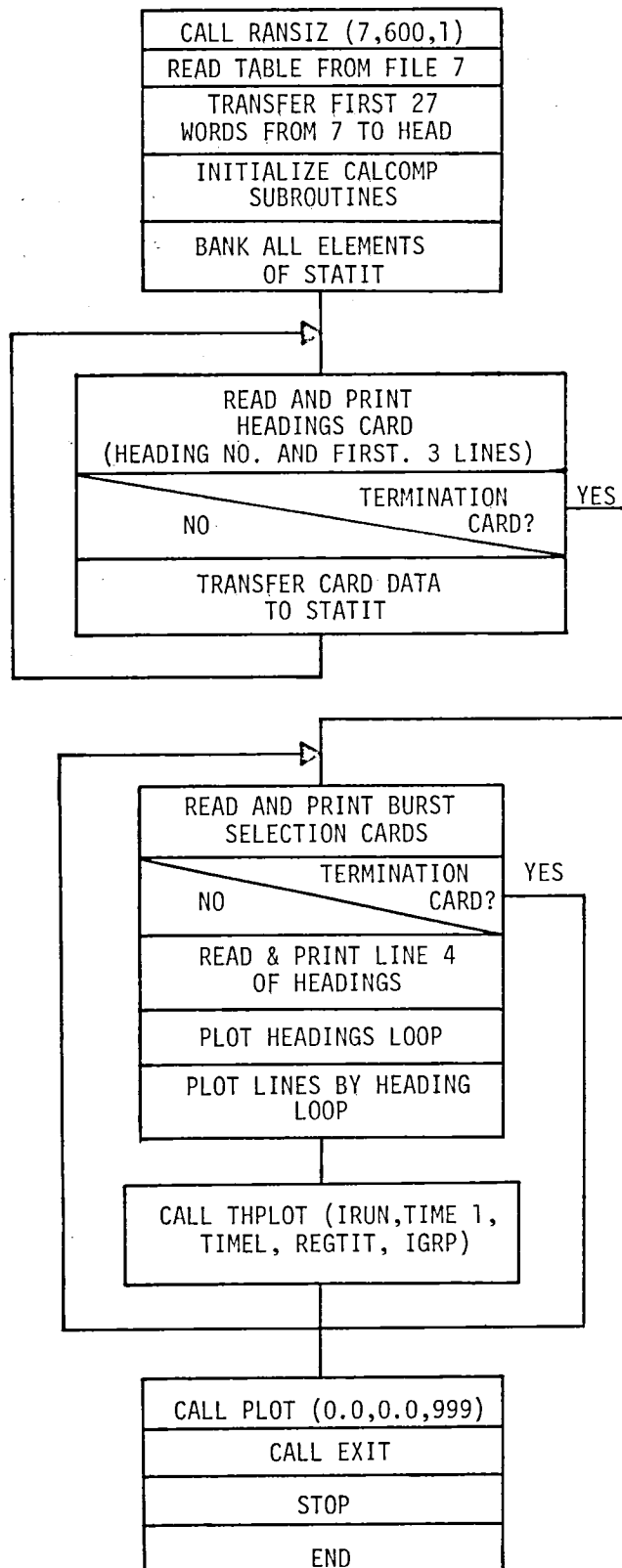
PLOT - A CALCOMP ROUTINE TO PLOT LINE DATA
 CALLING SEQUENCE
 CALL PLOT(ARG1,ARG2,ARG3)
 ARG1- -X POSITION TO MOVE PEN TO
 ARG2- -Y POSITION TO MOVE PEN TO
 ARG3- -PEN POSITION CODE,2=PEN DOWN,3=PEN UP.

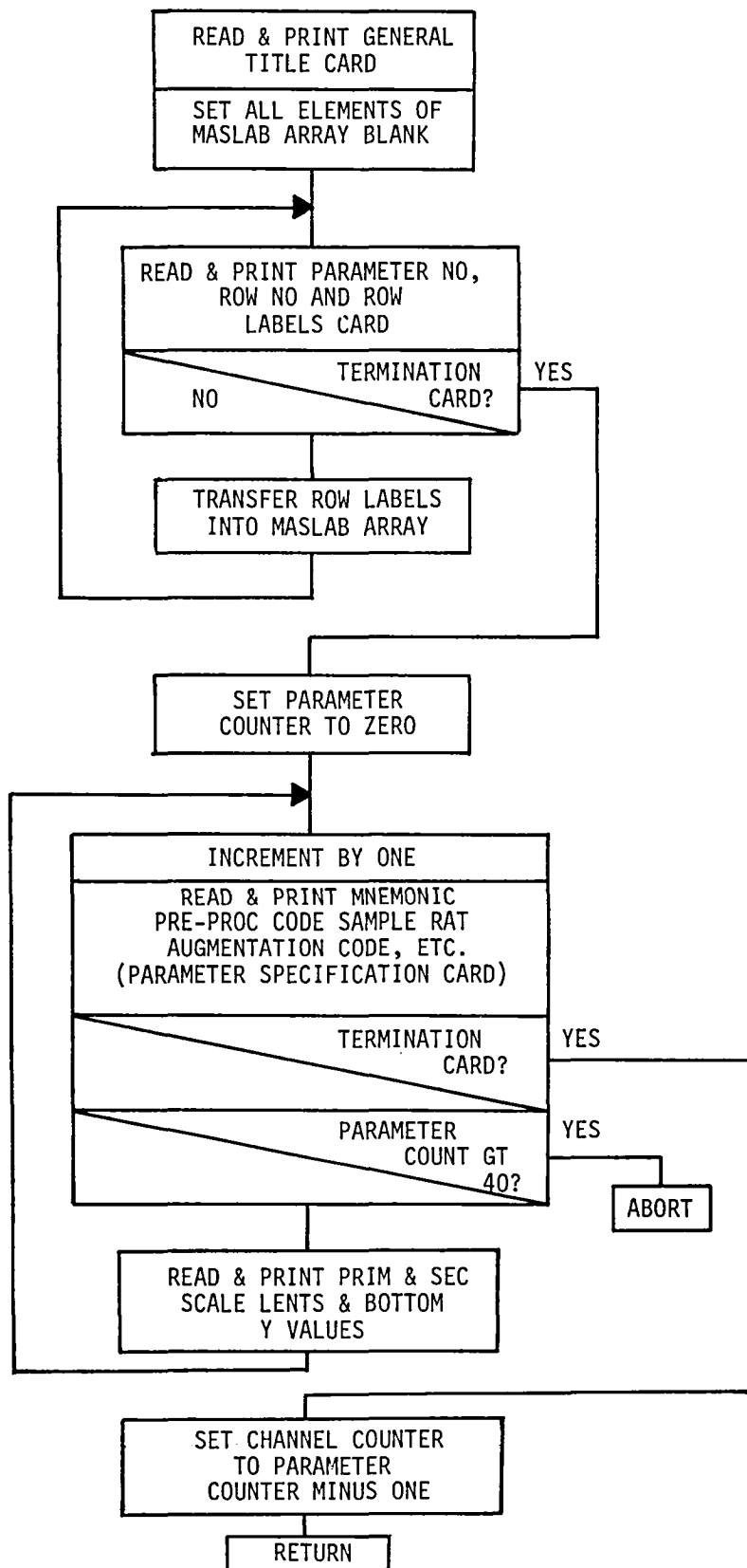
PLTFAC - ROUTINE TO CONVERT E. U. TO PEN POSITIONS
 CALLING SEQUENCE
 CALL PLTFAC(TSLP,SLPACT,TOR,0.0,TMX,PMN,PMX)
 SEE DESCRIPTION OF VARIABLES ABOVE

PVEC - ROUTINE TO PLOT SOLID LINE
 CALLING SEQUENCE
 CALL PVEC(OUTBUF(NFRM+1),OUTBUF(1),NFRM)
 SEE DESCRIPTION OF VARIABLES ABOVE

DASHLU - ROUTINE TO PLOT DASHED LINES
 CALLING SEQUENCE
 CALL DASHLU(OUTBUF(NFRM+1),OUTBUF(1),NFRM,SEGDN,0.075)
 SEE DESCRIPTION OF VARIABLES ABOVE

RANSIZ,RDFSUB,RDFRD,ENCD6 ARE DOCUMENTED ELSEWHERE IN THE
 RSRA PACKAGE.



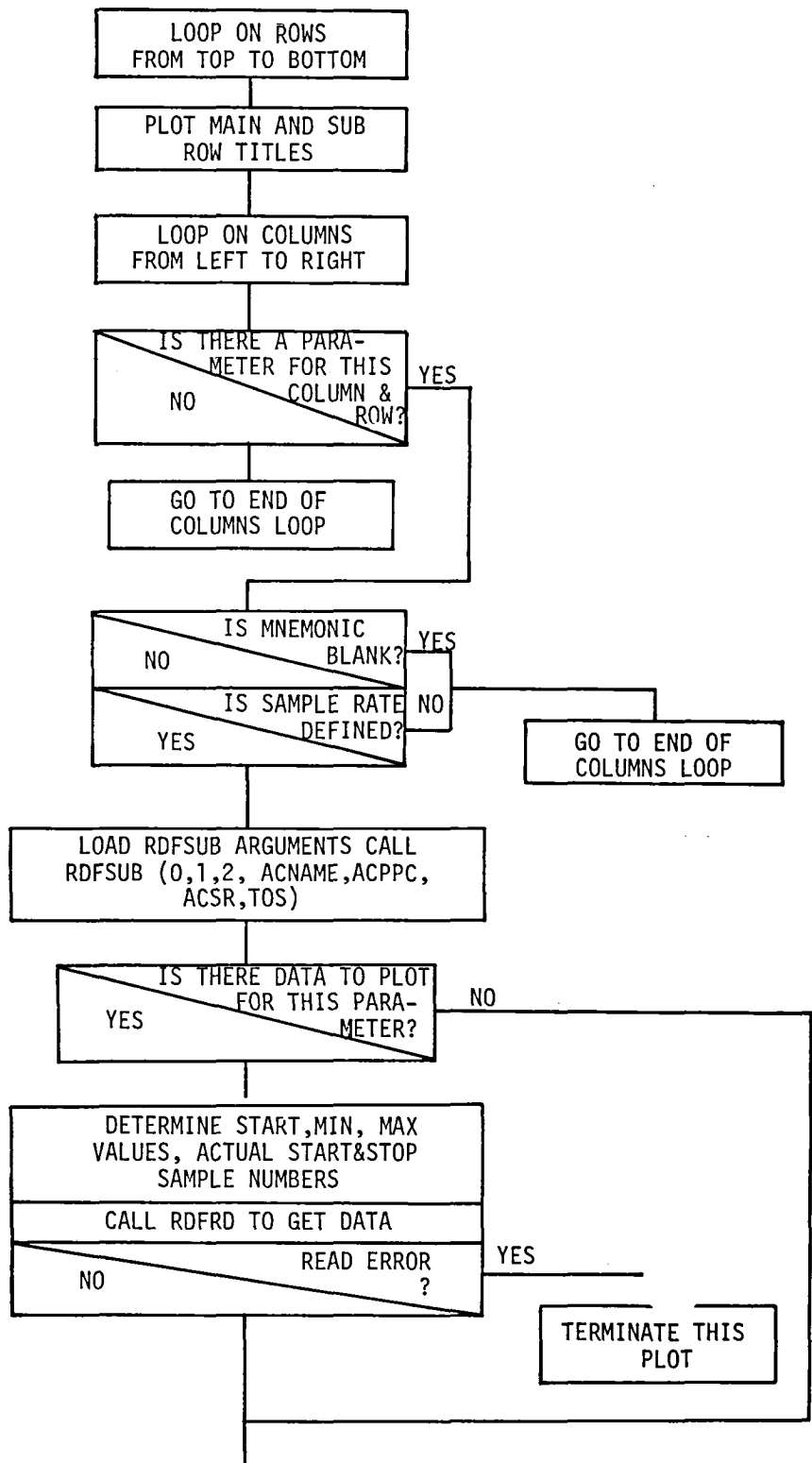


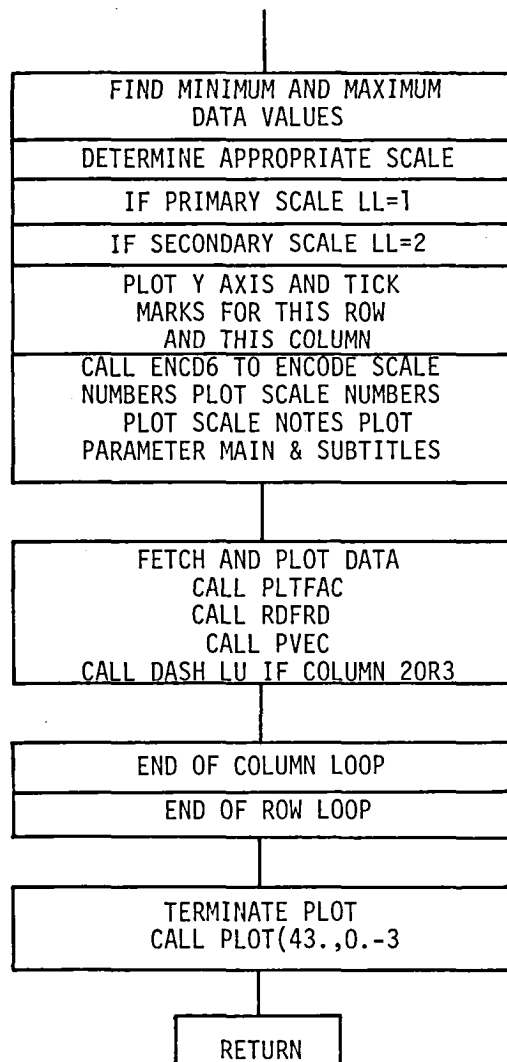
TRANSFER
THEAD (5) TO FLT
AND
THEAD (16) TO ETP
PLOT ETP, "FLT=",
FLT, "RUN=",

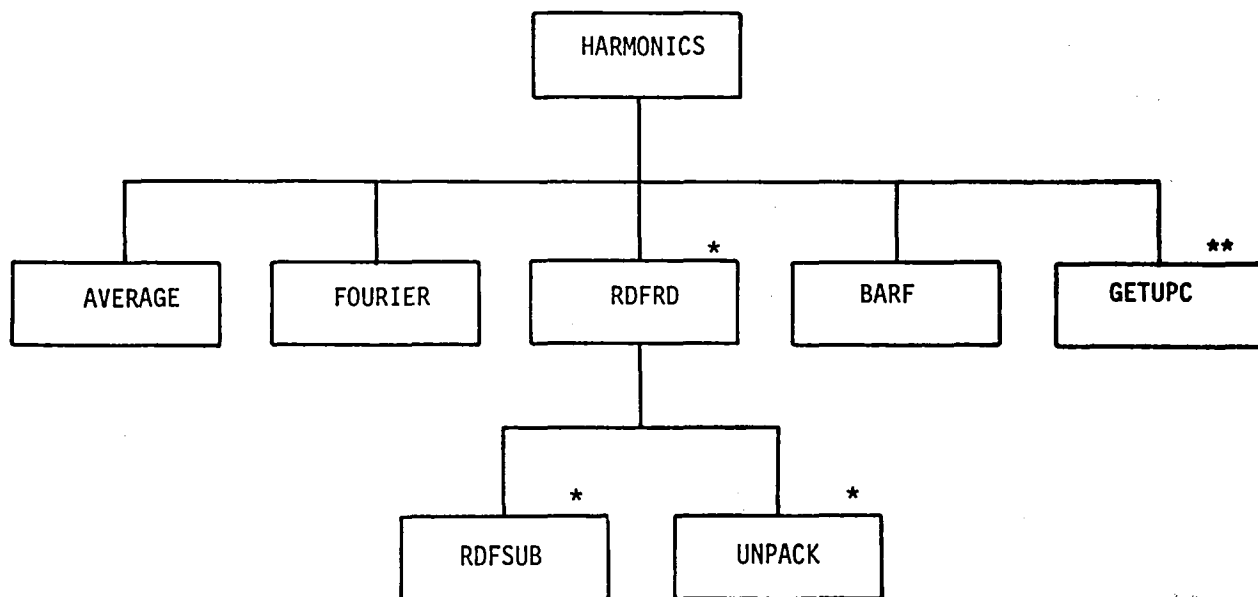
CONVERT IRUN TO REAL

CALL ENCD6
(RUN → CDBUFF(1))
PLOT RUN, "TO=",
CALL ENCD6
(TIME → CDBUFF(1))
PLOT TIME1
PLOT VERTICAL LINE
ON LEFT SIDE OF PLOT
PLOT "FIGURE",
FIGURE TITLE,
PLOT TITLE

PLOT LEGEND
PLOT ({)
PLOT VERTICAL DASH LINE
PLOT X AXIS AND
TICK MARKS
CALCULATE TIME
SCALE ANNOTATION
PLOT TIME SCALE
NUMBERS AND TITLE







* See Sub-Program RDFRD for Comments and Flowcharts

** See Program DATASK for Comments and Flowcharts

HIERARCHY CHART For HARMONIC ANALYSIS PROGRAM

HARMONICS

***** PROGRAM HARMONIC ANALYSIS *****
02/22/78

**PROGRAM IDENTIFICATION

PROGRAM NAME = RSRA HARMONIC ANALYSIS
PROGRAM NO. =
RESEARCHER = NORM MICHAUD (NASA WOLLOPS)
PROGRAMMER = GUS DOVI (COMPUTER SCIENCES CORP.)
ANALYST = KEN LEWIS (SIKORSKY AIRCRAFT)

COMPUTER = HW 625/635
MEMORY = 14K
PERIPHERALS = DISC SUBSYSTEM
TAPE SUBSYSTEM
LANGUAGE = HW 6000 FORTRAN (100 PERCENT)
NO. CARDS = 476

***PURPOSE

RSRA HARMONIC ANALYSIS READS DATA FROM FILES(05):(07):(09):(35).
THE DATA IS PROCESSED AND SCANNED FOR PROPER FORMAT. THE RAW DATA
FILE IS READ. FROM THIS DATA THE FOURIER COEFFICIENTS ARE
GENERATED AS WELL AS THE RESULTENT AMPLITUDES, PHASE ANGLES, AND
STANDARD SAMPLE DEVIATION. FOURIER COEFFICIENTS ARE LIMITED TO
144.

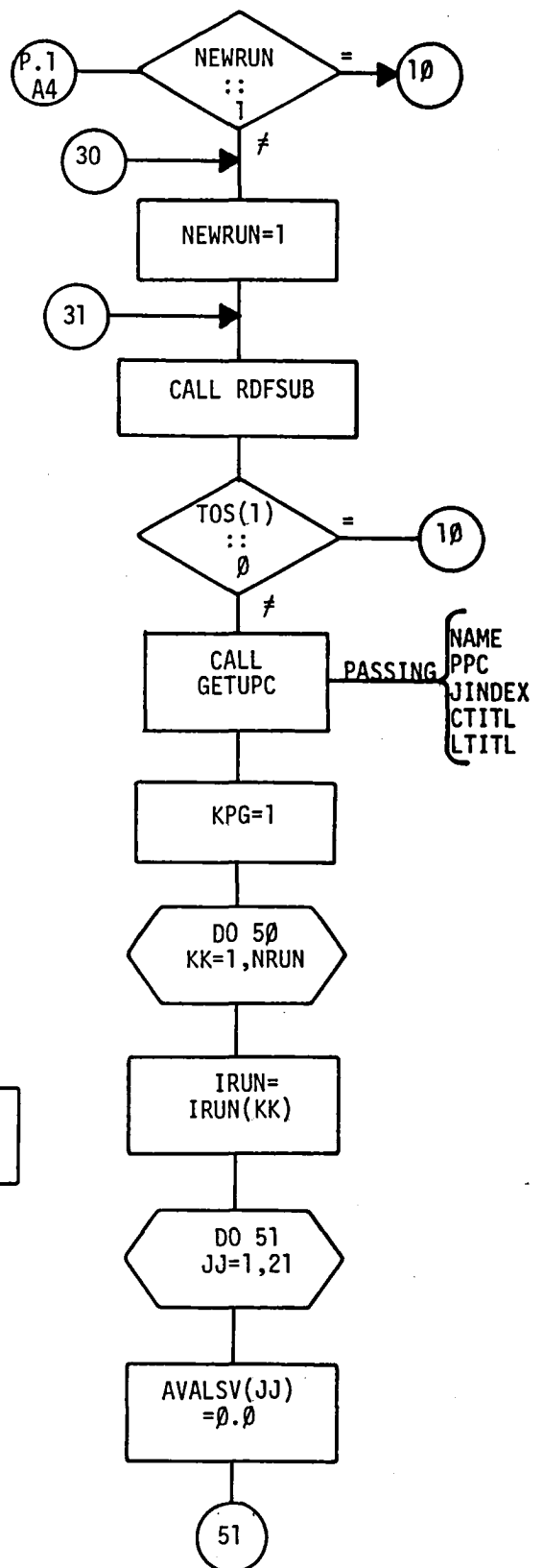
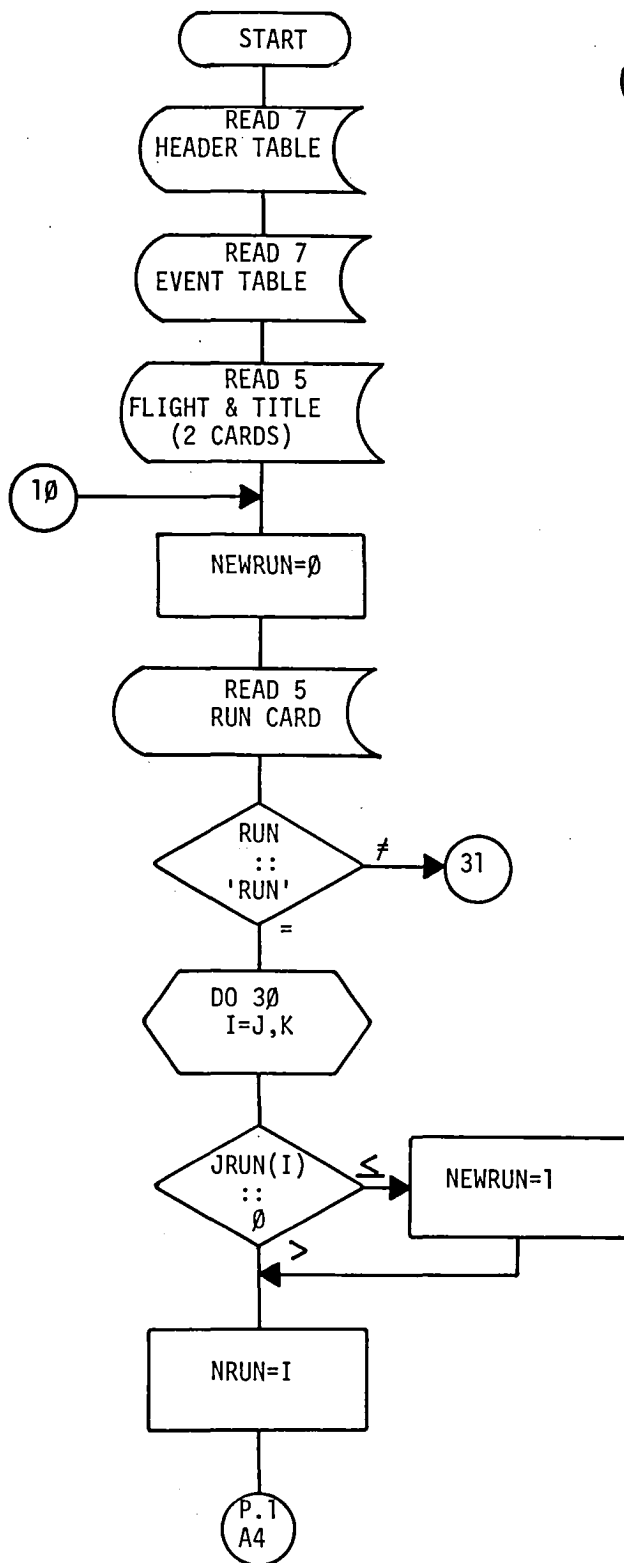
***I/O CONFIGURATION

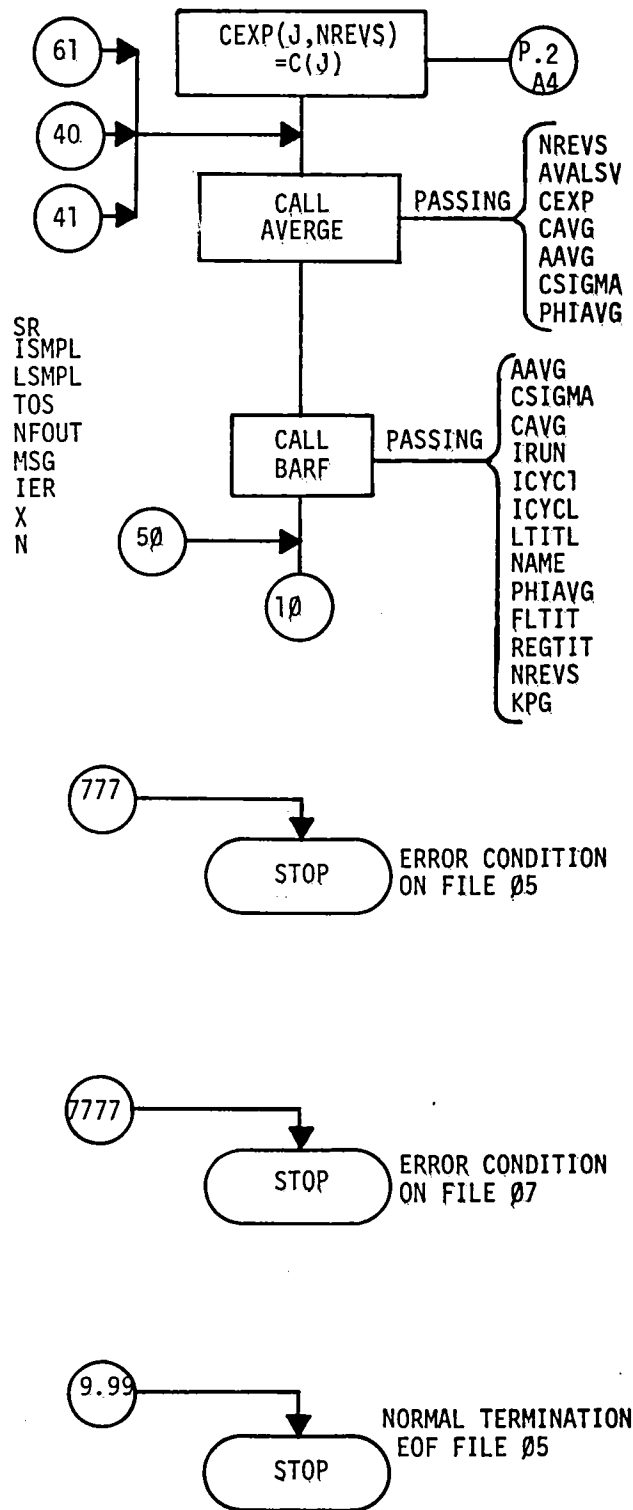
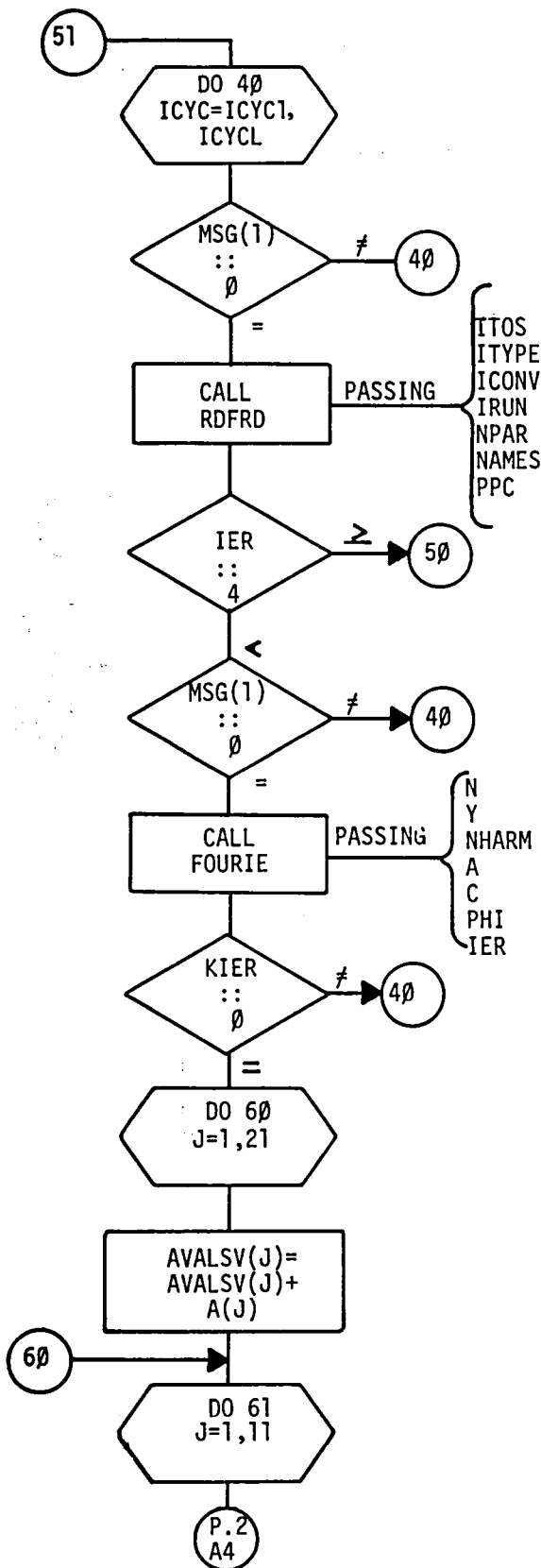
UNIT NO.	DEVICE TYPE	DESCRIPTION
05	CRD	CONTAINS TITLES AND RUN DATA.
07	DSK	RANDOM FILE CONTAINING DATA TABLES.
09	DSK	STATISTICS FILE USED BY SUBROUTINE RDFRD
35	DSK	UNIVERSAL PARAMETER CATALOG.

**SUBPROGRAMS REQUIRED

RDFSUR
GETUPC
RDFRD
FOURIE
AVERAGE
BARF

***** PROGRAM HARMONIC ANALYSIS *****





AVERAGE

***** SUBROUTINE AVERAGE *****
02/22/78

**PROGRAM IDENTIFICATION

PROGRAM NAME = AVERAGE
PROGRAM NO. =
RESEARCHER = NORM MICHAUD (NASA WOLLOPS)
PROGRAMMER = GUS DOVI (COMPUTER SCIENCES CORP.)
ANALYST = KEN LEWIS (SIKORSKY AIRCRAFT)

COMPUTER = HW 625/635
MEMORY =
PERIPHERALS = NONE
LANGUAGE = HW 6000 FORTRAN (100 PERCENT)
NO. CARDS = 37

**PURPOSE

TO GENERATE THE AVERAGE FOURIER COEFFICIENTS, RESULTANTS, PHASE ANGLES AND STANDARD DEVIATIONS OVER A RANGE OF (N-1)/2 HARMONICS. WHERE (N) IS THE NUMBER OF HARMONICS.

**INPUT

NREVS = INTEGER VALUE (0 .LT. NREVS .LE. 20)
AVALSV = (A) COEFFICIENTS OUTPUT FROM SUBPROGRAM FOURIE.
THE (A) COEFFICIENTS ARE ACCUMULATED INTO THE AVALSV ARRAY. AVALSV IS DIMENSIONED TO (21).

CEXP = ARRAY DIMENSIONED (11,20), CONTAINS ACCUMULATED RESULTANTS OF THE A(2*JJ) AND A(2*JJ+1) COEFFICIENTS OUTPUT BY SUBPROGRAM FOURIE.

**OUTPUT

CAVG = ARRAY DIMENSIONED (11), CONTAINS THE AVERAGE RESULTANT OF THE AVERAGE (A) AND (C) COEFFICIENTS.
WHERE
 $CAVG(JJ+1) = \sqrt{AAVG(2*JJ)**2 + AAVG(2*JJ+1)**2}$

AAVG = ARRAY DIMENSIONED (21), CONTAINS THE AVERAGE (A) COEFFICIENTS INPUT VIA ARRAY AVALSV.

CSIGMA = ARRAY DIMENSIONED (11), CONTAINS AVERAGE STANDARD DEVIATIONS.

PHIAVG = ARRAY DIMENSIONED (11), CONTAINS AVERAGE PHASE ANGLES DEFINED BY THE A(2*JJ) AND A(2*JJ+1) COEFFICIENTS.

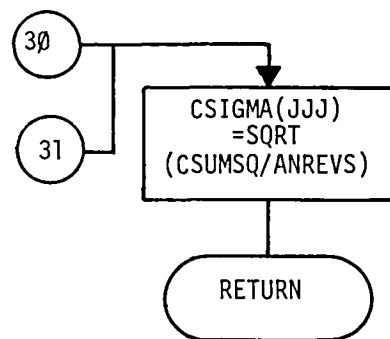
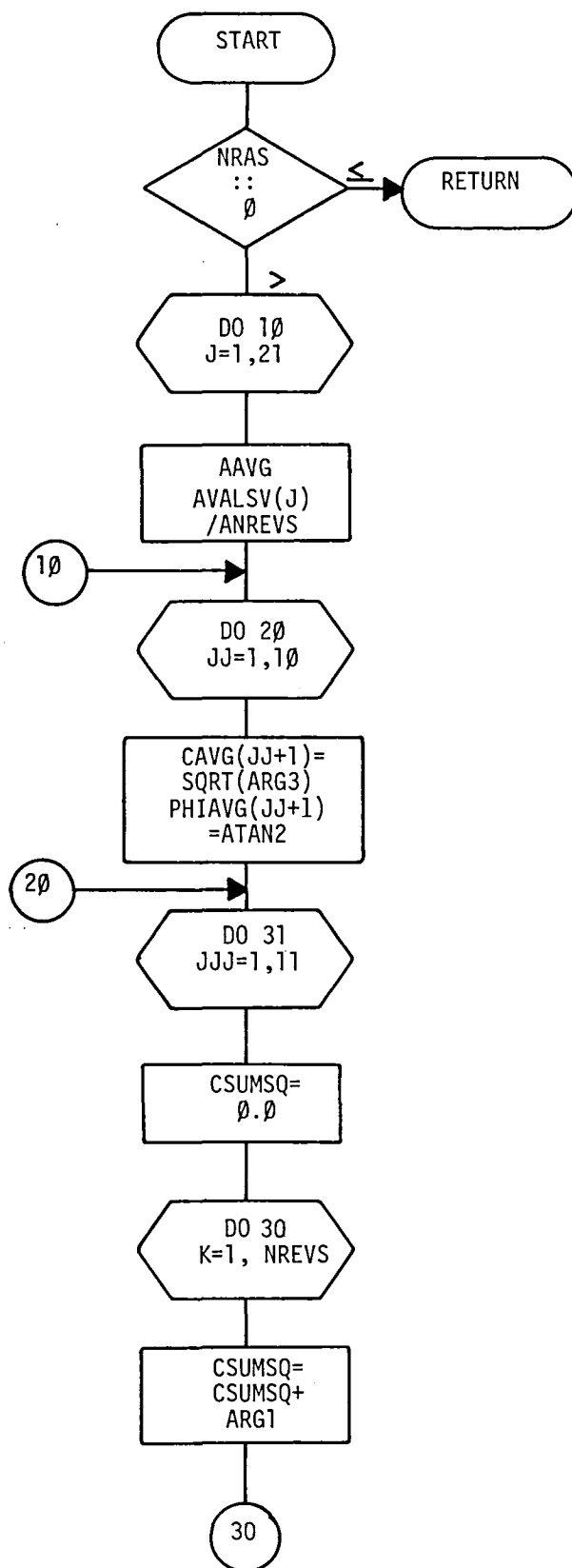
****RESTRICTIONS**

NONE

****SUBPROGRAMS REQUIRED**

NONE

***** SUBROUTINE AVERAGE *****



ARGUMENTS PASSED:

NREVS
AVALSV
CEXP
CAVG
AAVG
CSIGMA
PHIAVG

FOURIER

***** SUBROUTINE FOURIE *****

**PROGRAM IDENTIFICATION

PROGRAM NAME = FOURIE
PROGRAM NO. =
RESEARCHER = NORM MICHAUD (NASA WALLOPS)
PROGRAMMER = GUS DOVI (COMPUTER SCIENCES CORP.)
ANALYST = KEN LEWIS (SIKOPSKY AIRCRAFT)

COMPUTER = HW 625/635
MEMORY =
PERIPHERALS = NONE
LANGUAGE = HW 6000 FORTRAN (100 PERCENT)
NO. CARDS = 76

**PURPOSE

TO DETERMINE THE FOURIER COEFFICIENTS FOR A DATA VECTOR OF 144
VALUES. THE PHASE ANGLE IS ALSO COMPUTED.

**INPUT

N = NUMBER OF VALUES IN INPUT VECTOR
Y = ARRAY (INPUT VECTOR) DIMENSIONED (144).
NHARM = NHARM IS SET EQUAL TEN (10) IN THE CALLING PROGRAM.
NHARM IS AN INTEGER SPECIFYING THE NUMBER OF
(C) VALUES DESIRED. IF NHARM = 10 (C) SHOULD BE
DIMENSIONED (11) AND ARRAY (A) SHOULD BE DIMENSIONED
(21) IN THE CALLING PROGRAM. NOTE ((1) = (A(1)/N) AND
C(I) = $\text{SQRT}(A(J)**2 + A(J+1)**2)$).

**OUTPUT

A = ARRAY OF FOURIER COEFFICIENTS. THE SINE TERMS ARE
IN THE ODD SUBSCRIPTED ELEMENTS. THE COSINE TERMS
ARE IN THE EVEN SUBSCRIPTED ELEMENTS
C = ARRAY OF RESULTANT VECTORS.
 $C(N) = \text{SQRT}(A(N)**2 + A(N+1)**2)$
PHI = ARRAY OF PHASE ANGLES FOR USE WITH (C) VECTORS.
IER = 0 IMPLIES NO ERRORS.
1 IMPLIES (Y) VECTOR CONTAINS NULL VALUES.

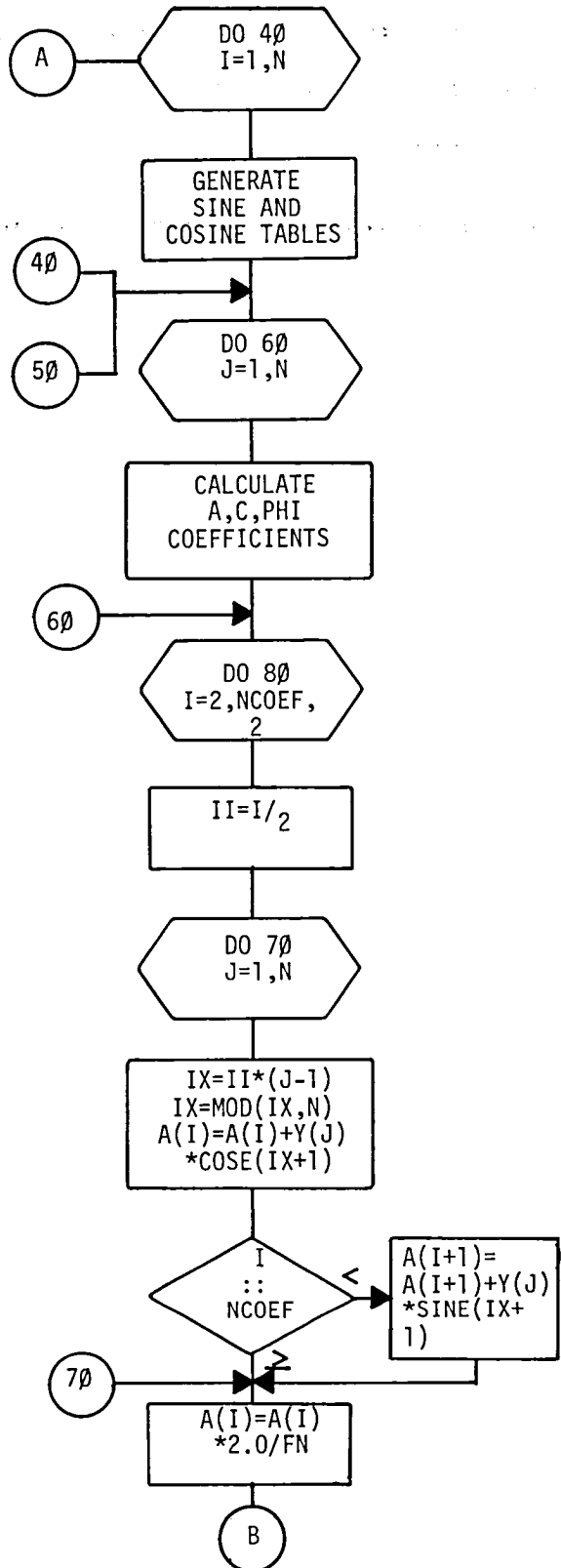
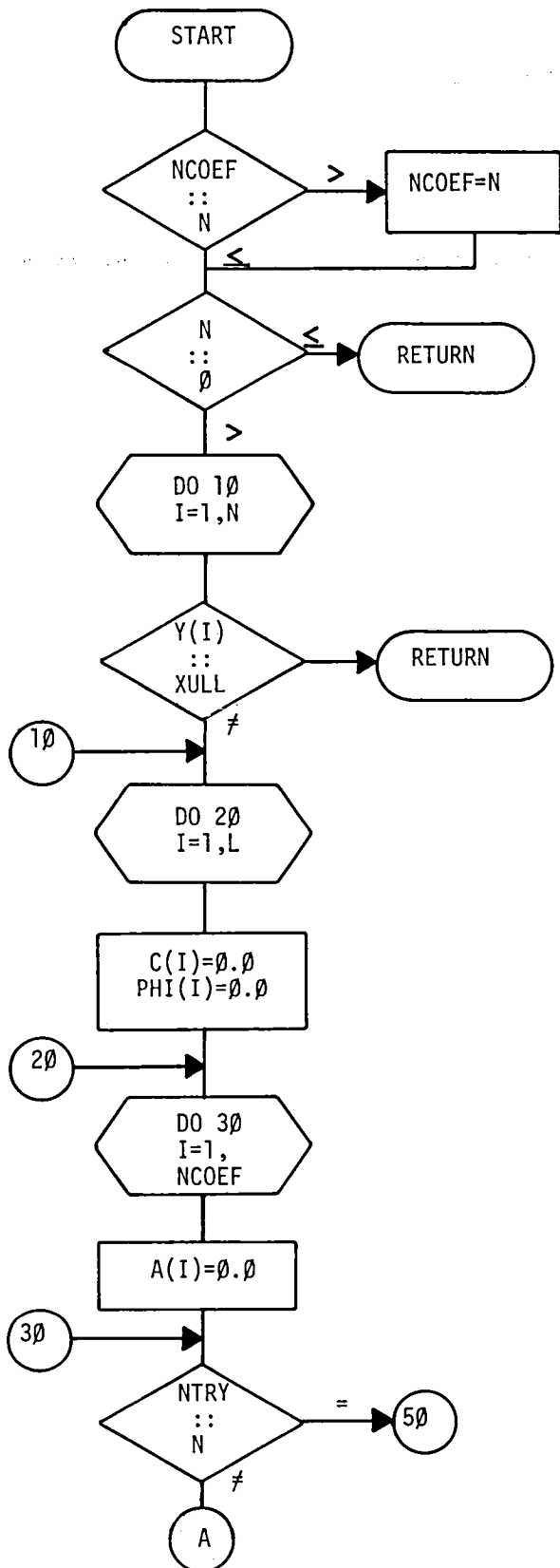
****RESTRICTIONS**

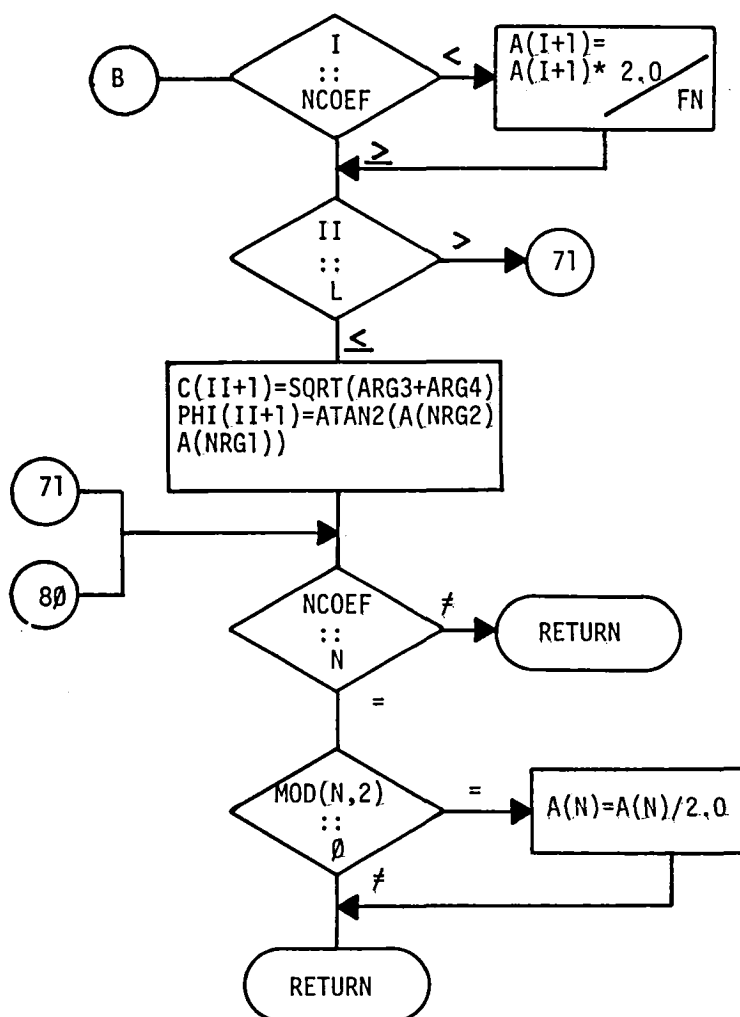
Y INPUT VECTOR LIMITED TO 144 ELEMENTS.

****SUBPROGRAMS REQUIRED**

NONE

******* SUBROUTINE FOURIE *******





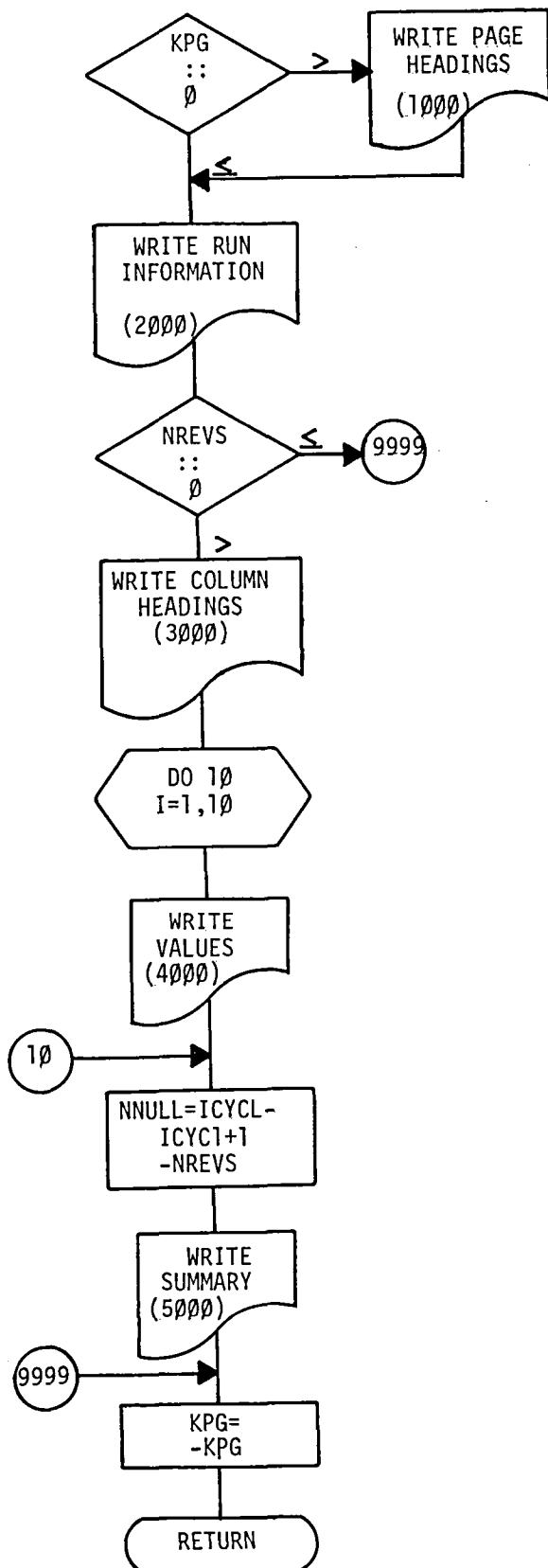
ARGUMENTS PASSED:

N
Y
NHARM
A
C
PHI
IER

BARF

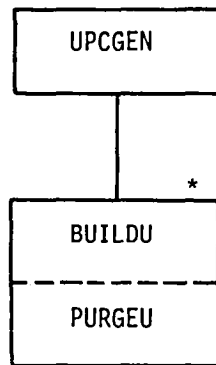
SUBROUTINE BARF(AAVG,CSIGMA,CAVG,IRUN,ICYC1,ICYCL,LTITL,NAME
X ,PHIAVG,FLTIT,REGTIT,NREVS,KPG)

**** RESULTS OF THE HARMONIC ANALYSIS ARE GENERATED UNDER SPECIFIED
**** FORMATS.



ARGUMENTS PASSED:

AAVG
CSIGMA
CAVG
IRUN
ICYC1
ICYCL
LTITL
NAME
PHIAVG
FLTIT
REGTIT
NREVS
KPG



*Comments and Flowcharts not available for this module.

HIERARCHY CHART For UPCGEN PROGRAM

UPCGEN

***** SUBROUTINE UPCGEN *****

PROGRAM IDENTIFICATION

PROGRAM NAME - UPCGEN
PROGRAM NO. - 1.1.2333
AUTHOR - DAVID L. DAVIS

COMPUTER - HW 625/635
MEMORY
PERIPHERALS -
LANGUAGE - HW 6000 FORTRAN

PURPOSE

CREAT AND MAINTAIN THE
UNIVERSAL PARAMETER CATALOG
FILE.

METHOD

A SET OF DATA CARDS ARE READ
PRECEDED BY A DIRECTIVE CARD.
THIS DIRECTIVE CARD INDICATES THE
ACTION TO BE PERFORMED. THE ACTION
MAY BE TO INITIALIZE THE FILE, INSERT
PARAMETERS, OR DELETE PARAMETERS.

***** UNIVERSAL PARAMETER CATALOG (UPC) FILE STRUCTURE *****

PERMANANT,RANDOM ACCESS DISC FILE

2 TO 139 RECORDS

280 WORDS PER RECORD

2760 PARAMETER ENTRIES WHEN FILE = 139 RECORDS

***** UPC RECORD DESCRIPTION *****

RECORD NO. 1 - TABLE OF CONTENTS

WD 1 - #UPC #
WD 2 - INTEGER NO. OF PARAMETERS IN CATALOG
WD 3,4- CONCATENATED NAME AND PPC OF
 . FIRST ENTRY IN FIRST CATALOG RECORD.
 .
 .
 .
WD 279,280 - CONCATENATED NAME AND PPC OF
 LAST ENTRY IN FILE.

THE CONCATENATED NAME AND PPC OF LAST ENTRY IN FILE
WILL IMMEDIATELY FOLLOW THE ITEM SPECIFYING THE LAST
REQUIRED CATALOG RECORD. ITS POSITION IS THEREFORE A
FUNCTION OF THE NO. OF PARAMETERS IN THE CATALOG AT
A RATE OF 20 PARAMETERS PER CATALOG RECORD.

***** RECORDS NO. 2 - 139 *****

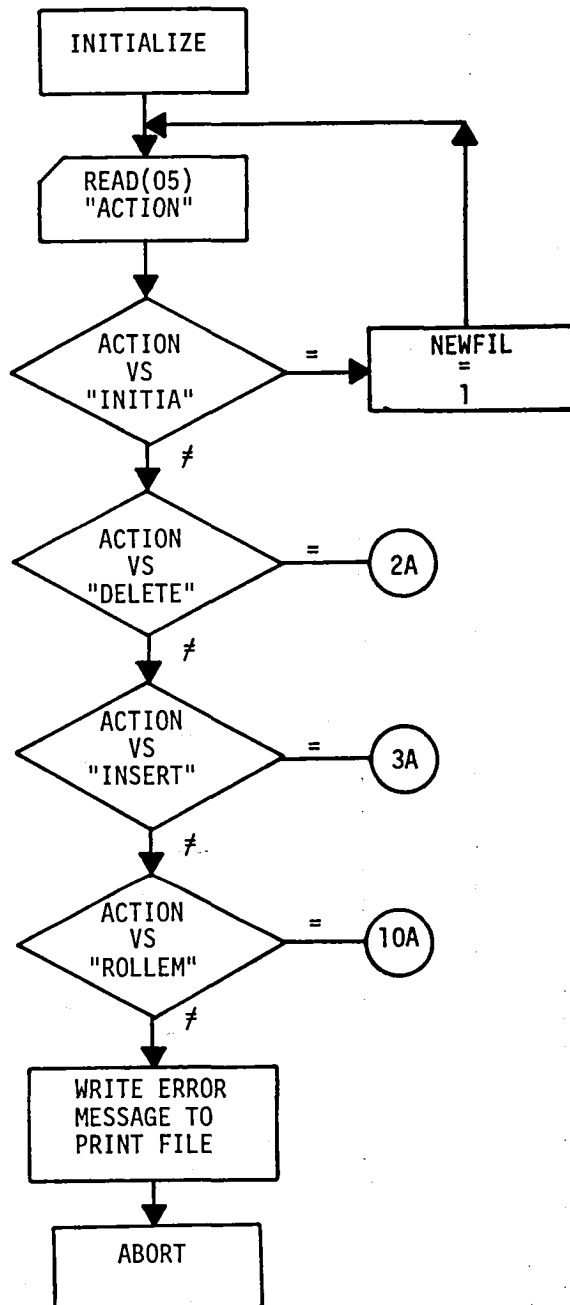
CATALOG RECORDS - 280 WORDS EACH (20 PARM) X (14 WDS/PARM)

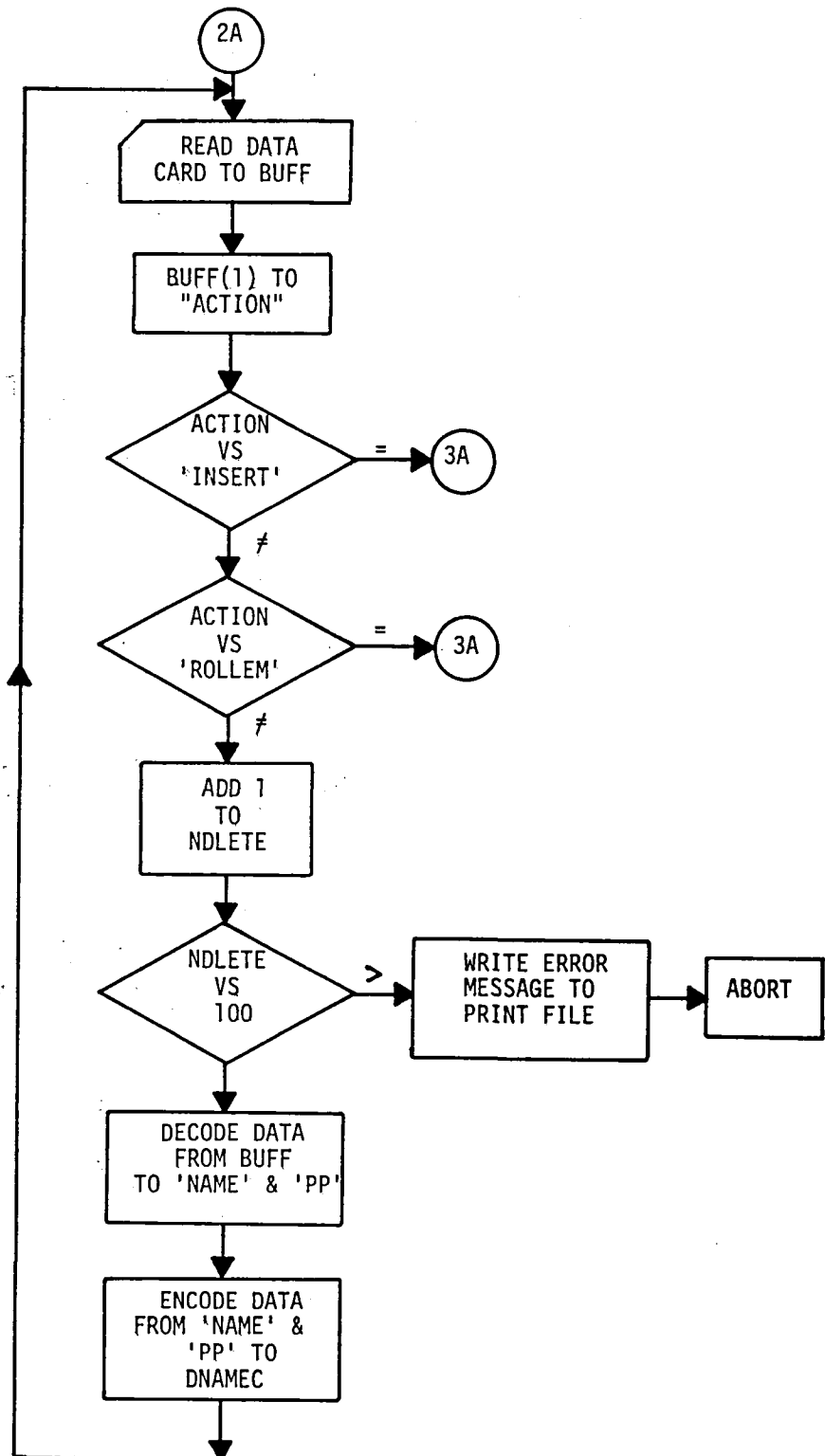
WD 1.2 NAME AND PPC OF PARM NO. 1
WD 3 PARAMETER CATEGORY
WD 4 INTEGER PRECISION CODE INDEX
WD 5.10 6 WORD COLUMN TITLE
WD 11.14 4 WORD LINE TITLE

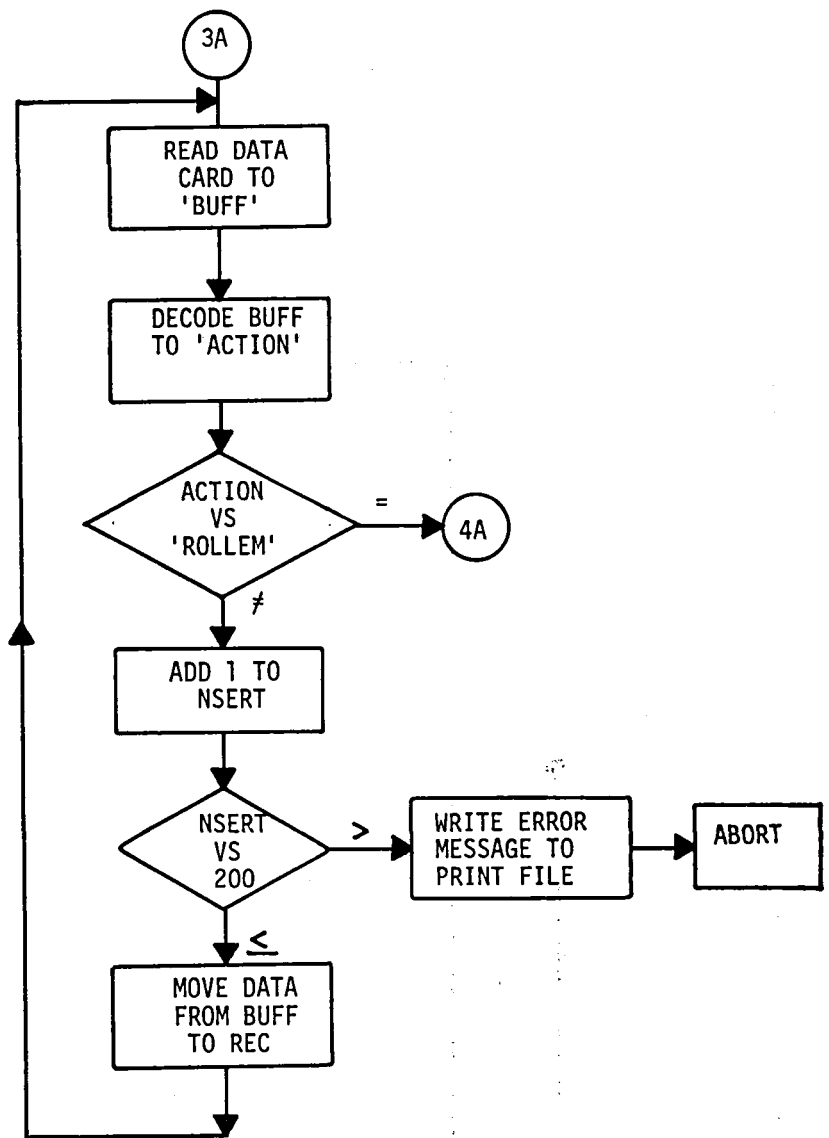
WD 15.16 NAME AND PPC OF PARM NO. 2

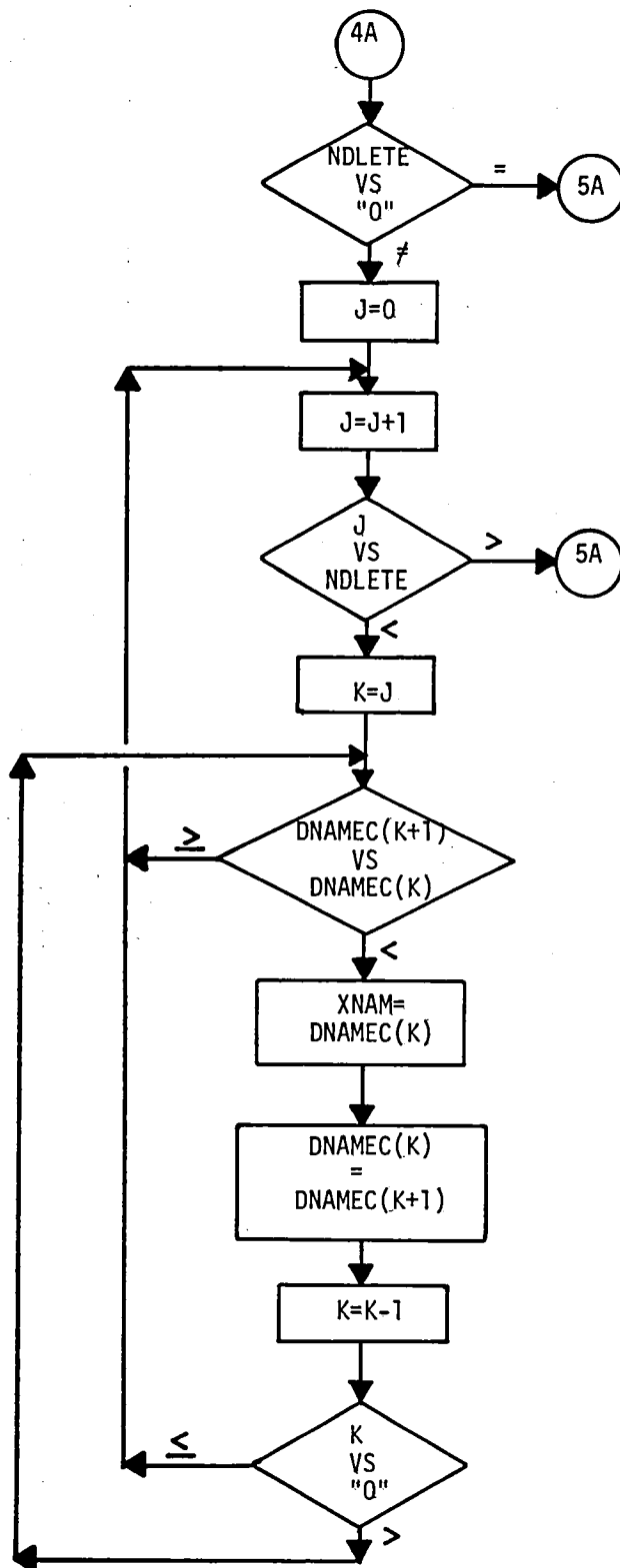
ETC

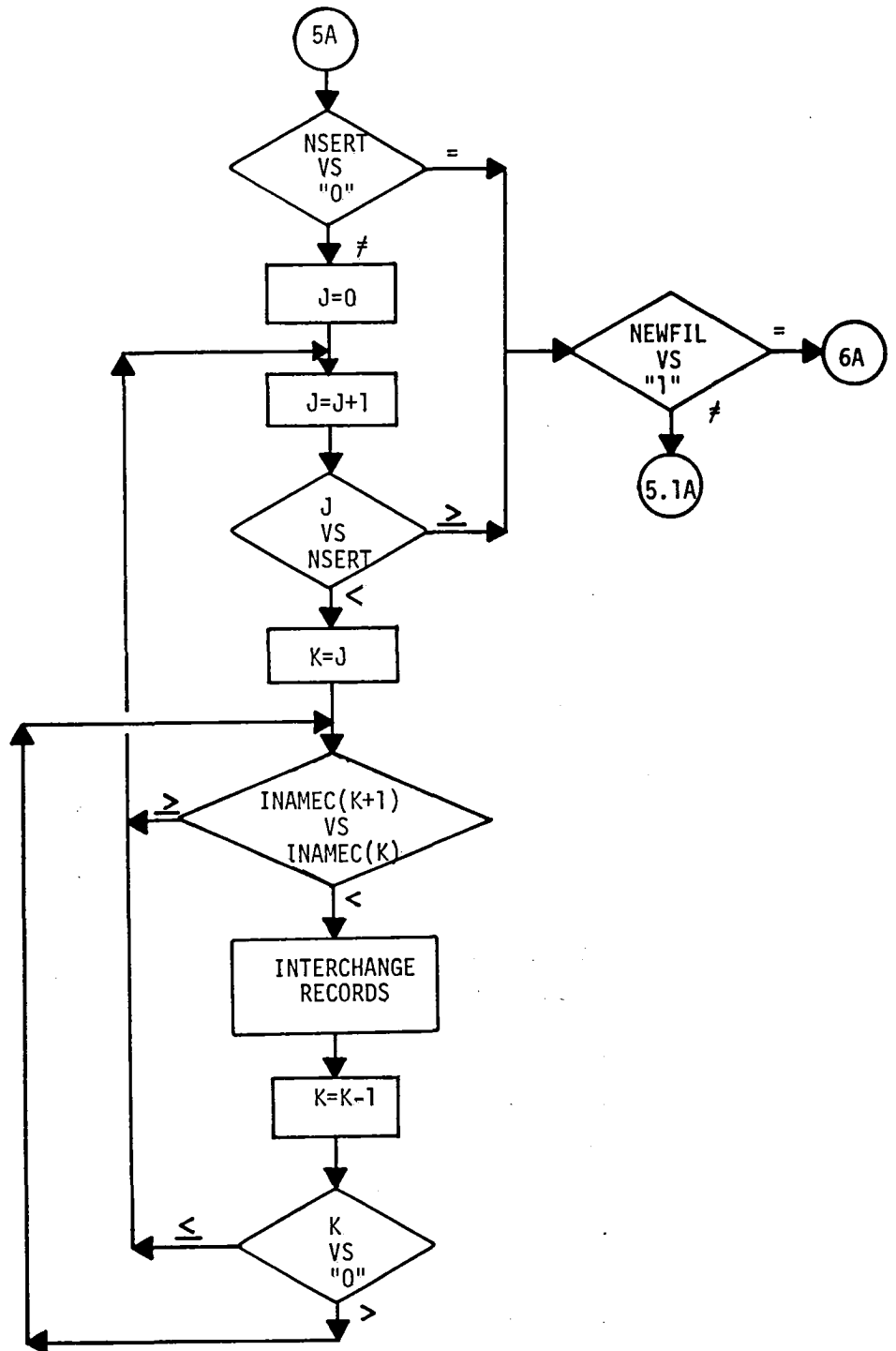
ALL PARAMETERS ARE ENTERED ALPHABETICALLY ACCORDING TO
CONCATENATED NAME AND PPC.

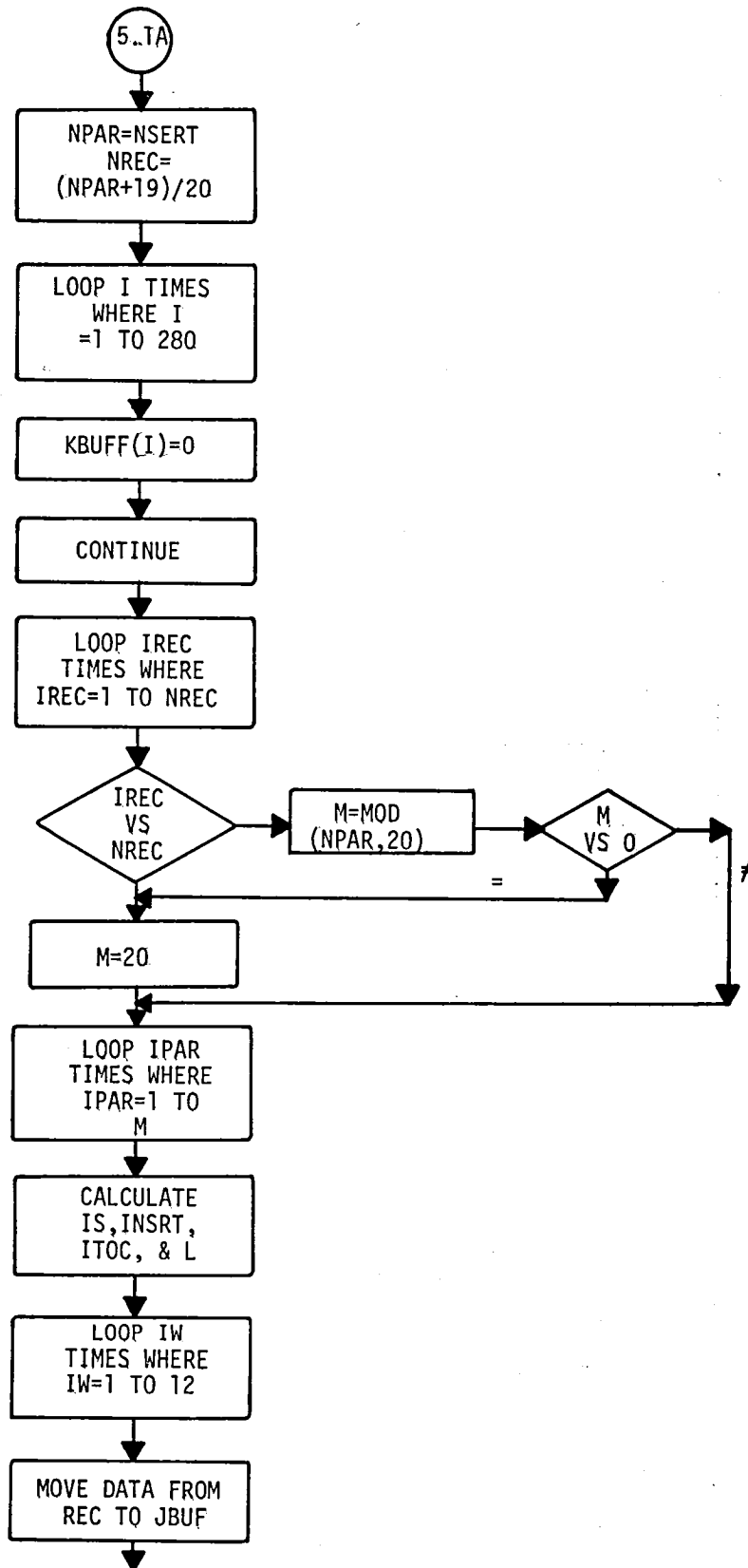


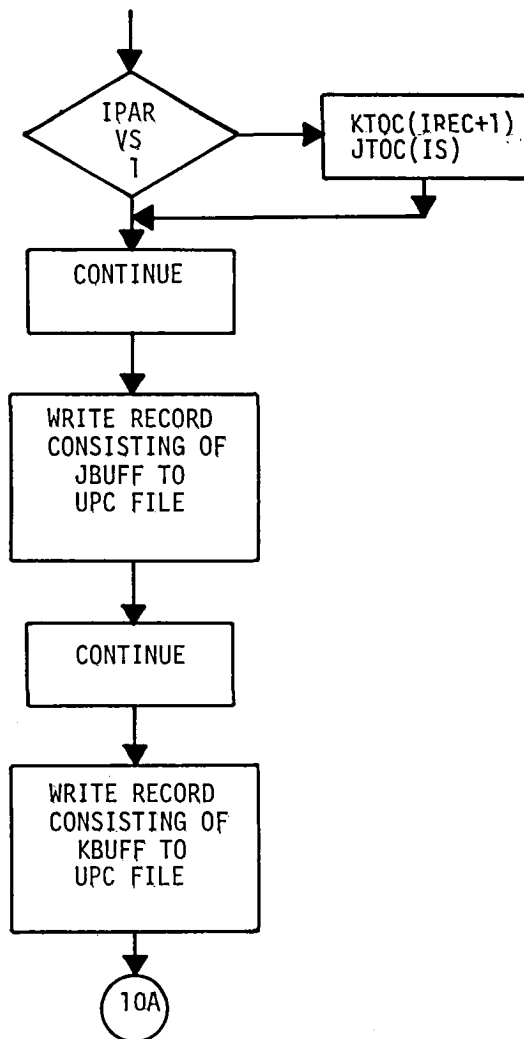


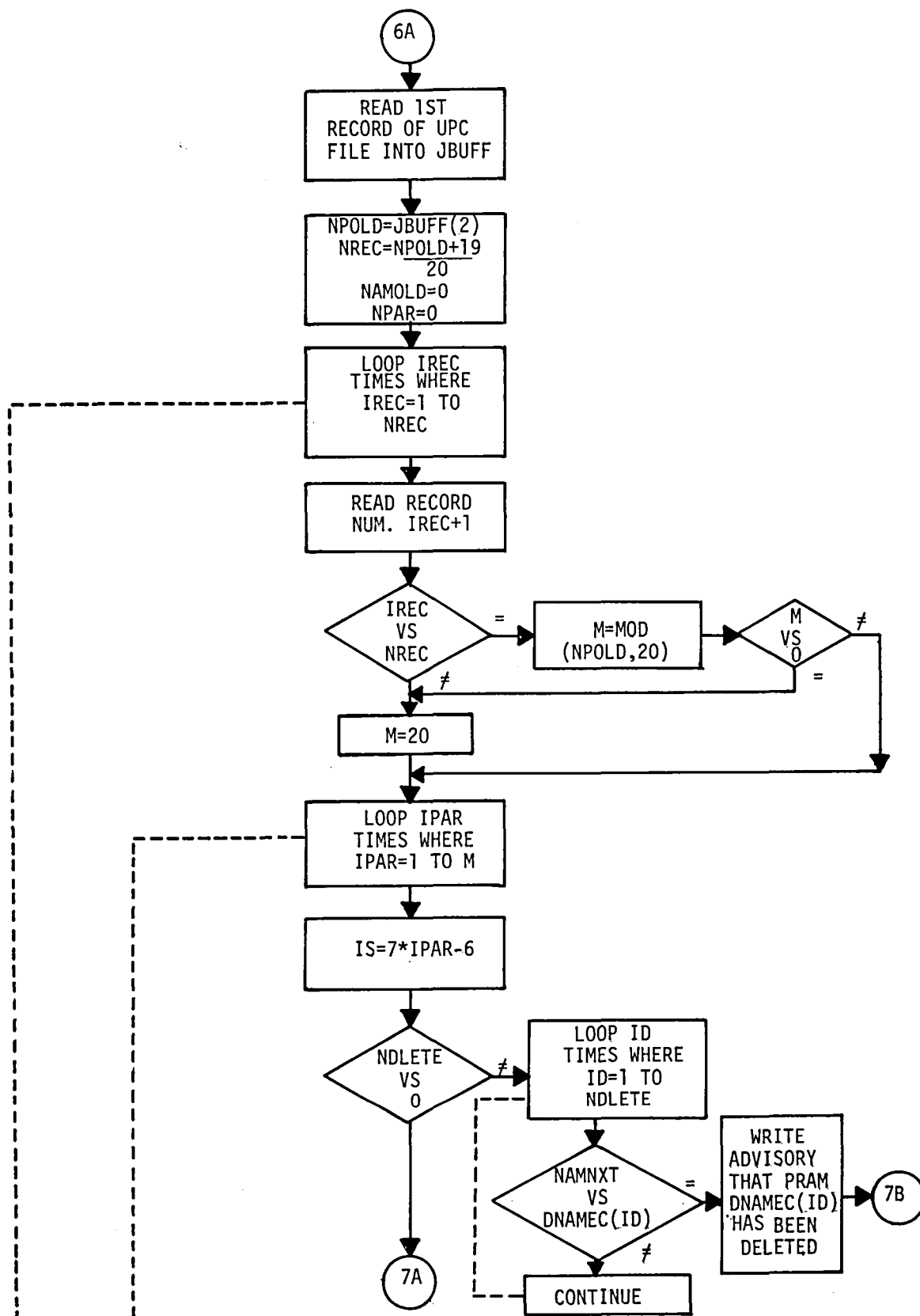


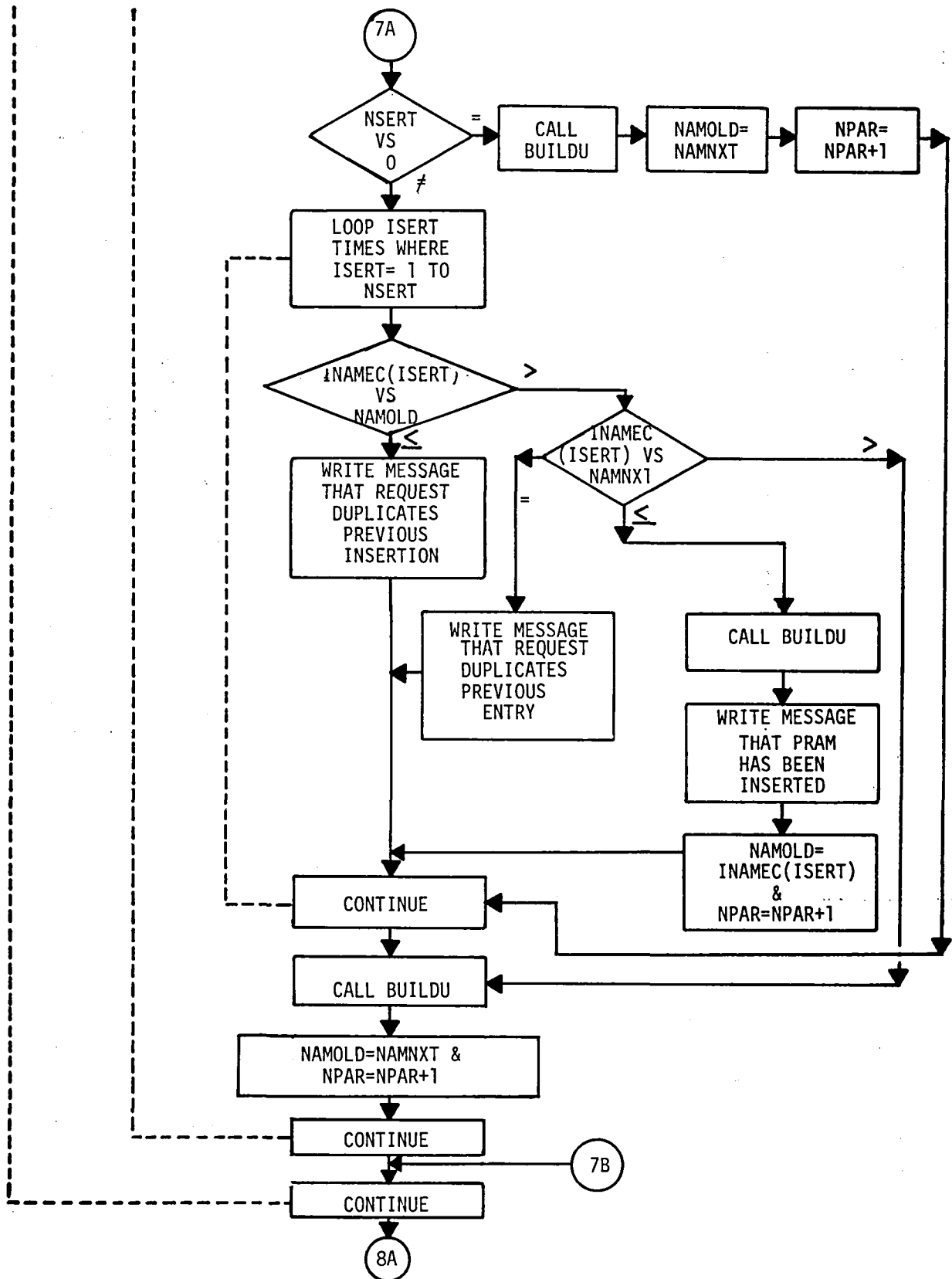


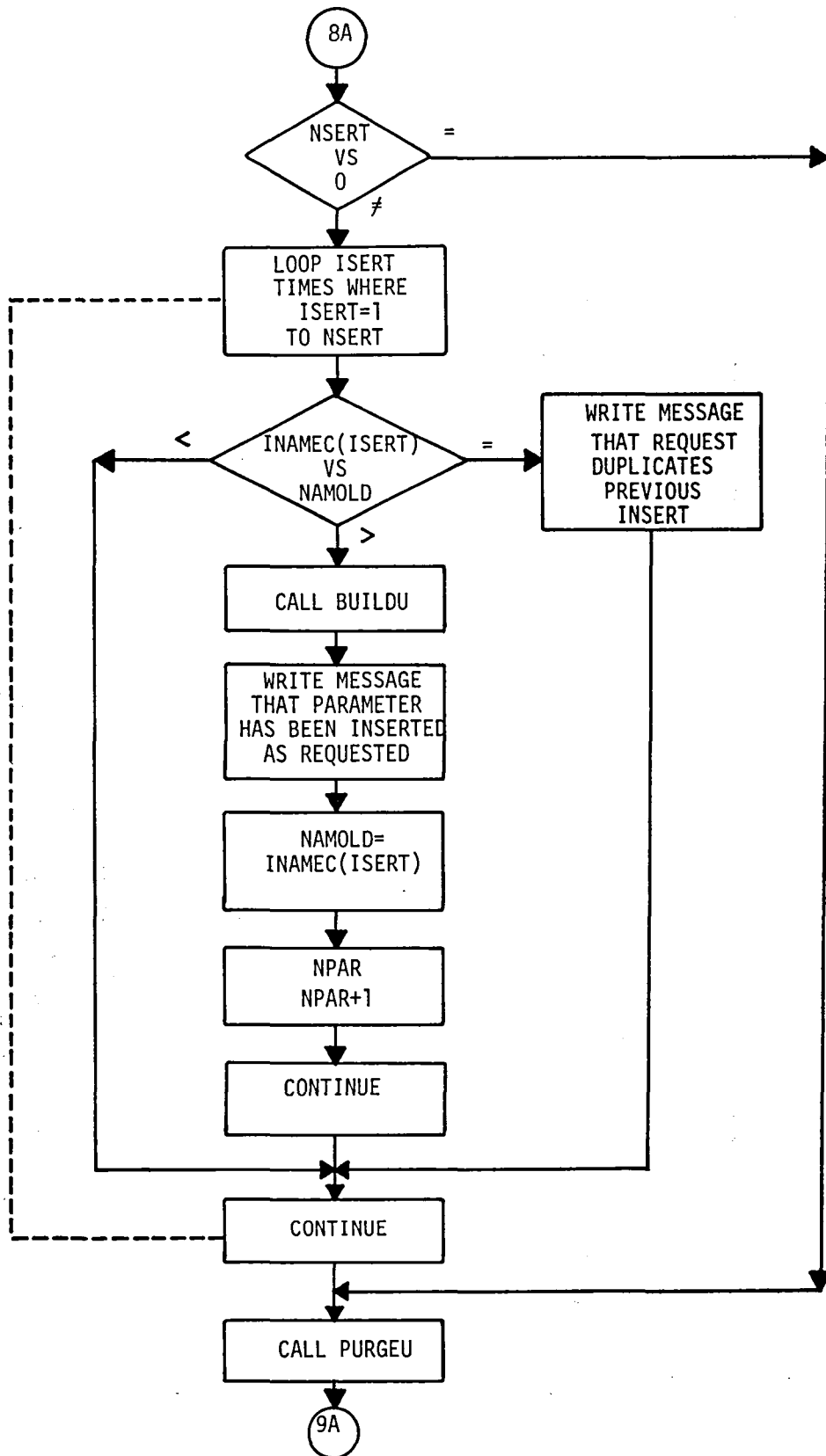


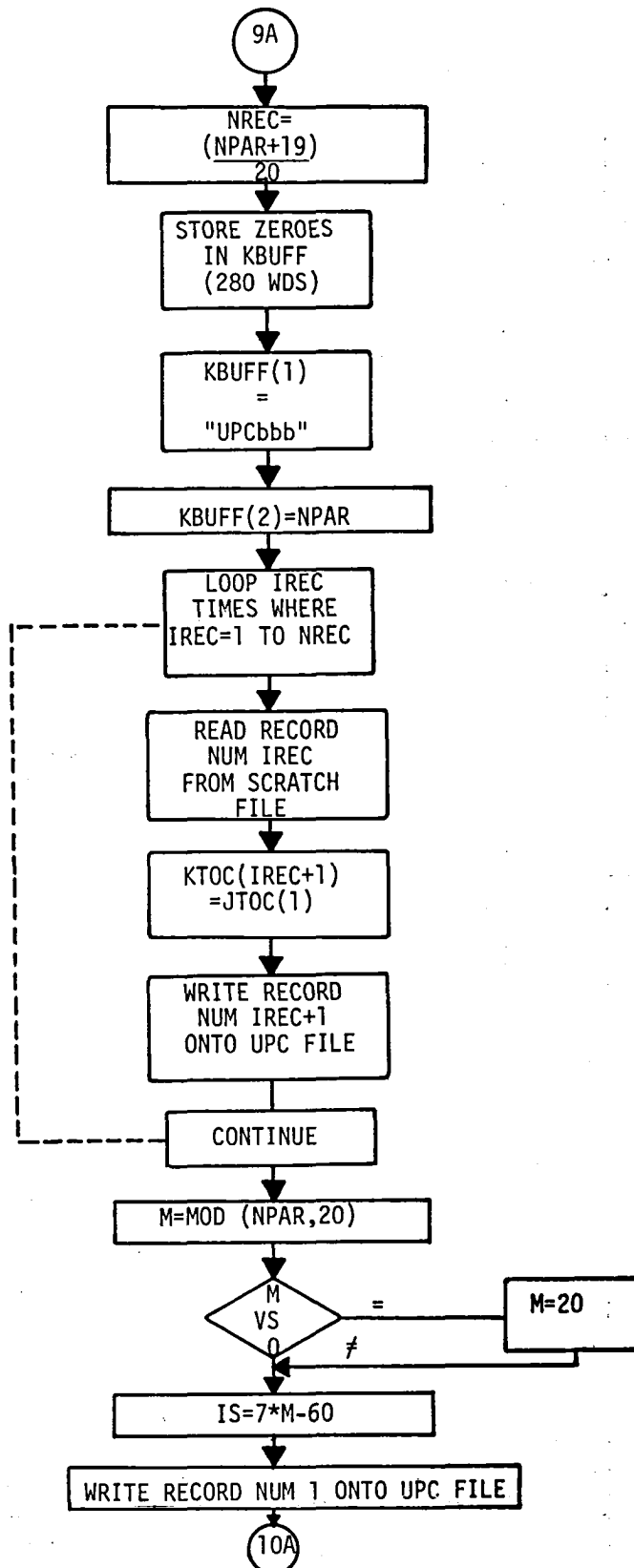


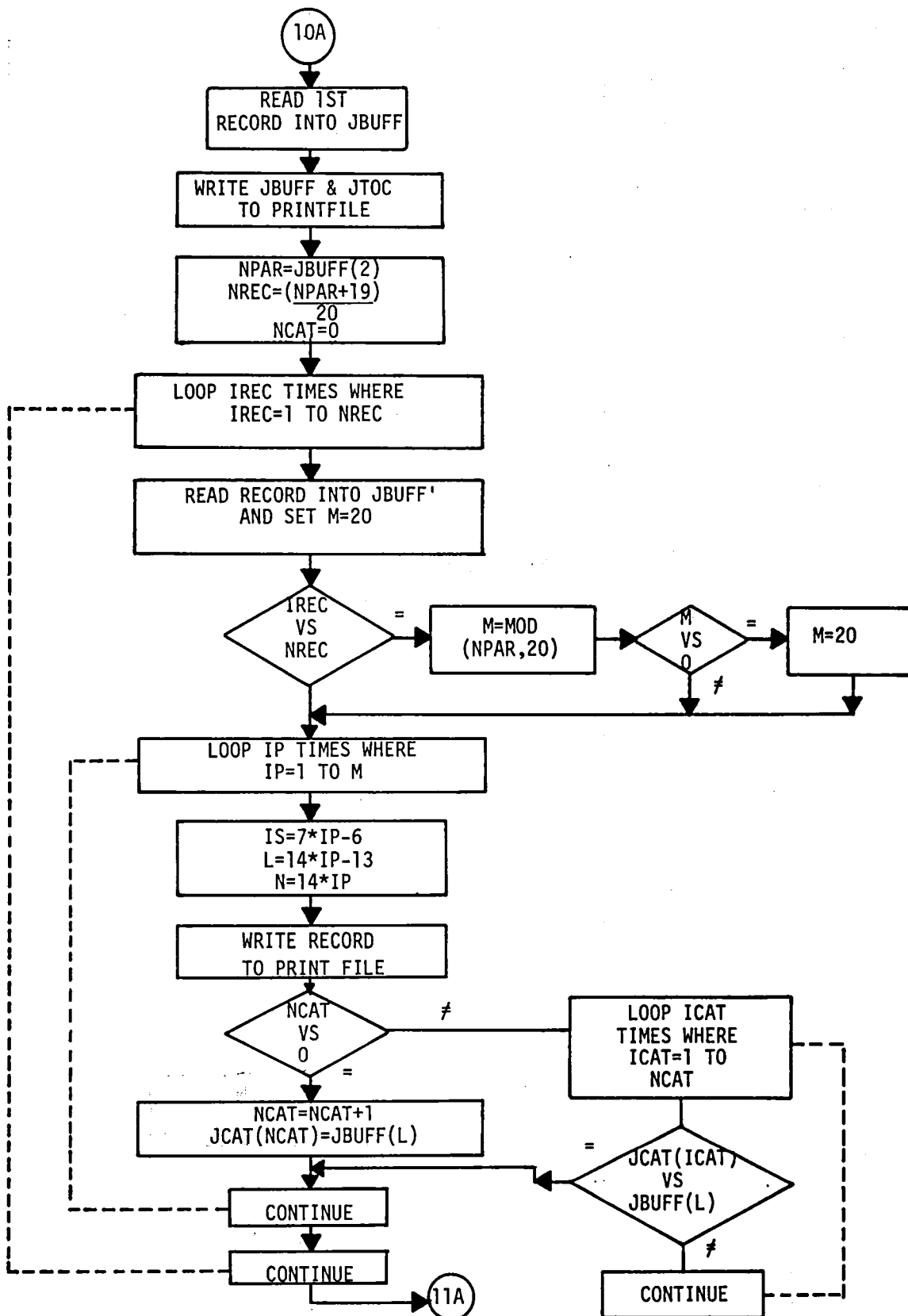


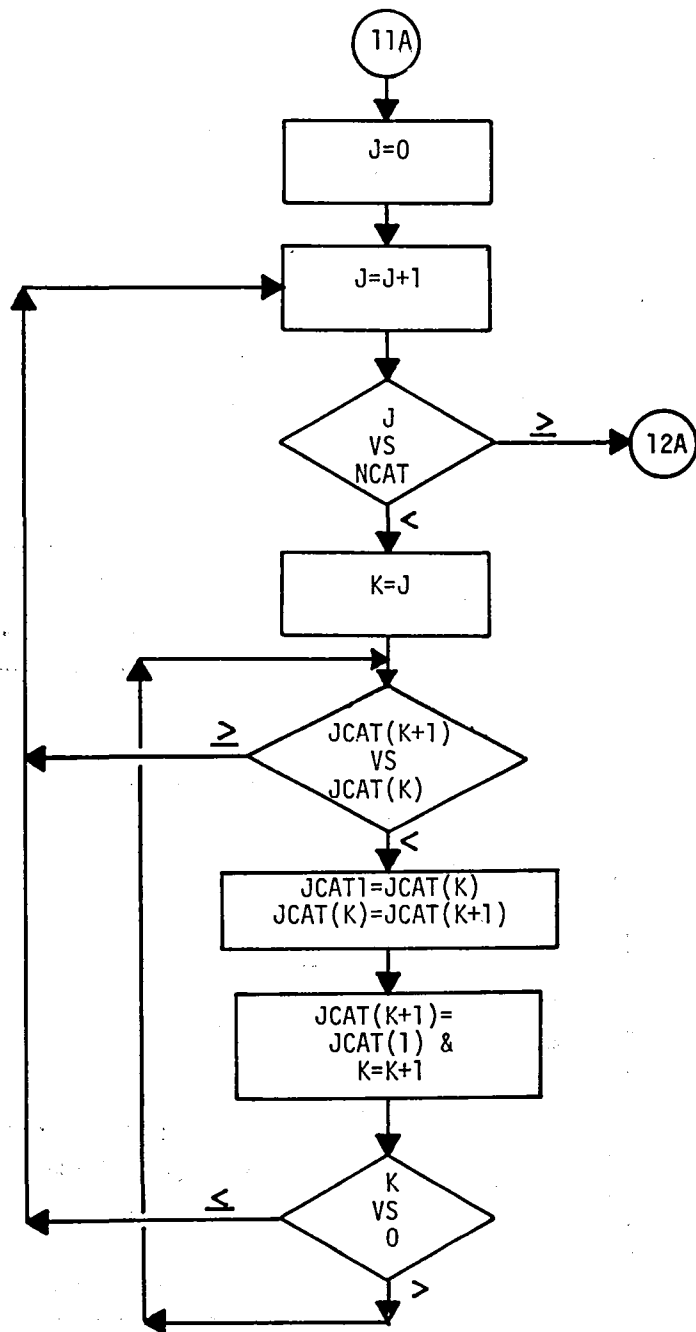


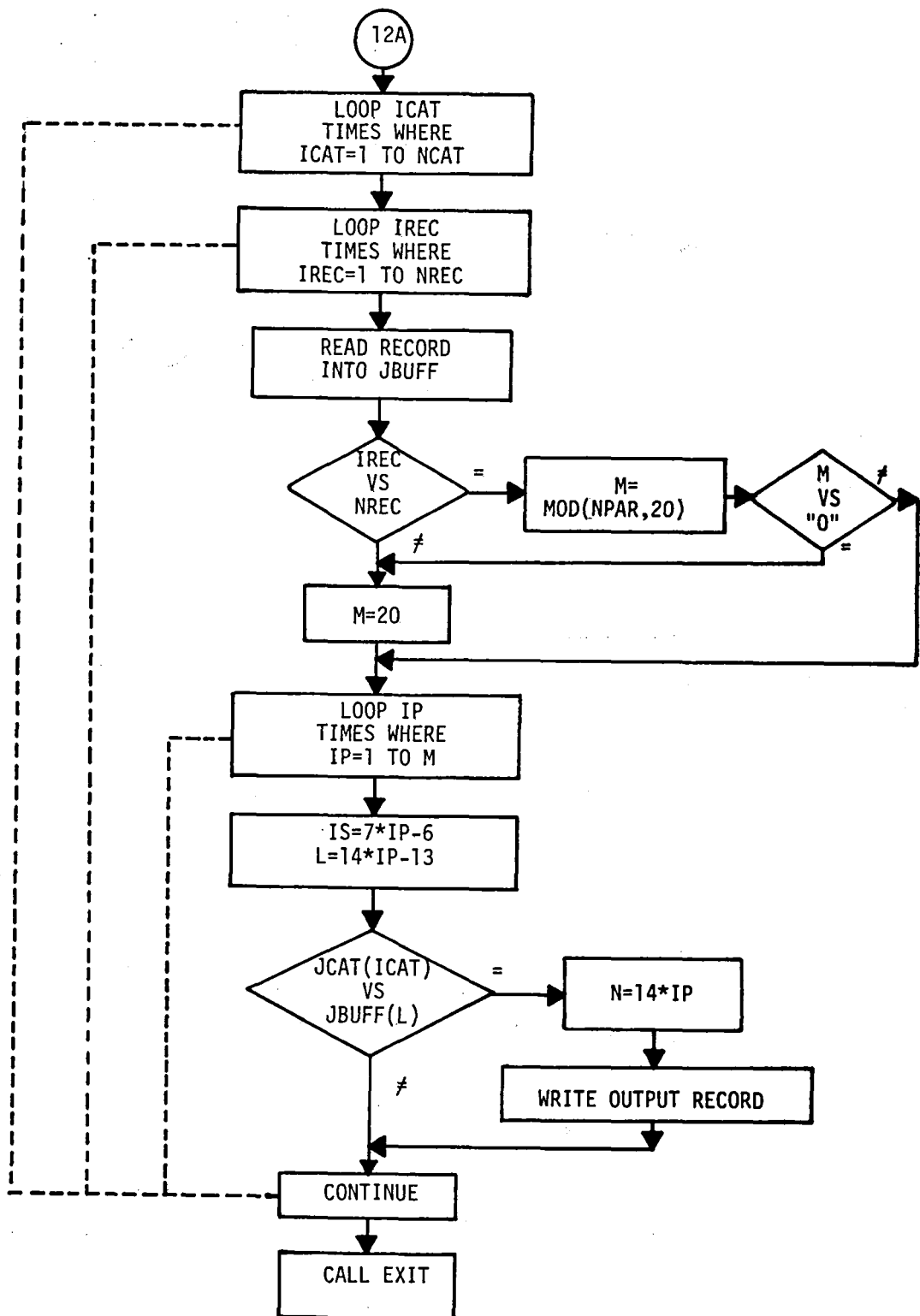


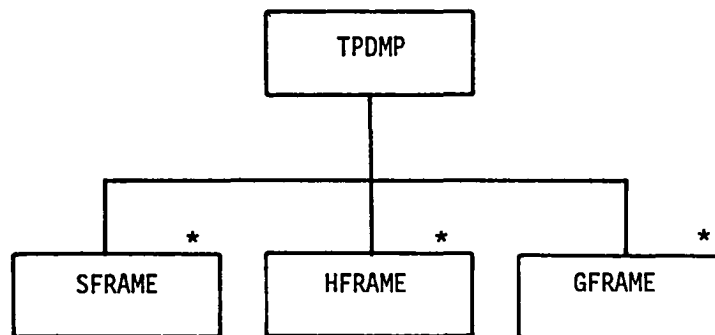












*Program Modules SFRAME, HFRAME, GFRAME documentation in NASA, WFC Program Library

HIERARCHY CHART FOR TPDMP PROGRAM

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TPDMP          9TRK TAPE DUMP PROGRAM
***** NASA Wallops VERSION OF 08/15/77

***** LANGUAGES-
          FORTRAN(Y (MAIN ROUTINE)
          GMAP(SUBROUTINES)

***** MACHINE-
          HW625 OR HW635

***** PURPOSE-
          TO DUMP PORTIONS, SPECIFIED BY THE USER, OF AN EMR 6130 TELEVENT
          II DATA TAPE IN A USABLE FORMAT.

***** METHOD-
          FROM THE CARD READER THE FOLLOWING INFORMATION IS READ<START
          TIME, STOP TIME, NUMBER OF RECORDS, TAPE FILE, STARTING WORD AND
          STOPPING WORD. THE PORTIONS OF THE 6130 TAPE DEFINED BY THIS
          CARD ARE THEN OUTPUT SEQUENTIALLY TO THE LINE PRINTER. ANY
          NUMBER OF THESE DATA CARDS MAY BE PRESENT SINCE AN EOF ON
          FILE 05 TERMINATES PROCESSING.

***** INPUT -ON FILE 05 (CARD READER)
          IDAY1 ,STARTING DAY
          IHR1  ,STARTING HOUR
          IMIN1 ,STARTING MINUTE
          ISEC1 ,STARTING SECOND
          JSEC1 ,STARTING TENTH OF A MILLISECOND
          IDAY2 ,STOPPING DAY
          IHR2  ,STOPPING HOUR
          IMIN2 ,STOPPING MINUTE
          ISEC2 ,STOPPING SECOND
          JSEC2 ,STOPPING TENTH OF A MILLISECOND
          IWSRT,STARTING WORD
          IWDSTP,STOPPING WORD
          -ON FILE 01 (6130 TAPE)
          ITIME ,FIVE WORD FRAME TIME
          IFR   ,TWO HUNDRED WORD FRAME DATA
          NWS   ,MAXIMUM NUMBER OF WORDS PER FRAME
***** OUTPUT-ON FILE 06 (LINE PRINTER)
          HEADR ,EIGHTY CHARACTER TAPE HEADER
          IFC   ,TAPE FILE TO BE PROCESSED
          IWSRT,STARTING WORD
          IWDSTP,STOPPING WORD
          ITIME ,FIVE WORD FRAME TIME
          IFR   ,TWO HUNDRED WORD FRAME DATA

***** RESTRICTIONS-
          TO OBTAIN ANY DATA AT LEAST ONE CARD MUST BE PRESENT. THIS CARD
          MAY BE BLANK IF STANDARD OPTIONS ARE WANTED.

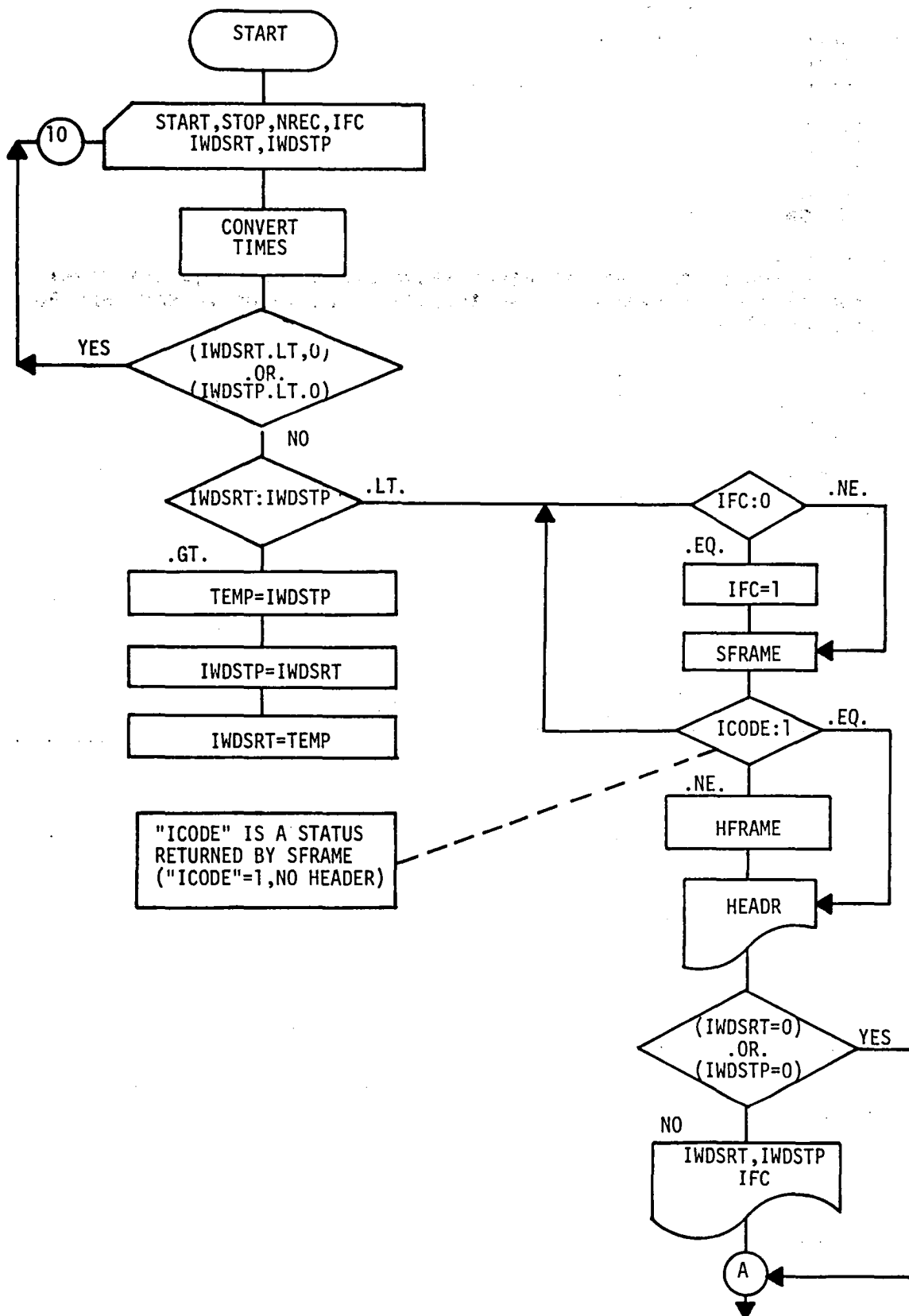
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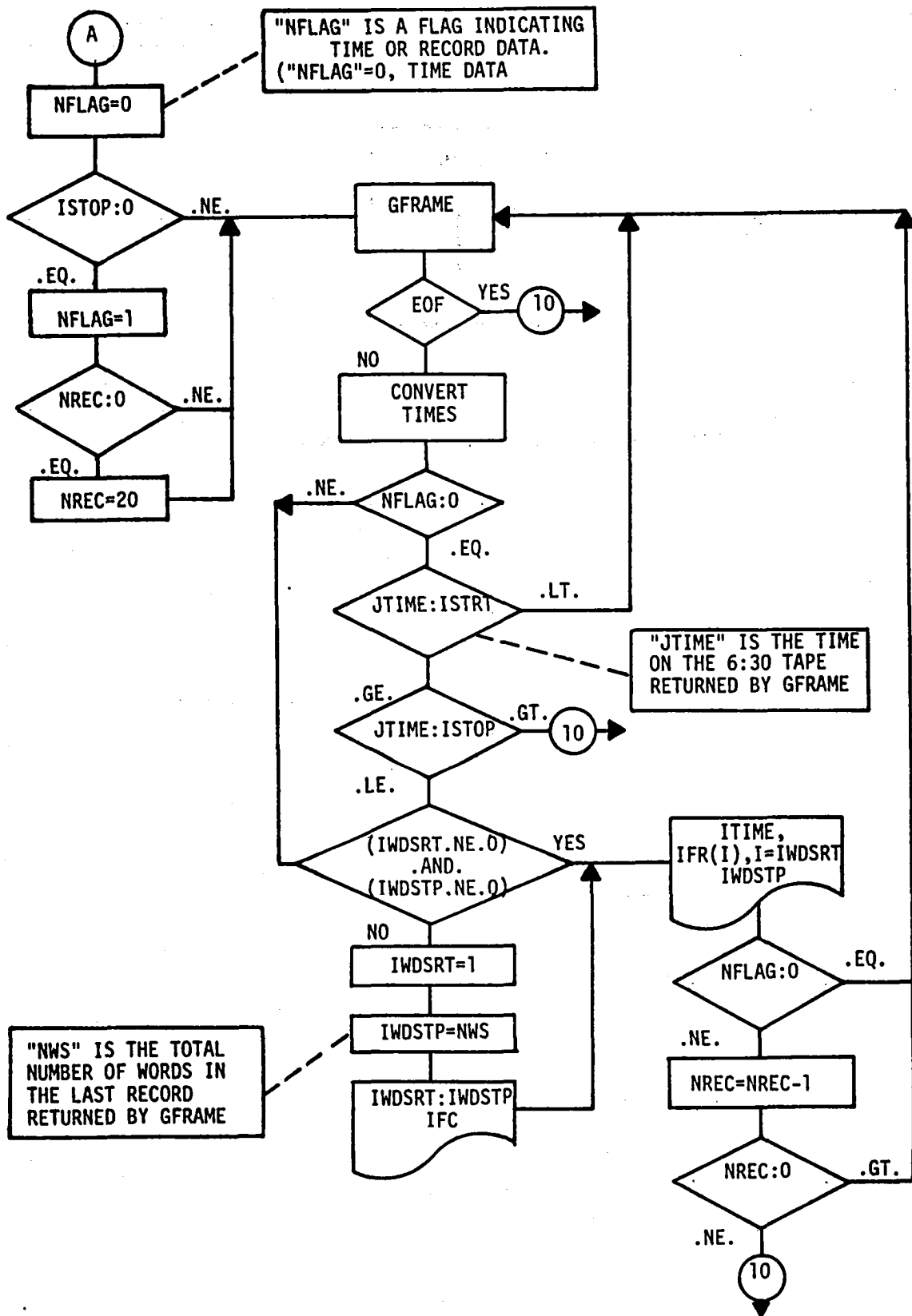
***** SUBROUTINES REQUIRED-

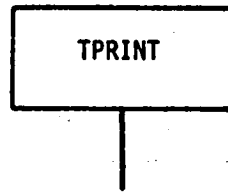
SFRAME
HFRAME
GFRAME
STATS
EBCRCD
TRANS
G8F36
G16F36

***** REMARK-

THE STANDARD OPTIONS DESCRIBED ABOVE ARE AS FOLLOWS< THE FIRST
TWENTY RECORDS FROM FILE ONE INCLUDING ALL WORDS IN EACH RECORD
ARE PRINTED.







(No Subprograms)

HIERARCHY CHART For TABLE PRINT PROGRAM

TPRINT TABLE PRINTOUT

***** NASA WALLOPS VERSION OF 08/15/77

***** LANGUAGE-
FORTRAN

***** MACHINE-
HW625 OR HW635

***** PURPOSE-
TO MAKE AVAILABLE IN A USABLE FORMAT THE INFORMATION CURRENTLY
PLACED ON AN RSRA TABLE FILE

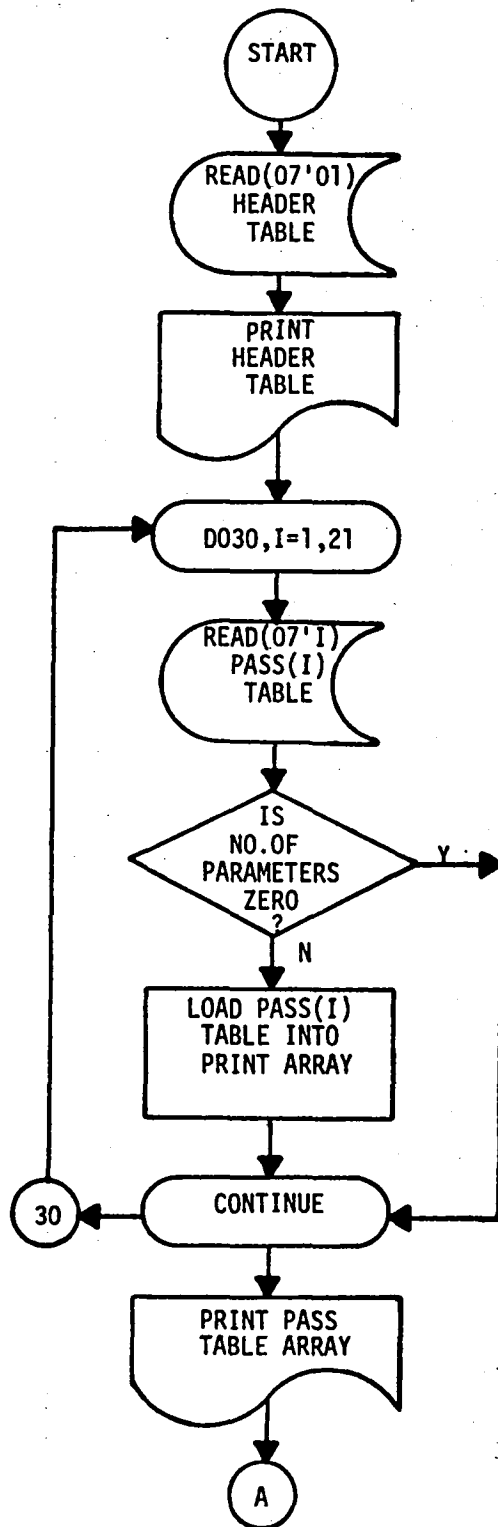
***** METHOD-
MAKING USE OF THE SUBROUTINE RANSIZ THE DISC FILE CONTAINING
THE TABLE WE ARE INTERESTED IN IS READ RECORD BY RECORD. AS
EACH RECORD IS READ THE WORDS CONTAINING INFORMATION ARE
PRINTED WITH APPROPRIATE LABELS. NO CARD INPUT IS USED.

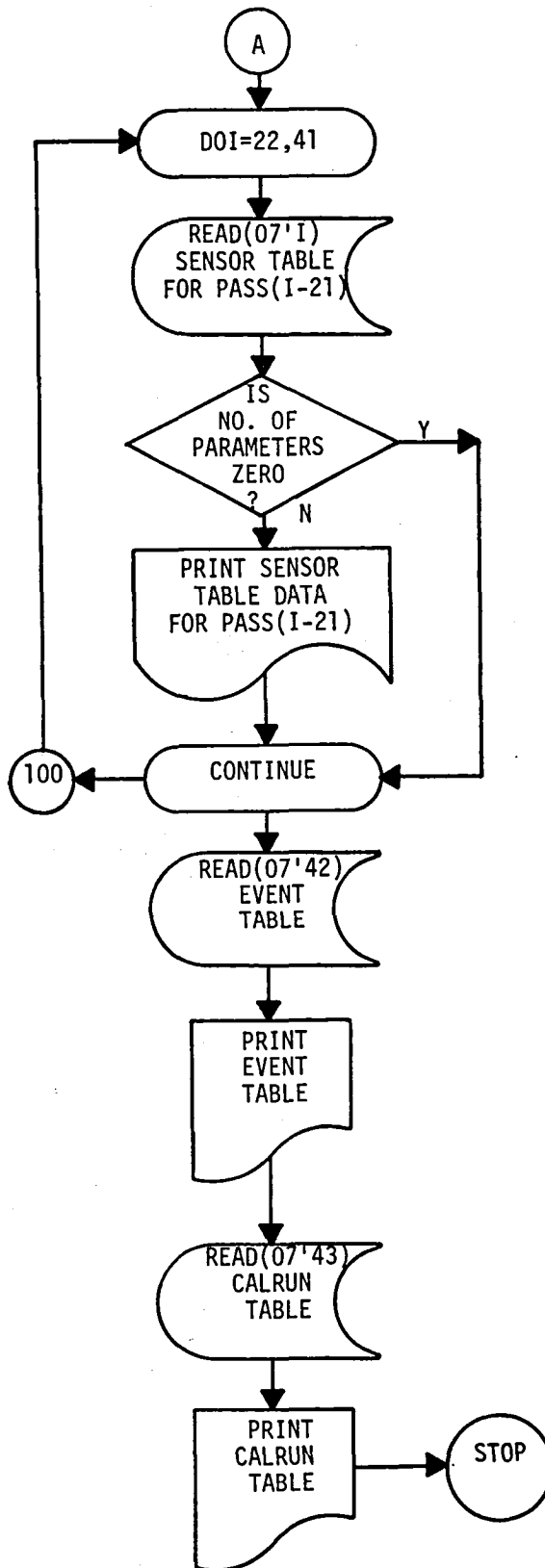
***** INPUT -ON FILE 07 (THE DISC FILE CONTAINING TABLE)
THEAD -TWENTY SEVEN WORD HEADER RECORD
TPASS -TWENTY RECORD, ONE HUNDRED TWENTY WORD PASS TABLE
TSNSNE -TWENTY RECORD, FIVE HUNDRED TWENTY WORD SENSOR TABLE
TEVNT -SIX HUNDRED WORD EVENT RECORD
TCALR -ONE HUNDRED TWENTY WORD CALIBRATION RECORD

***** OUTPUT-ON FILE 06 (THE LINE PRINTER)
THEAD -TWENTY SEVEN WORD HEADER RECORD
TPASS -TWENTY RECORD, ONE HUNDRED TWENTY WORD PASS TABLE
TSNSNE -TWENTY RECORD, FIVE HUNDRED TWENTY WORD SENSOR TABLE
TEVNT -SIX HUNDRED WORD EVENT RECORD
TCALR -ONE HUNDRED TWENTY WORD CALIBRATION RECORD

***** RESTRICTIONS-
NONE

***** SUBROUTINES-
NONE





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16. Abstract A system of independent computer programs for the processing of digitized pulse code modulated (PCM) and frequency modulated (FM) data. Information is stored in a set of random files and accessed to produce both statistical and graphical output. The software system is designed primarily to present these reports within a twenty-four hour period for quick analysis of the vehicle's performance.			
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